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**GEOMETRICALLY NONLINEAR ARC LENGTH SPARSE FINITE ELEMENT
ANALYSIS AND OPTIMAL DESIGN OF TRUSS STRUCTURES**

by

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A Dissertation Submitted to the Faculty of Old Dominion University
in Partial Fulfillment of the Requirements for the Degree
of

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CIVIL ENGINEERING

OLD DOMINION UNIVERSITY
August 2009

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ABSTRACT

**GEOMETRICALLY NONLINEAR ARC LENGTH SPARSE FINITE
ELEMENT ANALYSIS AND OPTIMAL DESIGN OF TRUSS
STRUCTURES**

Glenn A. Hrinda, P.E.
Old Dominion University, 2009
Director: Dr. Duc T. Nguyen

A technique for the optimization of stability-constrained geometrically nonlinear shallow trusses with snap-through behavior is demonstrated using the arc length method and a strain energy density approach within a discrete finite element formulation. The optimization method uses an iterative scheme that evaluates the performance of the design variables and then updates them according to a recursive formula that is controlled by the arc length method. A minimum weight design is achieved when a uniform nonlinear strain energy density is found in all members. This minimal condition places the design load just below the critical-limit load that causes snap-through of the structure. The optimization scheme is programmed into a nonlinear finite element algorithm to find the large strain energy at critical-limit loads. Examples of highly nonlinear trusses that are found in the literature are presented to verify the method.

This dissertation is dedicated to
my parents,
my wife, Liz,
and my children: Amy, Rachael, Joshua, Hannah and Zachary.

ACKNOWLEDGMENTS

I would like to thank my advisor (Professor Duc Nguyen) and committee members (Professor Gene Hou and Professor Chuh Mei) for their guidance and encouragement. Special thanks to Dr. Jay Warren for helping me to appreciate more about the arc length method and also to my NASA supervisor, Dr. John Korte for his insight and suggestions. Special thanks to Dr. Crisfield, since I was fortunate to find your two valuable volumes on the arc length method. Finally, I would like to dedicate my dissertation to my family for their patience, love and encouragement during the journey.

TABLE OF CONTENTS

Chapter	Page
I. INTRODUCTION	1
1.1 Overview.....	3
1.2 Objective.....	8
II. ARC LENGTH METHOD.....	10
2.1 Review of Arc Length Formulas.....	10
2.2 Linear/Nonlinear, Symmetrical/Unsymmetrical Equation Tests.....	19
III. GEOMETRICALLY NONLINEAR 3-D	
TRUSS ELEMENT STIFFNESS	21
3.1 Derivation of 3-D Geometrically Nonlinear Truss Element Stiffness.....	21
3.2 Element Internal Force.....	26
3.3 Nonlinear 3-D Truss Element Stiffness	29
IV. NONLINEAR TRUSS VERIFICATION TESTS.....	30
4.1 Single-Degree-of-Freedom Nonlinear Example.....	30
4.2 Star Dome Truss	35
4.3 Crisfield Arch Truss.....	45
V. SPARSE COMPUTING TECHNIQUES	51
5.1 Sparse Storage.....	51
5.2 Sparse Solver	57

Chapter	Page
5.3 Symbolic Sparse Factorization	59
VI. DERIVATIONS OF OPTIMUM NONLINEAR STRAIN ENERGY	
DENSITY FORMULAS.....	62
6.1 Green's Strain	63
6.2 Strain Energy Density Formulation	65
6.3 Optimality Criterion.....	67
VII. DESIGN-VARIABLE SCALING	75
7.1 Scale Strain Parameter	76
7.2 Program Outline	80
VIII. VERIFICATION EXAMPLES OF OPTIMIZED TRUSSES.....	82
8.1 Two-Member Symmetric Truss Example.....	83
8.2 Two-Member Asymmetric Truss Example	86
8.3 Four-Member Asymmetric Truss Example	88
8.4 Star Dome Truss Example	96
8.5 Large Shallow Truss Example.....	100
IX. DISCUSSION.....	102
X. CONCLUSIONS AND FUTURE RESEARCH	105
BIBLIOGRAPHY	108
APPENDIX A-Hrinda Rikarc Users' Input Data Description	111
A.1 Auro Function Example.....	111

Chapter	Page
A.2 Auro 2 Function Example.....	112
A.3 Hrinda 1 Function Example.....	114
A.4 Hrinda 3 Function Example.....	115
A.5 SDOF Crisfield Example	117
A.6 Star Dome Crisfield Example	120
A.6.1 Star Dome Geer Example	124
A.7 Truss Arch Example.....	125
A.7.1 Typical arch equilibrium paths	129
APPENDIX B- Hrinda Rikarc Optimization Users' Input Data Description.....	130
B.1 Optimum Khot 2 Element Symmetric Example	130
B.2 Optimum Khot 2 Element Unsymmetric Example	132
B.3 Optimum Khot 4 Element Asymmetric Example	135
B.4 Optimum Khot 30 Element Star Example.....	138
B.5 Optimum Khot Large Shallow Truss Example.....	144
APPENDIX C-FORTRAN Source Code.....	154
C.1 Hrinda Rikarc	154
C.2 Hrinda Rikarc Optimization	191
VITA.....	232

LIST OF TABLES

Table	Page
1. Quantitative results comparison of sdof problem using NASTRAN.....	33
2. Khot four bar truss nodal coordinates	53
3. Strain energy density distribution for two-element symmetric truss	84
4. Iteration weight history for two-element symmetric truss.....	84
5. Area and strain energy density distribution of two-element asymmetric truss.....	87
6. Iteration weight history of two-element asymmetric truss	87
7. Khot [13] element properties	89
8. Hrinda final design.....	90
9. Quantitative results of four-member truss problem using NASTRAN	91
10. Iteration weight history for four-member truss.....	92
11. SED per element at each iteration from Hrinda results	93
12. Area and strain energy density distribution in four-member truss	94
13. Effects of “dSEDtol” value on final weight and number of iterations	94
14. Effect of using different initial areas on the final weight	95
15. Star dome optimization groups	96
16. Star dome strain energy density and truss area design	98
17. Star dome weight summary	99
18. Final optimized group truss areas	99
19. Shallow truss strain energy density and final design areas.....	100
20. Hrinda and Khot Area comparisons.....	101
21. Hrinda shallow truss weight results	101

LIST OF FIGURES

Figure	Page
1. Solar power satellite platform.....	2
2. International Space Station	2
3. Photographs of fabricated MEMS switch	3
4. Equilibrium paths for nonlinear and bifurcation/eigenvalue buckling [15].....	6
5. Starting the arc length	11
6. Next iteration.	12
7. Convergence tests	14
8. Iteration on a normal.....	15
9. Details of iteration on a normal	16
10. Continuing iteration on normal.....	18
11. Nonlinear 3-D truss variables	23
12. Single-degree-of-freedom truss spring problem	31
13. Crisfield single-degree-of-freedom model.....	32
14. Load increment vs. displacement for the sdof problem.....	32
15. Single-degree-of-freedom deflections	34
16. Crisfield Three-dimensional star dome.....	36
17. Star dome deflections.....	39
18. Star dome deflections.....	40
19. Star dome deflections.....	41
20. NASTRAN/Hrinda star dome result at center load increment vs. vertical displacement	42

Figure	Page
20a. NASTRAN/Hrinda star dome magnified results of first snap-through from A to A'.	43
20b. NASTRAN/Hrinda star dome magnified results of second and third snap-through	44
21. Crisfield large circular arch	46
22. Arch deformations	47
23. Arch deformations	48
24. Arch deformations	49
25. Arch Load Deflection apex comparisons of NASTRAN vs. Hrinda.....	50
26. Khot four bar truss	52
27. Element connectivity arrays.....	53
28. Khot four element truss stiffness matrix after applying restraints.....	55
29. Truss elongation from load P	64
30. The Riks-Wempner arc length method on a normal plane for a single-degree- of-freedom system	77
31. Flowchart for the Hrinda optimizer program.....	79
32. Two-element symmetric truss with 200-lb apex load.....	83
33. Khot and Kamat load displacement curve for two-member symmetric truss with cross-section areas equal to 6.4977 in^2	84
34. Hrinda load displacement curve for two-member symmetric truss with cross- section areas equal to 6.4999 in^2	85
35. Two-element asymmetric truss	87

Figure	Page
36. Plan view of the four-member asymmetric truss example.....	89
37. Four-member truss at snap-through	89
38. Four-member asymmetric truss equilibrium path during snap-through	90
39. Load-displacement results for center node of four-member truss using Hrinda results in NASTRAN	91
40. Star dome truss example	96
41. Load-displacement results for center node of star dome truss using Khot results in NASTRAN.....	97
42. Shallow truss half-symmetry model with two point loads	100

CHAPTER I

INTRODUCTION

Large aerospace truss systems have been proposed over the years to support the future of orbital space technologies. For example, since the 1960's, various research organizations have supported the deployment of space-based solar power. The U.S. Department of Defense is currently studying how to deploy a solar power constellation to supply power to remote bases or on the battlefield. Also during the 1960's, Rockwell International began to study solar power satellites (SPS) that used large space truss structures (figure 1) for supporting microwave antennae and mirrors [1]. The International Space Station currently makes use of deployable trusses (figure 2) to support its solar array panels. Flexible structures that can be stowed in very limited volumes for efficient packing into launch payloads are desirable in order to reduce mission costs. The quick deployment of these structures reduces risks by minimizing extravehicular activities while increasing reliability by having few joints. All of these space-based concepts rely on truss systems to support their mission goals because a truss is easier to assemble in microgravity and offers a minimum weight design. The lighter and more efficient these structural systems become (i.e. with very slender members), the more likely they are to have nonlinear stability problems. Civil engineering structures are also prone to instability such as shallow domes, large spanning bridges and transmission towers. The analysis challenge is to find effective techniques that go beyond the

identification of Euler-type bifurcation points and find the optimal truss to carry applied limit loads without becoming unstable and releasing stored strain energy.

Space trusses may suddenly collapse if their failure modes are not understood. These structures may be designed to maintain their integrity even after an initial inelastic failure. Some structures may collapse after a localized failure of one of their members. This is a progressive failure that redistributes loads causing other members to fail until the total structure becomes unstable [2]. To accurately model a progressive failure, an analysis method that can create a load vs. displacement response during instability is required. Methods that have been used involved creating finite element models that update their stiffness according to nonlinear geometric response [2].

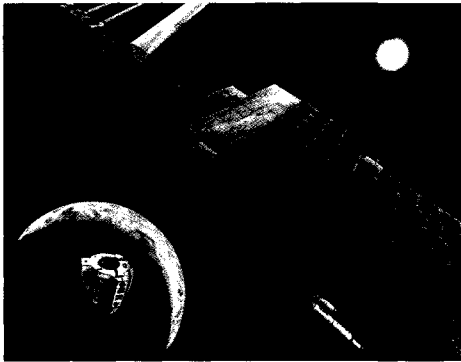


Figure 1. Solar power satellite platform.



Figure 2. International Space Station.

Another current use for optimizing snap-through type structures is in the miniaturization of electronic devices known as “micro electro mechanical systems” (MEMS) [3]. These are micro formed structures that are integrated into silicon chips. The micro structures may be formed by beams or plates that snap-through under electrostatic forces. Figure 3 shows a MEMS switch before and after snap-through. The

micro switch is a silicon beam about 25 micro meters in length that is activated by an electrostatic charge. The electronic industry uses these micro structures as switches

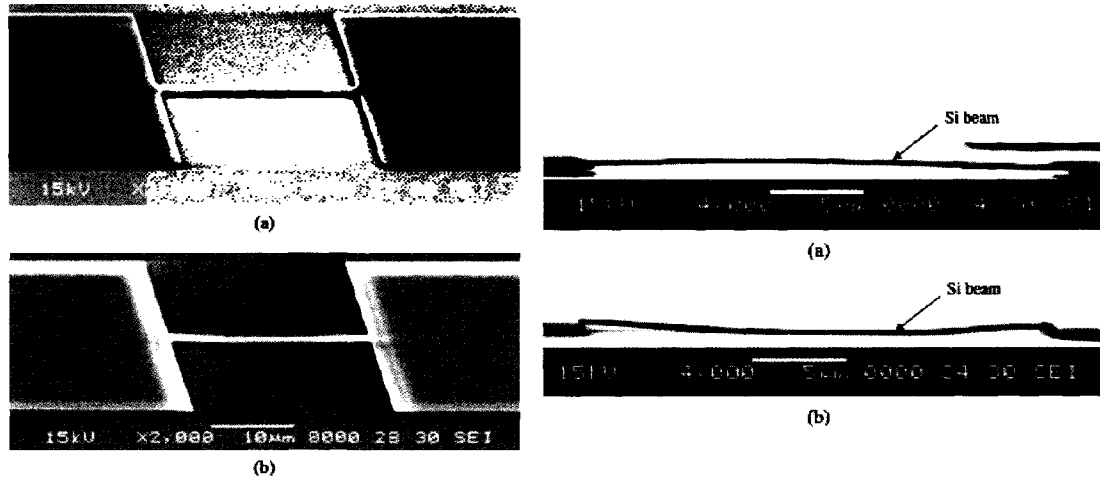


Figure 3. Photographs of fabricated MEMS switch, (a) before snap-through, (b) after snap-through [4].

which have the benefit of low power consumption, negligible heat gain and integration into micro chips [5]. Knowing the member size and electro-static load required to snap-through a micro-structure is necessary in designing the switch.

1.1 Overview

Weight optimization of slender truss members with stability constraints has been investigated by other researchers using various analytical techniques. Prager [6] discusses a general method of optimality that is subject to a single design constraint such as displacement, critical buckling load or natural frequency. Prager and Taylor [7] investigated columns under linear buckling constraints. Other investigators followed with schemes to optimize columns with multiple eigenvalues and design sensitivities with

constraints on buckling. Some of the earliest finite element optimization investigations began in the 1970's with linear buckling that ignored any large deformations. Khot, Venkayya, and Berke [8] presented an optimality criterion for minimizing weight to structures with stability requirements by using a linear eigenvalue buckling solution within a finite element analysis. Several other published works have studied the nonlinear buckling of shallow trusses. Kamat and Ruangsilasingha [9] addressed the problem of maximizing the critical load of shallow, three-dimensional (3-D) trusses. They developed sensitivity derivatives of the critical load with respect to design variables. Many case studies used in previously published works were taken from Crisfield [10] and [11]. The case examples he used challenged many nonlinear solvers to correctly follow a nonlinear snap-through load path. Crisfield used these problems to test nonlinear behavior in truss structures and to demonstrate the importance of identifying the critical-limit load along the equilibrium path.

Imperfections in the truss geometry also can reduce the load-carrying capability of a system. An investigation of random initial imperfections for frame-type structures that exhibit instability at limit points was performed by Warren [12]. He used an arc length approach to trace the nonlinear equilibrium paths of simple benchmark examples. Khot and Kamat [13] explained that the reduction in load capacity results primarily from the nonlinear response of a system and secondarily from imperfections in the geometry.

Optimizing the weight of truss structures that are undergoing large displacements requires analysis methods that accurately trace the equilibrium path and identify critical limit points. Most "shallow type" space truss designs will have snap-through response curves that are similar to those shown in figure 4. Depending on the geometry of the

design, the structure may have a snap-back path or may respond with bifurcation buckling.

The nonlinear buckling nature of “shallow-type” structures, as opposed to bifurcation or eigenvalue buckling, includes a post-buckling instability region along the equilibrium path as shown in figure 4. The nonlinear instability region is where “snap-through” occurs and the equilibrium path goes from one stable point (1) to another new stable point (2) as shown in figure 4. The nonlinear behavior places the critical limit load at 1 equal to 2 but corresponding to a new structural shape. The second stable point along the equilibrium path occurs after a large displacement of the structure. During this “snap-through,” the slope of the equilibrium path (load vs. deflection) will eventually become zero. The slope of this curve is also referred to as the tangent stiffness [14]. When the tangent stiffness softens and approaches zero for a single-degree-of-freedom (sdof) system, many nonlinear solvers will encounter convergence problems. Some solvers will immediately jump to point 2 without identifying the unstable snap-through path. Bifurcation buckling is also shown in figure 4 with a linear pre-buckling region along the equilibrium path up to a critical load point ($P_{critical}$). At the bifurcation point the structure immediately becomes unstable and buckles. The member is unable to support any further load which is not the case for nonlinear “snap-through” buckling. The focus of this work is on the fundamental path and not bifurcation points. This work also ignores inertial forces during snap-through and confines its interest to applying static methods.

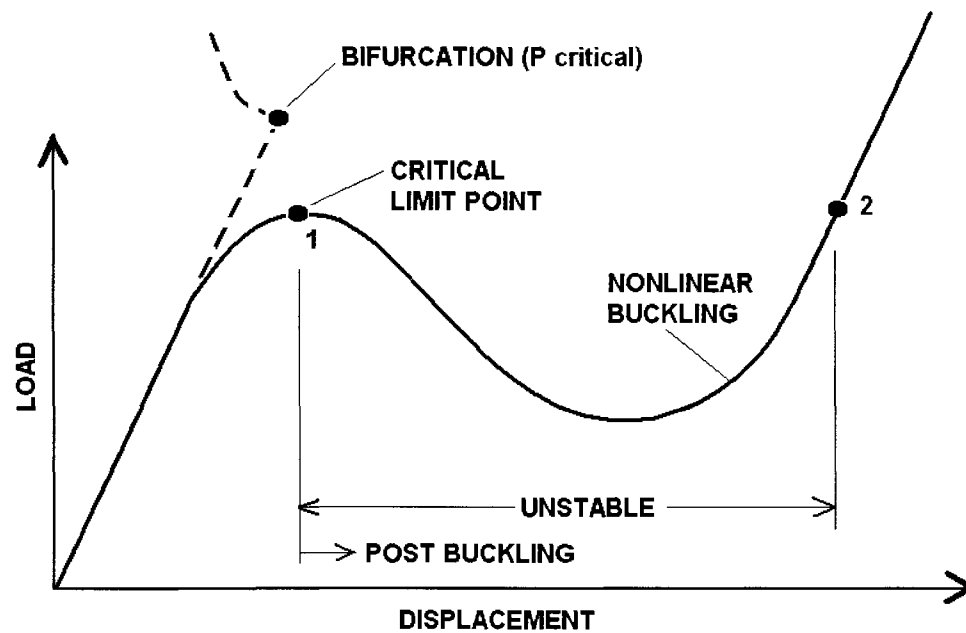


Figure 4. Equilibrium paths for nonlinear and bifurcation/eigenvalue buckling [15].

Nonlinear buckling responses result from the level of nonlinearity of the geometry in the design and the applied loading. Verification problems from Crisfield [10], [11] and [16] show the snap-through and snap-back behavior of several shallow truss designs. Achieving a minimum weight design of shallow trusses similar to the design examples from Crisfield requires limit-point stability constraints that can maximize critical load.

In [17], Khot, Kamat, and Venkayya offer exact closed-form solutions to simple shallow truss problems that have been optimized for weight. They make use of the minimization of the total potential energy that maximizes the load-carrying capability without instability. Optimizations of geometrically nonlinear trusses that are similar to those used by Crisfield were attempted later by Khot and Kamat [13]. These examples highlight the challenges that have been encountered with many analysis techniques in

following a nonlinear response path up to a critical-limit load. The sample problems also fully expose the short-comings of modern finite element programs by their lack of optimization scheme for stability- constrained problems. Sedaghati et al. [18] developed an optimization technique using the group theoretic approach. The method has stability constraints that use a strain energy density recurrence relationship to update the design variables. The technique involves obtaining a uniform strain energy density in all members to establish a minimum weight design. Sedaghati et al. further made use of shallow flexible truss structures to test and verify their methods.

The proposed Hrinda method was first used to investigate stability of shallow trusses prone to snap-through. These structures lose their stability differently than structures undergoing bifurcation buckling. Finite element programs typically solve for elastic stability by running an eigenvalue buckling solution. However, shallow truss structures will typically lose their ability to support any loads well below their bifurcation load. If a standard eigenvalue buckling solution is run in NASTRAN for a shallow truss structure, the load predicted in the analysis may be much higher than the snap-through load predicted using the arc length method in the proposed Hrinda program. Also, the use of the arc length method within the Hrinda program overcomes the limitations of classical solution techniques such as the Newton-Raphson method.

The solutions described by Khot, Kamat and Venkayya in [13], [17] and by Sedaghati et al. [18] rely on their own algorithms. These references do not elaborate on the nonlinear solver used by the authors. Also, the references do not mention combining nonlinear solver parameters to an optimization scheme as Hrinda has proposed. The Hrinda method also solves for the optimal weight within a finite element formulation

using advanced sparse techniques developed by Nguyen in [19]. The above references do not discuss any use of computer resources in their nonlinear solutions.

The NASTRAN nonlinear finite element analysis had convergence difficulties tracing the equilibrium paths of the examples in chapter 4. Careful selection of parameters used in NASTRAN eventually produced results found by Khot, Kamat and Venkayya in [13], [17] and by Sedaghati et al. [18].

1.2 Objective

The objective of this work is to develop an optimal design by using the principal of strain energy density and parameters in the arc length method to trace the nonlinear equilibrium path up to an instability point. A stable structural system exists when deformations are increasing as the applied load is increased; an unstable system exists when deformations are still increasing but the loads are decreasing. The Hrinda optimization method used in this work achieves an optimal design by combining the arc length method with a design-variable update scheme that identifies a uniform nonlinear strain energy density in all members. The method uses an iterative scheme that evaluates the performance of the design variables and then updates them according to a recursive formula that is controlled by the arc length method. The method is programmed into a new finite element algorithm developed from [20]. The Hrinda optimization algorithm is used to test the arc length updating scheme. The finite element program contains a 3-D truss element and an arc length method that could solve the snap-through and snap-back response of structures presented by Crisfield in [10], [11] and [16]. Examples of highly nonlinear trusses that have been found in the literature are presented to verify the method.

Only conservative systems that adhere to the theorem of minimum potential energy are considered. These are stable systems that are subjected to quasi-static proportional loads, where the equations of equilibrium make the potential energy stationary under small displacements [15].

CHAPTER II

ARC LENGTH METHOD

The Riks-Wempner arc length method is used in this work to solve highly geometric nonlinear structures that are to be weight optimized. Various versions of the arc length method have been presented by many researchers [10], [11], [12], [21] and [22] and incorporated into the finite element analysis procedures. For simplicity and to facilitate the discussion in subsequent sections, the Riks-Wempner arc length method is reviewed in section 2.1. The Riks-Wempner method is considered a partial arc length method because it relies on a normal to the tangent rather than the circular path to search for an equilibrium point [21]. The details of the iterative process along the normal are shown in figure 7 along with accompanying equations. The nonlinear equilibrium path is incrementally produced with load steps and convergence tests as depicted in figure 7.

2.1 Review of Arc Length Formulas

The Riks-Wempner arc length method traces the nonlinear equilibrium path by using an iterative process that begins by computing initial displacements Δq_0 based on a user-defined load increment $\Delta \lambda_0$, as shown in figure 5. The linear stiffness K_{T_0} is used to start the process and is replaced with the tangent stiffness K_{T_i} in further iterations.

The initial displacements Δq_0 are found using

$$\frac{\Delta \lambda_0}{\Delta q_0} = \frac{\lambda}{\Delta q_{\text{tot}}} \quad (2.1)$$

where $\lambda = 1$ and Δq_{tot} is derived from the expression

$$K_{T_0} \Delta q_{\text{tot}} = \lambda Q \quad (2.2)$$

where Q is the total applied loading. The notations that are given here for the displacements and loads are vector quantities with the stiffness notation understood as a matrix. Substituting into equation (2.1) yields

$$\frac{\Delta \lambda_0}{\Delta q_0} = \frac{\lambda = 1}{(\Delta q_{\text{tot}})_0} \quad (2.3)$$

which is solved for the initial displacement of

$$\Delta q_0 = \Delta \lambda_0 (\Delta q_{\text{tot}})_0 \quad (2.4)$$

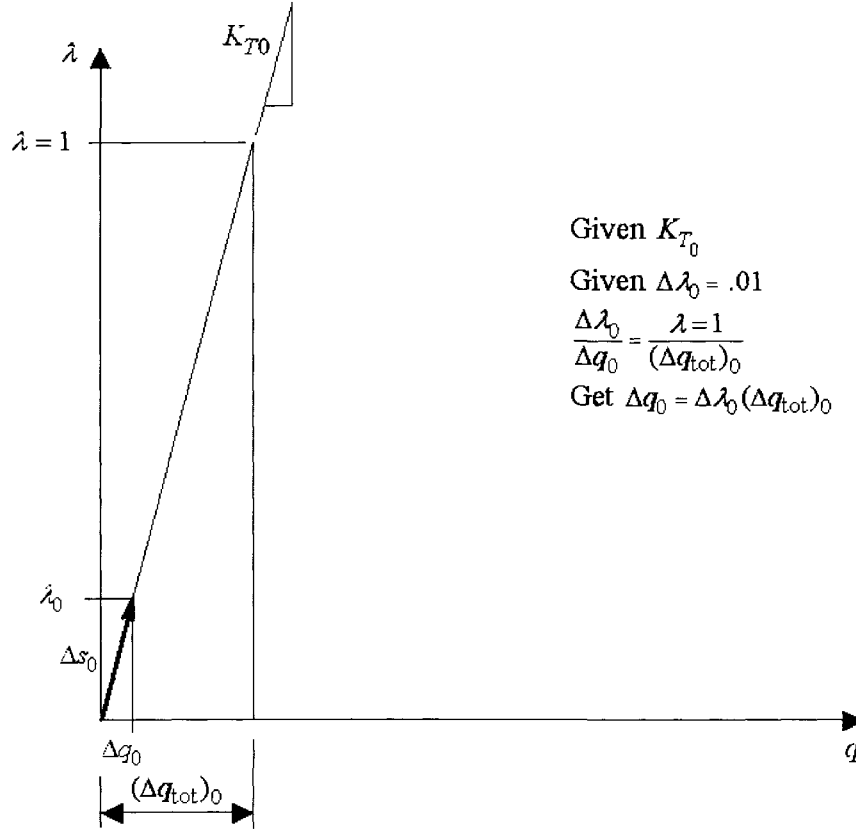


Figure 5. Starting the arc length.

The method then finds the next equilibrium point from the initial point 0 by using the tangent stiffness K_{T_1} as shown in figure 6. The tangent stiffness matrix is assembled by

using the nonlinear truss that is given in equation (3.30) in chapter 3; it is defined as the elastic linear stiffness that is given by equation (3.14) and added to the nonlinear geometric stiffness in equation (3.18). The sum of the linear elastic and nonlinear geometric matrices produces the global tangent stiffness at point i along the load-displacement path of the single-degree-of-freedom system. A new displacement Δq_{tot_i} is calculated from

$$K_{T_i} \Delta q_{\text{tot}_i} = \lambda Q \quad (2.5)$$

with $\lambda = 1$ as before.

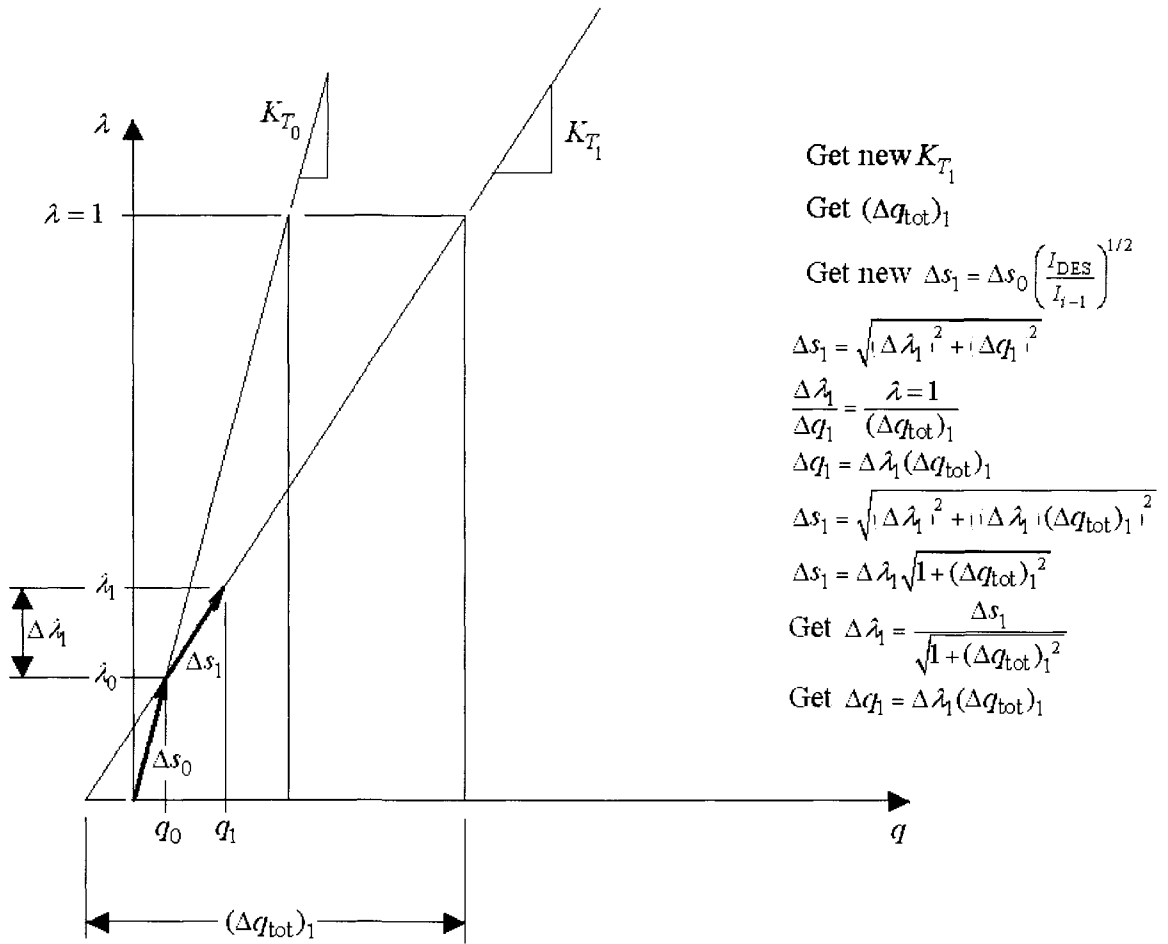


Figure 6. Next iteration.

The arc length used in the Riks-Wempner method is the straight line Δs_i ; this arc length is either constant or scaled by the user input with the following

$$\Delta s_i = \Delta s_{i-1} \left(\frac{I_{\text{DES}}}{I_{i-1}} \right)^{\frac{1}{2}} \quad (2.6)$$

The user decides on the required number of iterations I_{i-1} and on the number of desired iterations I_{des} . The arc length Δs_i is the tangent vector along the equilibrium path and can be calculated as

$$\Delta s_0 = \sqrt{\Delta \lambda_0^2 + (\Delta q^T)_0 \Delta q} \quad (2.7)$$

or by using

$$\Delta s_0 = \Delta \lambda_0 \sqrt{1 + \Delta q_{\text{tot}}^T \Delta q_{\text{tot}}} \quad (2.8)$$

The length of the next tangent vector Δs_1 can now be written as

$$\Delta s_1 = \Delta \lambda_1 \sqrt{1 + (\Delta q_{\text{tot}})_1^2} \quad (2.9)$$

In this equation, the unknown is $\Delta \lambda_1$, which can be solved by using

$$\Delta \lambda_1 = \frac{\Delta s_1}{\sqrt{1 + (\Delta q_{\text{tot}})_1^2}} \quad (2.10)$$

the incremental displacement can be found by using

$$\Delta q_1 = \Delta \lambda_1 (\Delta q_{\text{tot}})_1 \quad (2.11)$$

The next step is a test for convergence that first obtains the internal force F_1 . The residual forces can be calculated as

$$F_{R_1} = \lambda_1 Q - F_1 \quad (2.12)$$

Here, the residual forces are the differences in the internal forces that are calculated from the equilibrium path and are shown in figure 7.

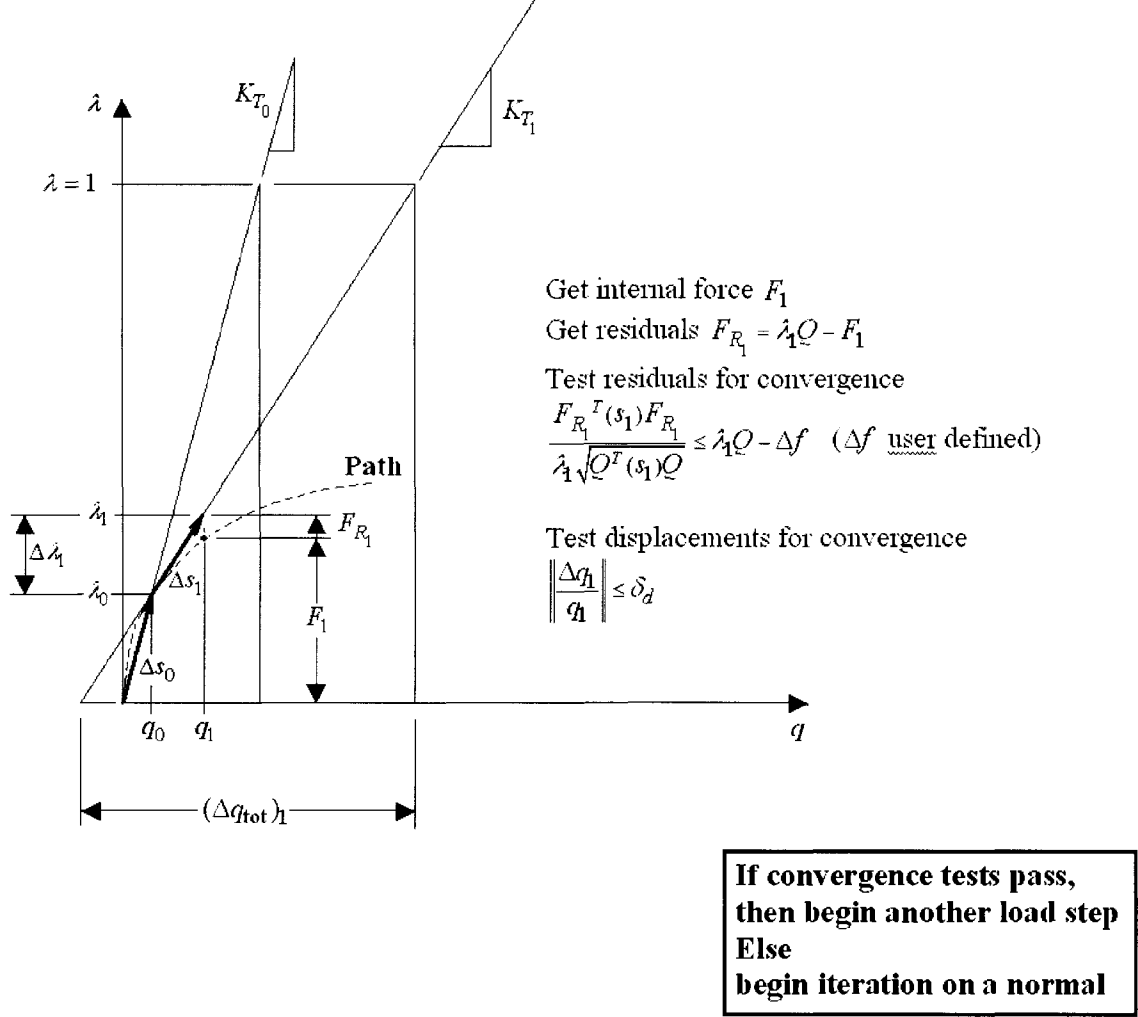


Figure 7. Convergence tests.

The following is used to test for load convergence:

$$\frac{F_{R_1}^T(s_1)F_{R_1}}{\lambda_1 \sqrt{Q^T(s_1)Q}} \leq \lambda_1 Q - \Delta f \quad (2.13)$$

where Δf is a user-defined tolerance value. If the statement is true, then the loads test is successful.

A convergence for displacements is also performed by using the ratio

The vector n_2 is normal to Δs_1 if

$$\frac{\Delta q_1}{\Delta \lambda_1} = \frac{\Delta \lambda_2}{\Delta q_2} \quad (2.15)$$

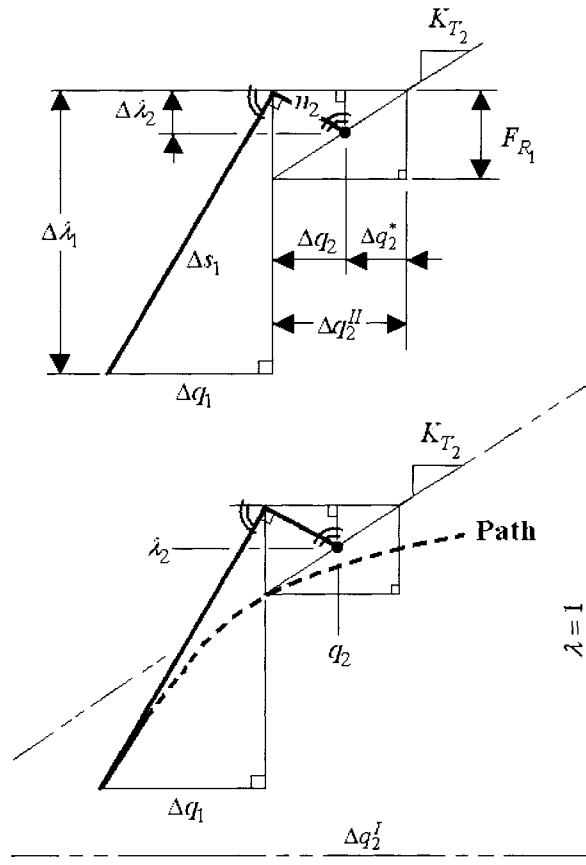
The equation comes from using the method of similar triangles as shown in figure 9. The relationship may also be written as

$$\Delta q_1 \Delta q_2 - \Delta \lambda_1 \Delta \lambda_2 = 0 \quad (2.16)$$

A new tangent stiffness $[K_{T_2}]$ is calculated and used in the following:

$$[K_{T_2}] \Delta q_2^{II} = F_{R_1} \quad (2.17)$$

where all variables are defined in figure 9.



If n_2 is $\perp \Delta s_1$

Use similar triangles:

$$\frac{\Delta q_1}{\Delta \lambda_1} = \frac{\Delta \lambda_2}{\Delta q_2}$$

$$\Delta q_1 \Delta q_2 - \Delta \lambda_1 \Delta \lambda_2 = 0$$

Get $[K_{T_2}]$

$$[K_{T_2}] \Delta q_2^{II} = F_{R_1}$$

$$\Delta q_2^{II} = [K_{T_2}]^{-1} F_{R_1}$$

$$\Delta q_2 = \Delta q_2^{II} - \Delta q_2^*$$

$$\frac{\Delta \lambda_2}{\Delta q_2^*} = \frac{(\lambda=1)}{\Delta q_2^I}$$

$$\Delta q_2^* = \frac{\Delta \lambda_2 \Delta q_2^I}{(\lambda=1)} = \Delta \lambda_2 \Delta q_2^I$$

$$\Delta q_2 = \Delta q_2^{II} - \Delta \lambda_2 \Delta q_2^I$$

$$\Delta q_1 \Delta q_2^{II} - \Delta \lambda_2 \Delta q_2^I - \Delta \lambda_1 \Delta \lambda_2 = 0$$

$$\Delta q_1 \Delta q_2^{II} - \Delta q_1 \Delta \lambda_2 \Delta q_2^I - \Delta \lambda_1 \Delta \lambda_2 = 0$$

$$\Delta q_1 \Delta q_2^{II} - \Delta \lambda_2 \Delta q_1 \Delta q_2^I + \Delta \lambda_1 = 0$$

$$\Delta \lambda_2 = \frac{\Delta q_1 \Delta q_2^{II}}{\Delta q_1 \Delta q_2^I + \Delta \lambda_1}$$

$$\boxed{\begin{aligned} \lambda_2 &= \lambda_0 + \Delta \lambda_1 + \Delta \lambda_2 \\ q_2 &= q_0 + \Delta q_1 + \Delta q_2 \end{aligned}}$$

Figure 9. Details of iteration on a normal.

Equation (2.17) can be rewritten as

$$\Delta q_2^{II} = [K_{T_2}]^{-1} F_{R_1} \quad (2.18)$$

The incremental displacement shown in figure 9 can be expressed as

$$\Delta q_2 = \Delta q_2^{II} - \Delta q_2^* \quad (2.19)$$

Using similar triangles, the following can now be obtained

$$\frac{\Delta \lambda_2}{\Delta q_2^*} = \frac{(\lambda = 1)}{\Delta q_2^I} \quad (2.20)$$

Terms can be rearranged to obtain

$$\Delta q_2^* = \frac{\Delta \lambda_2 \Delta q_2^I}{(\lambda = 1)} = \Delta \lambda_2 \Delta q_2^I \quad (2.21)$$

Combining equations (2.19) and (2.21) creates

$$\Delta q_2 = \Delta q_2^{II} - \Delta \lambda_2 \Delta q_2^I \quad (2.22)$$

Now, equation (2.16) is combined with equation (2.22) to obtain

$$\Delta q_1 (\Delta q_2^{II} - \Delta \lambda_2 \Delta q_2^I) - \Delta \lambda_1 \Delta \lambda_2 = 0$$

which can be reduced to

$$\Delta \lambda_2 = \frac{\Delta q_1 \Delta q_2^{II}}{(\Delta q_1 \Delta q_2^I + \Delta \lambda_1)} \quad (2.23)$$

and added to the previous load increments as follows:

$$\lambda_2 = \lambda_0 + \Delta \lambda_1 + \Delta \lambda_2 \quad (2.24)$$

Likewise, the displacement increments are summed by using equation (2.22) to yield

$$q_2 = q_0 + \Delta q_1 + \Delta q_2 \quad (2.25)$$

Equations (2.24) and (2.25) represent the load and displacement at location 2 along the equilibrium path. A convergence check is performed similar to that shown in figure 7 and in equations (2.12) through (2.14). If the test is passed, then a new load increment begins by using the tangent vector of equation (2.9). If the tests fail, then iteration down the normal vector n is started as shown in figure 10. The process continues until the convergence tests for load and displacement are both passed.

Structured state-of-the-art sparse equation solver technology such as sparse assembly algorithms, reordering algorithms to minimize fill-in-terms, and super node strategies for efficient unrolling techniques during numerical factorization phase were all incorporated into equations (2.5) and (2.18) of the arc length procedure [19] .

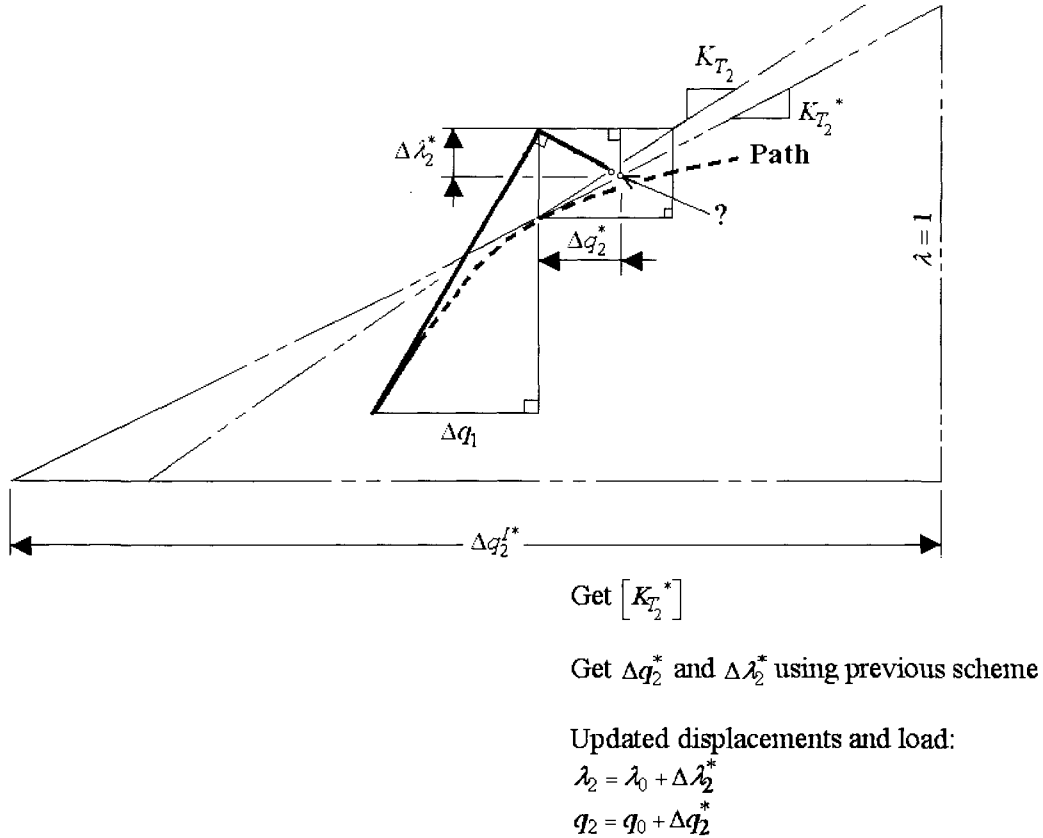


Figure 10. Continuing iteration on normal.

2.2 Linear/Nonlinear, Symmetrical/Unsymmetrical Equation Tests

The following equations were used in the proposed algorithm to test the arc length method and computer coding. Their simple mathematical solutions were a quick check of the arc length solver portion of the algorithm without utilizing the finite element sparse solver. The first system of equations are shown in equations (2.26) and (2.27). The equations are written in matrix format (2.28) to allow for input to the proposed algorithm.

$$24u_1^2 - 12u_2 = 0 \quad (2.26)$$

$$-12u_1 + 8u_2^2 = 20 \quad (2.27)$$

$$\begin{pmatrix} 24u_1 & -12 \\ -12 & 8u_2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 20 \end{pmatrix} \quad (2.28)$$

The unknowns, (u_1, u_2) , in (2.28) have a unique solution that is $(-0.7633, 1.165)$.

The next equation pair is shown below in (2.29) and (2.30). The equations are also placed into matrix form in (2.31).

$$24u_1 - 12u_2 = -2.0 \quad (2.29)$$

$$-12u_1 + 8u_2 = 0.0 \quad (2.30)$$

$$\begin{pmatrix} 24 & -12 \\ -12 & 8 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} -2.0 \\ 0.0 \end{pmatrix} \quad (2.31)$$

The solution to the unknowns (u_1, u_2) is given as $(-0.3333, -0.5000)$ respectively.

Another equation test used the system in (2.32) and (2.33). As performed in the previous tests, the equations are arranged in (2.34) for proper computer input format.

$$24u_1^3 - 16u_2 = 8 \quad (2.32)$$

$$-36u_1 + 6u_2^2 = -24 \quad (2.33)$$

$$\begin{pmatrix} 24u_1^2 & -16 \\ -36 & 6u_2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 8 \\ -24 \end{pmatrix} \quad (2.34)$$

The solution to the two unknowns is (.6675, -.05417).

Another equation pair is shown in (2.38) and (2.39) with the matrix form given in (2.40).

$$10u_1^2 + 2u_2^2 = 0.0 \quad (2.38)$$

$$2u_1^2 + 2u_2^2 = 0.0 \quad (2.39)$$

$$\begin{pmatrix} 10u_1 & 2u_2 \\ 2u_1 & 2u_2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0.0 \\ 0.0 \end{pmatrix} \quad (2.40)$$

The solution to the two unknowns (u_1, u_2) in (2.40) is (0,0).

The equations in this section were solved with the arc length method in the proposed algorithm. The solutions shown in this section were all verified by the algorithm.

Further testing was conducted using the nonlinear truss element as discussed in the next chapter.

A listing of the computer input files is given in appendices A.1-A.4.

CHAPTER III

GEOMETRICALLY NONLINEAR 3-D TRUSS ELEMENT STIFFNESS

In this work, we are interested in the behavior of 3-D truss members undergoing large displacements. In order to use and test the Hrinda optimization scheme, it became necessary to verify a 3-D truss stiffness matrix that could behave properly while undergoing large deflections. This requires a modification to the elastic stiffness that is typically used in the linear equation. The development of a properly formed geometric nonlinear stiffness matrix begins by altering the basic linear equation [23] of the applied force \vec{F} with the stiffness $[K]$ and nodal displacements \vec{u} , which can be written as

$$\vec{F} = [K]\vec{u} \quad (3.1)$$

The relationship is modified by introducing a nonlinear geometric matrix $[K]_G$ that is added to the elastic stiffness $[K]_E$ and written as

$$[K]_T = [K]_E + [K]_G \quad (3.2)$$

where $[K]_T$ is the tangent stiffness. The following sections offer a detailed formulation of the tangent stiffness matrix given by equation (3.2) and the testing that was required to assure it was working properly.

3.1 Derivation of 3-D Geometrically Nonlinear Truss Element Stiffness

Trusses that are undergoing large deflections must be analyzed for the deformed geometry of the structure. The linear equation (3.1) that relates the applied force \vec{F} with

the truss element stiffness $[K]$ and displacements \vec{u} must be modified to account for changes in nodal geometry as the load is applied. The standard elastic stiffness matrix $[K]_E$ is modified by the addition of a geometric stiffness matrix $[K]_G$ that depends on the geometry and the initial internal forces.

Note that efficient sparse assembly procedures [19] have been used in equation (3.2), while efficient sparse reordering algorithms (i.e., both to minimize fill-in terms and during the factorization phase) and sparse solvers with unrolling strategies [19] have been utilized in equation (3.2). The sparse assembly techniques are discussed in chapter 5.

Nonlinear analysis is usually divided into a sequence of load steps where the displacements are being solved after each load increment. The nonlinear stiffness is then updated with the displacement and the internal force values from the previous step. A discussion follows of the nonlinear truss element that is used in the finite element program in this study.

The following definitions are used to derive the elastic truss stiffness from the variables that are defined in figure 11. The element's original length is found by using the global nodal coordinates given as x_1, y_1, z_1 at end 1 and x_2, y_2, z_2 for end 2 to give

$$l_0 = \sqrt{(x_{21})^2 + (y_{21})^2 + (z_{21})^2} \quad (3.3)$$

where

$$x_{21} = (x_2 - x_1) \quad (3.4)$$

$$y_{21} = (y_2 - y_1) \quad (3.5)$$

$$z_{21} = (z_2 - z_1) \quad (3.6)$$

The change in displacements for an i th truss can be written as

$$x_{21D} = x_2 - x_1 + ux_2 - ux_1 \quad (3.7)$$

$$y_{21D} = y_2 - y_1 + uy_2 - uy_1 \quad (3.8)$$

$$z_{21D} = z_2 - z_1 + uz_2 - uz_1 \quad (3.9)$$

where ux_1, uy_1, uz_1 are the displacements at end 1 and ux_2, uy_2, uz_2 are the displacements at end 2. This may be used to write the final length of the element as

$$l_i = \sqrt{(x_{21D}^2 + y_{21D}^2 + z_{21D}^2)} \quad (3.10)$$

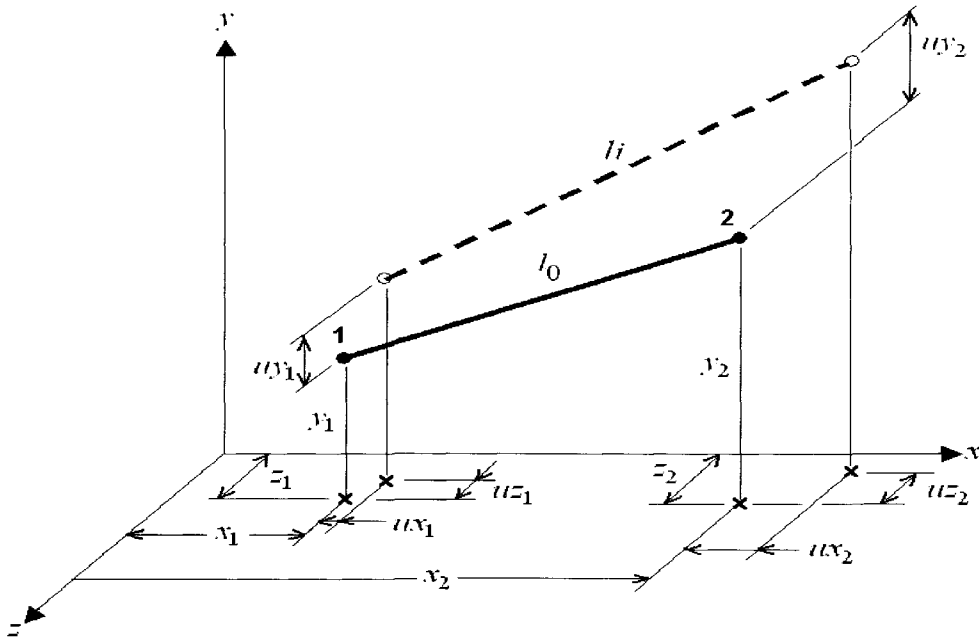


Figure 11. Nonlinear 3-D truss variables.

The tangent stiffness $[K]_T$ given by equation (3.2) is can be defined as outlined by

Crisfield in [10] as

$$[K]_T = \frac{\partial \vec{q}_i}{\partial \vec{p}} \quad (3.11)$$

where $\frac{\partial \vec{q}_i}{\partial \vec{p}}$ is the rate of change of the internal forces, \vec{q}_i , as the nodal displacements, \vec{p} ,

are changing. The tangent stiffness matrix is expanded by Crisfield into

$$[K]_T = \frac{\partial \vec{q}_i}{\partial \vec{p}} = 2\alpha A_o \vec{b} \frac{\partial \sigma}{\partial p} + 2\alpha A_o \frac{\partial \vec{b}}{\partial p} \sigma \quad (3.12)$$

The left side of the equation, $2\alpha A_o \vec{b} \frac{\partial \sigma}{\partial p}$, is the standard elastic stiffness matrix for a 3D

truss, $[K]_E$. The term to the right of the addition sign, $2\alpha A_o \frac{\partial \vec{b}}{\partial p} \sigma$, is the nonlinear

geometric stiffness matrix, $[K]_G$. In defining equation (3.12) the following definitions

are used: A_o =cross sectional area, σ is the stress, 2α =original length, l_0 .

The elastic stiffness matrix is derived as

$$2\alpha A_o \vec{b} \frac{\partial \sigma}{\partial p} = \frac{A_o E}{8\alpha^3} \begin{bmatrix} -x_{21D} \\ x_{21D} \\ -y_{21D} \\ y_{21D} \\ -z_{21D} \\ z_{21D} \end{bmatrix} \begin{bmatrix} -x_{21D} & x_{21D} & -y_{21D} & y_{21D} & -z_{21D} & z_{21D} \end{bmatrix} \quad (3.13)$$

This may be expanded using $8\alpha^3 = l_0^3$ to give the standard elastic stiffness

$$[K]_E = \frac{A_o E}{l_0^3} \begin{bmatrix} x_{21D}^2 & -x_{21D}x_{21D} & x_{21D}y_{21D} & -x_{21D}y_{21D} & x_{21D}z_{21D} & -x_{21D}z_{21D} \\ & x_{21D}^2 & -x_{21D}y_{21D} & x_{21D}y_{21D} & -x_{21D}z_{21D} & x_{21D}z_{21D} \\ & & y_{21D}^2 & -y_{21D}y_{21D} & y_{21D}z_{21D} & -y_{21D}z_{21D} \\ & & & y_{21D}^2 & -y_{21D}z_{21D} & y_{21D}z_{21D} \\ & SYM & & & z_{21D}^2 & -z_{21D}z_{21D} \\ & & & & & z_{21D}^2 \end{bmatrix} \quad (3.14)$$

The geometric stiffness matrix is found by using the right hand side of equation (3.12)

$$2\alpha A_o \frac{\partial \vec{b}}{\partial p} \sigma = \frac{A_o \sigma}{2\alpha} [B] \quad (3.15)$$

The strain-displacement vector in the above equation is obtained by taking the derivative of the Green's strain vector with respect to the nodal displacement vector to give

$$\frac{\partial \vec{b}}{\partial p} = \frac{1}{l_0^2} \begin{bmatrix} -u_{21} \\ u_{21} \\ -u_{21} \\ u_{21} \\ -u_{21} \\ u_{21} \end{bmatrix} \quad (3.16)$$

This type of strain measurement will be explained later in this chapter.

Also used in equation (3.15) is

$$[B] = \begin{bmatrix} 1 & -1 & 0 & 0 & 0 & 0 \\ & 1 & 0 & 0 & 0 & 0 \\ & & 1 & -1 & 0 & 0 \\ & & & 1 & 0 & 0 \\ SYM & & & & 1 & -1 \\ & & & & & 1 \end{bmatrix} \quad (3.17)$$

The geometric stiffness may be written using equation (3.15), (3.16) and $\sigma = \frac{AN}{A_0}$

$$[K]_G = \frac{AN}{l_0} \begin{bmatrix} 1 & -1 & 0 & 0 & 0 & 0 \\ & 1 & 0 & 0 & 0 & 0 \\ & & 1 & -1 & 0 & 0 \\ & & & 1 & 0 & 0 \\ & SYM & & & 1 & -1 \\ & & & & & 1 \end{bmatrix} \quad (3.18)$$

with AN equal to the internal elemental force. Equation (3.18) is further defined in the next section by defining the internal forces. Section 3.3 will then use this information to develop the full tangent stiffness.

3.2 Element Internal Force

The internal forces in the truss element are required for the geometric stiffness and are defined by using matrix notation. The element strain formulation uses a constant cross-sectional area and assumes that the length and area of the truss will remain large. The strain energy or the work done is one-half of the nodal forces multiplied by the corresponding deflections.

The internal force in the truss is now defined to include nonlinear effects. The force will be axial and is needed to update the nonlinear stiffness matrix. Defining the force in matrix notation is necessary for efficient computer programming. The internal force may be defined as

$$AN = EA_0\mathcal{E} \quad (3.19)$$

where Green's strain as formulated in chapter 6 is

$$\mathcal{E} = \frac{l_i^2 - l_0^2}{2l_0^2} \quad (3.20)$$

Substituting equations (3.3) and (3.10) into the strain equation leads to

$$\mathcal{E} = \frac{\begin{bmatrix} [(x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1)] + [(ux_2 - ux_1) & (uy_2 - uy_1) & (uz_2 - uz_1)] \\ [(x_2 - x_1) + (ux_2 - ux_1) & (y_2 - y_1) + (uy_2 - uy_1) & (z_2 - z_1) + (uz_2 - uz_1)] \end{bmatrix} \begin{bmatrix} (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \\ (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \end{bmatrix}}{2 \begin{bmatrix} (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \\ (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \end{bmatrix}} \quad (3.21)$$

This equation must be simplified to better adapt for computer programming. Therefore the following relationship is identified in the left part of the numerator

$$\begin{bmatrix} (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \end{bmatrix} + \begin{bmatrix} (ux_2 - ux_1) & (uy_2 - uy_1) & (uz_2 - uz_1) \end{bmatrix} \quad (3.22)$$

that can be written as

$$\begin{bmatrix} (x_2 - x_1) + (ux_2 - ux_1) & (y_2 - y_1) + (uy_2 - uy_1) & (z_2 - z_1) + (uz_2 - uz_1) \end{bmatrix} \quad (3.23)$$

This expression may now replace the left part of equation (3.21) as

$$\mathcal{E} = \frac{\begin{bmatrix} (x_2 - x_1) + (ux_2 - ux_1) & (y_2 - y_1) + (uy_2 - uy_1) & (z_2 - z_1) + (uz_2 - uz_1) \\ [(x_2 - x_1) + (ux_2 - ux_1) & (y_2 - y_1) + (uy_2 - uy_1) & (z_2 - z_1) + (uz_2 - uz_1)] \end{bmatrix} \begin{bmatrix} (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \\ (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \end{bmatrix}}{2 \begin{bmatrix} (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \\ (x_2 - x_1) & (y_2 - y_1) & (z_2 - z_1) \end{bmatrix}} \quad (3.24)$$

Multiplication is performed in the numerator to give

$$2(x_2 - x_1)(ux_2 - ux_1)^2 + 2(y_2 - y_1)(wy_2 - wy_1)^2 + 2(z_2 - z_1)(uz_2 - uz_1)^2 + (uz_2 - uz_1)^2 \quad (3.25)$$

The denominator in equation (3.24) is just $2l_0^2$ which leads to

$$\mathcal{E} = \frac{2(x_2 - x_1)(ux_2 - ux_1)^2 + 2(y_2 - y_1)(wy_2 - wy_1)^2 + 2(z_2 - z_1)(uz_2 - uz_1)^2}{2l_0^2} \quad (3.26)$$

where

$$2l_0^2 = 2 \begin{bmatrix} (x_2 - x_1) \\ (y_2 - y_1) \\ (z_2 - z_1) \end{bmatrix} \begin{bmatrix} (x_2 - x_1) \\ (y_2 - y_1) \\ (z_2 - z_1) \end{bmatrix} \quad (3.27)$$

This simplifies equation (3.26) to

$$\frac{1}{l_0^2} \left[(x_2 - x_1)(ux_2 - ux_1) + 2(y_2 - y_1)(wy_2 - wy_1) + 2(z_2 - z_1)(uz_2 - uz_1) + \frac{1}{2}(ux_2 - ux_1)^2 + \frac{1}{2}(wy_2 - wy_1)^2 + \frac{1}{2}(uz_2 - uz_1)^2 \right] \quad (3.28)$$

Substituting (3.28) into the internal force equation (3.19) and using (3.4)-(3.6) gives

$$AN = \frac{EA_0}{l_0^2} \left[x_{21}(ux_2 - ux_1) + y_{21}(wy_2 - wy_1) + z_{21}(uz_2 - uz_1) + \frac{(ux_2 - ux_1)^2}{2} + \frac{(wy_2 - wy_1)^2}{2} + \frac{(uz_2 - uz_1)^2}{2} \right] \quad (3.29)$$

3.3 Nonlinear 3-D Truss Element Stiffness

The tangent stiffness can now be written by substituting into equation (3.2) the elastic stiffness (3.14) and the geometric stiffness

(3.18) with the internal force equation (3.29) to give

$$[K]_T = \frac{A_0 E}{l_0^3} \left[\begin{array}{cccccc} x_{21D}^2 & -x_{21D}x_{21D} & x_{21D}y_{21D} & -x_{21D}y_{21D} & x_{21D}z_{21D} & -x_{21D}z_{21D} \\ x_{21D}^2 & -x_{21D}y_{21D} & x_{21D}y_{21D} & -x_{21D}z_{21D} & x_{21D}z_{21D} & x_{21D}z_{21D} \\ y_{21D}^2 & -y_{21D}x_{21D} & y_{21D}^2 & -y_{21D}z_{21D} & y_{21D}z_{21D} & -y_{21D}z_{21D} \\ y_{21D}^2 & -y_{21D}x_{21D} & -y_{21D}^2 & -y_{21D}z_{21D} & y_{21D}z_{21D} & y_{21D}z_{21D} \\ z_{21D}^2 & -z_{21D}x_{21D} & z_{21D}^2 & -z_{21D}z_{21D} & -z_{21D}z_{21D} & z_{21D}^2 \end{array} \right] +$$

$$SYM \left[\begin{array}{cccccc} 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \quad (3.30)$$

$$\frac{A_0 E}{l_0^3} \left[\begin{array}{cccccc} x_{21}(ux_2 - ux_1) + y_{21}(uy_2 - uy_1) + z_{21}(uz_2 - uz_1) & \frac{(ux_2 - ux_1)^2}{2} + \frac{(uy_2 - uy_1)^2}{2} + \frac{(uz_2 - uz_1)^2}{2} & \frac{(ux_2 - ux_1)(uy_2 - uy_1)}{2} & \frac{(ux_2 - ux_1)(uz_2 - uz_1)}{2} & \frac{(uy_2 - uy_1)(uz_2 - uz_1)}{2} & \frac{(ux_2 - ux_1)(uz_2 - uz_1)}{2} \end{array} \right]$$

$$SYM \left[\begin{array}{cccccc} 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 \end{array} \right]$$

CHAPTER IV

NONLINEAR TRUSS VERIFICATION TESTS

The proposed finite element program was tested and verified using several examples found in the literature with nonlinear NASTRAN solutions. Of particular interest was the ability to reproduce snap-through and snap-back behavior found in some structures. The examples were chosen as a robust test of this unstable behavior and brought confidence to the computer coding and numerical techniques used in the proposed algorithm.

4.1 Single-Degree-of-Freedom Nonlinear Example

The performance of the truss element was tested by Hrinda [20] against the snap-through and snap-back problems that were identified by Crisfield [10] and [16]. The criteria for a desirable element were the ability to accurately trace an equilibrium path and the ability to reach and pass the critical-limit points within an arc length solution. In [20], finite element analysis of the Crisfield snap-through and snap-back models were performed using the tangent stiffness given by equation 3.30 and NASTRAN. The first performance example was a single-degree-of-freedom finite element model used to demonstrate the arc length algorithm and verify results with NASTRAN and an exact solution. The problem is used in Crisfield [10] with the variables used to express the exact response equation shown in figure 12.

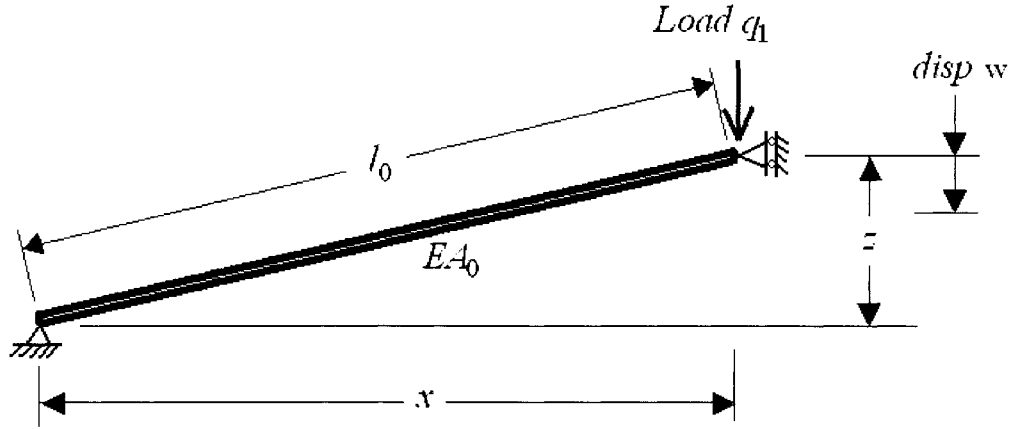


Figure 12. Single-degree-of-freedom truss spring problem.

The exact load displacement path is given in Crisfield [10] as:

$$q_i = \frac{EA_0 Z (2Zw - w^2)}{2l_o^3} \quad (4.1)$$

where

$$Z = (z + w)$$

(4.2)

and E =Young's modulus, A_0 =area and q_i =load increment

The finite element model used for verification is shown in figure 13. Restraints are provided to give free movement in the vertical direction on the right node. The model's elastic modulus is $10e6 \text{ \#/in}^2$ and the truss cross sectional area is 5 in^2 . A vertical downward load of 100 \# is applied at the second node. The truss model was also solved using the exact equation (4.1) by letting $EA_0 = 5.e7 \text{ \#}$, $x = 2500.in$, $z = 25.in$, $q_1 = 100$.

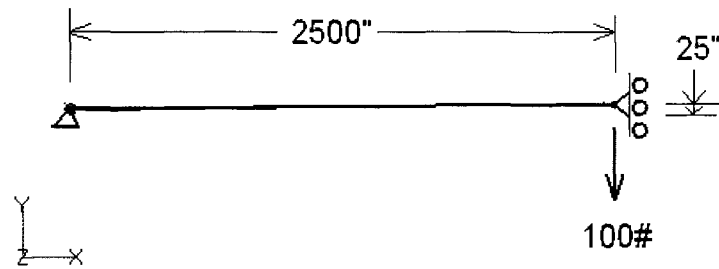


Figure 13. Crisfield single-degree-of-freedom model.

Results from the exact solution, proposed algorithm and NASTRAN are shown in the load-displacement plots in figure 14. The results in [20] showed that the truss tangent stiffness given by equation 3.30 was behaving properly for large geometric nonlinear responses. Figure 14 shows three equilibrium paths that are nearly the same. A numerical comparison of the four points (A thru D) shown in figure 14 are listed below in table 1.

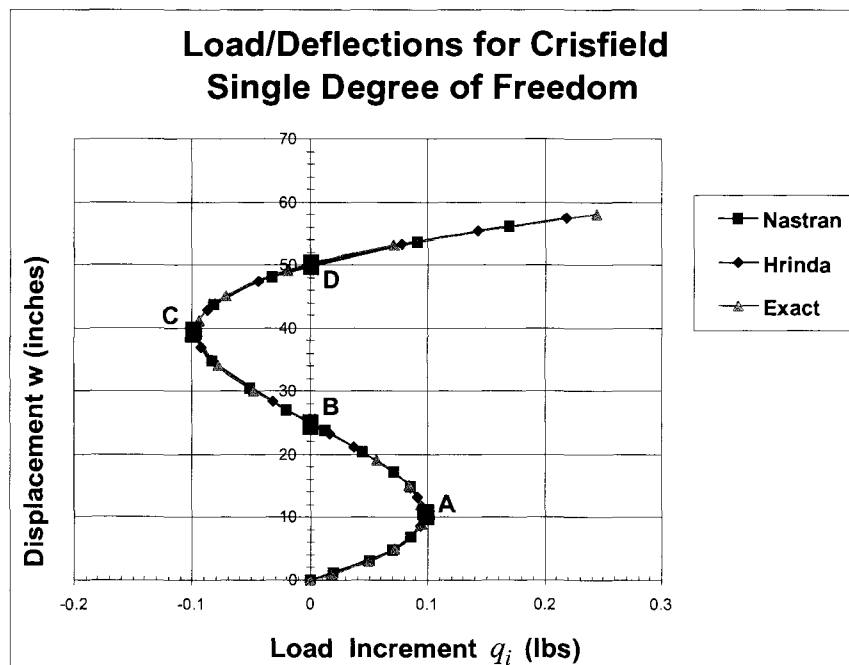


Figure 14. Load increment vs. displacement for the sdof problem.

Appendix A. 4 gives the computer model input file and a more detailed listing of the results plotted in figure 14. The vertical deflections for the sdof problem during snap-through are shown in the sequence of plots in figure 15.

Table 1. Quantitative results comparison of the sdof problem using NASTRAN, the finite element program by Hrinda [20] and the exact solution given by Crisfield [10]. A thru D are the data (load increment, displacement) associated with the curve in figure 14.

METHOD	A	B	C	D
NASTRAN	(.0935, 12.59)	(0.000, 24.82)	(-.0962, 39.26)	(.0077, 50.38)
Hrinda	(.0948, 12.00)	(0.000, 24.97)	(-.0961, 39.00)	(.0070, 50.34)
Exact	(.0948, 12.00)	(0.000, 25.00)	(-.0962, 39.26)	(.0077, 50.38)

This example demonstrates a classical snap-through equilibrium path that has been investigated in many [14], [15] and [24]. Further results for this example are presented in appendix A.5. In these results, changes in tangent stiffness and the slope of the equilibrium path (load vs. displacement) are plotted to show their behavior during limit points and snap-through events. The tangent stiffness reduces to zero at the start of instability and then becomes negative during an unstable snap-through.

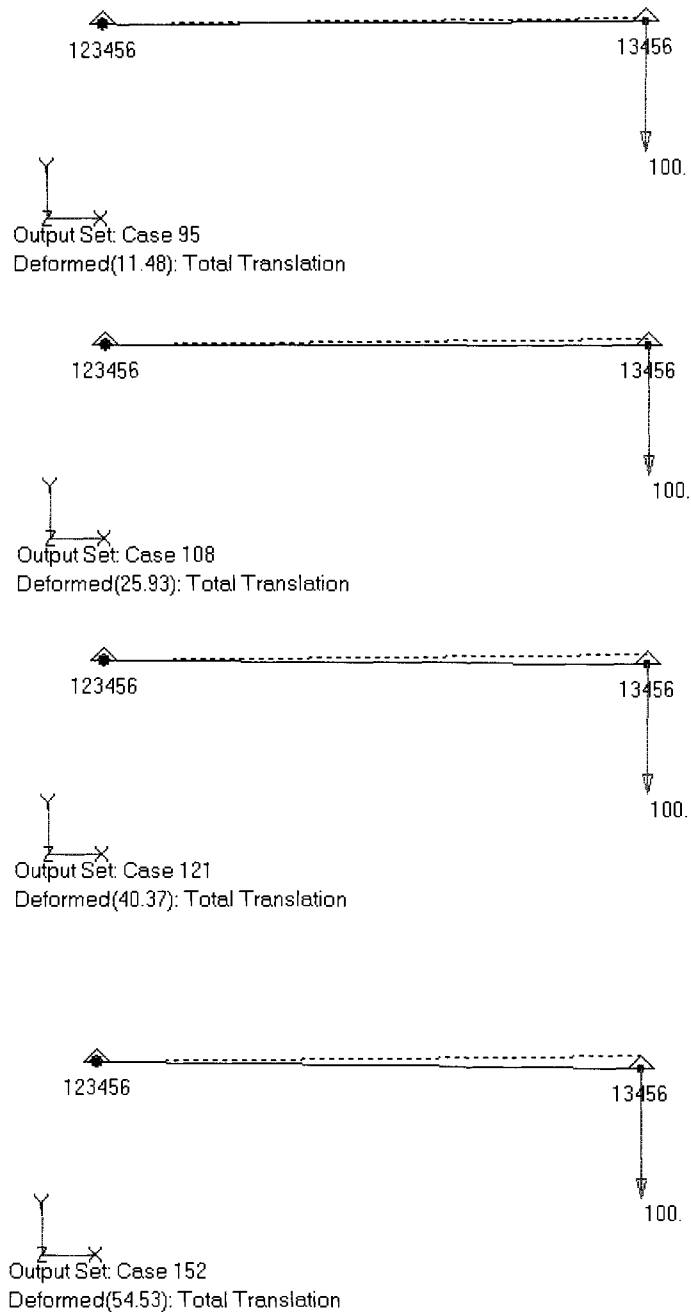


Figure 15. Single-degree-of-freedom deflections. Values given are for the right node with vertical displacements in inches.

4.2 Star Dome Truss

The Crisfield star dome model was taken from Crisfield [11] and has been studied by others to demonstrate a complex equilibrium path. The 3D shallow dome is shown in figure 16 with the two axes of the Cartesian co-ordinate system and the normal z axis indicating the out-of-plane dimensions of the nodes. The model differs from the [9] example by having one concentrated load acting downward at the center node. This load produces multiple snap-through and snap-backs as shown in figure 20. The shape of this equilibrium path is comparable with the equilibrium path found by Geers in [25]. This model is shown in Appendix A.6.1 with its “looping” equilibrium path that has the same shape as the Crisfield star dome equilibrium path in figure 20. Appendix A.6 gives the model input file and a listing of the output data used in figure 20.

The Crisfield star dome was solved using the Hrinda arc length computer program with results compared to a NASTRAN model. The load increment vs. vertical displacements of the center node are plotted in figure 20 and compared. This model introduced a major difficulty following the load path at snap points. The proposed algorithm was able to accurately follow the NASTRAN results and through several snap-through points. Figures 17-19 show the NASTRAN model's response along the equilibrium path of figure 20. Points “A-J” are important to mention in figure 20 because they define some key principles in understanding stability equilibrium paths. Points A, B, C, E, F, H, I and J all have zero tangent stiffness and represent an unstable structure.

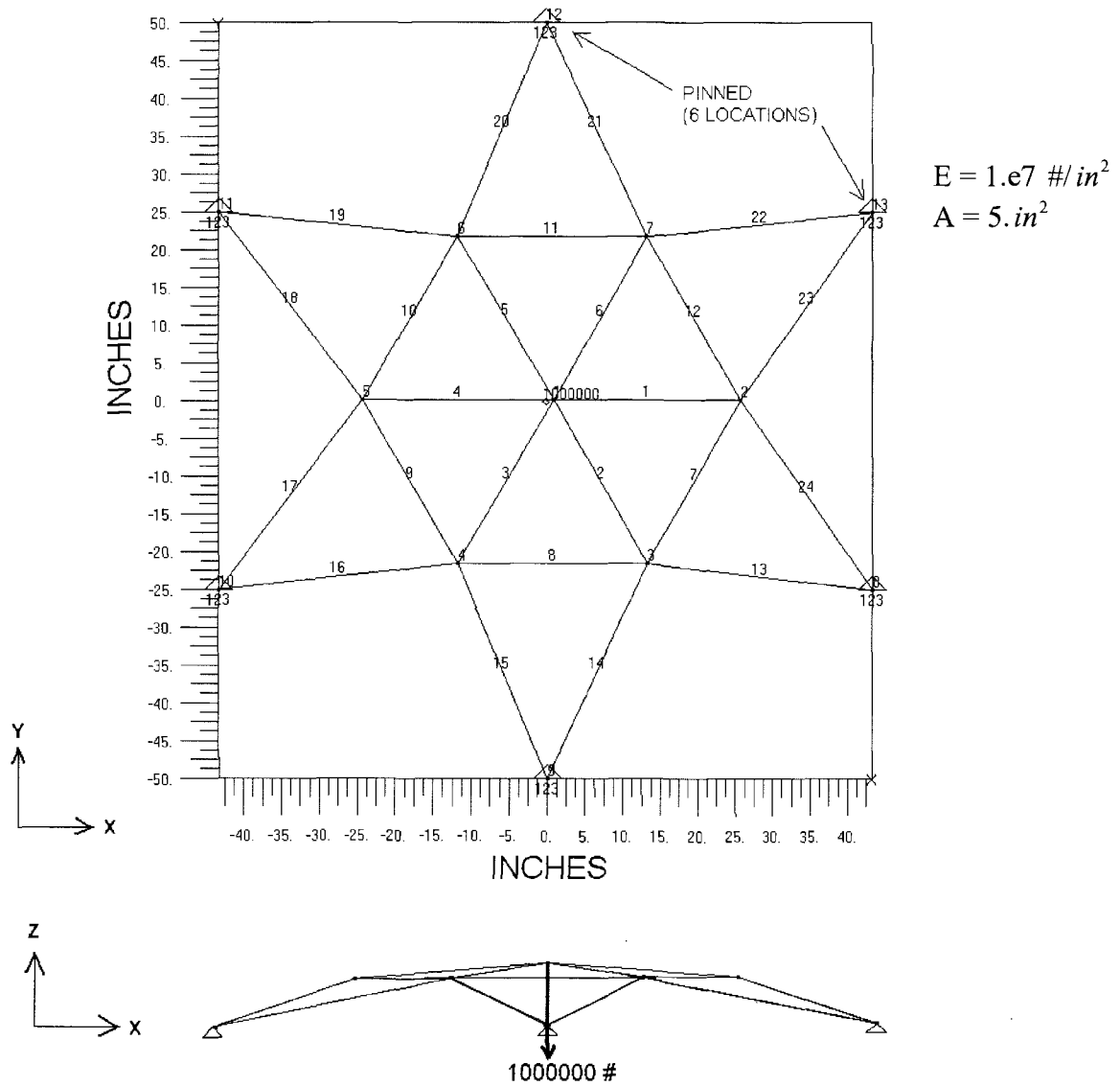
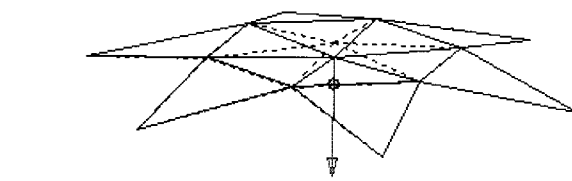


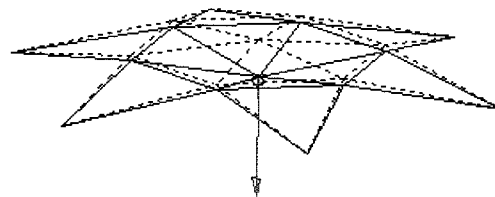
Figure 16. Crisfield three-dimensional star dome using 24 three dimensional truss elements, 13 nodes (39 dofs) and one concentrated load acting vertical downward at the center with the six outer nodes pinned.

Using figure 20, the first snap-through starts at A and continues past B until the same load at A is reached but at a much larger displacement. Figure 20a is a magnified view of the snap-through shown in figure 20. The magnified view shows the first limit point, A, and then an unstable snap-through until A' . The dashed line from A to A' represents the unstable part of the equilibrium path. Point A' is stable and marks the end of the first dynamic snap-through of the structure. Figure 17 shows the displacements of the inner six elements as they snap-through. Once at A' , the structure is once again stable and stationary. This is a second stable equilibrium state with the structure in a much different configuration. The applied load may now either incrementally increase from A' to the second limit point, C, as seen in figure 20, or just remain at the current load increment. If the applied load is allowed to continue then the tangent stiffness will become zero. Any infinitesimal increase in the applied load beyond C will cause the structure to begin another unstable snap-through. The unstable equilibrium path in figure 20 continues with the load decreasing and eventually reversing direction. The tangent stiffness becomes negative along this path as the structure deforms. The sequential plots of the structural displacements in figure 18 show that the outer elements, 13-24, are the main contributors to the second snap-through. Instead of immediately snapping through to point C' in figure 20b, the structure begins a snap-back. Here it should be mentioned that the applied dead load on the structure is the value at C. The next stable point on the path, C' , will also be at the same applied dead load as C. At D in figure 20, the equilibrium path begins to turn caused by the deflections reversing direction. In this case, D is where the tangent to the equilibrium path is vertical and a snap-back begins. The inner group of elements (1-6) produces the snap-back that can be seen in the last two displacement plots in figure

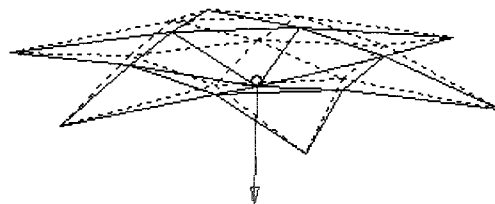
18. These plots show that the structure is rebounding upward starting with the inner ring of elements. As mentioned before, the equilibrium path will become stable at C' but must first pass through an unstable path characterized in figure 20 points D through J. At E, the tangent slope is parallel to the displacement axis as the snap-back continues through point F to point G. In figure 20, G is the limit of the snap-back and is shown in the last displacement plot in figure 18. The structure begins to displace downward again with the center ring of six elements undergoing the most movement. The displacement plots in figure 19 show these members deforming as the unstable equilibrium path in figure 20 is followed to point C' in figure 20b. A closer inspection of the unstable path reveals that the load pattern similar to the first snap-through event is present near point I in figure 20b. This represents the inner ring of elements reaching their maximum snap-through. They start pulling the outer ring of elements, 13-24, downward as shown in the last displacement plot in figure 19. Figure 20b shows that once the load becomes positive at I' , the structure has another snap-through from point I to I'' . The stable equilibrium point C' is next reached at the same applied dead load as C but with the structure in a completely different configuration. This example shows that a structure may become stable after reaching its first limit point. Another interpretation is that some structures may become stable after reaching a new buckled configuration. The purpose of this example was to demonstrate the effectiveness of the proposed Hrinda program by finding limit points and accurately tracing highly nonlinear equilibrium paths. The interest in this work is mostly focused on the first limit point and how to optimize a structure prone to snap-through. This will be investigated with a larger star dome example in chapter 8.



Output Set: Case 22
Deformed(2.678): T3 Translation

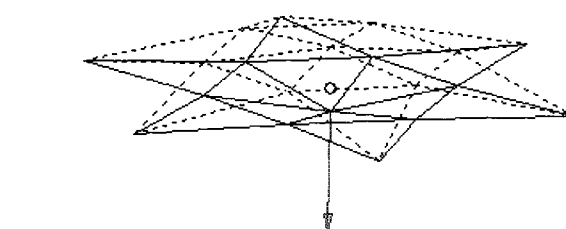



Output Set: Case 228
Deformed(7.395): T3 Translation

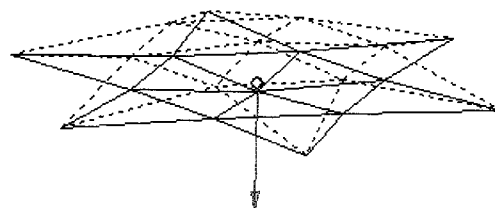



Output Set: Case 368
Deformed(9.237): T3 Translation

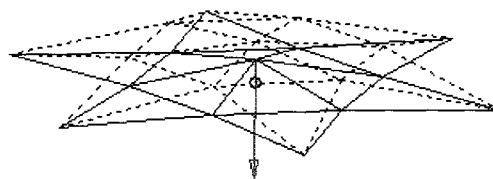
Figure 17. Star dome deflections. Values given are for the center node with vertical displacements in inches.




 Output Set: Case 435
 Deformed(12.94): T3 Translation




 Output Set: Case 443
 Deformed(9.88): T3 Translation




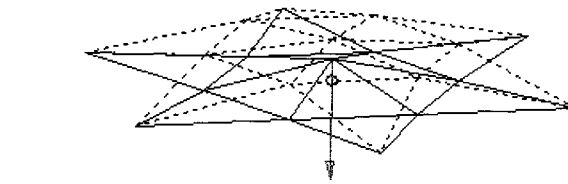

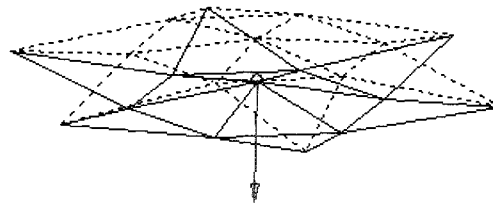


 Output Set: Case 458
 Deformed(5.909): T3 Translation

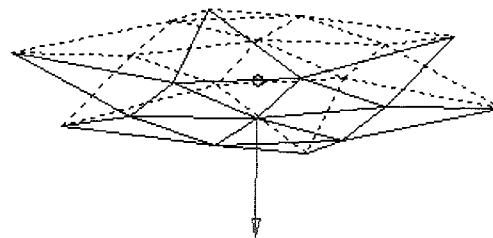
Figure 18. Star dome deflections. Values given are for the center node with vertical displacements in inches.




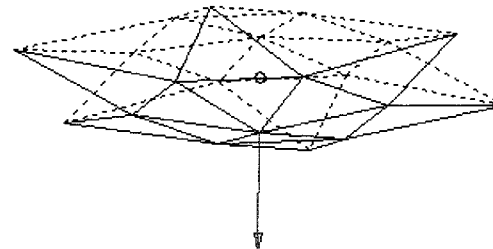

 Output Set: Case 464
 Deformed(7.336): T3 Translation




 Output Set: Case 486
 Deformed(11.28): T3 Translation




 Output Set: Case 502
 Deformed(15.63): T3 Translation





 Output Set: Case 543
 Deformed(19.28): T3 Translation

Figure 19. Star dome deflections. Values given are for the center node with vertical displacements in inches.

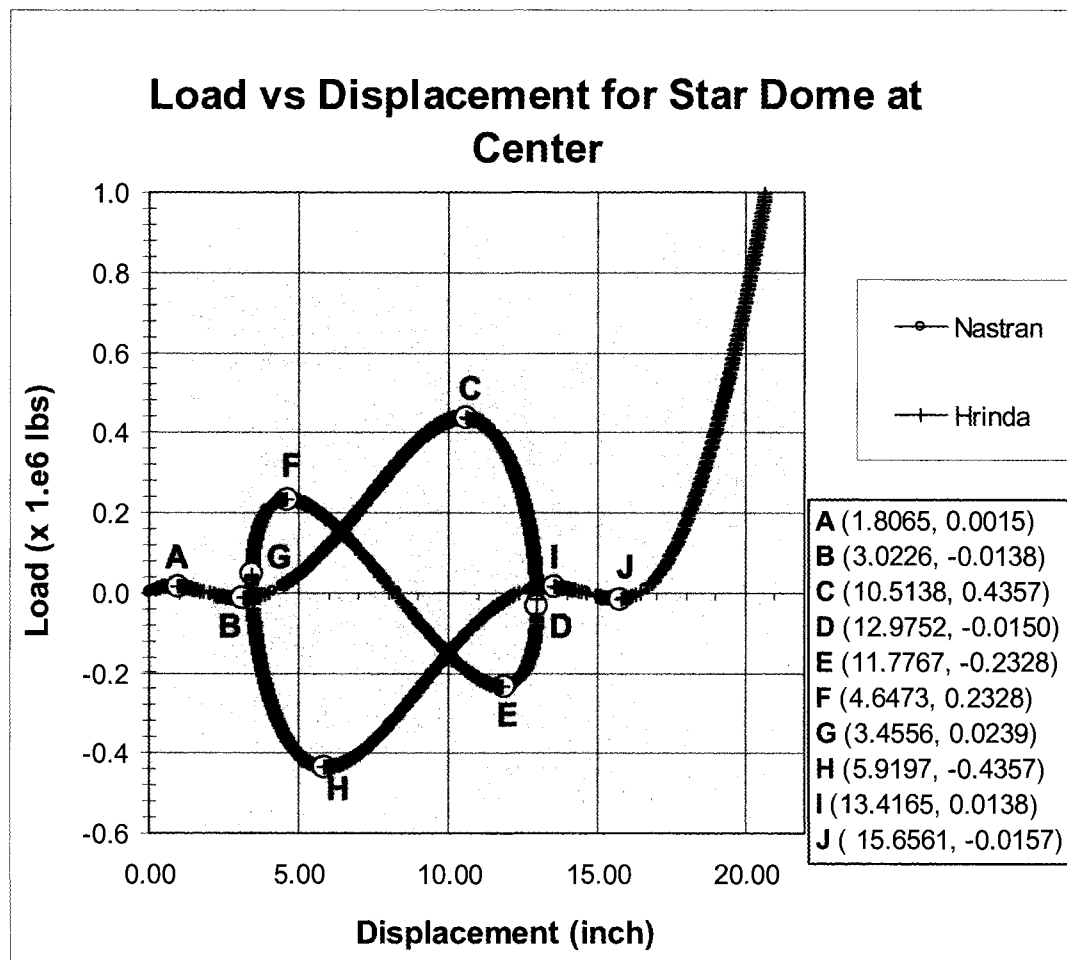


Figure 20. NASTRAN/Hrinda star dome result at center load increment vs. vertical displacement.

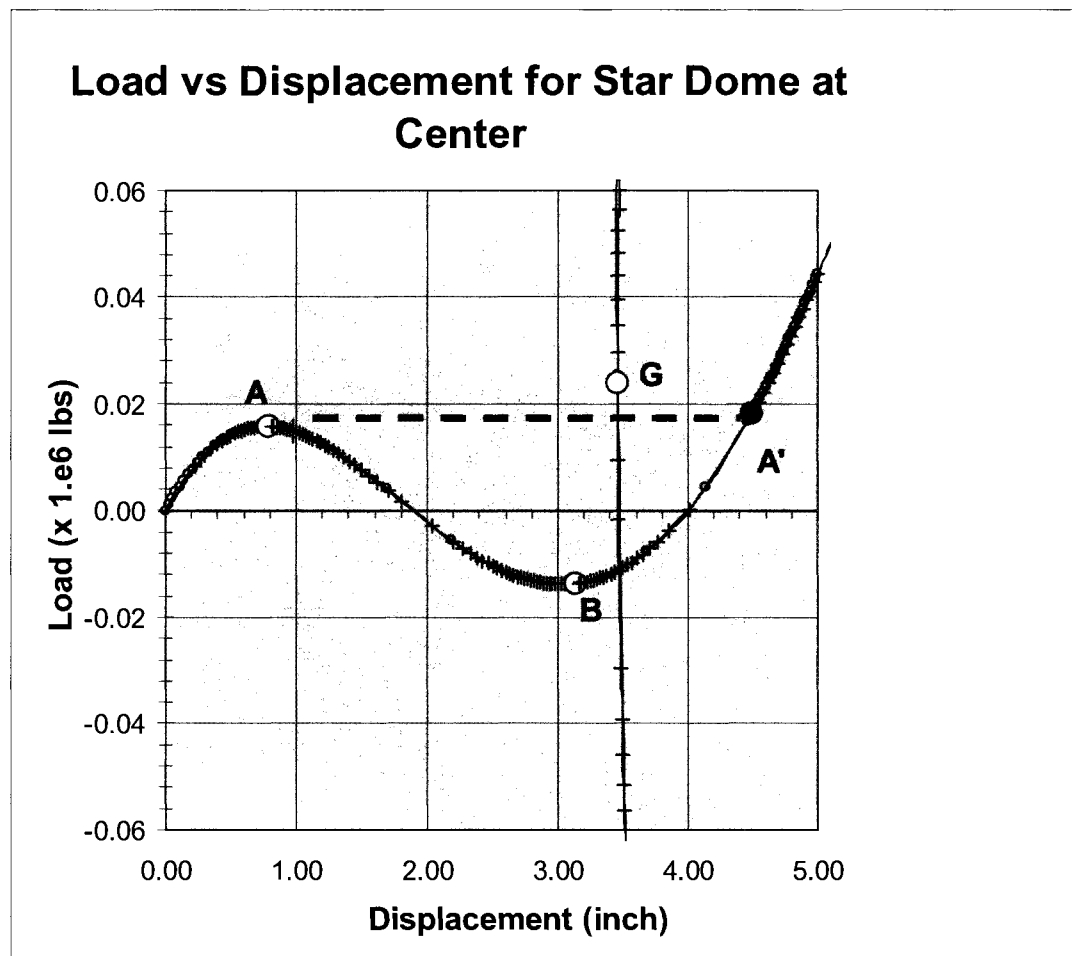


Figure 20a. NASTRAN/Hrinda star dome magnified results of first snap-through from A to A'.

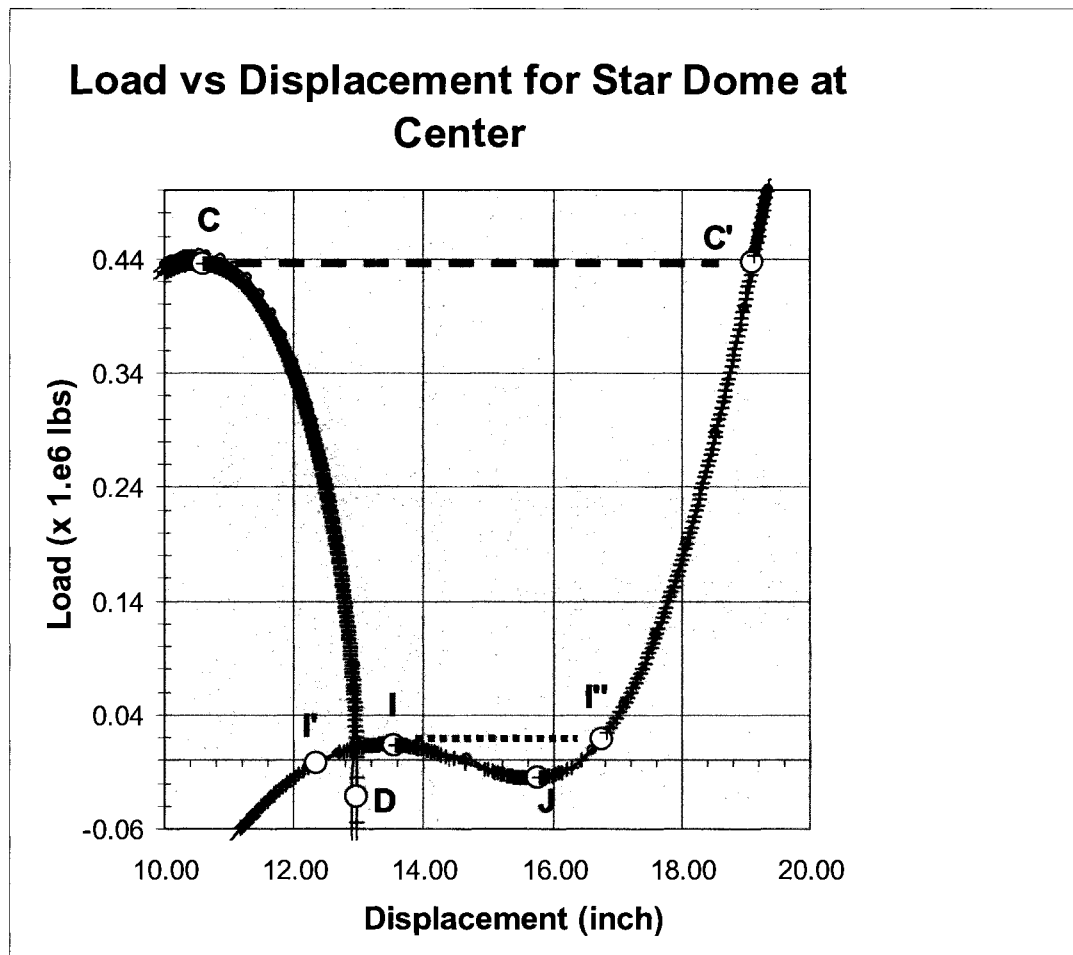


Figure 20b. NASTRAN/Hrinda star dome magnified results of second and third snap-through.

4.3 Crisfield Arch Truss

The model is taken from Crisfield [11] and tests multiple snap-through and snap-back equilibrium paths. The model has 101 elements with 42 nodes with a total of 126 degrees-of-freedom. The out-of-plane motion has been constrained with pin supports added to each end of the truss. Figure 21 shows the test model and the applied load of $1e7$ lbs at the apex. Figures 22 through 24 show the deflections from NASTRAN during multiple snappings of the arch. Figure 25 displays an abbreviated plot of NASTRAN results and the predicted response of the Hrinda arc length computer program. Appendix A.7 has the input file for this model and a listing of results used in figure 25. Appendix A.7.1 shows a typical equilibrium path for arches from [26]. The paths shown in the reference are very similar to the looping patterns in figure 25.

Referring to figure 25, the first snap-through, point A, starts when the tangent to the equilibrium path is parallel to the displacement axis. The arch becomes unstable and releases stored strain energy and dynamically traces the equilibrium path from A to B in figure 25. The deformed structure with the vertical apex node values is shown sequentially in figure 22. A snap-back starts at B and continues through C and on to D. This is seen in the deformed plots in figure 23. The snap-back is still unstable and occurs when the tangent to the equilibrium path is parallel to the load axis. The snap-back continues dynamically until D in figure 25 is reached. The equilibrium path now continues to E where another unstable snap-through begins. This is seen in the deformed plots in figure 24. The arc length program closely follows the equilibrium path found by NASTRAN.

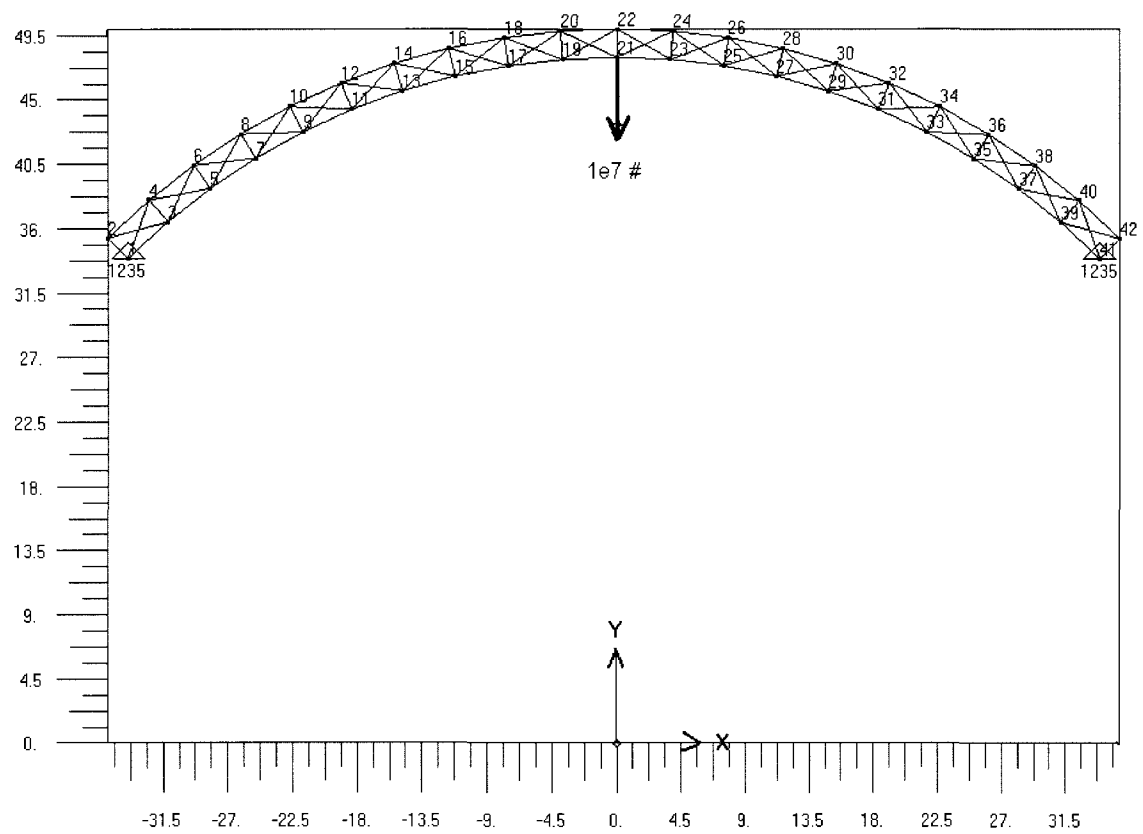
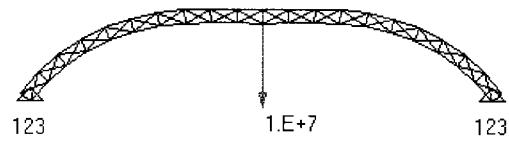
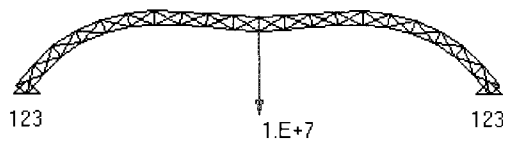


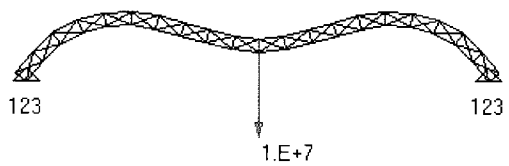
Figure 21. Crisfield large circular arch.



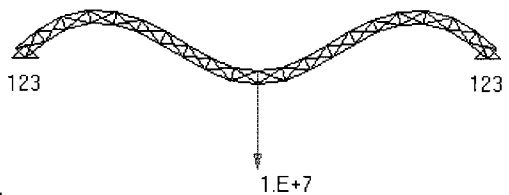
Output Set: Case 30
Deformed(2.619): Total Translation



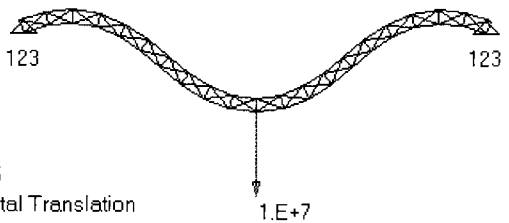
Output Set: Case 50
Deformed(4.752): Total Translation



Output Set: Case 75
Deformed(9.827): Total Translation



Output Set: Case 100
Deformed(17.94): Total Translation



Output Set: Case 125
Deformed(25.75): Total Translation

Figure 22. Arch deformations. Values given are for the apex node with vertical displacements in inches.

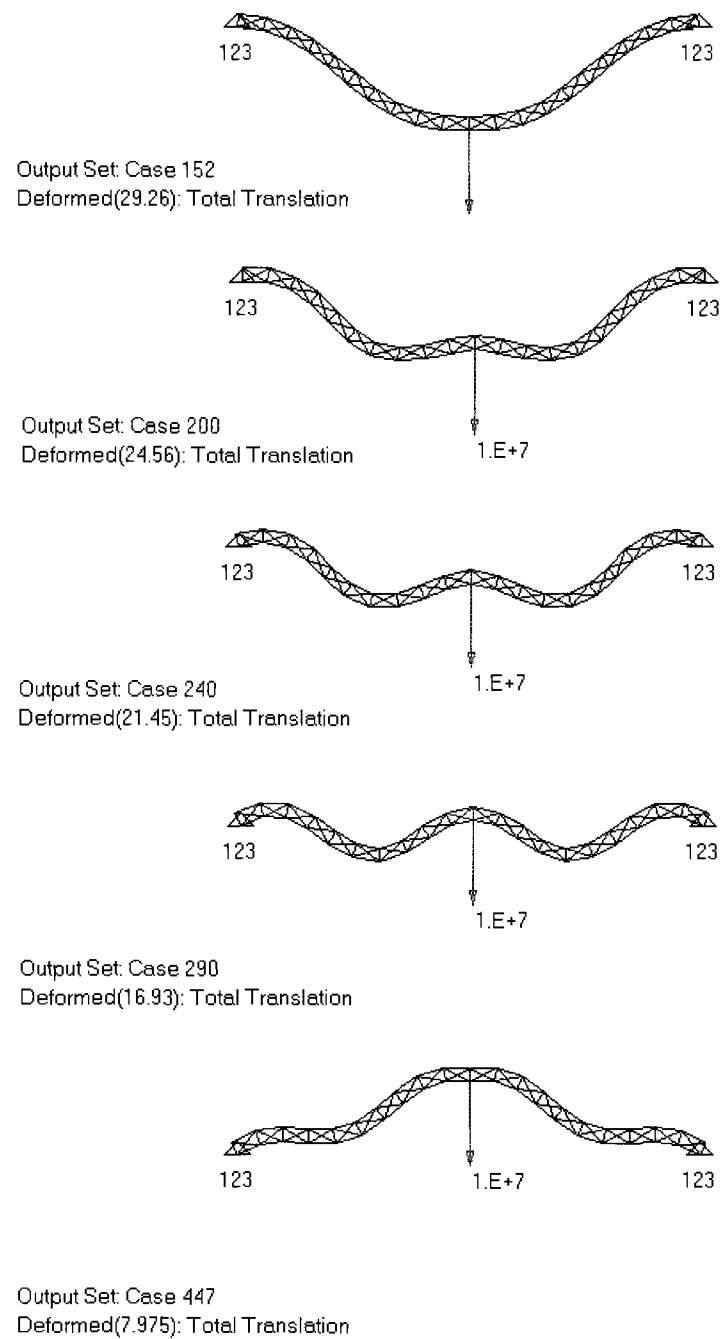
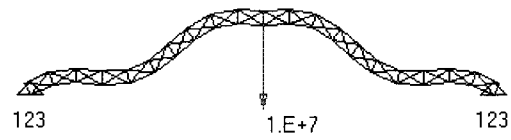
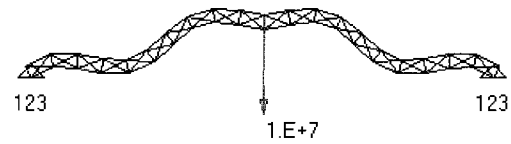


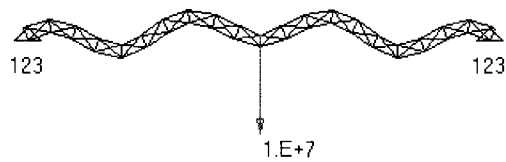
Figure 23. Arch deformations. Values given are for the apex node with vertical displacements in inches.



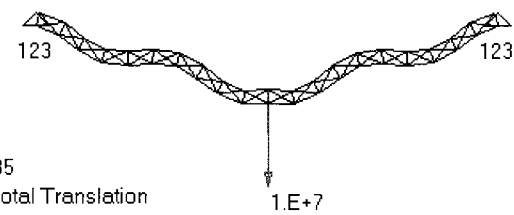
Output Set: Case 476
Deformed(7.63): Total Translation



Output Set: Case 500
Deformed(8.437): Total Translation



Output Set: Case 550
Deformed(15.27): Total Translation



Output Set: Case 635
Deformed(25.63): Total Translation

Figure 24. Arch deformations. Values given are for the apex node with vertical displacements in inches.

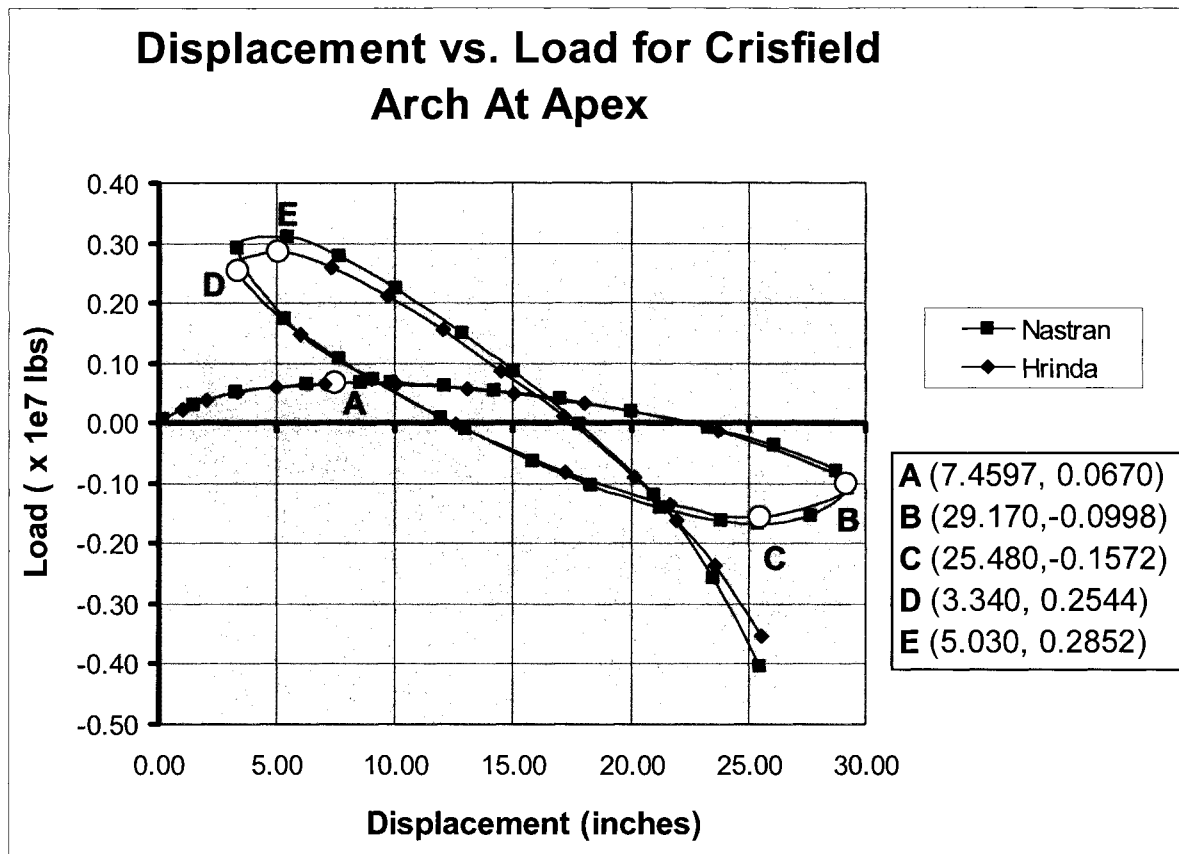


Figure 25. Arch Load Deflection apex comparisons of NASTRAN vs. Hrinda.

CHAPTER V

SPARSE COMPUTING TECHNIQUES

The stiffness matrix is used to describe the members' stiffness relations for computing member forces and displacements in a structure. The diagonals of the matrix are real terms with only a few non-zero, off-diagonal terms. The matrix is mostly populated with zeros and is referred to as “sparse.” The stiffness matrix is inverted and multiplied by a force array to give displacements. As the stiffness matrix increases in size, it becomes more time consuming to solve the system of equations for the unknown displacements. Also, the computer storage requirements for storing and inverting a full symmetric stiffness matrix could be too large with the lengthy computation time that prevents efficient use of computer resources. To overcome these computing problems and efficiently utilize the storage capacity of the computer system, the symmetric stiffness matrix information is stored in several single column arrays. The technique only stores the non-zero stiffness terms and thus reduces the computer storage requirement as well as the solution time. The sparse storage techniques in this work are from Nguyen in [19] and are programmed into the proposed algorithm.

5.1 Sparse Storage

The fundamental equations used in structural analysis are written in matrix form as

$$[K]\{Z\} = \{F\} \quad (5.1)$$

where $[K]$ is the structural stiffness matrix, $\{Z\}$ are the unknown displacements and $\{F\}$ are the applied forces. The system is usually symmetric and positive definite but may involve a large stiffness matrix. The size of the stiffness matrix will affect how fast the

system will be solved as well as the amount of computer storage required. The stiffness matrix is usually populated with many zero terms and only a few terms that describe the stiffness. These matrices are called “sparse” and are a major source of computation resources [19].

The process for reading in a sparse stiffness matrix from a finite element model is illustrated through the four bars sample given by Khot and Kamat in [13] and shown in figure 26. The 3D truss structure has 4 elements and 5 nodes with 15 degrees-of-freedom. There is one applied load acting in the negative z direction at node 5. The structure is pin supported at nodes 1 through 4. The nondimensional nodal coordinates are given in table 2.

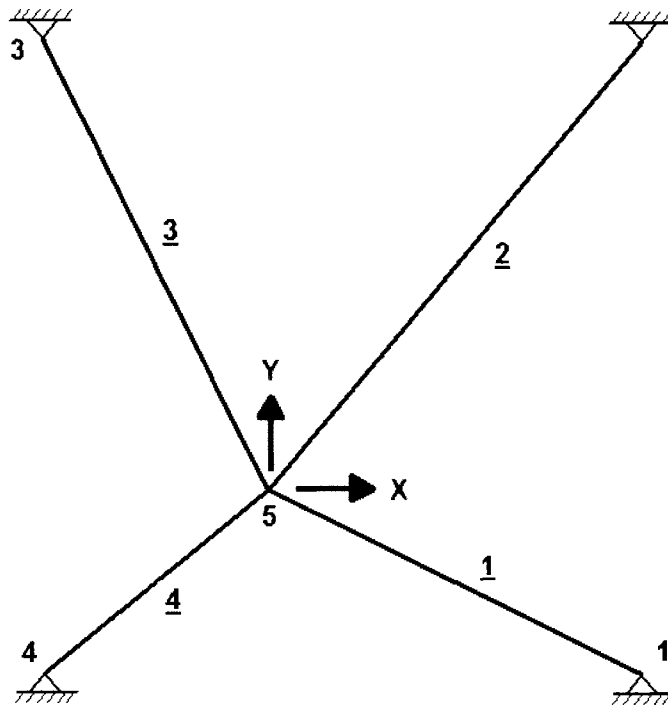


Figure 26. Khot four bar truss.

Table 2. Khot four bar truss nodal coordinates.

NODE	X	Y	Z
1	120.0	-60.0	0.0
2	120.0	144.0	0.0
3	-72.0	144.0	0.0
4	-72.0	-60.0	0.0
5	0.0	0.0	3.0

The global dof associated with each element can be shown in the following arrays

$$lm = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 13 \\ 14 \\ 15 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \\ 13 \\ 14 \\ 15 \end{bmatrix}, \begin{bmatrix} 7 \\ 8 \\ 9 \\ 13 \\ 14 \\ 15 \end{bmatrix}, \begin{bmatrix} 10 \\ 11 \\ 12 \\ 13 \\ 14 \\ 15 \end{bmatrix}$$

$$locbegin = 0, \quad 6, \quad 12, \quad 18$$

Figure 27. Element connectivity arrays.

The vertical load is represented in array “b” as shown in (5.2).

$$b = \begin{bmatrix} 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ -1.0 \end{bmatrix} \quad (5.2)$$

The four pinned constraints are given in array “iboundc” (5.3).

$$iboundc = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad (5.3)$$

The global stiffness can now be written as a 15 x 15 symmetric matrix and is shown in figure 28. The matrix is obtained from the four element arrays in figure 27 and the element stiffness in chapter 3. The arrays used to efficiently store the stiffness matrix in sparse form will now be discussed.

$$\begin{array}{cccccccc}
 \left[\begin{array}{ccccccc}
 1 & 0 & 0 & . & . & 0 & 0 & 0 \\
 0 & 1 & 0 & . & . & 0 & 0 & 0 \\
 0 & 0 & \text{.....} & . & . & . & . & . \\
 . & . & . & \text{.....} & . & . & . & . \\
 . & . & . & . & \text{.....} & . & . & . \\
 . & . & . & . & . & 156728.0 & 52393.59 & 1101.028 \\
 . & . & . & . & . & 52393.59 & 113969.42 & 1237.511 \\
 0 & 0 & 0 & . & . & 1101.028 & 1237.511 & 181.6088
 \end{array} \right] & \begin{array}{l} 1 \\ 2 \\ . \\ . \\ . \\ 13 \\ 14 \\ 15 \end{array} \\
 \begin{array}{ccccccc}
 1 & 2 & 3 & . & . & 13 & 14 & 15
 \end{array}
 \end{array}$$

Figure 28. Khot four element truss stiffness matrix after applying restraints.

The element-dof connectivity information is given in the following two arrays, “ia” and “ja.” Both arrays are constructed using the element conductivity arrays from figure 27. Array “ia” gives the locations of the first non-zero of each row of the element dof connectivity and is shown in (5.4).

$$ia = \begin{bmatrix} 1 \\ 7 \\ 13 \\ 19 \\ 25 \end{bmatrix} \quad (5.4)$$

Array “ja,” given in (5.5), contains the global dof column numbers for the non-zero terms of each row of the element dof connectivity.

$$ja = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 13 \\ 14 \\ 15 \\ 4 \\ 5 \\ 6 \\ 13 \\ 14 \\ 15 \\ 7 \\ 8 \\ 9 \\ 13 \\ 14 \\ 15 \\ 10 \\ 11 \\ 12 \\ 13 \\ 14 \\ 15 \end{bmatrix} \quad (5.5)$$

The values of the diagonal stiffness terms are then stored in “ad” given in (5.6).

$$ad = \begin{bmatrix} 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 156728.0469 \\ 139694.1853 \\ 181.6088 \end{bmatrix} \quad (5.6)$$

The stiffness values of the non-zero, off-diagonal terms are stored in array “an” and given in (5.7).

$$an = \begin{bmatrix} 52393.5876 \\ 1101.0280 \\ 1237.5111 \end{bmatrix} \quad (5.7)$$

The technique for storing the sparse matrix requires 15 diagonal storage terms and only 3 storage terms for the off-diagonal terms.

5.2 Sparse Solver

In order to solve for the unknown displacements in equation (5.1), the Choleski numerical factorization method [19] is used with the sparse matrix previously described.

The method has been extensively utilized within commercial finite element analysis

programs using sequential computers. The Choleski method consists of three computation steps that efficiently solve a system of linear equations by preventing the storage of a full square matrix. The steps are programmed into the proposed algorithm using sparse techniques that further increase solution efficiency. The first step starts with decomposition of

$$[K] = [U][U]^T \quad (5.8)$$

where $[U]$ is a lower factorized triangular matrix and the transpose, $[U]^T$, is the lower factorized triangular matrix. The diagonal terms of $[U]$ are defined as

$$u_{i,i} = \sqrt{k_{i,i} - \sum_{k=1}^{i-1} u_{k,i}^2} \quad (5.9)$$

and the off-diagonal terms as

$$u_{i,j} = \frac{a_{i,j} - \sum_{k=1}^{i-1} u_{k,j} u_{k,i}}{u_{i,i}} \quad (5.10)$$

where $j > i$.

The next step is a forward solution that begins by substituting $[U]$ into equation (5.8) to give

$$[U]^T [U][Z] = [F] \quad (5.11)$$

This equation can be altered by substituting an unknown vector $[y]$ for the product of $[U][Z]$ in equation (5.11) that leads to

$$[U]^T [y] = [F] \quad (5.12)$$

The forward solution of equation (5.12) yields the vector $[y]$ that is used in the next step.

The third and final step combines the factorized matrix $[U]$ and the vector $[y]$ from step two to obtain

$$[U][Z] = [y] \quad (5.13)$$

This leads to the final solution for the unknown displacements $[Z]$ in equation (5.1).

5.3 Symbolic Sparse Factorization

The efficiency of a sparse equation solution can be improved through symbolic sparse factorization. During the factorization phase for solving equation (5.11) there will be extra non-zero “fill-in” terms. The symbolic factorization will find the locations of all the non-zero off-diagonal terms in the factorized matrix $[U]$. For the four member truss example used in this chapter, two arrays are used to store the location information. The first array, shown in (5.14), is “ia” and gives the starting locations of the first non-zero, off-diagonal terms in the i th row of the factorized matrix $[U]$. The second array, given in (5.15), is “ja” and contains the column numbers corresponding to each nonzero, off-diagonal term in the i th row of $[U]$.

$$ia = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 3 \\ 4 \\ 4 \end{bmatrix} \quad (5.14)$$

$$ja = \begin{bmatrix} 14 \\ 15 \\ 15 \end{bmatrix} \quad (5.15)$$

Numerical factorization is performed inside the subroutine “numfald” found in appendix C. The inverse of the diagonal factorized matrix $[U]$ is given as

$$di = \begin{bmatrix} 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 1.0 \\ 6.3804E-6 \\ 8.1846E-6 \\ 5.9634E-3 \end{bmatrix} \quad (5.16)$$

The numerical values of the non-zero, off-diagonal terms in the factorized matrix $[U]$ are given as

$$un = \begin{bmatrix} 0.3342 \\ 7.0250E-3 \\ 7.116E-3 \end{bmatrix} \quad (5.17)$$

The last step of the sparse equation solver is the forward/backward solution performed by equations (5.11) through (5.13) and programmed into subroutine “fbed” in the Hrinda algorithm. The upper triangular matrix of the factorized matrix $[U]$ is input to the subroutine using the arrays defined. The solution is the unknown displacement array at the given input load increment.

CHAPTER VI

DERIVATION OF OPTIMUM NONLINEAR STRAIN ENERGY DENSITY FORMULAS

The discussion of using the strain energy density as an indicator of an optimal design begins with an explanation of the strain and potential energy in truss elements. The optimization problem can then be defined with a recurrence formula that is developed to update the design variable--in this case, the cross-sectional area of the member.

Green's strain is used to develop the strain energy density relationship in the 3-D truss element. This is the same strain measurement used in developing the tangent stiffness derived in chapter 3 and shown in equation (3.30). A truss element's mass density is included in the strain equation to obtain the level of strain energy in the element. This section begins by explaining the formulation of Green's strain and then the derivation of the strain energy with strain energy density to show the relationship in equation (6.18).

This relationship is used in developing the recurrence formula that modifies the cross-sectional area to reach a minimal weight design. Obtaining an updating recurrence relationship is possible by formulating a nonlinear constrained optimization problem that uses the potential energy as an equality constraint. The first step to solving the nonlinear constrained optimal problem and deriving an update scheme for the area is to form the Lagrangian. The method will demonstrate how to minimize the strain energy density while making sure the structure supports a load without becoming unstable. The method is the basic tool used in nonlinear constrained optimization problems. Section 6.2 illustrates the derivation of the optimality criterion using the potential energy as an

equality constraint and how it is incorporated into the Lagrangian. The discussion proceeds with differentiating with respect to the design variable to obtain the minimum potential energy. The strain energy density (SED) is introduced to obtain a Lagrange multiplier γ given in equation (6.49) and reproduced below:

$$\gamma_i = \frac{\sum_{i=1}^n SED}{\sum_{i=1}^n SED^2} \quad (6.1)$$

The Lagrange multiplier is placed into the recurrence formula (6.45) to obtain the final form of the recurrence formula given by equation (6.50) and also shown below:

$$(A_i)_{\text{iter}+1} = (A_i)_{\text{iter}} \left(\frac{\sum_{i=1}^n SED}{\sum_{i=1}^n SED^2} \right) (SED_i)^\lambda \quad (6.2)$$

This equation is the recurrence relation that is used to update the design variable A_i at the end of each converged arc length iteration. This difference equation defines each term of the sequence as a function of the preceding terms. The equation gives a new A_i , based on the strain energy density differences in all of the members. As an optimal solution is approached, the strain energy densities will become equal within an allowable user-specified difference.

6.1 Green's Strain

The strain in a truss element may be expressed as

$$\epsilon_E = \frac{x l_i^* - x l_i}{x l_i} \quad (6.3)$$

where xl is the original length along the local x-axis and xl_i is the new length of the i th member as shown in figure 29 [23].

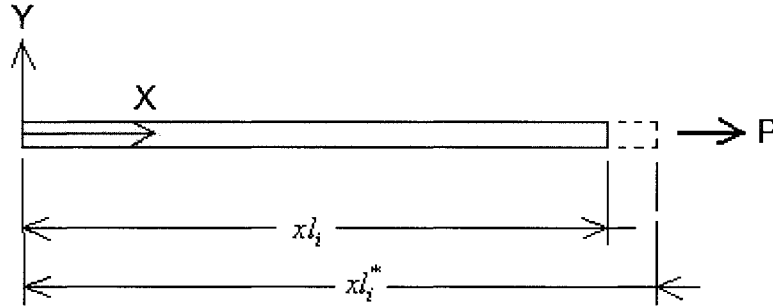


Figure 29. Truss elongation from load P.

Multiplying equation (6.3) by $\frac{xl_i^* + xl_i}{xl_i^* + xl_i}$ will result in

$$\frac{xl_i^* - xl_i}{xl_i} \left(\frac{xl_i^* + xl_i}{xl_i^* + xl_i} \right) = \frac{xl_i^{*2} - xl_i^2}{(xl_i xl_i^* + xl_i^2)} \quad (6.4)$$

Equation (6.4) may be expanded into the following:

$$\frac{xl_i^{*2} - xl_i^2}{(xl_i xl_i^* + xl_i^2)} = \frac{xl_i^{*2} - xl_i^2}{(xl_i xl_i^* + 2xl_i^2 - xl_i^2)} \quad (6.5)$$

Further manipulation of equation (6.5) is performed as shown in the following sequence:

$$\frac{xl_i^{*2} - xl_i^2}{(xl_i xl_i^* + 2xl_i^2 - xl_i^2)} = \frac{xl_i^{*2} - xl_i^2}{(2xl_i^2 + xl_i(xl_i^* - xl_i))} \quad (6.6)$$

$$\frac{xl_i^{*2} - xl_i^2}{(2xl_i^2 + xl_i(xl_i^* - xl_i))} = \frac{xl_i^{*2} - xl_i^2}{\left(2xl_i^2 + xl_i^2 \left(\frac{xl_i^* - xl_i}{xl_i} \right) \right)} \quad (6.7)$$

$$\frac{xl_i^{*2} - xl_i^2}{\left(2xl_i^2 + xl_i^2 \left(\frac{xl_i^* - xl_i}{xl_i} \right) \right)} = \frac{xl_i^{*2} - xl_i^2}{(2xl_i^2 + xl_i^2 \epsilon_E)} \quad (6.8)$$

$$\frac{x l_i^{*2} - x l_i^2}{(2x l_i^2 + x l_i^2 \varepsilon_E)} = \frac{x l_i^{*2} - x l_i^2}{x l_i^2 (2 + \varepsilon_E)} \quad (6.9)$$

For small elastic strains, equation (6.9) may be written as

$$\varepsilon_i = \frac{x l_i^{*2} - x l_i^2}{2x l_i^2} \quad (6.10)$$

The formulation is referred to as "Green's strain" [10].

6.2 Strain Energy Density Formulation

The length change of the element may be large; however, the strains are considered small enough to allow a linear stress strain relationship. Strain energy is stored within an elastic solid when the solid is deformed under load. In the absence of energy losses, such as from friction, damping or yielding, the strain energy is equal to the work done on the solid by external loads. Strain energy is a form of potential energy. The work, W , preformed by a gradually applied load is [23]

$$W = \frac{1}{2} P \Delta \quad (6.11)$$

where P is the internal load and Δ is the axial displacement. It should be noted here that equation 6.11 is still valid for nonlinear, large and finite displacement considered in this work since the strain resulting from such a displacement is assumed to be small enough for a linear stress strain relation [13]. The work that is done by external forces to cause deformation is stored within the truss in the form of strain energy. Based on the assumed linear stress strain relation, the strain energy SE_i of a typical truss element can be computed as

$$SE_i = \frac{1}{2} E_i A_i x l_i \epsilon_i^2 = \frac{1}{2} (\sigma_i = E_i \epsilon_i) A_i (\Delta_i = x l_i \epsilon_i)$$

$$SE_i = \frac{1}{2} P_i \Delta_i \quad (6.12)$$

This relationship is valid for systems that have no energy losses from sources such as friction, yielding or damping.

Substituting $P = AE(xl_i^* - xl_i)/xl_i$ for a truss element and $\Delta_i = (xl_i^* - xl_i)$ into the strain energy equation (6.12) yields

$$SE_i = \frac{1}{2} \frac{A_i E_i}{x l_i} (x l_i^* - x l_i)^2 \quad (6.13)$$

Here, A_i is the truss cross-sectional area and E is Young's modulus of the truss material.

The relationship can also be written in the form

$$SE_i = \frac{A_i E_i (x l_i)}{2} \left(\frac{x l_i^* - x l_i}{x l_i} \right)^2 \quad (6.14)$$

An alternative form of writing equation (6.3) is

$$\left(\frac{x l_i^* - x l_i}{x l_i} \right)^2 = \left(\epsilon_i - \frac{x l_i^* - x l_i}{x l_i} \right)^2 \quad (6.15)$$

This expression is substituted into equation (6.14) to give the strain energy for an i th element, which is

$$SE_i = A_i E_i (x l_i) \left(\epsilon_i - \frac{x l_i^* - x l_i}{x l_i} \right) \quad (6.16)$$

Strain energy density (SED) is the amount of strain energy per unit volume. The strain energy density can be found by dividing the strain energy by the volume of an element and can be written as

$$SED_i = \frac{SE_i}{(xl_i)A_i} \quad (6.17)$$

This relationship is modified for use in an optimum criterion by dividing the strain energy by the mass density ρ_i for an i th element to yield

$$SED_i = \frac{SE_i}{\rho_i xl_i A_i} \quad (6.18)$$

To further develop an optimality criterion for stability, a discussion of potential energy follows.

6.3 Optimality Criterion

The minimum weight optimization of a truss system is defined as:

$$W = \sum_{i=1}^n \rho_i A_i xl_i \quad (6.19)$$

where ρ_i is the material density of the i th element, A_i is the cross-sectional area of the i th element and xl_i is the new deformed length of the i th element with n number of elements.

The formal optimization problem can be defined as

$$\text{find} \quad \{A_i\} \quad (6.20)$$

$$\text{to minimize} \quad \sum_{i=1}^n \rho_i A_i xl_i \quad (6.21)$$

$$\text{subject to} \quad PE - \overline{PE} = 0 \quad (6.22)$$

This minimum weight equation is subject to the equality constraint

$$g = PE - \overline{PE} = 0 \quad (6.23)$$

Where PE is the total potential energy of a truss system and \overline{PE} is the total potential energy associated with the optimal design at the nonlinear critical limit load [13]. This equality constraint has the smallest cross-sectional area that is capable of sustaining an applied load just before the structure becomes unstable. This places a constraint on the limit load that is the same as constraining the total potential energy of the structure. For multiple members, the potential energy may be written as

$$PE = \sum_{i=1}^{\text{ele}} SE_i - \sum_{j=1}^{\text{nodes}} W_j \quad (6.24)$$

where SE_i is the strain energy in the i th element and W_j is the work that is produced from an external force. The relationship can also be written for a structural system that consists of n number of truss elements as

$$PE = \sum_{i=1}^n SE_i - \bar{u}^T \bar{F} \quad (6.25)$$

where SE_i identifies the strain energy in the i th element, \bar{u}^T is a vector transpose of the global displacements, and \bar{F} is the applied design load vector.

Lagrange developed the tool for solving optimality problems by developing the Lagrangian function which is written as

$$L = f(x) + \sum_{j=1}^m \gamma_j h_j(x) \quad (6.26)$$

$$\text{for finding} \quad x \in R^n \quad (6.27)$$

$$\text{to minimize} \quad f(x) \quad (6.28)$$

$$\text{subject to} \quad h_j(x) = 0 \quad j = 1, 2, \dots, m \quad (6.29)$$

where γ_j is called the Lagrange multiplier for the solution (x) that lies in some domain.

Lagrange multipliers find the maximum or minimum of a function of several variables subject to one or more constraints. This method reduces a problem with n variables with k constraints to a solvable problem with $n + k$ variables and no constraints. The method introduces a new, unknown scalar variable, the Lagrange multiplier, for each constraint and forms a linear combination that involves the multipliers as coefficients. The Lagrange multiplier can be thought of as how strong the constraint is working to get a point to a maximum or minimum. The objective is to find the conditions for some implicit function so that the derivative, in terms of the independent variables of a function, equals zero for some set of inputs. The point x is stationary in space if

$$\frac{\delta L}{\delta x_i} = 0 = \frac{\delta f}{\delta x_i} + \sum_{j=1}^m \gamma_j \frac{\delta h_j(x)}{\delta x_i} \quad i = 1, 2, \dots, n \quad (6.30)$$

and

$$h_j(x) = 0 \quad j = 1, 2, \dots, m \quad (6.31)$$

A stationary point merely means that the solution (x) causes the derivative of a function to equal zero, which is equivalent to the point at which the function stops increasing or decreasing. In the case presented in this work, the solution (x) is the value of the load that causes the tangent at that point to be parallel to the horizontal axis of figure 4. This is also the point of minimum strain energy density for all members along their equilibrium path. If this formulation is used and applied to minimizing weight in trusses, then the Lagrangian becomes (with $m = 1$, in equation 6.31)

$$L = \sum_{i=1}^n \rho_i A_i x l_i - \gamma (PE - \overline{PE}) \quad (6.32)$$

where γ is the Lagrange multiplier and $(PE - \overline{PE})$ is the difference between the total potential energy of the system PE and the target potential energy \overline{PE} of the optimal design at the critical limit load. We desire this difference in potential energy to be a minimum. Differentiating with respect to A_i (and sending the resulting equation to zero) gives

$$\rho_i x l_i - \gamma_1 \left(\frac{\partial PE}{\partial A_i} + \sum_{j=1}^{\text{dof}} \frac{\partial PE}{\partial u_j} \frac{\partial u_j}{\partial A_i} \right) = 0 \quad i = 1, 2, \dots, n \quad (6.33)$$

The potential energy is a function of the set of displacements. If these displacements place the structure in stable equilibrium then the total potential energy has a "stationary" value and the following can be written

$$\frac{\partial PE}{\partial u} = \frac{\partial SE}{\partial u} - F = 0 \quad (6.34)$$

This is the partial of the potential energy from equation (6.25). Using the zero statement of the equilibrium equation (6.34) with equation (6.33), the following simplified form is achieved:

$$\rho_i x l_i - \gamma_1 \left(\frac{\partial PE}{\partial A_i} \right) = 0 \quad (6.35)$$

Remarks:

1. After taking the derivative of the Lagrangian (see equation 6.32) with respect to the truss cross sectional area A_i , the term \overline{PE} do no longer appears in equation 6.35.
2. The Lagrangian in equation 6.32, without the term \overline{PE} , can also be interpreted as a multiple objective optimization problem. One would like to minimize the total

weight of a 3D truss structure and at the same time maximize the total potential energy PE (or minimize $-PE$), and the Lagrange multiplier γ can be considered as the “weighting factor” between the two different objects.

Consider now the potential energy in equation (6.25) as a function of the area of the section. A change in the potential energy with respect to a change in the area can be written as

$$\frac{\partial PE}{\partial A_i} = \frac{\partial SE_i}{\partial A_i} - \frac{\partial u_i F}{\partial A_i} \quad (6.36)$$

which can be expanded using (6.16) and (6.25)

$$\frac{\partial PE}{\partial A_i} = \frac{\delta}{\delta A_i} A_i E(xl_i) \left(\epsilon_i - \frac{xl_i^* - xl_i}{xl_i} \right) - \frac{\delta}{\delta A_i} \vec{u}^T \vec{F} \quad (6.37)$$

The partial derivative with respect to the area A_i is

$$\frac{\partial PE_i}{\partial A_i} = E(xl_i) \left(\epsilon_i - \frac{xl_i^* - xl_i}{xl_i} \right) \quad (6.38)$$

This may now be multiplied by $\frac{A_i}{A_i}$ to obtain the SE_i relation in the numerator

$$\frac{\partial PE_i}{\partial A_i} = E(xl_i) \left(\epsilon_i - \frac{xl_i^* - xl_i}{xl_i} \right) \left(\frac{A_i}{A_i} \right) \quad (6.39)$$

The numerator is equation (6.16) and is used to obtain the reduced form

$$\frac{\partial PE_i}{\partial A_i} = \frac{SE_i}{A_i} \quad (6.40)$$

This is possible because the nonlinear strain energy is only a function of the design variable. Equation (6.40) may now be placed into equation (6.35) to form

$$\rho_i x l_i - \gamma_1 \left(\frac{SE_i}{A_i} \right) = 0 \quad (6.41)$$

Dividing both sides of the above equation by $\rho_i x l_i$, the resulting equation can be rewritten as

$$\frac{\gamma_1}{\rho_i x l_i} \left(\frac{SE_i}{A_i} \right) = 1 \quad (6.42)$$

Using the definition of strain energy density, this equation can be given as the strain energy density optimality criterion of

$$\gamma_1 (SED_i) = 1 \quad (6.43)$$

Remarks:

1. Even for the nonlinear large displacement case, strain energy is still a linear function of design variables at cross section are A_i . However, the above statement is not true if design variables as “dimensions of cross sectional areas”, such as $A_i = b_i * h_i$ where b_i and h_i represent the base and height of a typical cross sectional member, respectively.
2. Since cross sectional areas A_i are used as design variables, scaling the areas and the load parameter by the same scale factor will not change the displacement pattern.

A recurrence formula for updating the area design variable is found by multiplying this formula by $(A_i)^\beta$ to give

$$(A_i)^\beta = (A_i)^\beta (\gamma_1) SED_i \quad (6.44)$$

where β is a parameter that controls the step size and the convergence rate.

Now, taking the β th root on each side

$$(A_i)_{\text{iter}+1} = (A_i)_{\text{iter}} (\gamma_1 SED_i)^{1/\beta} \quad (6.45)$$

gives the updated area for the next iteration. The use of this equation within the arc length method will set $1/\beta$ equal to the load increment multiplier λ_i , as shown in figure

8. The Lagrange multiplier γ_1 in equation (6.45) is unknown but may be found by utilizing equation (6.43) and recognizing that γ_1 will equal 1 at an ideal optimal [18].

Using equation (6.43), a residual may be defined as

$$Res_i = 1 - \gamma_1 (SED_i) \quad (6.46)$$

The residual for an i th member is the amount of estimated error in the member's sizing from the optimal. In statistics, the mean squared error is often used to analyze the performance of an estimated value from the true value. This may be applied to equation (6.46) by taking the sum of the residuals squared written as

$$\frac{1}{n} \sum_{i=1}^n (1 - \gamma_1 SED_i)^2 \quad (6.47)$$

where

i is the member number and n is the total number of members in the structure. The value of equation (6.47) is desired to be minimal. This can be accomplished by taking the partial derivative of the sum of the squares with respect to γ_1 which is written as

$$\frac{\partial}{\partial \gamma_1} \left[\frac{1}{n} \sum_{i=1}^n (1 - \gamma_1 SED_i)^2 \right] = 0 \quad (6.48)$$

The solution for γ_1 is the elementary function

$$\gamma_1 = \frac{\sum_{i=1}^n SED_i}{\sum_{i=1}^n SED_i^2} \quad (6.49)$$

and is placed into equation (6.45) along with λ to obtain the recurrence relation

$$(A_i)_{\text{iter}+1} = (A_i)_{\text{iter}} \left(\frac{\sum_{i=1}^n SED_i}{\sum_{i=1}^n SED_i^2} \right) (SED_i)^\lambda \quad (6.50)$$

CHAPTER VII

DESIGN-VARIABLE SCALING

The arc length method is used in the Hrinda optimization algorithm to both solve the nonlinear structural system and also as an update indicator to monitor the strain energy density in the truss elements of the system. As the equilibrium path is defined, parameters of the arc length are monitored and used to update the recurrence equation. The approach allows for updating the truss stiffness after each run with the arc length solver. As a critical-limit point is approached, the slope of the tangent to the equilibrium path approaches zero. The ideal solution would place the critical-limit load at the point where the slope goes to zero and all of the member strain energy densities become equal.

A recurrence relation is used to update the design variables in the Hrinda optimization algorithm--in this case, the cross-sectional areas of the truss members. Recurrence equations are used in iterative processes to keep track of and adjust variables in optimizations. Formulation of the updating recurrence relation relies on information from the arc length parameters. One of those parameters is the incremental external-load multiplier. The multiplier that is selected to update the recurrence equation depends on which phase the arc length solver is being processed. The solver has three phases; each phase checks the difference between the present total external load multiplier and the next load multiplier. This process is shown in the Hrinda optimization algorithm flowchart of figure 31. The checks indicate how close the load is to reaching a limit point and whether the arc length is becoming more horizontal with a decreasing slope.

7.1 Scale Strain Parameter

A new parameter used in the Hrinda optimization algorithm, called the scale strain parameter, is developed to use the size of the incremental external load at the end of each arc length iteration. The value of the scale strain parameter depends on the recurrence checks that are performed (see figure 30). The three possible values of the scale strain parameter SSP are

$$SSP = \lambda_0 + \Delta\lambda_0, \lambda_i + \Delta\lambda_i, \text{ or } \lambda_k + \Delta\lambda_k \quad (7.1)$$

where $\Delta\lambda_0$, $\Delta\lambda_i$ and $\Delta\lambda_k$ are the incremental load multipliers that are used along the load path. The initial load increment is $\Delta\lambda_0 = d\lambda_0$ and is supplied by the user at the start of the arc length procedure, as shown in figure 5. The value λ_0 is a preload value that is placed on the structure; this value is zero for the problems shown in this document. Figure 30 shows the other two incremental multipliers as $\Delta\lambda_i = d\lambda_i$, which is the incremental external multiplier at step i and $\Delta\lambda_k = d\lambda_k$, which is the incremental external multiplier at step k .

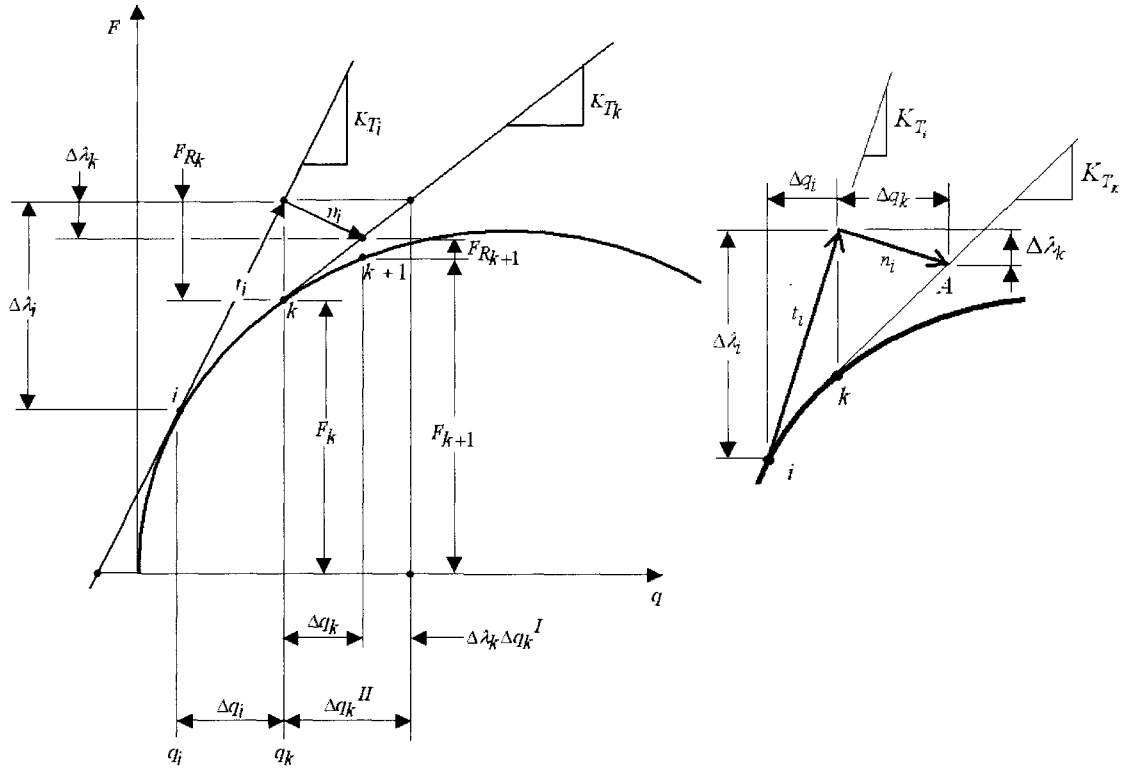


Figure 30. The Riks-Wempner arc length method on a normal plane for a single-degree-of-freedom system.

The new recurrence formula for scaling the design variable is taken from equation (6.50) and can be written by using the *SSP* as

$$SED_{scale} = (SED_{total}/SED_{total2})[SED(i)]^{SSP} \quad (7.2)$$

where

$$SED_{scale} \text{ is the strain energy density scaling factor} \quad (7.3)$$

$$SED_{total} \text{ is the total strain energy density} \quad (7.4)$$

$$SED_{total2} \text{ is } SED_{total}^2 \quad (7.5)$$

$$SED(i) \text{ is the strain energy density in the } i\text{th member} \quad (7.6)$$

$$SSP \text{ is the new scale strain parameter} \quad (7.7)$$

$$dSEDtol = \text{user-given differences between the strain energy densities for all elements} \quad (7.8)$$

The flowchart that is shown in figure 31 outlines the scheme for updating the area design variable *propsect*. Immediately after a solution is found in the arc length solver, the elemental strain energies are calculated and compared with the strain energy density tolerance *dSEDtol*. If all members are within the tolerance, then the solution is optimal. If one member fails the tolerance test then a new *SSP* is calculated from the initial multiplier *dI0* or the incremental external multipliers *dli* and *dlk*.

The strain energy density check is shown in the flowchart in figure 31 and graphically explained in figure 30. Each user-defined tolerance depends on the type of model, the level of fidelity that the user selects for in weight reduction, and how the structure was initially modeled. The whole structure can be optimized for weight, or truss members can be grouped together for sizing. If the absolute difference in strain energy density is below the tolerance, then the solution is considered to be at its optimum. A minimum area is used to avoid zero- area trusses. A zero-area indicates that the truss member is necessary for a stable structure but carries no load. The minimum-area check is made to ensure that member sizes are greater than the user-provided area.

Another check of all of the strain energy densities is made using the user-provided *dSEDtol*. Only solid rods are used in this work, but any section could be used. The new strain energy densities are then computed with the updated areas.

The strategies that are explained for using the recurrence formula will be demonstrated using sample problems that are solved using a nonlinear solution in NASTRAN. The results of other nonlinear structures that have been published in

numerous references will also be used to verify the proposed algorithm with the strain energy density and arc length procedure.

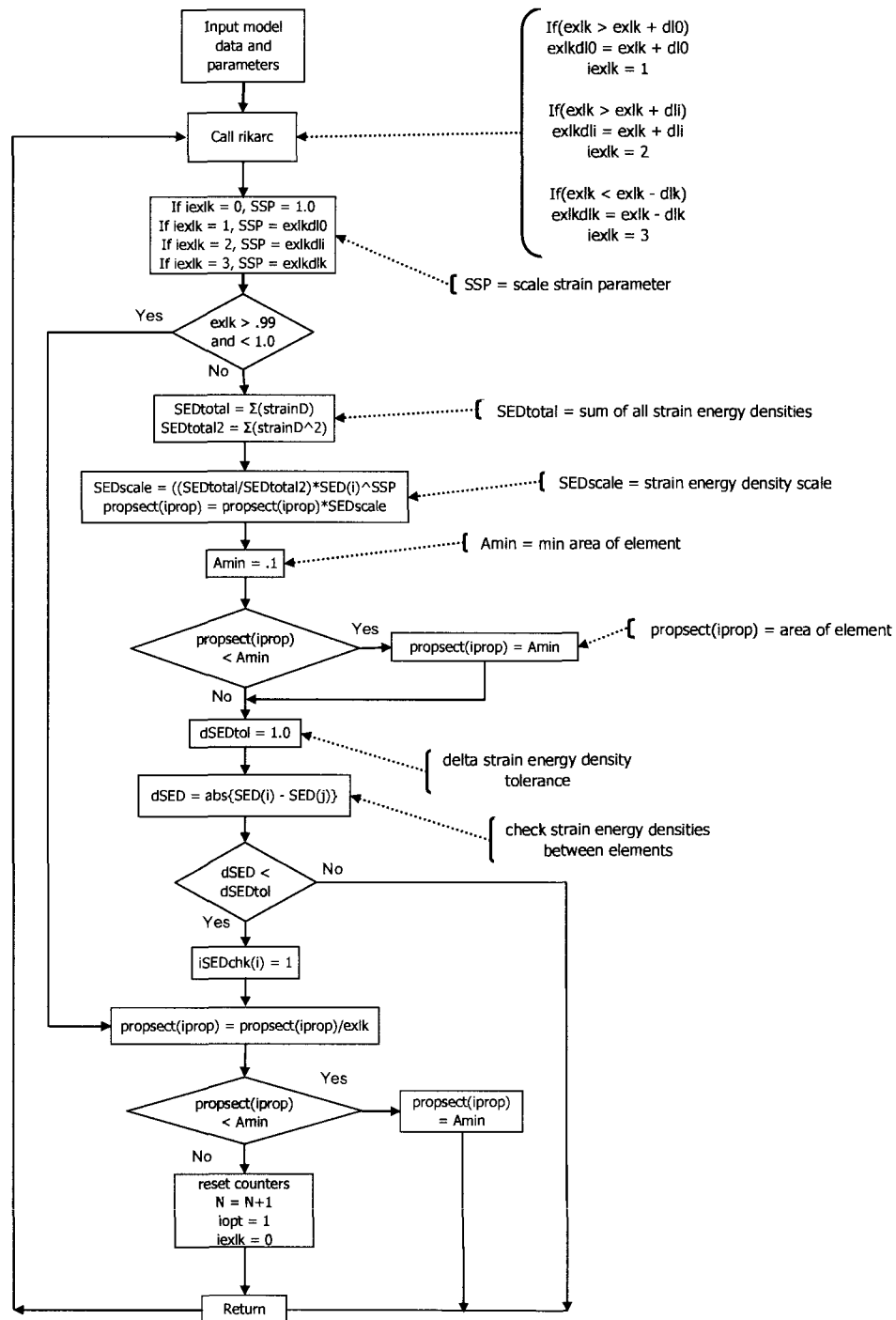


Figure 31. Flowchart for the Hrinda optimizer program.

7.2 Program Outline

The finite element analysis is implemented in the FORTRAN subroutine “rikarc.”

This main routine assembles and solves the finite element model using an arc length method to trace the geometrically nonlinear equilibrium path. The “rikarc” subroutine also contains other routines that use sparse storage and sparse equation solving techniques. A listing of the program may be found in appendix C.

Within “rikarc” is the major subroutine “syseqn” that assembles the nonlinear system of equations from global stiffness matrix that is stored in a one-dimensional array. Inside “syseqn” are numerous other subroutines that apply portions of a sparse equation solution algorithm developed by Nguyen [19]. The subroutine “symbass” starts the process to assemble a symmetrical sparse stiffness matrix by assigning pointers to the first non-zero row term of the element connectivity.

The main FORTRAN subroutines are listed below in the order they are called in the algorithm and explained in the following paragraphs.

```
call generalip
call materprop
call sectprop
call nodecoor
call elconect
call loads
call supportdof
```

Call Rikarc

```
call syseqn
  call symbass
  call copy_int
  call assembly
    call info_elstif
    call elstif
    call numass
```

```

call minfills
call symfactd
call copy_int
call transad
    call transa2d
call supernode
call numfa1d
call fbed

call resid
call test
call result
call itnrml
    call syseqn
    call resid
    call test

```

The first block of subroutines, “generalip” through “supportdof,” are used to input general information about the finite element model. Subroutine “generalip” will read an input file containing: number of supports, number of degree-of-freedom at each node, the degree-of-freedom of each load, number of material properties, number of section properties and the type of element. Subroutine “materprop” reads in the material properties and “sectprop” reads in the cross sectional properties of all the finite elements. The nodal xyz coordinates are read by the subroutine “nodecoor.” Input of the element connectivity is accomplished by the subroutine “elconnect” which reads the order and element number from the input data and places them into a one-dimensional array, “ie”. The subroutine “loads” reads all the applied loads given in the input file. The subroutine “supportdof” also reads the support degree-of-freedoms from the input file.

CHAPTER VIII

VERIFICATION EXAMPLES OF OPTIMIZED TRUSSES

The following sample problems are used to verify the proposed nonlinear optimization method. All of the examples attempt to find the minimum weight of truss areas to support an applied load without buckling. The problems are shallow trusses that have critical limit points and are taken from Khot and Kamat [13] and reviewed in [26]. The first two problems solve a two-element, two-dimensional (2-D) system. A vertical load is applied at the mid-point with pinned end conditions. The next problem is a four-element system that has four different lengths with four cross sections to be optimized. Then, a larger star dome problem is presented, which is similar to the Crisfield star dome in volume two [11]. This problem was minimized by using four cross-sectional area groups that were related to the layout of the design. The last problem is a large shallow truss that is more correct to space trusses. The problem allows for each of the members to be solved for a unique design variable. Here, the system has 13 cross sections that are sized to support a vertical load without snapping through. The solutions that were found in all the examples were compared with those solutions that were published by Khot, as well as with NASTRAN. The areas found by the proposed technique were used in the NASTRAN models. Here, the displacements of the NASTRAN solutions were checked against those found by the proposed algorithm. The first example results are also compared with an analytical solution given by Crisfield [10].

8.1 Two-Member Symmetric Truss Example

The first example that is used to verify the proposed algorithm is a two-member symmetric shallow truss with a 200-lb concentrated load, as shown in figure 32. The problem is taken from Khot and Kamat [13] and is optimized to find the minimum sectional area that can support the 200-lb load without a sudden strain energy release and structure snap-through. All degrees-of-freedom were constrained except at the center node.

Two different initial areas of 3.0 in^2 and 5.0 in^2 were chosen to test the ability of the algorithms to find a unique area for each member. Table 3 shows the initial and final strain energy density distributions in the two elements. The strain energy density in the members become nearly equal at 0.878, which makes the final relative strain energy density equal to 1.0 to indicate an optimal design. Both members were sized to equal areas of 6.499 in^2 , slightly larger than the results that were found by Khot and Kamat in [13] (i.e. 6.4977 in^2 for both members). The total weight summary of the members after each iteration is given in table 4.

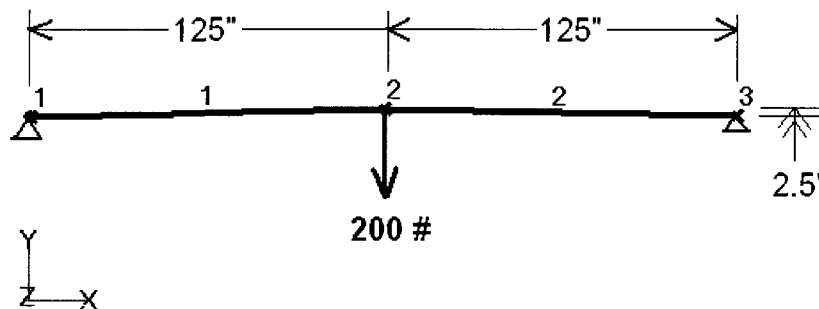


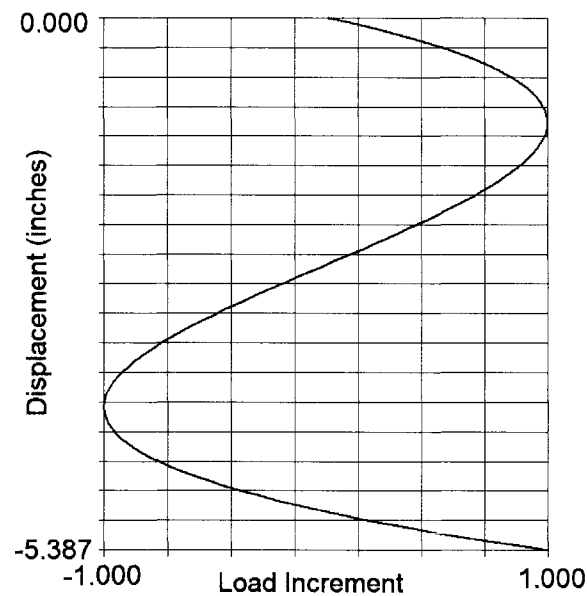
Figure 32. Two-element symmetric truss with 200-lb apex load.

Table 3. Strain energy density distribution for two-element symmetric truss.

Element	Initial Area, in ²	Initial SED	Initial Relative SED	Final SED	Final Relative SED	Final Area, in ²
1	3.00	1.38806	1.00000	0.87799	1.00000	6.4990
2	5.00	0.49960	0.35993	0.87802	1.00000	6.4989

Table 4. Iteration weight history for two-element symmetric truss.

Iteration	Weight, lb	exlk
1	0.100020E+03	0.577049E+00
2	0.803310E+02	0.493552E+00
3	0.799019E+02	0.491683E+00
3	0.799019E+02	0.491682E+00
4	0.162507E+03	0.100000E+01

Figure 33. Khot and Kamat load displacement curve for two-member symmetric truss with cross-section areas equal to 6.4977 in^2 .

The published results given in [13] used an area of 6.4977 in^2 and are close to optimal. However, the NASTRAN and analytical results as well as the Hrinda solution show the truss will not support the 200-lb load; snap-through buckling will still occur. The smaller area (i.e., 6.4977 in^2 from [13]) was used in a NASTRAN analysis to obtain the results that are plotted in figure 33. The equilibrium path shows two critical-limit points, with the first at a load increment of .99959, or an applied load of 200 lb times .99959, which equals 199.9180 lb. The first limit point is reached, and then the structure responds with a snap-through before reaching the intended design load. An analytical solution was also obtained using the exact load displacement path equation given in Crisfield [10]. Here the analytical result also showed that a slightly larger area of 6.499 in^2 was required to support the 200-lb load.

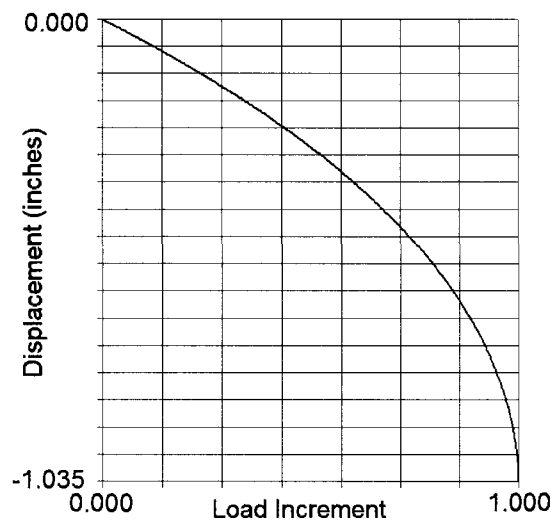


Figure 34. Hrinda load displacement curve for two-member symmetric truss with cross-section areas equal to 6.499 in^2 .

The areas obtained from the proposed algorithm were substituted into the NASTRAN model of the two-element symmetric truss that was used in figure 34. The areas for both elements were the same as can be expected from symmetry (i.e., 6.499 in^2). This optimal cross section produces a maximum displacement of 1.0354 in. at the maximum load increment of 1.0, as shown in figure 34. The area obtained from the proposed Hrinda algorithm was slightly higher than in [13] and did not cause an instability snap-through. The differences between the Hrinda and Khot/Kamat results are negligible. The two results demonstrate the sensitivity of the optimal solution to the number of significant digits used in the design and solution parameters. If a larger load increment is used during the arc length solution, the design area may be slightly smaller as in [13]. The two designs are nearly identical but illustrate how a slight imperfection can affect the design, as stated by Bruns et al. [27], Khot and Kamat [13] and Sedaghati et al. [18]. Appendix B.1 lists the computer model file and output results used in creating the equilibrium path in figure 34.

8.2 Two-Member Asymmetric Truss Example

The next verification problem is an asymmetric, two-element truss, shown in figure 35. The two-element truss has the same 200-lb applied load and support conditions as in the first example. The problem is also taken from Khot and Kamat [13]. A summary of the strain element density results that were obtained with the proposed algorithm is given in table 5. The optimal area is achieved after the difference between the strain energy density in both members falls within the user-defined parameter $dSEDtol$. The final optimal areas were 2.6673 in^2 and 2.6641 in^2 ; for a practical design, they were the same in both members. The weight history is shown in table 6 for each iteration, with a final

design weight of 66.64 lb. This result compares closely with the result from Khot and Kamat of 66.53 lb [13]. Appendix B.2 gives the computer model input file used in producing the results listed in tables 5 and 6.

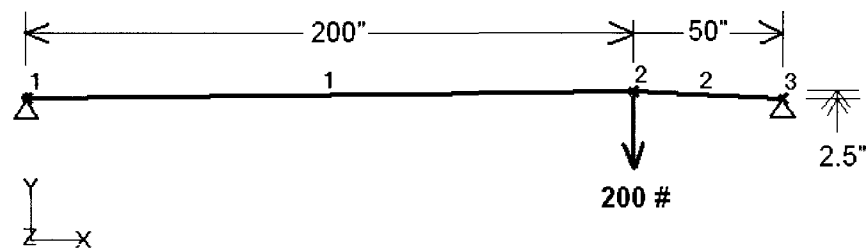


Figure 35. Two-element asymmetric truss.

Table 5. Area and strain energy density distribution of two-element asymmetric truss.

Element	Initial Area, in ²	Initial SED	Initial Relative SED	Final Area, in ²	Final SED	Final Relative SED
1	1.00	1.5047	0.2497	0.266730E+01	2.1532	1.0000
2	2.00	6.0266	1.0000	0.266409E+01	2.1495	0.9983

Table 6. Iteration weight history of two-element asymmetric truss.

Iteration	Weight, (lb)	exlk
1	0.450094E+02	0.625349E+00
2	0.241347E+02	0.360397E+00
3	0.246053E+02	0.369088E+00
4	0.248345E+02	0.372661E+00
5	0.249026E+02	0.373692E+00
6	0.249205E+02	0.373962E+00
7	0.666391E+02	0.100000E+01

8.3 Four-Member Asymmetric Truss Example

The next problem that was investigated was an optimized, asymmetric four-element truss with stability constraints that were presented by Khot and Kamat [13] and analyzed using the Hrinda optimization approach. The model is shown in figures 36 and 37 with a vertical loading of 200 lb at the center node. The first part of the analysis was to create a nonlinear NASTRAN model and test the results that were given in [13] for possible snap-through behavior. The areas that were used in the NASTRAN analysis were the final design areas from [13]; these are shown in table 7. The load deflection plot of the center node is displayed in figure 38; the plot shows that a critical-limit point is reached before the design load of 200 lb. Table 9 lists the four main data points shown by the plot in figure 38. A critical-limit point is reached at a load increment of 0.9174 with a displacement equal to 1.2597 in. Strain energy that is stored in the structure is released, and the load decreases with increasing load. The load goes to zero at about 3.0 in. (point B in fig. 38) and changes direction until another limit point is reached at a maximum load increment of 0.9174 at a displacement equal to 4.7217 in. (point C in figure 38). The curve shown in figure 38 demonstrates that the structure is only able to support a load of 0.9174×200 lb or 183.48 lb. Figure 37 is a plot of the deflected shape after snap-through.

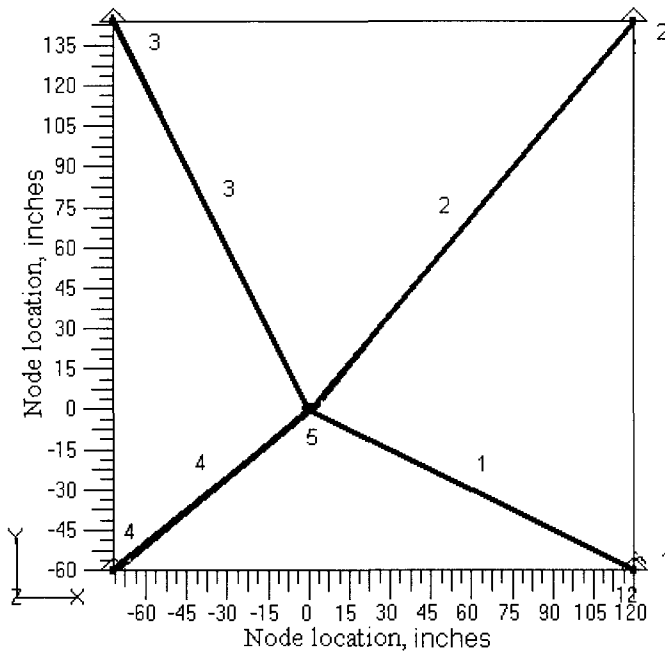


Figure 36. Plan view of the four-member asymmetric truss example.

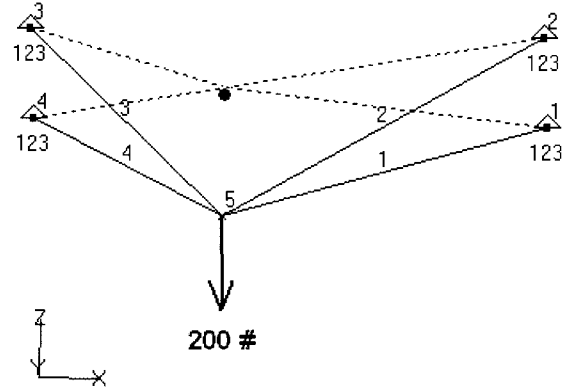


Figure 37. Four-member truss at snap-through.

Table 7. Khot [13] element properties.

Element	Area, in ²
1	0.217240E+01
2	0.163832E+01
3	0.172547E+01
4	0.292330E+01

Now the Hrinda optimization algorithm method is used to solve and optimize the same problem that was given in [13]. The initial area for all of the members was 2.20 in^2 , with the final areas shown in table 8. The final optimized weight is 115.066 lb, as shown in the iteration history that is given in table 10. The final results that were derived from the Hrinda method were used in a NASTRAN nonlinear analysis; the results for the center node are plotted in figure 39.

Table 8. Hrinda final design.

Element	Area, in ²
1	0.216836E+01
2	0.165063E+01
3	0.173753E+01
4	0.288408E+01

The load increment in figure 39 goes to 1.0 with a displacement of 1.249 in. This plot demonstrates that the structure can support the 200-lb load without snap-through buckling. The maximum load increment is reached at 1.0 and is multiplied by the applied load of 200 lb. The strain energy density distribution results for each iteration found by Hrinda are summarized in table 11. The results show that the strain energy densities in all of the members are nearly equal in iteration 20.

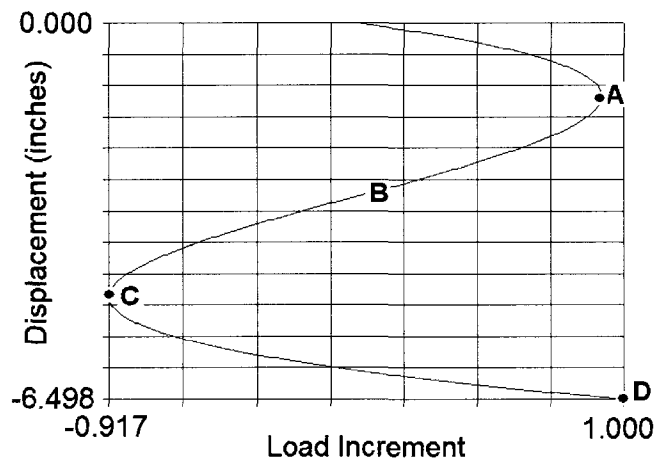


Figure 38. Four-member asymmetric truss equilibrium path during snap-through.

Table 9 lists key quantitative results that are indicated in figure 38.

Table 9. Quantitative results of four-member truss problem using NASTRAN that are shown in figure 38 given as (load increment, displacement).

A	B	C	D
.9174, 1.2597	0.000, 3.00	-.9174, 4.7217	1.000, 6.498

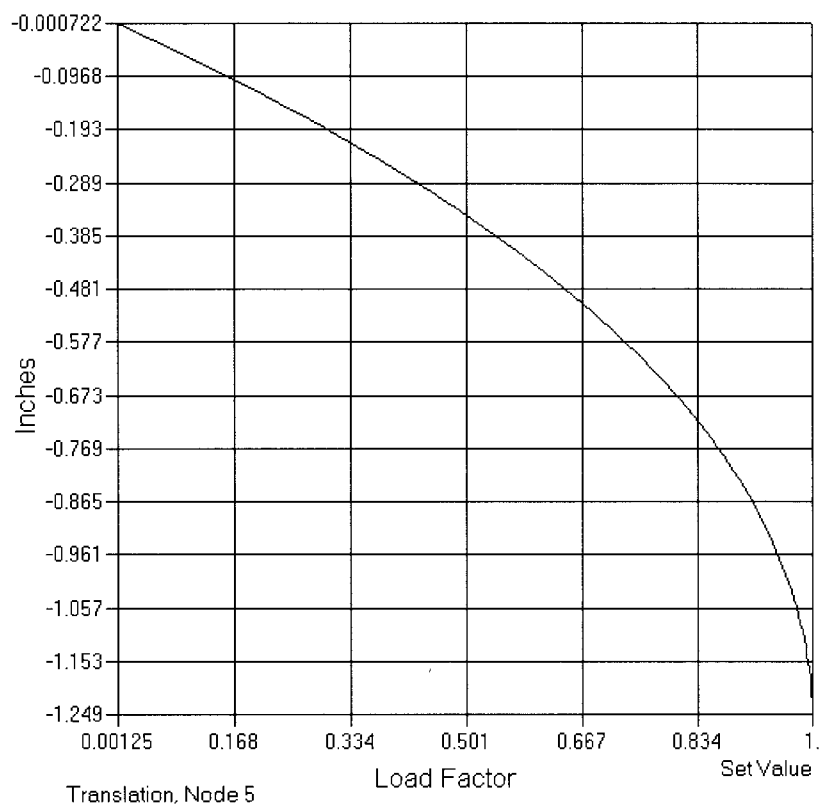


Figure 39. Load increment-displacement results for center node of four-member truss using Hrinda results in NASTRAN.

Table 10. Iteration weight history for four-member truss.

Iteration	Weight, lb.	exlk
1	0.12682196E+03	0.100030E+01
2	0.12177516E+03	0.100013E+01
3	0.11858018E+03	0.100004E+01
4	0.11654891E+03	0.100001E+01
5	0.11525130E+03	0.993698E+00
6	0.10874612E+03	0.937731E+00
7	0.10487218E+03	0.905957E+00
8	0.10064500E+03	0.871200E+00
9	0.98937661E+02	0.858015E+00
10	0.97439280E+02	0.845865E+00
11	0.97044707E+02	0.842990E+00
12	0.96626275E+02	0.839536E+00
13	0.96581425E+02	0.839265E+00
14	0.96460005E+02	0.838257E+00
15	0.96471788E+02	0.838386E+00
16	0.96431562E+02	0.838045E+00
17	0.96443952E+02	0.838159E+00
18	0.96428782E+02	0.838028E+00
19	0.96435934E+02	0.838092E+00
20	0.11506603E+03	0.100000E+01

Table 10 shows the weight and load factors for each iteration during the Hrinda analysis. The first iteration has the load level at 1.00 and the weight at 126.82 lbs. This means that the load was fully applied, but the element SED differences were too large and exceeded the SED tolerance of $dSED_{tol}=1.d-2$.

Table 12 summarizes the Hrinda results by listing the initial SED values and comparing them when an optimal solution is reached. The last two columns show how the final SED values are nearly 1.0, thus indicating the optimal design has been found.

Table 11. SED per element at each iteration from Hrinda results.

Iteration No.	Element	SED	Iteration No.	Element	SED
1	1	1.054980E+00	11	1	1.521010E+00
	2	6.206980E-01		2	1.443440E+00
	3	6.735780E-01		3	1.448930E+00
	4	1.890250E+00		4	1.621580E+00
2	1	1.188370E+00	12	1	1.495660E+00
	2	7.835400E-01		2	1.549700E+00
	3	8.288730E-01		3	1.546510E+00
	4	1.902710E+00		4	1.431000E+00
3	1	1.321840E+00	13	1	1.512990E+00
	2	9.517260E-01		2	1.476600E+00
	3	9.900690E-01		3	1.479020E+00
	4	1.931050E+00		4	1.558940E+00
4	1	1.526660E+00	14	1	1.501880E+00
	2	1.177230E+00		2	1.526780E+00
	3	1.210970E+00		3	1.525260E+00
	4	2.070520E+00		4	1.471600E+00
5	1	1.560360E+00	15	1	1.510310E+00
	2	1.269670E+00		2	1.493510E+00
	3	1.296040E+00		3	1.494590E+00
	4	1.992890E+00		4	1.531240E+00
6	1	1.438140E+00	16	1	1.503250E+00
	2	1.743000E+00		2	1.514660E+00
	3	1.731370E+00		3	1.513950E+00
	4	1.122350E+00		4	1.489290E+00
7	1	1.553770E+00	17	1	1.508780E+00
	2	1.300650E+00		2	1.501070E+00
	3	1.322680E+00		3	1.501550E+00
	4	1.921000E+00		4	1.518320E+00
8	1	1.459330E+00	18	1	1.504550E+00
	2	1.675270E+00		2	1.509780E+00
	3	1.665410E+00		3	1.509460E+00
	4	1.223960E+00		4	1.498140E+00
9	1	1.536430E+00	19	1	1.506280E+00
	2	1.381530E+00		2	1.502740E+00
	3	1.393620E+00		3	1.502960E+00
	4	1.747390E+00		4	1.510630E+00
10	1	1.482270E+00	20	1	1.491650E+00
	2	1.596440E+00		2	1.488160E+00
	3	1.590250E+00		3	1.488370E+00
	4	1.350300E+00		4	1.495930E+00

Table 12. Area and strain energy density distribution in four-member truss.

Element	Initial Area, in ²	Initial SED	Initial Relative SED	Final Area, in ²	Final SED	Final Relative SED
1	2.20	0.105498E+01	0.558117	0.216836E+01	0.149165E+01	.997139
2	2.20	0.620698E+00	0.328368	0.165063E+01	0.148816E+01	.994806
3	2.20	0.673578E+00	0.356343	0.173753E+01	0.148837E+01	.994946
4	2.20	0.189025E+01	1.000000	0.288408E+01	0.149593E+01	1.00000

Table 13. Effects of “dSEDtol” value on final weight and number of iterations.

dSEDtol	Final Weight #	Iterations
2.0	0.12682196E+03	1
1.0	0.11858018E+03	3
0.8	0.11525130E+03	5
0.5	0.11552458E+03	9
0.1	0.11507860E+03	14
0.01	0.11506603E+03	20

The effect on the final weight of using different values for “dSEDtol” is shown in table 13. Large values of this parameter were sized for a heavier structure but with less iterations. As the parameter value was reduced, the weight of the structure approached the optimum but more iterations were required. This shows how the parameter may be used when analyzing a new structure. The value could be set to a larger value and then gradually made smaller until a final weight value stabilizes, thus indicating the optimal weight is being approached. If decreasing the “dSEDtol” parameter has little effect on the final weight, the user may also increase the value to reduce the number of iterations.

The element SEDs at the end of each iteration are listed in table 11. The SED in the first iteration for elements 1-4 are: 1.05498, 0.620698, 0.673578 and 1.89025, respectively. The SEDs of the elements are not equal to their differences above the SED

tolerance of 1.d-2. The program adjusts the element areas for the next iterations until the last iteration is reached. The load at the last iteration is fully applied with the element SEDs for elements 1-4 as: 1.49165, 1.48816, 1.48837 and 1.49593, respectively.

The number of iterations may be reduced by raising the element SED tolerance values. A large “dSEDtol” value causes the program to stop at a weight slightly heavier. Another run of the program used a “dSEDtol=.1” to show the result of raising the tolerance value. Table 14 shows the effect of using different initial areas as the final weight and the number of iterations to reach a solution. The results show that initial values affect solution times. The table also lists the sum of the initial area, $A_{initial}$, divided by the final area, A_{final} , for the four elements. The larger the sum of the ratios becomes, the more iterations are required to reach a solution.

Table 14. Effect of using different initial areas on the final weight and number of iterations required to each a final design. All elements used the same initial area. The difference in strain energy density, dSEDtol, was equal to .001 for the five runs in this table.

Initial Areas Elements 1-4	Final Weight #	Number of Iterations	$\sum \frac{A_{initial}}{A_{final}}$
1.00	0.11505859E+03	5	3.1492
2.00	0.11505639E+03	7	3.9787
2.20	0.11506603E+03	20	4.3764
3.00	0.15386057E+03	19	5.9678
4.00	0.20518989E+03	16	7.9572

8.4 Star Dome Truss Example

The next problem that is presented is the shallow star dome truss example that is introduced by Khot and Kamat [13] and shown in figure 40. The design has 30 members with pin supports at the outer nodes and one vertical load at the center. The design sizing is formed on four optimization groups, which are listed in table 15. The minimum area for all elements is 0.1 in^2 . A downward vertical load of 200 lbs is applied at the center of the structure.

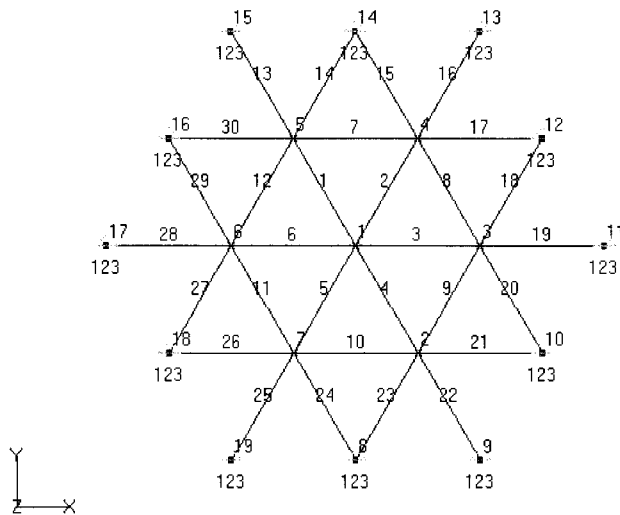


Table 15. Star dome optimization groups.

Group I	1 - 6
Group II	7 - 12
Group III	13, 16, 19, 22, 25, 28
Group IV	14, 15, 17, 18, 20, 21, 23, 24, 26, 27, 29, 30

Figure 40. Star dome truss example.

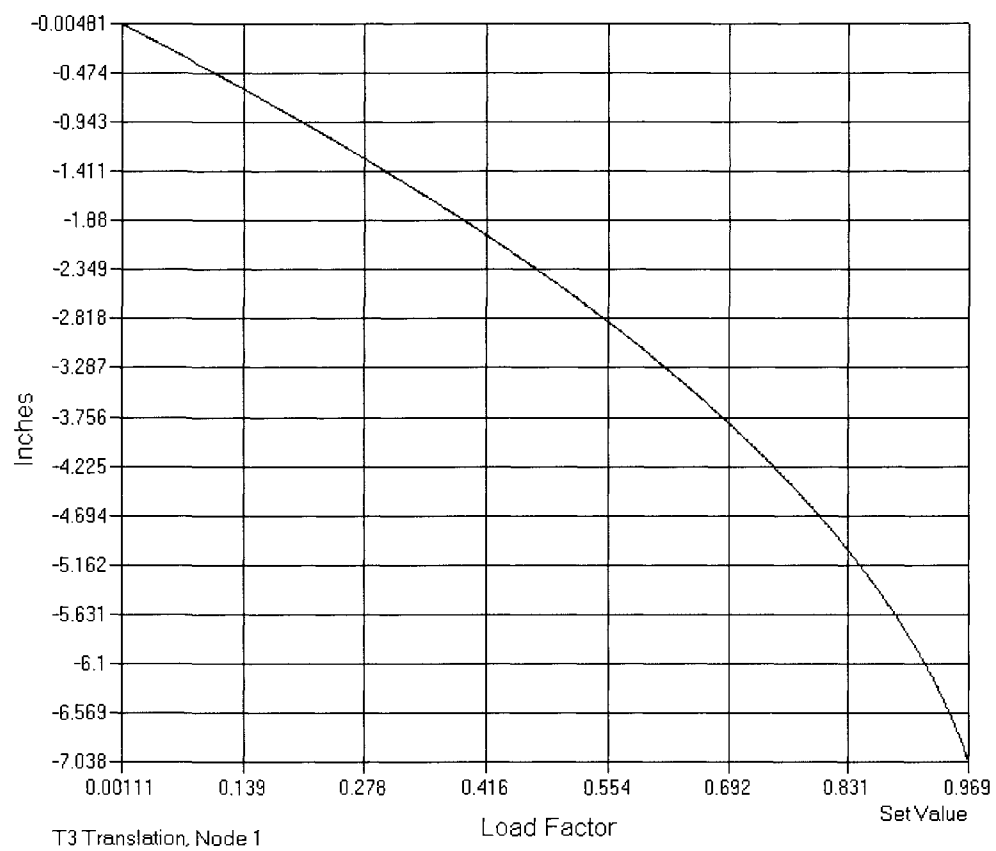


Figure 41. Load-displacement results for center node of star dome truss using Khot results in NASTRAN.

Table 16. Star dome strain energy density and truss area design.

Element	Initial SED	Initial Relative SED	Final SED	Final Relative SED	Final Area, in ²
1	0.194286E+02	1.000000	0.156044E+02	1.000000	0.168767E+01
2	0.194286E+02	1.000000	0.156044E+02	1.000000	0.168767E+01
3	0.194286E+02	1.000000	0.156044E+02	1.000000	0.168767E+01
4	0.194286E+02	1.000000	0.156044E+02	1.000000	0.168767E+01
5	0.194286E+02	1.000000	0.156044E+02	1.000000	0.168767E+01
6	0.194286E+02	1.000000	0.156044E+02	1.000000	0.168767E+01
7	0.126056E+02	0.648817	0.156121E+02	0.999507	0.136980E+01
8	0.126056E+02	0.648817	0.156121E+02	0.999507	0.136980E+01
9	0.126056E+02	0.648817	0.156121E+02	0.999507	0.136980E+01
10	0.126056E+02	0.648817	0.156121E+02	0.999507	0.136980E+01
11	0.126056E+02	0.648817	0.156121E+02	0.999507	0.136980E+01
12	0.126056E+02	0.648817	0.156121E+02	0.999507	0.136980E+01
13	0.740568E+00	0.038117	0.160748E+02	0.970737	0.262472E+00
14	0.183099E-05	0.000000	0.428412E+01	0.274546	0.100000E+00
15	0.183099E-05	0.000000	0.428412E+01	0.274546	0.100000E+00
16	0.740568E+00	0.038117	0.160748E+02	0.970737	0.262472E+00
17	0.183208E-05	0.000000	0.428411E+01	0.274546	0.100000E+00
18	0.183349E-05	0.000000	0.428413E+01	0.274546	0.100000E+00
19	0.740566E+00	0.038117	0.160748E+02	0.970737	0.262472E+00
20	0.183349E-05	0.000000	0.428413E+01	0.274546	0.100000E+00
21	0.183208E-05	0.000000	0.428411E+01	0.274546	0.100000E+00
22	0.740568E+00	0.038117	0.160748E+02	0.970737	0.262472E+00
23	0.183099E-05	0.000000	0.428412E+01	0.274546	0.100000E+00
24	0.183099E-05	0.000000	0.428412E+01	0.274546	0.100000E+00
25	0.740568E+00	0.038117	0.160748E+02	0.970737	0.262472E+00
26	0.183208E-05	0.000000	0.428411E+01	0.274546	0.100000E+00
27	0.183349E-05	0.000000	0.428413E+01	0.274546	0.100000E+00
28	0.740566E+00	0.038117	0.160748E+02	0.970737	0.262472E+00
29	0.183349E-05	0.000000	0.428413E+01	0.274546	0.100000E+00
30	0.183208E-05	0.000000	0.428411E+01	0.274546	0.100000E+00

Table 17. Star dome weight summary.

Iteration	Weight #
1	0.108690E+04
2	0.496329E+03
3	0.516501E+03
4	0.551977E+03
5	0.591325E+03
6	0.638388E+03
7	0.694186E+03
8 (final)	0.762154E+03

Table 18. Final optimized group truss areas.

Group	Area, in ² Hrinda	Area, in ² Khot/Kamat
I	0.168767E+01	1.6926
II	0.136980E+01	1.3754
III	0.262472E+00	0.2693
IV	0.100000E+00	0.1000

The strain energy density summary and the final member areas are given in table 16. The relative strain energy densities are also given; group IV is sized to the minimum 0.10 in^2 . Group IV members have been sized to the minimum area so that their relative strain energy densities do not approach unity. Table 17 shows the total design weights after each iteration, with a final weight of 762.154 lb. This weight compares well with the final optimized design weight of 766.188 lb given by Khot and Kamat [13]. The group sizing results are shown in table 18; these results also compare closely with the results from Khot and Kamat [13].

The Khot areas were used in a NASTRAN model with the results for the center node equilibrium path plotted in figure 41. The NASTRAN analysis ended with an error stating that the solution ended prematurely and the analysis could not continue to the full loading.

8.5 Large Shallow Truss Example

The next problem is a large symmetric shallow truss, which is presented by Khot and Kamat in [13]. The design (see figure 42) includes 23 members that are pinned at node 1 and sized for two applied loads of 300 lb and 600 lb with symmetric boundary conditions at the apex.

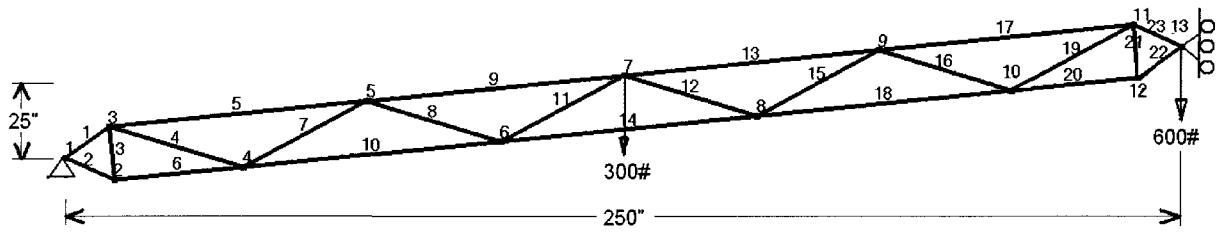


Figure 42. Shallow truss half-symmetry model with two point loads.

Table 19. Shallow truss strain energy density and final design areas.

Element	Initial SED	Initial Relative SED	Final SED	Final Relative SED
1	0.265608E+01	0.81200	0.159399E+01	0.99744
2	0.230073E+01	0.70337	0.159181E+01	0.99608
3	0.574825E+00	0.17573	0.156642E+01	0.98019
4	0.209752E-01	0.00641	0.150678E+01	0.94287
5	0.238759E+01	0.72992	0.159198E+01	0.99618
6	0.172523E+01	0.52743	0.158655E+01	0.99279
7	0.207116E-01	0.00633	0.150819E+01	0.94375
8	0.199578E-01	0.00610	0.150978E+01	0.94475
9	0.327102E+01	1.00000	0.159808E+01	1.00000
10	0.109587E+01	0.33502	0.157836E+01	0.98766
11	0.193169E-01	0.00591	0.150947E+01	0.94455
12	0.192245E-01	0.00588	0.150930E+01	0.94445
13	0.323500E+01	0.98899	0.159787E+01	0.99987
14	0.621099E+00	0.18988	0.156713E+01	0.98063
15	0.196568E-01	0.00601	0.150949E+01	0.94456
16	0.201948E-01	0.00617	0.150776E+01	0.94348
17	0.236487E+01	0.72298	0.159179E+01	0.99606
18	0.109313E+01	0.33419	0.157830E+01	0.98762
19	0.206514E-01	0.00631	0.150652E+01	0.94271
20	0.171458E+01	0.52417	0.158643E+01	0.99271
21	0.564183E+00	0.17248	0.156607E+01	0.99221
22	0.227937E+01	0.69684	0.159163E+01	0.99596
23	0.262691E+01	0.80309	0.159378E+01	0.99731

Table 20. Hrinda and Khot Area comparisons.

Element	Final Area, in ² (Hrinda)	Final Area, in ² (Khot)
1	0.257384E+01	2.4747
2	0.240403E+01	2.3695
3	0.121047E+01	1.1837
4	0.231500E+00	0.2609
5	0.243846E+01	2.3694
6	0.208529E+01	2.0551
7	0.231386E+00	0.2259
8	0.229998E+00	0.2227
9	0.284772E+01	2.7512
10	0.167302E+01	1.6353
11	0.227155E+00	0.1945
12	0.226557E+00	0.1941
13	0.283215E+01	2.7463
14	0.126479E+01	1.2751
15	0.228240E+00	0.2230
16	0.228500E+00	0.2249
17	0.242697E+01	2.3649
18	0.167087E+01	1.6351
19	0.229750E+00	0.2590
20	0.207890E+01	0.0524
21	0.119933E+01	1.1756
22	0.239295E+01	2.3626
23	0.255980E+01	2.4687

Table 21. Hrinda shallow truss weight results.

Iteration	Weight, #
1	0.156524E+03
2	0.134545E+03
3	0.123092E+03
4	0.116857E+03
5	0.113505E+03
6	0.111891E+03
7	0.111382E+03
8	0.111581E+03
9	0.112211E+03
10	0.113076E+03
11	0.114034E+03
12	0.114992E+03
13	0.115892E+03
14	0.116704E+03
15	0.117415E+03
16	0.118024E+03
17	0.118539E+03
18	0.118968E+03
19	0.119322E+03
20	0.119612E+03
21 (final)	0.119850E+03

The strain energy density summary is listed in table 19, and the final member areas are shown in table 20. A $dSEDtol = .10$ is imposed for all elements. The member areas that are derived with the Hrinda optimization algorithm are listed next to those of Khot and Kamat [13] for comparison in table 20. All of the members are in close agreement except member 20. This is because the Hrinda results imposed a minimum area of 0.1 in^2 so that the optimizer was forced to size accordingly. The Hrinda weight summary is given in table 21 with the final weight of 119.85 lb. Doubling this value to account for symmetry yields the final shallow truss weight of 239.70 lb, which is close to the final weight of 234.13 lb found by Khot and Kamat [13].

CHAPTER IX

DISCUSSION

The Lagrange multiplier (γ) is written as a function of the strain energy densities (SED) in equation (6.49). The equation is placed into the design variable equation (6.45) to form a simple updating equation (6.50). The exponential recurrence formula (6.50) out-performed other updating relationships by being able to adjust the design variable to obtain the correct minimum weights given by the chapter 8 examples. Other relationships were attempted; however, they could not achieve a uniform SED . An optimal structure exists when all members have the same SED . This optimality criteria was introduced in equation (6.43) which is repeated below

$$\gamma_1 (SED_i) = 1 \quad (9.1)$$

According to this relationship, when all the member SED s in a structure are the same an optimal design exists. A practical design will not have an exact adherence to equation (9.1) but allows the SED_i s in the members to approach uniformity. This was observed in the example problems of chapter 8 where the SED s are shown to approach uniform values. More iteration would be required to reduce the residuals between the member SED s in equation (6.46).

Other design variable updating relationships failed most likely from not using statistical modeling of the residuals as discussed in chapter six. Minimizing the Lagrange multiplier in the sum of the residual equation (6.45) produced acceptable results. Other statistical modeling techniques for measuring the difference in member's SED s could be incorporated into the program to investigate performance in gaining the optimal solution.

Several members of the "Star Dome Truss" in example 4 of section 8.4 were sized to the design minimal area of $.1 \text{ in}^2$. Table 16 lists the member results and shows members: 14, 15, 17, 18, 20, 21, 23, 24, 26, 27, 29 and 30 at the design minimal area. This is due to the light loads in the members or members that have no load in them and are passive. The same condition also exists for member 20 of the example in section 8.5. Sizing results for member 20 are listed in table 20 and show that the Khot area ($.0524 \text{ in}^2$) is much less than the Hrinda obtained area (2.0824 in^2). The difference is from the Hrinda program enforcing a minimum area of $.1 \text{ in}^2$ that caused the program to adjust other members to still achieve a final weight nearly equal to the Khot optimal weight. The condition may change as the applied loading is placed at different nodes on the structure or if the load direction is changed.

Modern design of lightweight truss structures has been achieved through the use of analysis techniques that were developed to investigate nonlinear instabilities. The application of loads to a truss system that produces nonproportional displacements is nonlinear; increases in the loading will make the structure unstable or cause it to buckle. In [21], these systems are called highly flexible structures (HFS) and are designed for large elastic displacements and without any plastic deformation. These HFS may either show bifurcation or limit-point instability. Bifurcation instability occurs when the structure has a sudden geometric change and is characterized by an abrupt equilibrium path change along the load path. Strain energy from a compressive force is converted to bending strain energy without a large force increase. This conversion can best be visualized as a typical Euler buckling of a slender column. The second type of nonlinear structural response is limit-point instability. This behavior is represented as a gradually

changing equilibrium path with no sudden changes. Increasing the load beyond the limit point causes a release of strain energy as the stiffness becomes negative.

Lightweight truss structures are often highly flexible with unpredictable nonlinear responses and may become unstable before a bifurcation point is reached. An understanding of elastic stability behavior in nonlinear structures can be gained by graphically representing the load and the displacement (i.e. the equilibrium path of the structure).

Methods that overcome the challenges of accurately identifying nonlinear equilibrium paths have been improving and have been developed to include optimization at limit points. With varying success, a growing number of attempts have been made to optimize a structure at a limit load. The challenge is to design a flexible structure to undergo large displacements and remain functional without a loss of stability.

CHAPTER X

CONCLUSIONS AND FUTURE RESEARCH

The optimization of stability-constrained truss structures that exhibit highly nonlinear snap-through behavior has been accomplished using the arc length method and the principal of strain energy density. The iterative scheme for updating design variables was used in a finite element approach (the proposed algorithm) that also used the critical buckling load at snap-through as the design load. The algorithm was able to find the optimum weight to prevent snap-through buckling and was used to size structures prone to snap-through. These included slender member systems such as reticulated shallow domes and large built-up arches. The problems that were executed agreed closely with previous truss examples that were found in the literature. The minimum weight was shown to exist when a uniform strain energy density was achieved in the members. The results verify that the use of the arc length parameters can be used as performance indicators to update the design variables. The technique was applied to design problems with highly nonlinear trusses that are prone to global instability failures, but the technique has also been tested on linear optimization problems. Initial results show that the arc length and strain energy density parameters can be used to find the lightest truss that exhibits linear behavior.

The exploration of space will require light weight structures to enable new technologies and missions. The highly flexible structures have minimal weight and a small stowed volume that make them desirable for space applications. Among NASA's

technology investment initiatives are large, on-orbit structures that support optical reflectors for solar power, communication networks and space telescopes.

The structures must be assembled in orbit or designed to be easily deployed with a low risk of failure. Future methods for analyzing and measuring the nonlinear behavior of HFS will be required. Attempting to demonstrate these types of slender structures on Earth presents many challenges. Having tools that can accurately predict the structure's response in a space environment will improve conceptual designs and help direct research efforts.

A unique feature of the proposed Hrinda algorithm was the discovery of how it could be used to size MEMS in the electronic industry. Micro snap-through structures have been evolving as rapid switches that are integrated into solid-state circuits [2]. A difficult problem in their design is finding the limit point of the switch at snap-through. The author's algorithm should be able to size a micro-switch at snap-through but also for snap-back. Further investigation into the snap-back behavior of micro-structures may lead to new applications and MEMS devices.

The proposed Hrinda method is warranted because it is a self contained algorithm that automatically finds the lightest truss structure that supports a load just before a loss of stability. This capability of combining the arc length parameters to predict an update to the design variables is unique. The author has shown that his work takes an existing powerful nonlinear numerical technique, the arc length method, and uses its parameters to update a weight optimization problem.

The significant contribution of this work is to show how the arc-length method can be used to not only solve the nonlinear system but also to incorporate its parameters into an

optimization scheme. The author uses existing information from the arc-length method as it solves for the equilibrium path and applies this information to the weight minimization of the members. Dynamic inertial effects during the unstable region along the equilibrium path have been excluded by the author. According to the work of Alfutov [15] and Ziegler [28], a static approach leads to the same results as a dynamic approach.

The proposed Hrinda program also incorporates sparse computer techniques that allow for efficient use of computer resources [19]. This may lead to further development of the algorithm by not limiting the size of models and allowing more complicated shallow structures to be investigated.

Future work may involve the use of the Hrinda arc length program to investigate progressive failure in 3d space trusses. The ability of an inelastic analysis tool that confidently predicts limit points would be beneficial in designing orbital structures, transmission towers, bridges or structures that span long distances such as sports arenas [5]. By knowing how the internal load in these structures is redistributed due to damage or loss of stiffness in a member could help in the design of robust structures that are less prone to a catastrophic event. Modeling of post-buckled structures that can trace their equilibrium path from an initial limit point to a new stable point can give insight on system failures and what design improvements are necessary for surviving failure scenarios. If a structure can survive a dynamic snap-through event, it may be able to be designed for higher loads such as HFS presented by Pai [21].

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APPENDIX A-Hrinda Rikarc Users' Input Data Description

A.1 Auro Function Example

$$10u_1^2 + 2u_2^2 = 0.0$$

$$2u_1^2 + 2u_2^2 = 0.0$$

$$\begin{pmatrix} 10u_1 & 2u_2 \\ 2u_1 & 2u_2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0.0 \\ 0.0 \end{pmatrix}$$

The solution to the two unknowns (u_1, u_2) in (2.40) is (0,0).

The input file:

```

4      3      2      2      1      1      1      0      0      0      1      12      1
1      0      0      0      0      0
      6      12      24      4      4      4
1.e7    1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23
5.0     1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23    1.23
1      0.      0.      0.
2      2500.   25.     0.
      1      1      2
1 1.d-8
2 1.d-8
3 0.0
4 0.0
5 0.0
6 0.0

```

The following are User changes made inside the program:

c.....set "iex" to indicate that this is a function test

c.....This is done at beginning of the program
iex=10 !Function Testing

c....User will edit "subroutine elstif" to suit the desired function

subroutine elstif.....

If(iex .eq. 10)then

c**Function Test**

C***Auroa's soln=(0,0) **OK**

esm(1,1) = 10.d0

esm(1,2) = 2.d0

esm(2,1) = 2.d0

esm(2,2) = 2.d0

C***Arora's nonlinear soln=(0,0) **OK**

finx(1) = 10.d0*ux(1) + 2.d0*uy(1)

finy(1) = 2.d0*ux(1) + 2.d0*uy(1)

c....User will edit "subroutine rikarc" to suit the function

c....being solved. These are the arclength parameters that

c....produced the correct solutions.

Subroutine rikarc.....

c***Arora's nonlinear page 331 soln=(0,0)

dl0 = 1.0d-1

dlmax = 1.0d-1

dlmin = 1.0d-2

exlmax = 1.d0

itedes = 2

toldis = 1.d-3

tolfor = 1.d-4

c...User may edit "subroutine result" for desired output format

	istep	exlk	appliedforce1	appliedforce2	a(1)	a(2)	it	ad(5)	ad(7)
*	1	0.10000000E+00	0.1000E-08	0.1000E-08	0.0000E+00	0.5000E-09	2	0.1000E+01	0.1113-307
*	2	0.20000000E+00	0.2000E-08	0.2000E-08	0.0000E+00	0.1000E-08	3	0.1000E+01	0.1113-307
*	3	0.28164966E+00	0.2816E-08	0.2816E-08	0.0000E+00	0.1408E-08	3	0.1000E+01	0.1113-307
*	4	0.33938469E+00	0.3394E-08	0.3394E-08	0.0000E+00	0.1697E-08	3	0.1000E+01	0.1113-307
*	5	0.37589952E+00	0.3759E-08	0.3759E-08	0.0000E+00	0.1879E-08	3	0.1000E+01	0.1113-307
*	6	0.39698137E+00	0.3970E-08	0.3970E-08	0.0000E+00	0.1985E-08	3	0.1000E+01	0.1113-307
*	7	0.40825010E+00	0.4083E-08	0.4083E-08	0.0000E+00	0.2041E-08	3	0.1000E+01	0.1113-307
*	8	0.41825010E+00	0.4183E-08	0.4183E-08	0.0000E+00	0.2091E-08	3	0.1000E+01	0.1113-307
*	61	0.94825010E+00	0.9483E-08	0.9483E-08	0.2068E-26	0.4741E-08	2	0.1000E+01	0.1113-307
*	62	0.95825010E+00	0.9583E-08	0.9583E-08	0.2068E-26	0.4791E-08	2	0.1000E+01	0.1113-307
*	63	0.96825010E+00	0.9683E-08	0.9683E-08	0.2068E-26	0.4841E-08	2	0.1000E+01	0.1113-307
*	64	0.97825010E+00	0.9783E-08	0.9783E-08	0.0000E+00	0.4891E-08	2	0.1000E+01	0.1113-307
*	65	0.98825010E+00	0.9883E-08	0.9883E-08	0.0000E+00	0.4941E-08	2	0.1000E+01	0.1113-307
*	66	0.99825010E+00	0.9983E-08	0.9983E-08	0.0000E+00	0.4991E-08	2	0.1000E+01	0.1113-307
*	67	0.10082501E+01	0.1008E-07	0.1008E-07	0.0000E+00	0.5041E-08	2	0.1000E+01	0.1113-307

A.2 Auro 2 Function Example

$$24u_1 - 12u_2 = -2.0$$

$$-12u_1 + 8u_2 = 0.0$$

$$\begin{pmatrix} 24 & -12 \\ -12 & 8 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} -2.0 \\ 0.0 \end{pmatrix}$$

The solution to the unknowns (u_1, u_2) is given as $(-.3333, -.5000)$ respectively.

The input file:

```

4 3 2 2 1 1 1 0 0 0 1 12 1
1 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
5.0 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 0. 0. 0.
2 2500. 25. 0.
1 1 2
1 -2.d0
2 0.d0
3 0.0
4 0.0
5 0.0
6 0.0

```

The following are User changes made inside the program:

c.....set "iex" to indicate that this is a function test

c.....This is done at beginning of the program

iex=10 !Function Testing

c....User will edit "subroutine elastif" to suit the desired function

subroutine elastif.....

If(iex .eq. 10)then

c***Function Test**

C***Arora's nonlinear 2 soln=(-.33, -.5) **OK**

esm(1,1)= 24.d0

esm(1,2)= -12.d0

esm(2,1)= -12.d0

esm(2,2)= 8.d0

Endif

C***Arora's nonlinear 2 sol=(-.33, -.5) **OK**

finx(1) = 24.d0*ux(1) - 12.d0*uy(1)

finy(1) = -12.d0*ux(1) + 8.d0*uy(1)

c....User will edit "subroutine rikarc" to suit the function

c....being solved. These are the arclength parameters that

c....produced the correct solutions.

Subroutine rikarc.....

c>>> Arora's nonlinear 2 ex={-1/3,-1/2} <<< OK

dl0 = 1.0d-1

dlmax = 1.0d-1

dlmin = 1.0d-2

exlmax = 1.d0

itedes = 2

toldis = 1.d-3

tolfor = 1.d-4

c...User may edit "subroutine result" for desired output format

	istep	exlk	appliedforce1	appliedforce	a(1)	a(2)	it	ad(5)	ad(7)
*	1	0.10000000E+00	-.2000E+00	0.0000E+00	-.3333E-01	-.5000E-01	2	0.1000E+01	0.1113-307
*	2	0.21280366E+00	-.4256E+00	0.0000E+00	-.7093E-01	-.1064E+00	3	0.1000E+01	0.1113-307
*	3	0.30198417E+00	-.6040E+00	0.0000E+00	-.1007E+00	-.1510E+00	3	0.1000E+01	0.1113-307
*	4	0.36371055E+00	-.7274E+00	0.0000E+00	-.1212E+00	-.1819E+00	3	0.1000E+01	0.1113-307
*	5	0.40225448E+00	-.8045E+00	0.0000E+00	-.1341E+00	-.2011E+00	3	0.1000E+01	0.1113-307
*	6	0.42434893E+00	-.8487E+00	0.0000E+00	-.1414E+00	-.2122E+00	3	0.1000E+01	0.1113-307
*	7	0.43611369E+00	-.8722E+00	0.0000E+00	-.1454E+00	-.2181E+00	3	0.1000E+01	0.1113-307
*	8	0.44653339E+00	-.8931E+00	0.0000E+00	-.1488E+00	-.2233E+00	3	0.1000E+01	0.1113-307
*	9	0.45693546E+00	-.9139E+00	0.0000E+00	-.1523E+00	-.2285E+00	3	0.1000E+01	0.1113-307
*	10	0.46732039E+00	-.9346E+00	0.0000E+00	-.1558E+00	-.2337E+00	3	0.1000E+01	0.1113-307
*	11	0.47768867E+00	-.9554E+00	0.0000E+00	-.1592E+00	-.2388E+00	3	0.1000E+01	0.1113-307
*	12	0.48804077E+00	-.9761E+00	0.0000E+00	-.1627E+00	-.2440E+00	3	0.1000E+01	0.1113-307
*	13	0.49837716E+00	-.9968E+00	0.0000E+00	-.1661E+00	-.2492E+00	3	0.1000E+01	0.1113-307
*	14	0.50869831E+00	-.1017E+01	0.0000E+00	-.1696E+00	-.2543E+00	3	0.1000E+01	0.1113-307
*	15	0.51900466E+00	-.1038E+01	0.0000E+00	-.1730E+00	-.2595E+00	3	0.1000E+01	0.1113-307
*	16	0.52929667E+00	-.1059E+01	0.0000E+00	-.1764E+00	-.2646E+00	3	0.1000E+01	0.1113-307
*	17	0.53957476E+00	-.1079E+01	0.0000E+00	-.1799E+00	-.2698E+00	3	0.1000E+01	0.1113-307
*	18	0.54983936E+00	-.1100E+01	0.0000E+00	-.1833E+00	-.2749E+00	3	0.1000E+01	0.1113-307
*	19	0.56009090E+00	-.1120E+01	0.0000E+00	-.1867E+00	-.2800E+00	3	0.1000E+01	0.1113-307
*	20	0.57032978E+00	-.1141E+01	0.0000E+00	-.1901E+00	-.2852E+00	3	0.1000E+01	0.1113-307
*	21	0.58055642E+00	-.1161E+01	0.0000E+00	-.1935E+00	-.2903E+00	3	0.1000E+01	0.1113-307
*	22	0.59077120E+00	-.1182E+01	0.0000E+00	-.1969E+00	-.2954E+00	3	0.1000E+01	0.1113-307
*	23	0.60097453E+00	-.1202E+01	0.0000E+00	-.2003E+00	-.3005E+00	3	0.1000E+01	0.1113-307
*	24	0.61116678E+00	-.1222E+01	0.0000E+00	-.2037E+00	-.3056E+00	3	0.1000E+01	0.1113-307
*	25	0.62134833E+00	-.1243E+01	0.0000E+00	-.2071E+00	-.3107E+00	3	0.1000E+01	0.1113-307
*	26	0.63151955E+00	-.1263E+01	0.0000E+00	-.2105E+00	-.3158E+00	3	0.1000E+01	0.1113-307
*	27	0.64168081E+00	-.1283E+01	0.0000E+00	-.2139E+00	-.3208E+00	3	0.1000E+01	0.1113-307
*	28	0.65183246E+00	-.1304E+01	0.0000E+00	-.2173E+00	-.3259E+00	3	0.1000E+01	0.1113-307
*	29	0.66197485E+00	-.1324E+01	0.0000E+00	-.2207E+00	-.3310E+00	3	0.1000E+01	0.1113-307
*	30	0.67210834E+00	-.1344E+01	0.0000E+00	-.2240E+00	-.3361E+00	3	0.1000E+01	0.1113-307
*	31	0.68223326E+00	-.1364E+01	0.0000E+00	-.2274E+00	-.3411E+00	3	0.1000E+01	0.1113-307
*	32	0.69234995E+00	-.1385E+01	0.0000E+00	-.2308E+00	-.3462E+00	3	0.1000E+01	0.1113-307
*	33	0.70245873E+00	-.1405E+01	0.0000E+00	-.2342E+00	-.3512E+00	3	0.1000E+01	0.1113-307
*	34	0.71255992E+00	-.1425E+01	0.0000E+00	-.2375E+00	-.3563E+00	3	0.1000E+01	0.1113-307
*	35	0.72265384E+00	-.1445E+01	0.0000E+00	-.2409E+00	-.3613E+00	3	0.1000E+01	0.1113-307
*	36	0.73274081E+00	-.1465E+01	0.0000E+00	-.2442E+00	-.3664E+00	2	0.1000E+01	0.1113-307
*	37	0.74282113E+00	-.1486E+01	0.0000E+00	-.2476E+00	-.3714E+00	2	0.1000E+01	0.1113-307
*	38	0.75289511E+00	-.1506E+01	0.0000E+00	-.2510E+00	-.3764E+00	2	0.1000E+01	0.1113-307
*	39	0.76296303E+00	-.1526E+01	0.0000E+00	-.2543E+00	-.3815E+00	2	0.1000E+01	0.1113-307
*	40	0.77302519E+00	-.1546E+01	0.0000E+00	-.2577E+00	-.3865E+00	2	0.1000E+01	0.1113-307
*	41	0.78308188E+00	-.1566E+01	0.0000E+00	-.2610E+00	-.3915E+00	2	0.1000E+01	0.1113-307
*	42	0.79313338E+00	-.1586E+01	0.0000E+00	-.2644E+00	-.3966E+00	2	0.1000E+01	0.1113-307
*	43	0.80317996E+00	-.1606E+01	0.0000E+00	-.2677E+00	-.4016E+00	2	0.1000E+01	0.1113-307
*	44	0.81322190E+00	-.1626E+01	0.0000E+00	-.2711E+00	-.4066E+00	2	0.1000E+01	0.1113-307
*	45	0.82325947E+00	-.1647E+01	0.0000E+00	-.2744E+00	-.4116E+00	2	0.1000E+01	0.1113-307
*	46	0.83329292E+00	-.1667E+01	0.0000E+00	-.2778E+00	-.4166E+00	2	0.1000E+01	0.1113-307
*	47	0.84332253E+00	-.1687E+01	0.0000E+00	-.2811E+00	-.4217E+00	2	0.1000E+01	0.1113-307
*	48	0.85334854E+00	-.1707E+01	0.0000E+00	-.2844E+00	-.4267E+00	2	0.1000E+01	0.1113-307
*	49	0.86337121E+00	-.1727E+01	0.0000E+00	-.2878E+00	-.4317E+00	2	0.1000E+01	0.1113-307

```

* 50 0.87339077E+00 -1.747E+01 0.0000E+00 -2.911E+00 -4.367E+00 2 0.1000E+01 0.1113-307
* 51 0.88340749E+00 -1.767E+01 0.0000E+00 -2.945E+00 -4.417E+00 2 0.1000E+01 0.1113-307
* 52 0.89342159E+00 -1.787E+01 0.0000E+00 -2.978E+00 -4.467E+00 2 0.1000E+01 0.1113-307
* 53 0.90343330E+00 -1.807E+01 0.0000E+00 -3.011E+00 -4.517E+00 2 0.1000E+01 0.1113-307
* 54 0.91344287E+00 -1.827E+01 0.0000E+00 -3.045E+00 -4.567E+00 2 0.1000E+01 0.1113-307
* 55 0.92345052E+00 -1.847E+01 0.0000E+00 -3.078E+00 -4.617E+00 2 0.1000E+01 0.1113-307
* 56 0.93345647E+00 -1.867E+01 0.0000E+00 -3.112E+00 -4.667E+00 2 0.1000E+01 0.1113-307
* 57 0.94346094E+00 -1.887E+01 0.0000E+00 -3.145E+00 -4.717E+00 2 0.1000E+01 0.1113-307
* 58 0.95346415E+00 -1.907E+01 0.0000E+00 -3.178E+00 -4.767E+00 2 0.1000E+01 0.1113-307
* 59 0.96346631E+00 -1.927E+01 0.0000E+00 -3.212E+00 -4.817E+00 2 0.1000E+01 0.1113-307
* 60 0.97346764E+00 -1.947E+01 0.0000E+00 -3.245E+00 -4.867E+00 2 0.1000E+01 0.1113-307
* 61 0.98346833E+00 -1.967E+01 0.0000E+00 -3.278E+00 -4.917E+00 2 0.1000E+01 0.1113-307
* 62 0.99346860E+00 -1.987E+01 0.0000E+00 -3.312E+00 -4.967E+00 2 0.1000E+01 0.1113-307
* 63 0.10034686E+01 -2.007E+01 0.0000E+00 -3.345E+00 -5.017E+00 2 0.1000E+01 0.1113-307

```

A.3 Hrinda 1 Function Example

$$24u_1^2 - 12u_2 = 0$$

$$-12u_1 + 8u_2^2 = 20$$

$$\begin{pmatrix} 24u_1 & -12 \\ -12 & 8u_2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 20 \end{pmatrix}$$

The unknowns, (u_1, u_2) in (2.28) have a unique solution that is $(-0.7633, 1.165)$.

The input file:

```

4 3 2 2 1 1 1 0 0 0 1 12 1
1 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
5.0 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 0. 0. 0.
2 2500. 25. 0.
1 1 2
1 0.d0
2 20.d0
3 0.0
4 0.0
5 0.0
6 0.0

```

The following are User changes made inside the program:

```

c.....set "icx" to indicate that this is a function test
c.....This is done at beginning of the program
      icx=10 !Function Testing
c....User will edit "subroutine elstif" to suit the desired function
c***Hrinda 1 (0.,20.) OK **OK**(-.7633, 1.165)
      subroutine elstif.....
      If(icx .eq. 10)then
c**Function Test**
      esm(1,1)= 24.d0*ux(1) + 2.d-6
      esm(1,2)= -12.d0 + 1.d-6
      esm(2,1)= -12.d0 + 1.d-6
      esm(2,2)= 8.d0*uy(1) + 2.d-6
      Endif
c***Hrinda 1 **OK**
      finx(1)=(24.d0*ux(1)+2.d-6)*ux(1)+(-12.d0+1.d-6)*uy(1)
      finy(1)=(-12.d0+1.d-6)*ux(1)+(8.d0*uy(1)+2.d-6)*uy(1)

```

c....User will edit "subroutine rikarc" to suit the function
c....being solved. These are the arclength parameters that
c....produced the correct solutions.

Subroutine rikarc.....

```
c***Hrinda 1      **OK**
      dl0 = 1.d-2
      dlmax = 1.d-3
      dlmin = 1.d-4
      exlmax = 1.d0
      itedes = 2
      toldis = 1.d-3
      tolfor = 1.d-4
```

c...User may edit "subroutine result" for desired output format

istep	exlk	appliedforce1	appliedforce2	a(1)	a(2)	it	ad(5)	ad(7)
* 1	0.10000124E-01	0.0000E+00	0.2000E+00	-1.667E-01	0.5556E-03	3	0.1000E+01	0.1113-307
* 2	0.11891384E-01	0.0000E+00	0.2378E+00	-1.982E-01	0.7856E-03	3	0.1000E+01	0.1113-307
* 3	0.13427767E-01	0.0000E+00	0.2686E+00	-2.238E-01	0.1002E-02	3	0.1000E+01	0.1113-307
* 4	0.14509699E-01	0.0000E+00	0.2902E+00	-2.418E-01	0.1170E-02	3	0.1000E+01	0.1113-307
* 5	0.15192002E-01	0.0000E+00	0.3038E+00	-2.532E-01	0.1282E-02	3	0.1000E+01	0.1113-307
....								
* 7613	0.99924043E+00	0.0000E+00	0.1998E+02	-7.628E+00	0.1164E+01	1	0.1000E+01	0.1113-307
* 7614	0.99942254E+00	0.0000E+00	0.1999E+02	-7.628E+00	0.1164E+01	2	0.1000E+01	0.1113-307
* 7615	0.99953597E+00	0.0000E+00	0.1999E+02	-7.629E+00	0.1164E+01	1	0.1000E+01	0.1113-307
* 7616	0.99971813E+00	0.0000E+00	0.1999E+02	-7.629E+00	0.1164E+01	2	0.1000E+01	0.1113-307
* 7617	0.99983154E+00	0.0000E+00	0.2000E+02	-7.629E+00	0.1164E+01	1	0.1000E+01	0.1113-307
* 7618	0.10000138E+01	0.0000E+00	0.2000E+02	-7.629E+00	0.1164E+01	2	0.1000E+01	0.1113-307

A.4 Hrinda 3 Function Example

$$24u_1^3 - 16u_2 = 8$$

$$-36u_1 + 6u_2^2 = -24$$

$$\begin{pmatrix} 24u_1^2 & -16 \\ -36 & 6u_2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 8 \\ -24 \end{pmatrix}$$

The solution to the two unknowns is (.6675, -.05417).

The input file:

```
4 3 2 2 1 1 1 0 0 0 1 12 1
1 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
5.0 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 0. 0. 0.
2 2500. 25. 0.
1 1 2
1 8.d0
2 -24.d0
3 0.0
4 0.0
5 0.0
6 0.0
```

The following are User changes made inside the program:

c.....set "iex" to indicate that this is a function test

c.....This is done at beginning of the program

ie x=10 !Function Testing

c....User will edit "subroutine elstif" to suit the desired function

```
c***Hrinda 3 (6675, -.05417.) **OK**
    esm(1,1) = 24.d0*ux(1)*ux(1) + 2.d-10
    esm(1,2) = -16.d0
    esm(2,1) = -36.d0
    esm(2,2) = 6.d0*uy(1) + 2.d-10
```

```
c***Hrinda 3 **OK**
    finx(1)=(24.d0*ux(1)*ux(1)+2.d-10)*ux(1)+
c      (-16.d0)*uy(1)

    finy(1)=(-36.d0)*ux(1)+
c      (6.d0*uy(1)+2.d-10)*uy(1)
```

c....User will edit "subroutine rikarc" to suit the function

c....being solved. These are the arclength parameters that

c....produced the correct solutions.

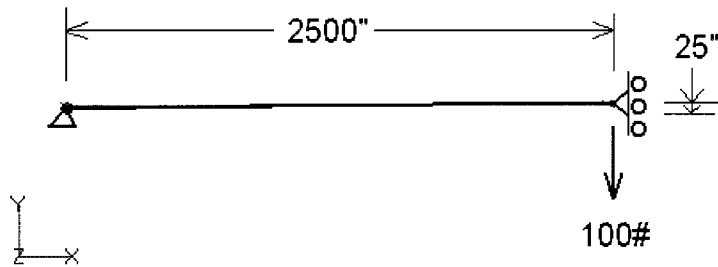
Subroutine rikarc.....

```
c***Hrinda 3 **OK**
    dl0 = 1.d-1
    dlmax = 1.d-2
    dlmin = 1.d-3
    exlmax = 1.d0
    itedes = 2
    toldis = 1.d-4
    tolfor = 1.d-5
```

c...User may edit "subroutine result" for desired output format

	istep	exlk	appliedforce1	appliedforce2	a(1)	a(2)	it	ad(5)	ad(7)
*	1	0.19961451E+00	0.1597E+01	-.4791E+01	0.1346E+00	-.9615E-01	7	0.1000E+01	0.1113-307
*	2	0.21535532E+00	0.1723E+01	-.5169E+01	0.1453E+00	-.1031E+00	60	0.1000E+01	0.1113-307
*	3	0.22811530E+00	0.1825E+01	-.5475E+01	0.1540E+00	-.1086E+00	50	0.1000E+01	0.1113-307
*	4	0.23709132E+00	0.1897E+01	-.5690E+01	0.1602E+00	-.1124E+00	43	0.1000E+01	0.1113-307
*	5	0.24274855E+00	0.1942E+01	-.5826E+01	0.1640E+00	-.1148E+00	37	0.1000E+01	0.1113-307
*	6	0.24600811E+00	0.1968E+01	-.5904E+01	0.1663E+00	-.1161E+00	33	0.1000E+01	0.1113-307
*	7	0.24774850E+00	0.1982E+01	-.5946E+01	0.1674E+00	-.1168E+00	29	0.1000E+01	0.1113-307
*	8	0.24929112E+00	0.1994E+01	-.5983E+01	0.1685E+00	-.1175E+00	28	0.1000E+01	0.1113-307
*	483	0.99015099E+00	0.7921E+01	-.2376E+02	0.6608E+00	-.6236E-01	9	0.1000E+01	0.1113-307
*	484	0.99163279E+00	0.7933E+01	-.2380E+02	0.6617E+00	-.6121E-01	9	0.1000E+01	0.1113-307
*	485	0.99311261E+00	0.7945E+01	-.2383E+02	0.6627E+00	-.6005E-01	9	0.1000E+01	0.1113-307
*	486	0.99459605E+00	0.7957E+01	-.2387E+02	0.6636E+00	-.5887E-01	10	0.1000E+01	0.1113-307
*	487	0.99607197E+00	0.7969E+01	-.2391E+02	0.6646E+00	-.5770E-01	10	0.1000E+01	0.1113-307
*	488	0.99754589E+00	0.7980E+01	-.2394E+02	0.6656E+00	-.5653E-01	10	0.1000E+01	0.1113-307
*	489	0.99901778E+00	0.7992E+01	-.2398E+02	0.6665E+00	-.5535E-01	10	0.1000E+01	0.1113-307
*	490	0.10004876E+01	0.8004E+01	-.2401E+02	0.6675E+00	-.5417E-01	10	0.1000E+01	0.1113-307

A.5 SDOF Crisfield Example



Input file:

```

5  3  2  1  1  1  1  0  0  0  1 12  1
1  0  0  0  0  0
   6 12 24  4  4  4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
5.0 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1  0. 0. 0.
2 2500. 25. 0.
   1 1 2
5 -100.d0
1 0.0
2 0.0
3 0.0
4 0.0
6 0.0

```

The following are User changes made inside the program:
c....User will edit "subroutine rikarc" to suit the function
c....being solved. These are the arclength parameters that
c....produced the correct solutions.

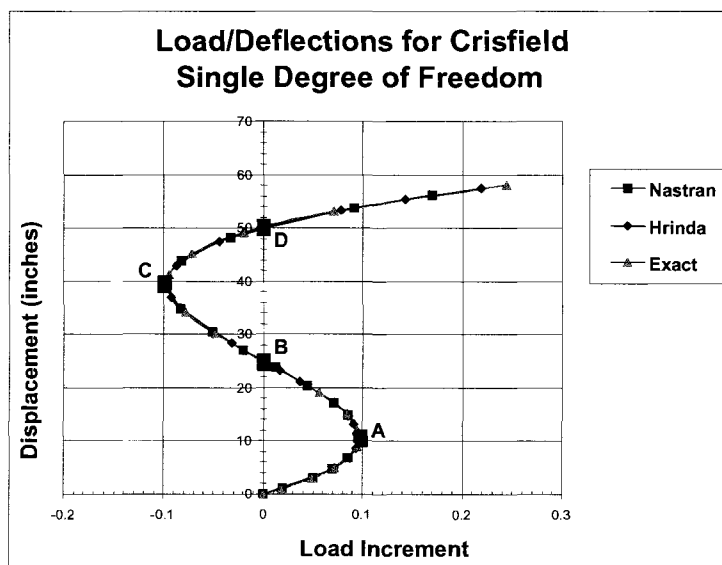
Subroutine rikarc.....

```

c** Crisfield sdof Bar Truss
C** Symmetric
C** This is 2 nodes, 1 element
   itedes = 1
   dl0 = .001d0
   dlmax = .001d0
   dlmin = .0001d0
   exlmax = 1.d0
   toldis = 1.d-4
   tolfor = 1.d-4

```

c...User may edit "subroutine result" for desired output format



METHOD	A	B	C	D
NASTRAN	.0935, 12.59	0.000, 25.00	-.0962, 39.26	.0077, 50.38
Hrinda	.0948, 12.00	0.000, 24.94	-.0961, 39.00	.0070, 50.34
Exact	.0948, 12.00	0.000, 24.82	-.0962, 39.26	.0077, 50.38

istep	exlk	appliedforce	a(5)	it	ad(4)	ad(5)	ad(6)
* 1	0.997002E-03	-.9970E-01	-.5001E-01	2	0.1000E+01	0.1988E+01	0.1000E+01
* 2	0.108259E-01	-.1083E+01	-.5601E+00	4	0.1000E+01	0.1867E+01	0.1000E+01
* 3	0.115603E-01	-.1156E+01	-.5995E+00	3	0.1000E+01	0.1858E+01	0.1000E+01
* 2203	0.948627E-01	-.9486E+01	-.1198E+02	2	0.1000E+01	-.1868E+00	0.1000E+01
* 2204	0.948534E-01	-.9485E+01	-.1199E+02	2	0.1000E+01	-.1875E+00	0.1000E+01
* 2205	0.948440E-01	-.9484E+01	-.1199E+02	2	0.1000E+01	-.1881E+00	0.1000E+01
* 2206	0.948345E-01	-.9483E+01	-.1200E+02	2	0.1000E+01	-.1887E+00	0.1000E+01
* 2207	0.948251E-01	-.9483E+01	-.1200E+02	2	0.1000E+01	-.1893E+00	0.1000E+01
* 2208	0.948156E-01	-.9482E+01	-.1201E+02	2	0.1000E+01	-.1900E+00	0.1000E+01
* 4623	0.167073E-02	-.1671E+00	-.2483E+02	3	0.1000E+01	-.9997E+00	0.1000E+01
* 4624	0.138450E-02	-.1384E+00	-.2486E+02	3	0.1000E+01	-.9998E+00	0.1000E+01
* 4625	0.104450E-02	-.1044E+00	-.2490E+02	3	0.1000E+01	-.9998E+00	0.1000E+01
* 4626	0.605247E-03	-.6052E-01	-.2494E+02	3	0.1000E+01	-.9998E+00	0.1000E+01
* 4627	-0.105074E-03	0.1051E-01	-.2501E+02	3	0.1000E+01	-.9998E+00	0.1000E+01
* 4628	-0.502351E-01	0.5024E+01	-.3026E+02	7	0.1000E+01	-.8672E+00	0.1000E+01
* 4629	-0.502791E-01	0.5028E+01	-.3026E+02	2	0.1000E+01	-.8670E+00	0.1000E+01
* 4630	-0.503232E-01	0.5032E+01	-.3027E+02	2	0.1000E+01	-.8667E+00	0.1000E+01
* 6364	-0.960673E-01	0.9607E+01	-.3898E+02	2	0.1000E+01	-.6234E-01	0.1000E+01
* 6365	-0.960704E-01	0.9607E+01	-.3898E+02	2	0.1000E+01	-.6167E-01	0.1000E+01
* 6366	-0.960735E-01	0.9607E+01	-.3899E+02	2	0.1000E+01	-.6100E-01	0.1000E+01
* 6367	-0.960765E-01	0.9608E+01	-.3899E+02	2	0.1000E+01	-.6033E-01	0.1000E+01
* 6368	-0.960795E-01	0.9608E+01	-.3900E+02	2	0.1000E+01	-.5965E-01	0.1000E+01
* 6369	-0.960825E-01	0.9608E+01	-.3900E+02	2	0.1000E+01	-.5898E-01	0.1000E+01
* 6370	-0.960854E-01	0.9609E+01	-.3901E+02	2	0.1000E+01	-.5831E-01	0.1000E+01
* 6371	-0.960883E-01	0.9609E+01	-.3901E+02	2	0.1000E+01	-.5764E-01	0.1000E+01
* 6372	-0.960912E-01	0.9609E+01	-.3902E+02	2	0.1000E+01	-.5696E-01	0.1000E+01
* 6373	-0.960940E-01	0.9609E+01	-.3902E+02	2	0.1000E+01	-.5629E-01	0.1000E+01
* 8406	0.653863E-02	-.6539E+00	-.5032E+02	3	0.1000E+01	0.2077E+01	0.1000E+01
* 8407	0.686351E-02	-.6864E+00	-.5034E+02	3	0.1000E+01	0.2081E+01	0.1000E+01

* 8408	0.717635E-02	-.7176E+00	-.5035E+02	3	0.1000E+01	0.2085E+01	0.1000E+01
* 8409	0.747862E-02	-.7479E+00	-.5037E+02	3	0.1000E+01	0.2088E+01	0.1000E+01
* 8410	0.777155E-02	-.7772E+00	-.5038E+02	3	0.1000E+01	0.2092E+01	0.1000E+01
* 8411	0.805611E-02	-.8056E+00	-.5039E+02	3	0.1000E+01	0.2095E+01	0.1000E+01
* 8412	0.833315E-02	-.8333E+00	-.5041E+02	3	0.1000E+01	0.2098E+01	0.1000E+01
* 8413	0.860338E-02	-.8603E+00	-.5042E+02	3	0.1000E+01	0.2101E+01	0.1000E+01

The sdof problem is gradually loaded in increments until point "A" is reached. Figure I illustrates this relationship and shows a stable structure up to point "A". A slight load change just after this point will cause the structure to lose stability and snap to a new equilibrium point "E." Point "A" is the stability "limit point" of the structure and is indicated by a loss of tangent stiffness and the slope of the load vs. displacement decreasing to zero. Internal loads and strains increase until point "A" is reached. During "snap-through" from point "A" to "E" the structure releases the stored strain energy. At point "E" the load continues to be applied as the structure deforms along a stable path.

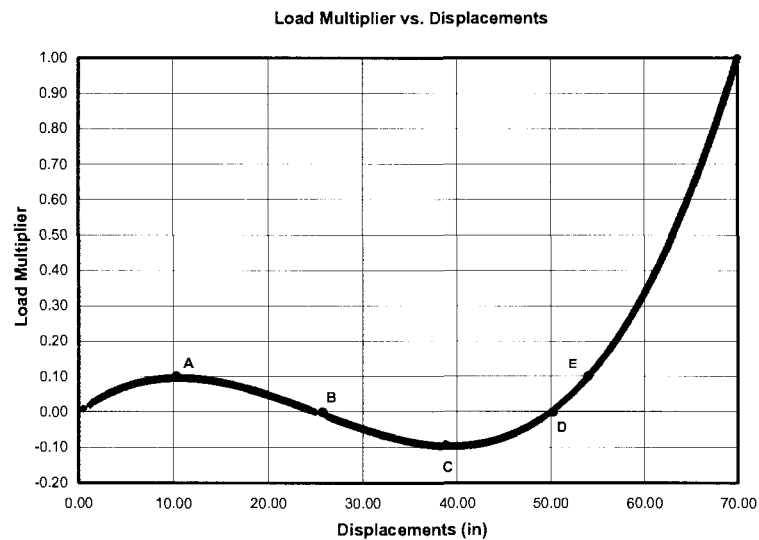


Figure I. Sdof load vs. displacement equilibrium path.

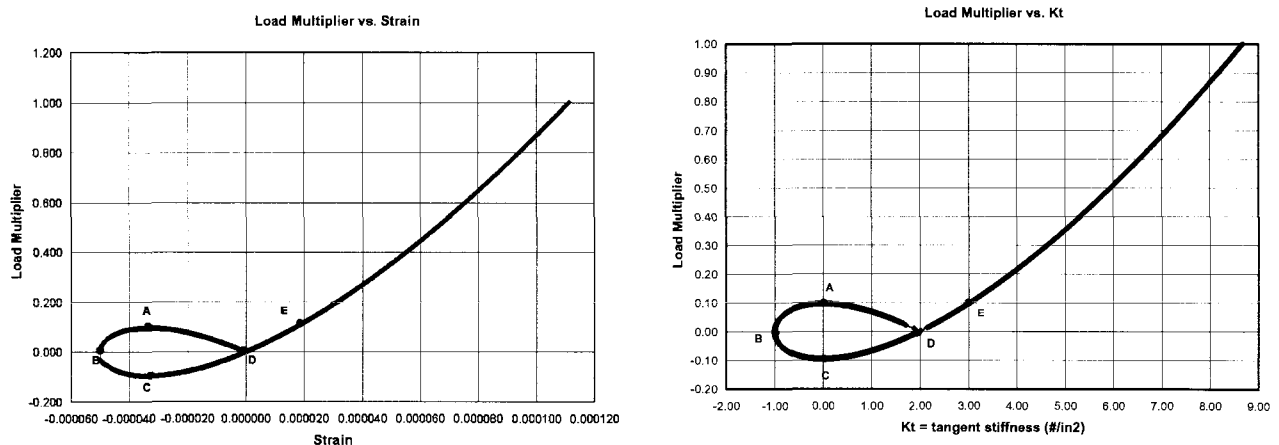
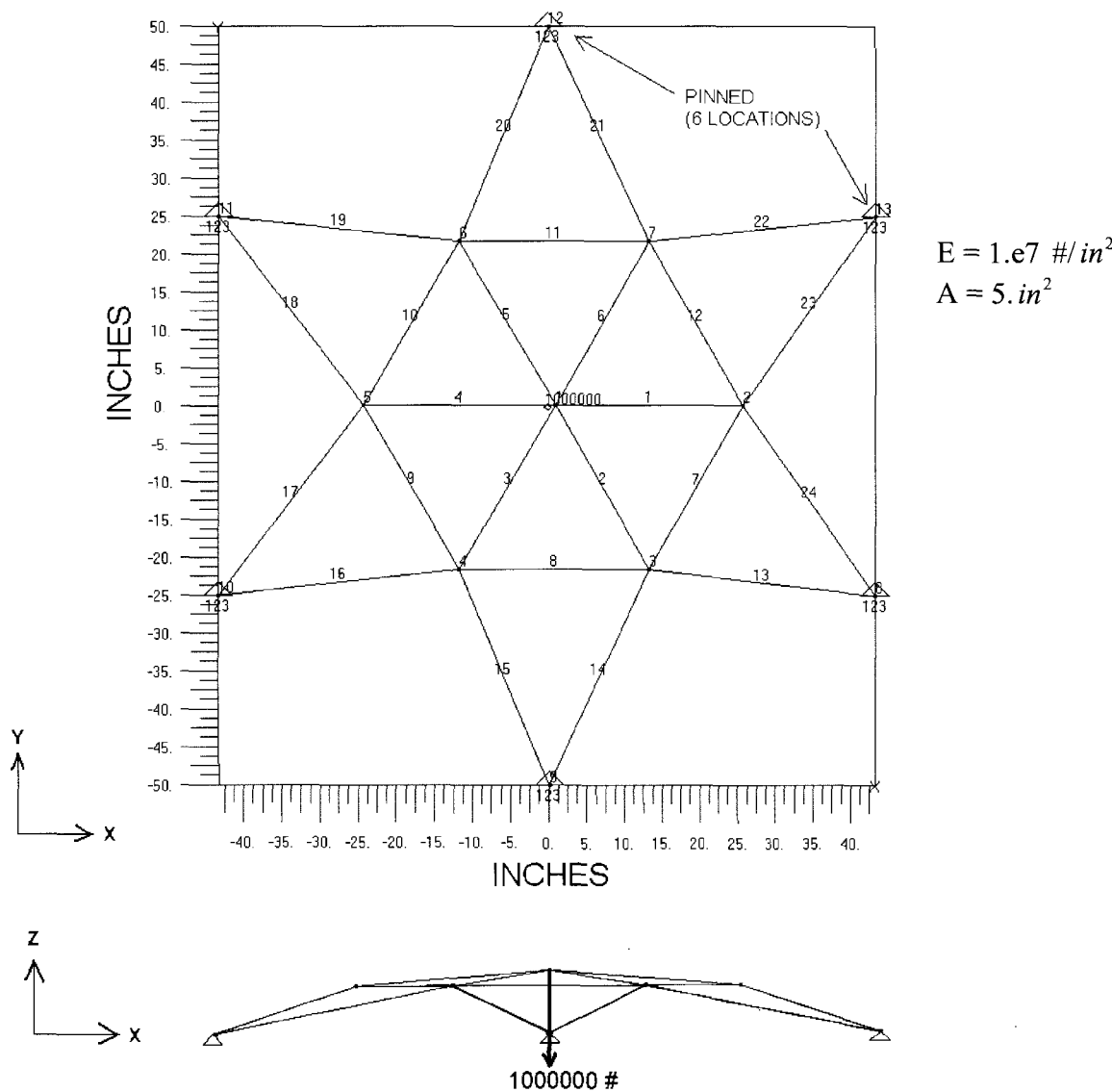


Figure II. Tangent stiffness and Strain as a function of the load multiplier.

A.6 Star Dome Crisfield Example



Crisfield Three-dimensional star dome.

```
*****
Input file:
18 3 13 1 1 1 0 0 0 1 12 1
24 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
5.0 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 0. 0.0 8.216
2 25. 0.0 6.216
3 12.5 -21.6506 6.216
4 -12.5 -21.6506 6.216
5 -25. 0.0 6.216
6 -12.5 21.6506 6.216
7 12.5 21.6506 6.216
```

```

8   43.3013 -25.   0.0
9   0.0      -50.   0.0
10  -43.3013 -25.   0.0
11  -43.3013  25.   0.0
12   0.0      50.   0.0
13  43.3013  25.   0.0

```

```

1   1   2
2   1   3
3   4   1
4   5   1
5   6   1
6   1   7
7   3   2
8   4   3
9   5   4
10  5   6
11  6   7
12  7   2
13  3   8
14  9   3
15  4   9
16  10  4
17  10  5
18  11  5
19  11  6
20  6   12
21  12  7
22  7   13
23  2   13
24  2   8

```

```

3   -1.d6
22  0.0
23  0.0
24  0.0
25  0.0
26  0.0
27  0.0
28  0.0
29  0.0
30  0.0
31  0.0
32  0.0
33  0.0
34  0.0
35  0.0
36  0.0
37  0.0
38  0.0
39  0.0

```

The following are User changes made inside the program:
c....User will edit "subroutine rikarc" to suit the function
c....being solved. These are the arclength parameters that
c....produced the correct solutions.

Subroutine rikarc.....

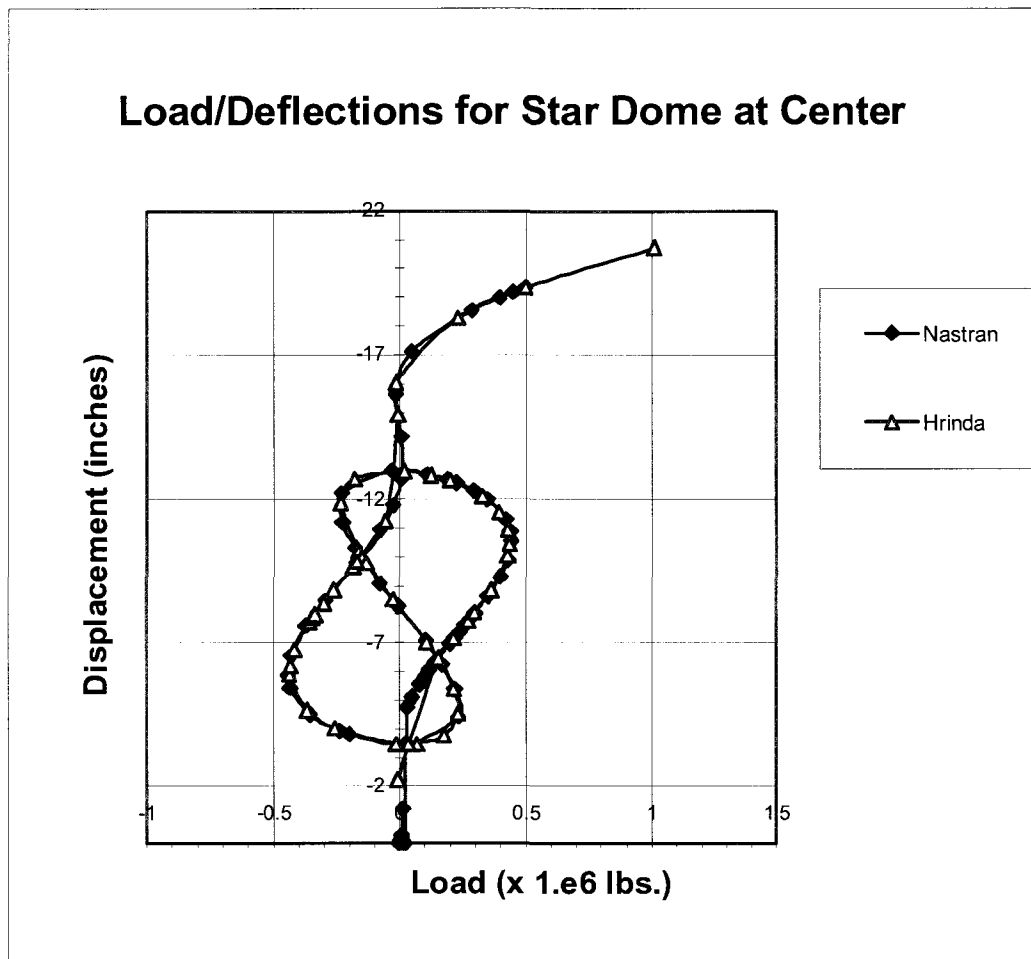
C** 3D Truss , Dome_in.dat & Dome2_in.dat

C** This is a 13 nodes, 24 elements,

```

itedes=1
dl0 = .1d0
dlmax = .1d0
dlmin = .001d0
exlmax = 1.d0
toldis = 1.d-6
tolfor = 1.d-6

```

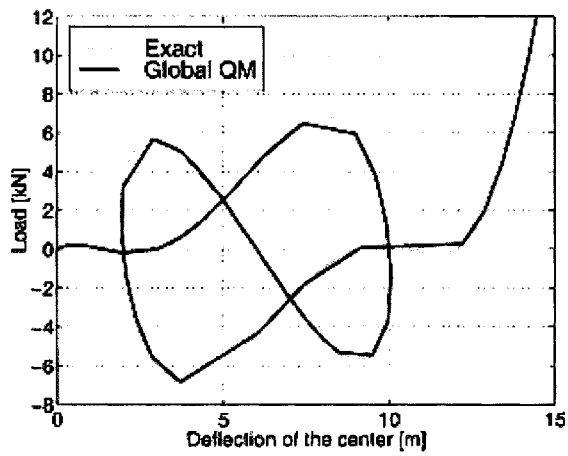
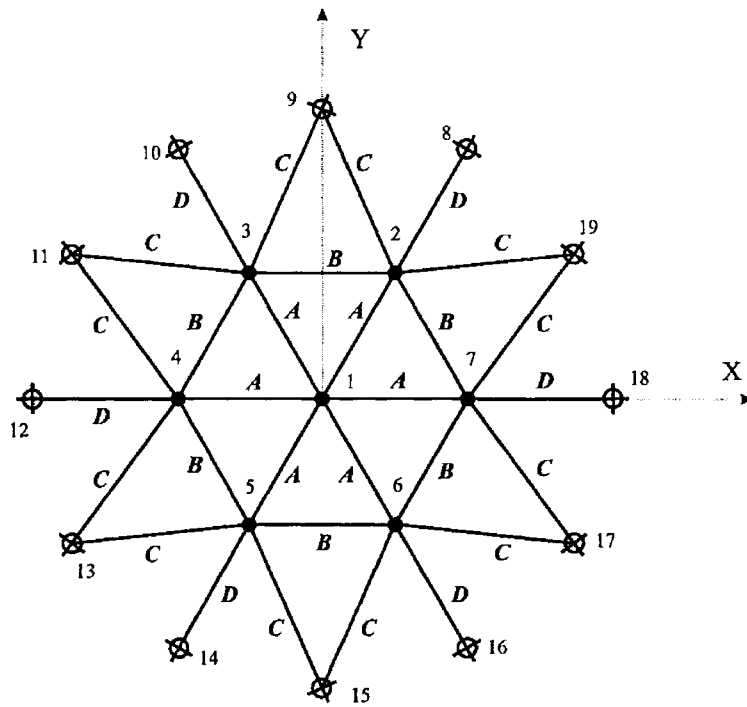


NASTRAN/Hrinda star dome result at center load increment vs. vertical displacement.

istep	exlk	appliedforce	a(1)	a(2)	a(3)	a(4)	a(5)	a(6)	it
* 1	-0.613198E-02	0.61E+04	0.8176E-17	0.9569E-17	-2214E+01	0.3939E-01	-8266E-19	0.1228E+00	3
* 2	0.153542E+00	-0.15E+06	-4192E-16	-5105E-17	-6455E+01	-1267E+00	-4306E-17	-6402E+00	6
* 3	0.215746E+00	-0.22E+06	0.1489E-15	0.2964E-17	-7139E+01	-1701E+00	0.6667E-17	-9146E+00	3
* 239	0.435728E+00	-0.44E+06	0.1643E-15	-1.986E-15	-1.048E+02	-3753E+00	-6752E-17	-2923E+01	2
* 240	0.435747E+00	-0.44E+06	-1.700E-15	0.7847E-16	-1.049E+02	-3758E+00	0.2872E-16	-2931E+01	2
* 241	0.435759E+00	-0.44E+06	-1.185E-15	-5.368E-16	-1.050E+02	-3763E+00	-3.975E-16	-2940E+01	2
* 242	0.435764E+00	-0.44E+06	0.2131E-15	-3.607E-16	-1.051E+02	-3768E+00	0.4574E-16	-2948E+01	2
* 243	0.435763E+00	-0.44E+06	-1.309E-15	0.5790E-16	-1.052E+02	-3773E+00	0.2716E-16	-2956E+01	2
* 244	0.435755E+00	-0.44E+06	-1.580E-15	-1.310E-15	-1.053E+02	-3777E+00	0.5843E-17	-2964E+01	2
* 413	0.340246E+00	-0.34E+06	0.6311E-16	0.3436E-16	-1.199E+02	-4250E+00	0.2277E-16	-4385E+01	2
* 414	0.339142E+00	-0.34E+06	0.1600E-15	0.5224E-16	-1.200E+02	-4251E+00	0.1863E-16	-4394E+01	2
* 524	0.180440E+00	-0.18E+06	0.1668E-15	0.2785E-16	-1.268E+02	-4148E+00	-9725E-16	-5375E+01	3
* 525	0.178632E+00	-0.18E+06	0.2451E-16	-4.119E-16	-1.269E+02	-4145E+00	0.8214E-18	-5385E+01	3
* 589	0.155746E-01	-0.16E+05	-1.664E-16	-2.999E-16	-1.296E+02	-3794E+00	-1.122E-17	-6149E+01	3
* 590	0.730061E-02	-0.73E+04	0.1501E-17	-3.359E-16	-1.297E+02	-3771E+00	0.7526E-16	-6185E+01	4
* 591	-0.515021E-02	0.52E+04	0.1629E-17	-7.737E-16	-1.297E+02	-3735E+00	-9.992E-16	-6238E+01	4
* 592	-0.541731E-01	0.54E+05	-3.265E-17	0.7351E-17	-1.297E+02	-3580E+00	0.2697E-16	-6441E+01	4
* 593	-0.599799E-01	0.60E+05	0.1265E-15	-8.314E-16	-1.297E+02	-3560E+00	-2.009E-16	-6464E+01	3
* 669	-0.232823E+00	0.23E+06	0.3174E-17	-3.527E-16	-1.182E+02	-2507E+00	-9.562E-17	-7070E+01	2
* 670	-0.232867E+00	0.23E+06	0.4125E-16	0.2075E-16	-1.180E+02	-2498E+00	0.2450E-16	-7069E+01	2

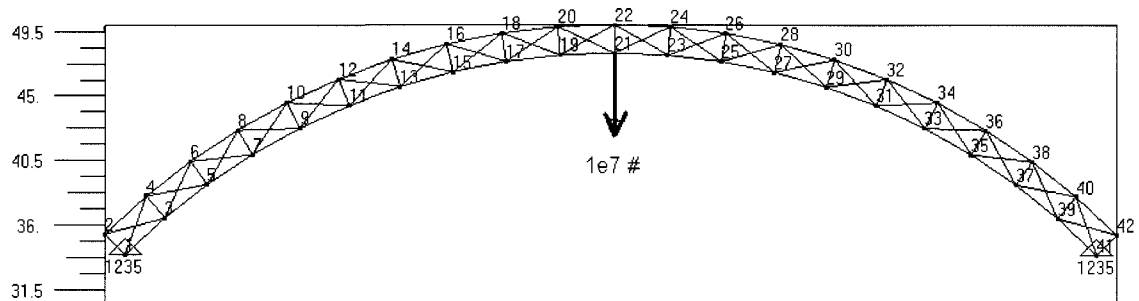
* 671	-0.232871E+00	0.23E+06	0.3503E-16	0.9808E-16	-.1178E+02	-.2489E+00	0.1705E-16	-.7068E+01	2
* 672	-0.232836E+00	0.23E+06	0.5177E-16	-.2098E-16	-.1176E+02	-.2480E+00	0.1762E-16	-.7067E+01	2
* 673	-0.232762E+00	0.23E+06	0.3601E-16	-.4980E-16	-.1173E+02	-.2471E+00	-.4898E-16	-.7066E+01	2
* 815	-0.204542E-01	0.20E+05	0.3731E-16	-.3498E-16	-.8442E+01	-.1947E+00	-.7169E-17	-.6284E+01	3
* 816	-0.123623E-01	0.12E+05	0.5664E-16	-.5167E-16	-.8352E+01	-.1946E+00	-.3982E-16	-.6257E+01	3
* 817	0.465015E-02	-0.47E+04	-.7081E-16	0.8067E-16	-.8165E+01	-.1945E+00	0.2490E-16	-.6200E+01	3
* 818	0.165824E-01	-0.17E+05	0.5209E-16	0.2565E-16	-.8033E+01	-.1946E+00	0.2285E-16	-.6161E+01	3
* 819	0.221251E-01	-0.22E+05	0.7540E-16	-.5478E-16	-.7972E+01	-.1947E+00	-.6859E-17	-.6142E+01	3
* 930	0.209148E+00	-0.21E+06	-.3798E-16	-.5826E-16	-.5517E+01	-.2221E+00	-.1202E-15	-.5481E+01	2
* 931	0.210123E+00	-0.21E+06	0.4768E-16	-.2723E-16	-.5496E+01	-.2226E+00	-.2655E-16	-.5477E+01	2
* 969	0.232782E+00	-0.23E+06	0.3314E-16	-.9228E-17	-.4693E+01	-.2473E+00	-.1355E-16	-.5366E+01	2
* 970	0.232847E+00	-0.23E+06	-.4531E-16	-.2432E-16	-.4671E+01	-.2482E+00	-.1155E-17	-.5365E+01	2
* 971	0.232874E+00	-0.23E+06	-.2047E-16	-.2192E-17	-.4648E+01	-.2491E+00	-.3750E-17	-.5364E+01	2
* 972	0.232861E+00	-0.23E+06	-.5596E-17	-.6167E-17	-.4626E+01	-.2500E+00	0.2581E-17	-.5363E+01	2
* 973	0.232807E+00	-0.23E+06	0.1661E-16	-.3682E-16	-.4604E+01	-.2509E+00	0.7232E-17	-.5362E+01	2
* 1021	0.167104E+00	-0.17E+06	0.7190E-18	-.2870E-16	-.3699E+01	-.3109E+00	-.5400E-17	-.5558E+01	3
* 1022	0.164629E+00	-0.16E+06	0.3760E-16	0.1252E-16	-.3688E+01	-.3122E+00	-.3747E-17	-.5567E+01	3
* 1066	0.242534E-01	-0.24E+05	0.3588E-16	0.4785E-16	-.3456E+01	-.3677E+00	-.2386E-16	-.6114E+01	3
* 1067	0.177412E-01	-0.18E+05	-.3917E-16	-.1578E-16	-.3456E+01	-.3697E+00	-.2677E-16	-.6141E+01	3
* 1068	0.984429E-02	-0.98E+04	-.5195E-17	-.6479E-16	-.3458E+01	-.3721E+00	0.5287E-16	-.6174E+01	4
* 1069	-0.107554E-02	0.11E+04	0.3507E-17	0.5043E-16	-.3462E+01	-.3753E+00	0.8465E-16	-.6221E+01	4
* 1070	-0.264425E-01	0.26E+05	-.2698E-16	0.1455E-16	-.3477E+01	-.3823E+00	0.8203E-17	-.6330E+01	4
* 1233	-0.343350E+00	0.34E+06	0.7152E-16	0.6841E-17	-.4459E+01	-.4248E+00	0.1259E-17	-.8071E+01	2
* 1234	-0.344445E+00	0.34E+06	-.4792E-16	0.1120E-17	-.4467E+01	-.4248E+00	0.1146E-16	-.8080E+01	2
* 1398	-0.435750E+00	0.44E+06	0.2257E-15	-.3707E-15	-.5898E+01	-.3780E+00	-.3254E-16	-.9464E+01	2
* 1399	-0.435761E+00	0.44E+06	-.2428E-16	0.1066E-15	-.5908E+01	-.3775E+00	-.7967E-16	-.9473E+01	2
* 1400	-0.435765E+00	0.44E+06	-.2049E-13	0.1358E-14	-.5918E+01	-.3770E+00	-.1590E-14	-.9481E+01	2
* 1401	-0.435762E+00	0.44E+06	-.2853E-15	-.2821E-15	-.5928E+01	-.3765E+00	-.3754E-16	-.9489E+01	2
* 1402	-0.435753E+00	0.44E+06	-.1598E-15	-.1811E-15	-.5938E+01	-.3760E+00	-.1115E-15	-.9497E+01	2
* 1580	-0.331597E+00	0.33E+06	-.4930E-15	0.5050E-15	-.8010E+01	-.2539E+00	-.1691E-17	-.1089E+02	2
* 1581	-0.330474E+00	0.33E+06	-.5672E-15	0.9321E-15	-.8024E+01	-.2530E+00	0.7949E-16	-.1089E+02	2
* 1789	-0.103347E-01	0.10E+05	-.7438E-16	-.7564E-16	-.1213E+02	-.1211E-01	-.2052E-15	-.1238E+02	3
* 1790	-0.726969E-02	0.73E+04	-.9706E-16	0.5381E-16	-.1221E+02	-.8720E-02	0.7074E-16	-.1240E+02	4
* 1791	-0.341595E-02	0.34E+04	-.7354E-16	-.3989E-16	-.1232E+02	-.4240E-02	-.5810E-16	-.1241E+02	4
* 1792	0.359781E-02	-0.36E+04	0.1605E-15	0.1521E-15	-.1257E+02	0.4854E-02	0.1299E-15	-.1245E+02	4
* 1793	0.642444E-02	-0.64E+04	0.5770E-16	-.1230E-15	-.1269E+02	0.9087E-02	-.1156E-15	-.1247E+02	4
* 1815	0.137843E-01	-0.14E+05	-.7873E-16	0.1205E-15	-.1337E+02	0.2796E-01	0.1533E-15	-.1253E+02	2
* 1816	0.137997E-01	-0.14E+05	-.7936E-16	-.1230E-15	-.1339E+02	0.2844E-01	0.5844E-16	-.1253E+02	2
* 1817	0.138019E-01	-0.14E+05	-.1233E-15	-.1961E-16	-.1341E+02	0.2890E-01	0.3602E-16	-.1253E+02	2
* 1818	0.137911E-01	-0.14E+05	-.5295E-16	-.8328E-16	-.1343E+02	0.2936E-01	0.7594E-17	-.1254E+02	2
* 1819	0.137672E-01	-0.14E+05	0.2722E-17	0.8255E-16	-.1346E+02	0.2981E-01	0.6709E-16	-.1254E+02	2
* 1846	0.413953E-02	-0.41E+04	0.1627E-15	0.1153E-15	-.1433E+02	0.3978E-01	-.6988E-16	-.1255E+02	3
* 1847	0.240007E-02	-0.24E+04	-.6418E-16	-.6669E-16	-.1442E+02	0.3991E-01	-.9039E-16	-.1255E+02	4
* 1848	-0.609470E-03	0.61E+03	0.2127E-16	0.1646E-15	-.1458E+02	0.3969E-01	0.6023E-16	-.1255E+02	4
* 1849	-0.155059E-01	0.16E+05	-.2793E-16	0.4145E-16	-.1578E+02	0.2102E-01	0.1394E-15	-.1247E+02	7
* 1850	-0.153784E-01	0.15E+05	0.1122E-16	-.9711E-16	-.1580E+02	0.2039E-01	0.2843E-16	-.1247E+02	3
* 1882	0.927250E-01	-0.93E+05	-.1213E-15	-.1040E-16	-.1748E+02	-.4076E-01	-.1077E-15	-.1244E+02	3
* 1883	0.971263E-01	-0.97E+05	0.5593E-16	-.3976E-16	-.1751E+02	-.4204E-01	0.9955E-16	-.1244E+02	3
* 1915	0.246890E+00	-0.25E+06	-.3316E-16	-.1103E-15	-.1835E+02	-.7499E-01	0.7449E-16	-.1254E+02	3
* 1916	0.251848E+00	-0.25E+06	-.1623E-15	-.1193E-15	-.1838E+02	-.7585E-01	-.1624E-15	-.1254E+02	3
* 1998	0.713684E+00	-0.71E+06	0.7391E-17	-.2302E-15	-.1997E+02	-.1310E+00	-.4011E-17	-.1293E+02	2
* 1999	0.719994E+00	-0.72E+06	0.1088E-15	-.3288E-16	-.1998E+02	-.1316E+00	-.7749E-16	-.1293E+02	2
* 2040	0.993136E+00	-0.99E+06	-.5285E-16	0.3851E-16	-.2068E+02	-.1532E+00	0.3018E-16	-.1315E+02	2
* 2041	0.100015E+01	-0.10E+07	-.8968E-16	0.7435E-17	-.2069E+02	-.1537E+00	0.3067E-16	-.1315E+02	2

A.6.1 Star Dome Geer Example [25]



Shallow star dome model and equilibrium path of the center node from [22].

A.7 Truss Arch Example



Input file:

```

46  3  42  1  1  1  1  0  0  0  1  12  1
101 0  0  0  0  0
6   12  24  4  4  4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
5.d0 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1  -33.9400  33.9400  0.0
2  -35.3500  35.3500  0.0
3  -31.1725  36.4983  0.0
4  -32.4675  38.0146  0.0
5  -28.2128  38.8315  0.0
6  -29.3848  40.4447  0.0
7  -25.0791  40.9254  0.0
8  -26.1210  42.6256  0.0
9  -21.7908  42.7669  0.0
10 -22.6961  44.5436  0.0
11 -18.3682  44.3447  0.0
12 -19.1313  46.1870  0.0
13 -14.8323  45.6492  0.0
14 -15.4485  47.5456  0.0
15 -11.2050  46.6722  0.0
16 -11.6705  48.6112  0.0
17 -7.50861  47.4075  0.0
18 -7.82054  49.3770  0.0
19 -3.76591  47.8504  0.0
20 -3.92236  49.8383  0.0
21 0.000000  47.9984  0.0
22 0.000000  49.9924  0.0
23 3.76591  47.8504  0.0
24 3.92236  49.8383  0.0
25 7.50861  47.4075  0.0
26 7.82054  49.3770  0.0
27 11.2050  46.6722  0.0
28 11.6705  48.6112  0.0
29 14.8323  45.6492  0.0
30 15.4485  47.5456  0.0
31 18.3682  44.3447  0.0
32 19.1313  46.1870  0.0
33 21.7908  42.7669  0.0
34 22.6961  44.5436  0.0
35 25.0791  40.9254  0.0
36 26.1210  42.6256  0.0
37 28.2128  38.8315  0.0
38 29.3848  40.4447  0.0
39 31.1725  36.4983  0.0
40 32.4675  38.0146  0.0
41 33.9400  33.9400  0.0
42 35.3500  35.3500  0.0
1  1  2
2  1  3
3  1  4
4  2  3
5  2  4

```

6	3	4
7	3	5
8	3	6
9	4	5
10	4	6
11	5	6
12	5	7
13	5	8
14	6	7
15	6	8
16	7	8
17	7	9
18	7	10
19	8	9
20	8	10
21	9	10
22	9	11
23	9	12
24	10	11
25	10	12
26	11	12
27	11	13
28	11	14
29	12	13
30	12	14
31	13	14
32	13	15
33	13	16
34	14	15
35	14	16
36	15	16
37	15	17
38	15	18
39	16	17
40	16	18
41	17	18
42	17	19
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44	18	19
45	18	20
46	19	20
47	19	21
48	19	22
49	20	21
50	20	22
51	21	22
52	21	23
53	21	24
54	22	23
55	22	24
56	23	24
57	23	25
58	23	26
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60	24	26
61	25	26
62	25	27
63	25	28
64	26	27
65	26	28
66	27	28
67	27	29
68	27	30
69	28	29
70	28	30
71	29	30
72	29	31
73	29	32
74	30	31
75	30	32
76	31	32

77	31	33
78	31	34
79	32	33
80	32	34
81	33	34
82	33	35
83	33	36
84	34	35
85	34	36
86	35	36
87	35	37
88	35	38
89	36	37
90	36	38
91	37	38
92	37	39
93	37	40
94	38	39
95	38	40
96	39	40
97	39	41
98	39	42
99	40	41
100	40	42
101	41	42
65	-1.e7	
1	0.0	
2	0.0	
3	0.0	
6	0.0	
9	0.0	
12	0.0	
15	0.0	
18	0.0	
21	0.0	
24	0.0	
27	0.0	
30	0.0	
33	0.0	
36	0.0	
39	0.0	
42	0.0	
45	0.0	
48	0.0	
51	0.0	
54	0.0	
57	0.0	
60	0.0	
63	0.0	
66	0.0	
69	0.0	
72	0.0	
75	0.0	
78	0.0	
81	0.0	
84	0.0	
87	0.0	
90	0.0	
93	0.0	
96	0.0	
99	0.0	
102	0.0	
105	0.0	
108	0.0	
111	0.0	
114	0.0	
117	0.0	
120	0.0	
121	0.0	
122	0.0	
123	0.0	

126 0.0

The following are User changes made inside the program:

c....User will edit "subroutine rikarc" to suit the function

c....being solved. These are the arclength parameters that

c....produced the correct solutions.

Subroutine rikarc.....

itedes=1

dl0 = .1d0

dlmax = .1d0

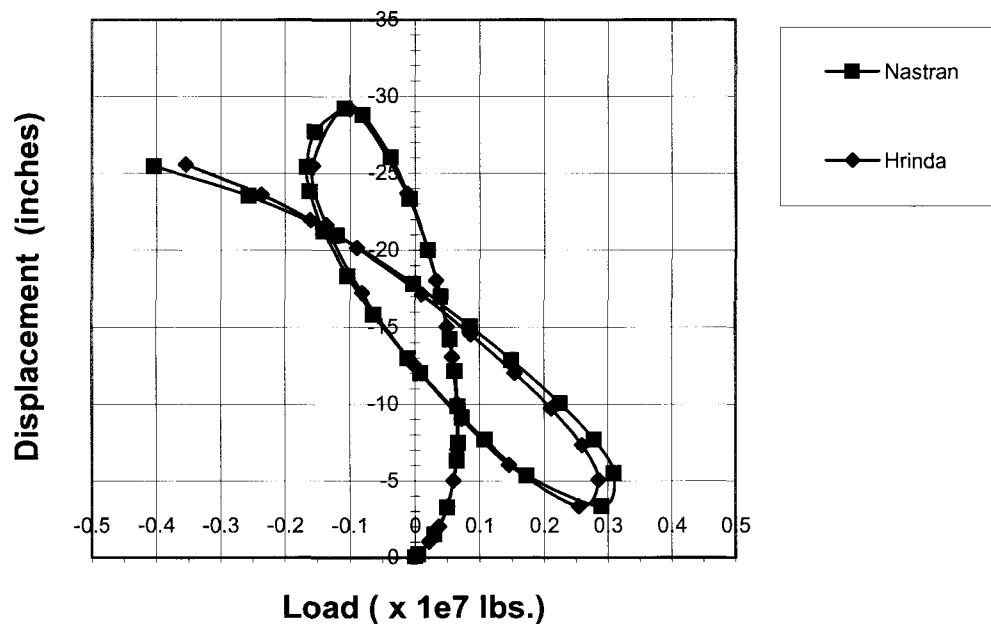
dlmin = .001d0

exlmax = 1.d0

toldis = 1.d-6

tolfor = 1.d-6

Load/Deflections for Crisfield Arch At Apex



istep	exlk	appliedforce	dqtot(61)	dqtot(62)	dqtot(64)	dqtot(65)	dqtot(85)	dqtot(86)	it
* 1	0.531440E-01	-0.53E+06	-.7517E-14	-.3746E+01	-.6235E-14	-.3756E+01	0.3898E+00	-.1145E+01	5
* 4	0.664279E-01	-0.66E+06	0.2493E-13	-.8209E+01	0.2064E-13	-.8233E+01	0.3418E+00	-.3228E+01	3
* 5	0.664471E-01	-0.66E+06	0.9998E-14	-.8502E+01	0.8104E-14	-.8526E+01	0.3265E+00	-.3385E+01	3
* 8	0.664154E-01	-0.66E+06	-.6406E-14	-.8697E+01	-.5501E-14	-.8722E+01	0.3156E+00	-.3490E+01	2
* 362	0.282235E-01	-0.28E+06	0.8742E-14	-.1871E+02	0.3345E-14	-.1875E+02	-.5498E+00	-.1022E+02	2
* 506	0.769218E-03	-0.77E+04	0.5957E-14	-.2228E+02	0.5431E-14	-.2231E+02	-.7713E+00	-.1331E+02	3
* 507	0.291910E-03	-0.29E+04	0.6732E-14	-.2234E+02	0.4643E-14	-.2236E+02	-.7733E+00	-.1336E+02	4
* 508	-0.869883E-03	0.87E+04	0.4835E-14	-.2247E+02	0.4446E-14	-.2250E+02	-.7778E+00	-.1348E+02	4
* 895	-0.980111E-01	0.98E+06	0.2253E-14	-.2917E+02	0.3607E-14	-.2914E+02	-.2035E-01	-.2226E+02	2
* 896	-0.985132E-01	0.99E+06	0.2510E-14	-.2917E+02	0.1652E-14	-.2914E+02	-.1406E-01	-.2228E+02	2
* 897	-0.990241E-01	0.99E+06	-.7839E-15	-.2917E+02	-.3038E-14	-.2914E+02	-.7707E-02	-.2231E+02	2
* 1011	-0.157188E+00	0.16E+07	0.8517E-13	-.2553E+02	0.1072E-12	-.2550E+02	0.4838E+00	-.2269E+02	2
* 1012	-0.157192E+00	0.16E+07	0.1082E-11	-.2550E+02	0.1324E-11	-.2546E+02	0.4834E+00	-.2268E+02	2
* 1013	-0.157191E+00	0.16E+07	0.4365E-12	-.2546E+02	0.5347E-12	-.2542E+02	0.4829E+00	-.2267E+02	2
* 1414	-0.183943E-02	0.18E+05	-.5008E-14	-.1258E+02	-.8636E-14	-.1262E+02	-.1351E+01	-.1636E+02	3
* 1415	-0.337339E-03	0.34E+04	0.6401E-14	-.1250E+02	0.5833E-14	-.1254E+02	-.1367E+01	-.1631E+02	4

* 1416	0.781457E-02	-0.78E+05	0.1009E-14	-1.209E+02	0.2602E-14	-1.213E+02	-1.451E+01	-1.601E+02	4
* 1805	0.254398E+00	-0.25E+07	-6.390E-14	-3.340E+01	-5.319E-14	-3.356E+01	-2.244E+01	-6.707E+01	2
* 1806	0.255460E+00	-0.26E+07	-3.141E-14	-3.340E+01	-2.339E-14	-3.356E+01	-2.236E+01	-6.676E+01	2
* 1807	0.256540E+00	-0.26E+07	-9.737E-15	-3.341E+01	-1.137E-14	-3.358E+01	-2.227E+01	-6.645E+01	2
* 1844	0.285894E+00	-0.29E+07	-1.057E-13	-4.609E+01	-8.906E-14	-4.647E+01	-1.822E+01	-6.133E+01	2
* 1845	0.285911E+00	-0.29E+07	-1.826E-12	-4.652E+01	-1.647E-12	-4.690E+01	-1.815E+01	-6.140E+01	2
* 1846	0.285906E+00	-0.29E+07	-2.261E-13	-4.695E+01	-1.896E-13	-4.734E+01	-1.809E+01	-6.147E+01	2
* 2218	0.287532E-02	-0.29E+05	0.2494E-14	-1.739E+02	0.5450E-14	-1.754E+02	-1.431E+01	-1.180E+02	3
* 2219	0.220860E-03	-0.22E+04	-1.007E-13	-1.747E+02	-7.334E-14	-1.762E+02	-1.434E+01	-1.185E+02	4
* 2220	-0.257602E-01	0.26E+06	0.2591E-14	-1.830E+02	-4.778E-15	-1.844E+02	-1.455E+01	-1.230E+02	5
* 2630	-0.306386E+00	0.31E+07	-9.173E-14	-2.184E+02	-1.090E-13	-2.177E+02	-1.099E+01	-1.626E+02	2

A.7.1 Typical arch equilibrium paths ([29], page 109)

109

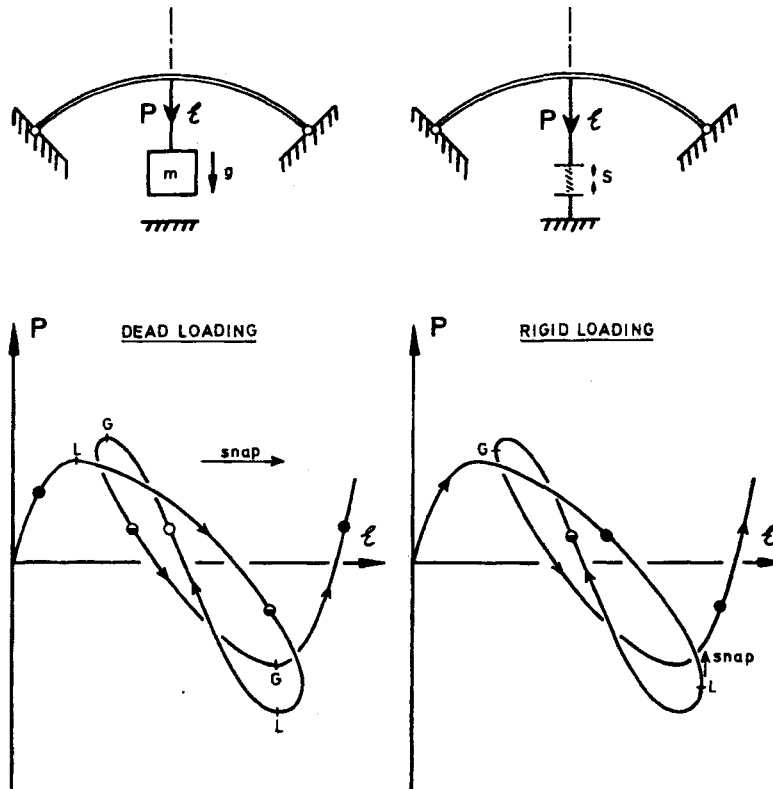


Figure 5.6 Load-corresponding deflection response of a symmetric arch (after Biexeno and Grammel, 1960). A solid circle denotes zero, a half-solid circle denotes one, and an open circle denotes two degrees of instability. Note that ξ here represents the corresponding deflection of the load (not the end-restraint, as in the rest of the chapter)

APPENDIX B- Hrinda Rikarc Optimization Users' Input Data Description

B.1 Optimum Khot 2 Element Symmetric Example

Two-element symmetric truss

The input files:

khot_2ele_mod_in_sym.dat

```
7 3 3 1 1 1 2 0 0 0 1 12 1 1
2 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 0. 0. 0.
2 125. 2.5 0.
3 250. 0. 0.
1 1 1 2
2 2 2 3
5 -200.d0
5 1 -2.5
```

khot_2ele_mod_in_sym_areas.dat

```
3.0d0
5.0d0
```

khot_2ele_mod_sym_sup.dat

```
1 0.0
2 0.0
3 0.0
6 0.0
7 0.0
8 0.0
9 0.0
```

```
open(unit=5,file='khot_2ele_mod_in_sym.dat',status='old')
open(unit=8,file='khot_2ele_mod_in_sym_areas.dat',status='old')

open(unit=5,file='khot_2ele_mod_in_sym.dat',status='old')

open(unit=51,file='khot_2ele_mod_sym_sup.dat',status='old')

dSEDtol=1.d-3
Amin=.1d0
C** Shallow_truss & Khot 4element
itedes=1
dl0=.1d0
dlmax=.10d0
dlmin=.001d0
exlmx=1.d0
toldis=1.d-4
tolfor=1.d-4

c** "Khot_2ele_mod_in.dat"*****
appliedforce=exlk * exfor(5)
weighttotal=0.d0
Do 55 i=1,nel
weighttotal=weighttotal+weight(i)
55 Continue

if(istep .eq. 1) then
c write(15,63)'N'=',N
c 63 format(i4)
write(15,53)
53 format(' istep exlk appliedforce a(4)
$ a(5) it Weight Areal Area2
$ xlie 1 xlie 2 finl N Nevenodd')
endif
```

```

c      If(Nevenodd .eq. 2 .or. Nevenodd .eq. 0)then

      write(15,50) '*',istep,exlk,appliedforce,
c      dqtot(4),dqtot(5),it,weighttotal,
c      propsect(1),propsect(2),xlie(1),xlie(2),finl(1),N,
c      Nevenodd

c      endif

50  format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
c 1x,i5,1x,e14.6,2x,e12.6,2x,e12.6,2x,e14.8,2x,e14.8,1x,e8.2,
c i4,2x,i4)

```

MSC-Nastran run deck
Khot_2ele_sym_msc_2009.dat

```

ID E:\Mscn4w30\data\PhD\Opti,FEMAP
SOL NLSTATIC
TIME 10000
CEND
ECHO = NONE
DISPLACEMENT = ALL
SPC = 1
LOAD = 1
NLPARM = 1
BEGIN BULK
$ *****
$ Written by : FEMAP
$ Version : 5.00
$ Translator : MSC/NASTRAN
$ From Model : E:\Mscn4w30\data\PhD\Optimization\Khot_2ele_GAH_symmetric.MOD
$ Date : Sun Feb 02 18:09:01 2003
$ *****
$
NLPARM 1 200 AUTO 5 200 UP ALL+
+ 0.01 0.01 1.E-7 30 25 4 0.2 0.5+
+ 5 20. 20.
NLPC1 1 MRIKS 0.25 4. 12 900
PARAM,LGDISP,1
PARAM,AUTOSPC,YES
PARAM,GRDPNT,0
CORD2C 1 0 0. 0. 0. 0. 0. 1.+FEMAPC1
+FEMAPC1 1. 0. 1.
CORD2S 2 0 0. 0. 0. 0. 0. 1.+FEMAPC2
+FEMAPC2 1. 0. 1.
$ FEMAP Load Set 1 : Untitled
FORCE 1 2 0 1. 0. -200. 0.
$ FEMAP Constraint Set 1 : Untitled
SPC 1 1 12345 0.
SPC 1 2 345 0.
SPC 1 3 12345 0.
$ FEMAP Property 1 : Untitled
PROD 1 1 6.4999 0. 0. 0.
$ FEMAP Property 2 : Untitled
PROD 2 1 6.4999 0. 0. 0.
$ FEMAP Material 1 : Untitled
MAT1 1 1.E+7 0. 0. 0.
GRID 1 0 0. 0. 0. 0
GRID 2 0 125. 2.5 0. 0
GRID 3 0 250. 0. 0. 0
CROD 1 1 1 2
CROD 2 2 2 3
ENDDATA

```

SED_out.txt

```

1SED= 0.138806E+01 Area= 0.300000E+01 exlk= 0.577049E+00 SSP= 0.000000E+00 SEDavg= 0.943830E+00 N= 1
2SED= 0.499600E+00 Area= 0.500000E+01 exlk= 0.577049E+00 SSP= 0.000000E+00 SEDavg= 0.943830E+00 N= 1
1SED= 0.820330E+00 Area= 0.333916E+01 exlk= 0.493552E+00 SSP= 0.577049E+00 SEDavg= 0.890393E+00 N= 2

```

```

2SED= 0.960456E+00 Area = 0.308603E+01 exlk= 0.493552E+00 SSP= 0.577049E+00 SEDavg= 0.890393E+00 N= 2
1SED= 0.887714E+00 Area = 0.319704E+01 exlk= 0.491683E+00 SSP= 0.493551E+00 SEDavg= 0.888604E+00 N= 3
2SED= 0.889494E+00 Area = 0.319384E+01 exlk= 0.491683E+00 SSP= 0.493551E+00 SEDavg= 0.888604E+00 N= 3
1SED= 0.888589E+00 Area = 0.319546E+01 exlk= 0.491682E+00 SSP= 0.491682E+00 SEDavg= 0.888604E+00 N= 4
2SED= 0.888619E+00 Area = 0.319541E+01 exlk= 0.491682E+00 SSP= 0.491682E+00 SEDavg= 0.888604E+00 N= 4
1SED= 0.877988E+00 Area = 0.649904E+01 exlk= 0.100000E+01 SSP= 0.491682E+00 SEDavg= 0.878002E+00 N= 5
2SED= 0.878017E+00 Area = 0.649893E+01 exlk= 0.100000E+01 SSP= 0.491682E+00 SEDavg= 0.878002E+00 N= 5

```

fea3d2_out.txt

istep	exlk	appliedforce	a(4)	a(5)	it	Weight	Area1	Area2	xlie 1	xlie 2	fin1	N	Nevenodd
* 1	0.100000E+00	-0.20E+02	0.4083-319	0.5105-316	3	0.162507E+03	0.649904E+01	0.649893E+01	0.12502402E+03	0.12502402E+03	-51E+03	5	2
* 2	0.168959E+00	-0.34E+02	0.8661E-08	-5319E-01	3	0.162507E+03	0.649904E+01	0.649893E+01	0.12502331E+03	0.12502331E+03	-87E+03	5	2
* 25	0.257597E+00	-0.52E+02	0.2150E-07	-1342E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12502238E+03	0.12502238E+03	-14E+04	5	2
* 103	0.329470E+00	-0.66E+02	0.2802E-07	-1765E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12502159E+03	0.12502159E+03	-18E+04	5	2
* 188	0.405717E+00	-0.81E+02	0.3525E-07	-2242E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12502071E+03	0.12502071E+03	-22E+04	5	2
* 310	0.510999E+00	-0.10E+03	0.4587E-07	-2963E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12501942E+03	0.12501942E+03	-29E+04	5	2
* 467	0.638187E+00	-0.13E+03	0.6003E-07	-3961E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12501770E+03	0.12501770E+03	-38E+04	5	2
* 571	0.716302E+00	-0.14E+03	0.6976E-07	-4676E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12501652E+03	0.12501652E+03	-44E+04	5	2
* 708	0.809851E+00	-0.16E+03	0.8304E-07	-5693E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12501491E+03	0.12501491E+03	-52E+04	5	2
* 874	0.904407E+00	-0.18E+03	0.9981E-07	-7061E+00	2	0.162507E+03	0.649904E+01	0.649893E+01	0.12501287E+03	0.12501287E+03	-63E+04	5	2
* 1232	0.999990E+00	-0.20E+03	0.1363E-06	-1047E+01	1	0.162507E+03	0.649904E+01	0.649893E+01	0.12500844E+03	0.12500844E+03	-86E+04	5	2
* 1233	0.100000E+01	-0.20E+03	0.1364E-06	-1048E+01	1	0.162507E+03	0.649904E+01	0.649893E+01	0.12500843E+03	0.12500843E+03	-86E+04	5	2

B.2 Optimum Khot 2 Element Unsymmetric Example

Two-element asymmetric truss

The input files:

khot_2ele_mod_in_unsym.dat

```

7 3 3 1 1 1 2 0 0 0 1 12 1 1
2 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 0. 0. 0.
2 200. 2.5 0.
3 250. 0. 0.
1 2 1 2
2 1 2 3
5 -200.d0
5 1 -2.5

```

khot_2ele_mod_in_unsym_areas.dat

```

1.0d0
2.0d0

```

khot_2ele_mod_unsym_sup.dat

```

1 0.0
2 0.0
3 0.0
6 0.0
7 0.0
8 0.0
9 0.0

```

```
open(unit=5,file='khot_2ele_mod_in_unsym.dat',status='old')
```



```

open(unit=8,file='khot_2ele_mod_in_unsym_areas.dat',status='old')

open(unit=5,file='khot_2ele_mod_in_unsym.dat',status='old')

open(unit=51,file='khot_2ele_mod_unsym_sup.dat',status='old')

dSEDtol=1.d-2 !Khot_2ele
C** Khot paper
itedes=1
dl0 = .1d0
dlmax = .10d0
dlmin = .001d0
exlmx = 1.d0
toldis = 1.d-4
tolfor = 1.d-4

c** "Khot_2ele_mod_in.dat"*****
appliedforce = exlk * exfor(5)
weighttotal=0.d0
  Do 55 i=1,nel
c    print *, 'istep=', istep
c    print *, 'i=', i
c    print *, 'weighttotal=', weighttotal
c    print *, 'weight(_)=', weight(i)
c    pause
cd   SEDratio(i)=strainD(i)/weight(i)
    weighttotal=weighttotal+weight(i)
55   Continue

    if(istep .eq. 1) then
c      write(15,63)'N=',N
c 63   format(i4)
      write(15,53)
53   format(' istep  exlk   appliedforce  a(4)
$ a(5)  it   Weight  Area1  Area2
$   xlie 1   xlie 2   fin1  N  Nevenodd')
      endif

c      If(Nevenodd .eq. 2 .or. Nevenodd .eq. 0)then

        write(15,50) '*,',istep,exlk,appliedforce,
c      dqtot(4),dqtot(5),it,weighttotal,
c      propsect(1),propsect(2),xlie(1),xlie(2),fin1(1),N,
c      Nevenodd

c      endif

50   format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
c 1x,i5,1x,e14.6,2x,e12.6,2x,e12.6,2x,e14.8,2x,e14.8,1x,e8.2,
c i4,2x,i4)

MSC-Nastran run deck
Khot_2bar_unsym_msc_2009.dat
INIT MASTER(S)
ID E:\Mscn4w30\data\PhD\Opti, MSC/N
SOL NLSTATIC
TIME 10000
DIAG 5
CEND
ECHO = NONE
DISPLACEMENT = ALL
SPC = 1
LOAD = 1
NLPARM = 1
BEGIN BULK
$ *****
$ Written by : MSC/NASTRAN for Windows
$ Version : 5.00
$ Translator : MSC/NASTRAN
$ From Model : E:\Mscn4w30\data\PhD\Optimization\Khot_2.MOD

```

```

$ Date : Wed Jan 29 18:55:33 2003
$ *****
$
NLPARM 1 500 AUTO 5 5 UP ALL+
+ 0.001 0.001 1.E-7 30 25 4 0.2 0.5+
+ 5 20. 20.
NLPCI 1 MRIKS 0.25 4. 200 500
PARAM,LGDISP,1
PARAM,PRGPST,NO
PARAM,AUTOSPC,YES
PARAM,K6ROT,100.
PARAM,MAXRATIO,1.E+8
PARAM,GRDPNT,0
CORD2C 1 0 0. 0. 0. 0. 0. 1.+MSC/NC1
+MSC/NC1 1. 0. 1.
CORD2S 2 0 0. 0. 0. 0. 0. 1.+MSC/NC2
+MSC/NC2 1. 0. 1.
$ MSC/NASTRAN for Windows Load Set 1 : Untitled
FORCE 1 2 0 1. 0. -200. 0.
$ MSC/NASTRAN for Windows Constraint Set 1 : Untitled
SPC 1 1 12345 0.
SPC 1 2 345 0.
SPC 1 3 12345 0.
$ MSC/NASTRAN for Windows Property 1 : Untitled
PROD 1 1 2.66409 0. 0. 0.
$ MSC/NASTRAN for Windows Property 2 : Untitled
PROD 2 1 2.6673 0. 0. 0.
$ MSC/NASTRAN for Windows Material 1 : Untitled
MAT1 1 1.E+7 0. 0. 0.
GRID 1 0 0. 0. 0. 0
GRID 2 0 200. 2.5 0. 0
GRID 3 0 250. 0. 0. 0
CROD 1 1 1 2
CROD 2 2 2 3
ENDDATA

```

SED_out.tx

```

1SED= 0.150470E+01 Area = 0.200000E+01 exlk= 0.625349E+00 SSP= 0.000000E+00 SEDavg= 0.376565E+01 N= 1
2SED= 0.602659E+01 Area = 0.100000E+01 exlk= 0.625349E+00 SSP= 0.000000E+00 SEDavg= 0.376565E+01 N= 1

1SED= 0.231180E+01 Area = 0.929589E+00 exlk= 0.360397E+00 SSP= 0.625348E+00 SEDavg= 0.197169E+01 N= 2
2SED= 0.163158E+01 Area = 0.110690E+01 exlk= 0.360397E+00 SSP= 0.625348E+00 SEDavg= 0.197169E+01 N= 2

1SED= 0.221038E+01 Area = 0.974113E+00 exlk= 0.369088E+00 SSP= 0.360397E+00 SEDavg= 0.210798E+01 N= 3
2SED= 0.200558E+01 Area = 0.102302E+01 exlk= 0.369088E+00 SSP= 0.360397E+00 SEDavg= 0.210798E+01 N= 3

1SED= 0.217852E+01 Area = 0.990456E+00 exlk= 0.372661E+00 SSP= 0.369087E+00 SEDavg= 0.215116E+01 N= 4
2SED= 0.212381E+01 Area = 0.100352E+01 exlk= 0.372661E+00 SSP= 0.369087E+00 SEDavg= 0.215116E+01 N= 4

1SED= 0.217041E+01 Area = 0.995071E+00 exlk= 0.373692E+00 SSP= 0.372660E+00 SEDavg= 0.216341E+01 N= 5
2SED= 0.215641E+01 Area = 0.998681E+00 exlk= 0.373692E+00 SSP= 0.372660E+00 SEDavg= 0.216341E+01 N= 5

1SED= 0.216756E+01 Area = 0.996269E+00 exlk= 0.373962E+00 SSP= 0.373691E+00 SEDavg= 0.216579E+01 N= 6
2SED= 0.216402E+01 Area = 0.997468E+00 exlk= 0.373962E+00 SSP= 0.373691E+00 SEDavg= 0.216579E+01 N= 6

1SED= 0.215320E+01 Area = 0.266409E+01 exlk= 0.100000E+01 SSP= 0.373691E+00 SEDavg= 0.215135E+01 N= 7
2SED= 0.214950E+01 Area = 0.266730E+01 exlk= 0.100000E+01 SSP= 0.373691E+00 SEDavg= 0.215135E+01 N= 7

```

fea3d2_out.txt

```

istep exlk appliedforce a(4) a(5) it Weight Area1 Area2 xlie 1 xlie 2 finl N Nevenodd
* 1 0.100000E+00 -0.20E+02 0.2119-317 0.5484-316 3 0.666391E+02 0.266730E+01 0.266409E+01 0.20001317E+03 0.50061848E+02 -.33E+03 7 2
* 2 0.168959E+00 -0.34E+02 -0.1971E-02 -0.5315E-01 3 0.666391E+02 0.266730E+01 0.266409E+01 0.20001142E+03 0.50061409E+02 -.56E+03 7 2
* 3 0.208033E+00 -0.42E+02 -0.3286E-02 -0.8926E-01 3 0.666391E+02 0.266730E+01 0.266409E+01 0.20001040E+03 0.50061154E+02 -.70E+03 7 2

* 100 0.326738E+00 -0.63E+02 -0.6319E-02 -0.1747E+00 2 0.666391E+02 0.266730E+01 0.266409E+01 0.20000718E+03 0.50060348E+02 -.11E+04 7 2
* 663 0.780432E+00 -0.16E+03 -0.1789E-01 -0.5346E+00 2 0.666391E+02 0.266730E+01 0.266409E+01 0.19999176E+03 0.50056491E+02 -.32E+04 7 2

```

```

* 1233 0.999964E+00 -0.20E+03 -.3104E-01 -.1048E+01 1 0.666391E+02 0.266730E+01 0.266409E+01 0.19997423E+03 0.50052110E+02 -.55E+04 7 2
* 1234 0.999976E+00 -0.20E+03 -.3106E-01 -.1049E+01 1 0.666391E+02 0.266730E+01 0.266409E+01 0.19997420E+03 0.50052103E+02 -.55E+04 7 2
* 1235 0.999987E+00 -0.20E+03 -.3108E-01 -.1050E+01 1 0.666391E+02 0.266730E+01 0.266409E+01 0.19997418E+03 0.50052095E+02 -.55E+04 7 2
* 1236 0.999996E+00 -0.20E+03 -.3110E-01 -.1051E+01 1 0.666391E+02 0.266730E+01 0.266409E+01 0.19997415E+03 0.50052088E+02 -.55E+04 7 2
* 1237 0.100000E+01 -0.20E+03 -.3113E-01 -.1052E+01 1 0.666391E+02 0.266730E+01 0.266409E+01 0.19997412E+03 0.50052081E+02 -.55E+04 7 2

```

B.3 Optimum Khot 4 Element Asymmetric Example

four-member asymmetric

The input files:

khot_4ele_mod_in.dat

```

12 3 5 1 1 1 4 0 0 0 1 12 1 1
4 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 120. -60. 0.
2 120. 144. 0.
3 -72. 144. 0.
4 -72. -60. 0.
5 0. 0. 3.
1 1 1 5
2 2 2 5
3 3 3 5
4 4 4 5
15 -200.d0
15 1 1.0

```

khot_4ele_mod_in_areas.dat

```

2.20d0
2.20d0
2.20d0
2.20d0

```

khot_4ele_mod_sup.dat

```

1 0.0
2 0.0
3 0.0
4 0.0
5 0.0
6 0.0
7 0.0
8 0.0
9 0.0
10 0.0
11 0.0
12 0.0

```

```

open(unit=5,file='khot_4ele_mod_in.dat',status='old')
open(unit=8,file='khot_4ele_mod_in_areas.dat',status='old')

```

```

open(unit=5,file='khot_4ele_mod_in.dat',status='old')

```

```

dSEDtol=1.d-2 !Khot_4ele
Amin=.1d0

```

C** Shallow truss & Khot 4element

```

itedes=1
dl0 = .1d0
dlmax = .10d0
dlmin = .001d0
exlmax = 1.d0
toldis = 1.d-4
tolfor = 1.d-4

```

```

c***Khot_4ele_mod_in_initial.dat*****
appliedforce = exlk * exfor(15)

```

```

weighttotal=0.d0
  Do 55 i=1,nel
    weighttotal=weighttotal+weight(i)
55    Continue

    if(istep .eq. 1) then
      write(15,53)
53    format(' istep   exlk   appliedforce   a(14)
$ a(15)   it   Weight   Area1   Area2
$ Area3   Area4   xlie 1   xlie 2   fin1')
      endif

      write(15,50) '*,istep,exlk,appliedforce,
c dqtot(14),dqtot(15),it,weighttotal,
c propsect(1),propsect(2),propsect(3),propsect(4),
c xlie(1),xl原因(2),fin1(1)

50    format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
c 1x,i5,1x,e14.8,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,
c e14.8,2x,e14.8,1x,e8.2)

```

MSC-Nastran run deck

Khot_4bar_msc_2009.dat

INIT MASTER(S)

ID E:\Mscn4w30\data\PhD\Opti,MSC/N

SOL SESTATIC

TIME 10000

DIAG 5

CEND

ECHO = NONE

DISPLACEMENT = ALL

SPC = 1

LOAD = 1

BEGIN BULK

\$ *****

\$ Written by : MSC/NASTRAN for Windows

\$ Version : 5.00

\$ Translator : MSC/NASTRAN

\$ From Model : E:\Mscn4w30\data\PhD\Optimization\Khot_4bar_2009.MOD

\$ Date : Wed Jan 29 18:23:28 2003

\$ *****

\$

PARAM,PRGPST,NO

PARAM,AUTOSPC,YES

PARAM,K6ROT,100.

PARAM,MAXRATIO,1.E+8

PARAM,GRDPNT,0

CORD2C 1 0 0. 0. 0. 0. 0. 1.+MSC/NC1

+MSC/NC1 1. 0. 1.

CORD2S 2 0 0. 0. 0. 0. 0. 1.+MSC/NC2

+MSC/NC2 1. 0. 1.

\$ MSC/NASTRAN for Windows Load Set 1 : Untitled

FORCE 1 5 0 1. 0. 0. -200.

\$ MSC/NASTRAN for Windows Constraint Set 1 : Untitled

SPC 1 1 123 0.

SPC 1 2 123 0.

SPC 1 3 123 0.

SPC 1 4 123 0.

\$ MSC/NASTRAN for Windows Property 1 : Untitled

PROD 1 1 2.1724 0. 0. 0.

\$ MSC/NASTRAN for Windows Property 2 : Untitled

PROD 2 1 1.63832 0. 0. 0.

\$ MSC/NASTRAN for Windows Property 3 : Untitled

PROD 3 1 1.72547 0. 0. 0.

\$ MSC/NASTRAN for Windows Property 4 : Untitled

PROD 4 1 2.9233 0. 0. 0.

\$ MSC/NASTRAN for Windows Material 1 : Untitled

MAT1 1 1.E+7 0.1 0.1 0. 0.

GRID 1 0 120. -60. 0. 0

GRID 2 0 120. 144. 0. 0

```

GRID    3    0   -72.  144.    0.    0
GRID    4    0   -72.  -60.    0.    0
GRID    5    0    0.    0.    3.    0
CROD    1    1    1    5
CROD    2    2    2    5
CROD    3    3    3    5
CROD    4    4    4    5
ENDDATA

```

SED_out.txt

```

1SED= 0.105498E+01 Area = 0.220000E+01 exlk= 0.100030E+01 SSP= 0.000000E+00 SEDavg= 0.105988E+01 N= 1
2SED= 0.620698E+00 Area = 0.220000E+01 exlk= 0.100030E+01 SSP= 0.000000E+00 SEDavg= 0.105988E+01 N= 1
3SED= 0.673578E+00 Area = 0.220000E+01 exlk= 0.100030E+01 SSP= 0.000000E+00 SEDavg= 0.105988E+01 N= 1
4SED= 0.189025E+01 Area = 0.220000E+01 exlk= 0.100030E+01 SSP= 0.000000E+00 SEDavg= 0.105988E+01 N= 1

1SED= 0.118837E+01 Area = 0.215400E+01 exlk= 0.100013E+01 SSP= 0.100000E+00 SEDavg= 0.117587E+01 N= 2
2SED= 0.783540E+00 Area = 0.204272E+01 exlk= 0.100013E+01 SSP= 0.100000E+00 SEDavg= 0.117587E+01 N= 2
3SED= 0.828873E+00 Area = 0.205949E+01 exlk= 0.100013E+01 SSP= 0.100000E+00 SEDavg= 0.117587E+01 N= 2
4SED= 0.190271E+01 Area = 0.228335E+01 exlk= 0.100013E+01 SSP= 0.100000E+00 SEDavg= 0.117587E+01 N= 2

1SED= 0.132184E+01 Area = 0.212725E+01 exlk= 0.100004E+01 SSP= 0.100000E+00 SEDavg= 0.129867E+01 N= 3
2SED= 0.951726E+00 Area = 0.193505E+01 exlk= 0.100004E+01 SSP= 0.100000E+00 SEDavg= 0.129867E+01 N= 3
3SED= 0.990069E+00 Area = 0.196194E+01 exlk= 0.100004E+01 SSP= 0.100000E+00 SEDavg= 0.129867E+01 N= 3
4SED= 0.193105E+01 Area = 0.236368E+01 exlk= 0.100004E+01 SSP= 0.100000E+00 SEDavg= 0.129867E+01 N= 3

1SED= 0.152666E+01 Area = 0.211247E+01 exlk= 0.100001E+01 SSP= 0.100000E+00 SEDavg= 0.149635E+01 N= 4
2SED= 0.117723E+01 Area = 0.185951E+01 exlk= 0.100001E+01 SSP= 0.100000E+00 SEDavg= 0.149635E+01 N= 4
3SED= 0.121097E+01 Area = 0.189281E+01 exlk= 0.100001E+01 SSP= 0.100000E+00 SEDavg= 0.149635E+01 N= 4
4SED= 0.207052E+01 Area = 0.243794E+01 exlk= 0.100001E+01 SSP= 0.100000E+00 SEDavg= 0.149635E+01 N= 4

1SED= 0.156036E+01 Area = 0.210494E+01 exlk= 0.993698E+00 SSP= 0.100000E+00 SEDavg= 0.152974E+01 N= 5
2SED= 0.126967E+01 Area = 0.180534E+01 exlk= 0.993698E+00 SSP= 0.100000E+00 SEDavg= 0.152974E+01 N= 5
3SED= 0.129604E+01 Area = 0.184287E+01 exlk= 0.993698E+00 SSP= 0.100000E+00 SEDavg= 0.152974E+01 N= 5
4SED= 0.199289E+01 Area = 0.250440E+01 exlk= 0.993698E+00 SSP= 0.100000E+00 SEDavg= 0.152974E+01 N= 5

1SED= 0.143814E+01 Area = 0.207251E+01 exlk= 0.937731E+00 SSP= 0.993697E+00 SEDavg= 0.150872E+01 N= 6
2SED= 0.174300E+01 Area = 0.144827E+01 exlk= 0.937731E+00 SSP= 0.993697E+00 SEDavg= 0.150872E+01 N= 6
3SED= 0.173137E+01 Area = 0.150888E+01 exlk= 0.937731E+00 SSP= 0.993697E+00 SEDavg= 0.150872E+01 N= 6
4SED= 0.112235E+01 Area = 0.314450E+01 exlk= 0.937731E+00 SSP= 0.993697E+00 SEDavg= 0.150872E+01 N= 6

1SED= 0.155377E+01 Area = 0.193008E+01 exlk= 0.905957E+00 SSP= 0.937730E+00 SEDavg= 0.152453E+01 N= 7
2SED= 0.130065E+01 Area = 0.161519E+01 exlk= 0.905957E+00 SSP= 0.937730E+00 SEDavg= 0.152453E+01 N= 7
3SED= 0.132268E+01 Area = 0.167226E+01 exlk= 0.905957E+00 SSP= 0.937730E+00 SEDavg= 0.152453E+01 N= 7
4SED= 0.192100E+01 Area = 0.232092E+01 exlk= 0.905957E+00 SSP= 0.937730E+00 SEDavg= 0.152453E+01 N= 7

1SED= 0.145933E+01 Area = 0.191715E+01 exlk= 0.871200E+00 SSP= 0.905956E+00 SEDavg= 0.150599E+01 N= 8
2SED= 0.167527E+01 Area = 0.136565E+01 exlk= 0.871200E+00 SSP= 0.905956E+00 SEDavg= 0.150599E+01 N= 8
3SED= 0.166541E+01 Area = 0.143558E+01 exlk= 0.871200E+00 SSP= 0.905956E+00 SEDavg= 0.150599E+01 N= 8
4SED= 0.122396E+01 Area = 0.279394E+01 exlk= 0.871200E+00 SSP= 0.905956E+00 SEDavg= 0.150599E+01 N= 8

1SED= 0.153643E+01 Area = 0.184131E+01 exlk= 0.858015E+00 SSP= 0.871199E+00 SEDavg= 0.151474E+01 N= 9
2SED= 0.138153E+01 Area = 0.147919E+01 exlk= 0.858015E+00 SSP= 0.871199E+00 SEDavg= 0.151474E+01 N= 9
3SED= 0.139362E+01 Area = 0.154695E+01 exlk= 0.858015E+00 SSP= 0.871199E+00 SEDavg= 0.151474E+01 N= 9
4SED= 0.174739E+01 Area = 0.230218E+01 exlk= 0.858015E+00 SSP= 0.871199E+00 SEDavg= 0.151474E+01 N= 9

1SED= 0.148227E+01 Area = 0.184888E+01 exlk= 0.845865E+00 SSP= 0.858015E+00 SEDavg= 0.150482E+01 N= 10
2SED= 0.159644E+01 Area = 0.135583E+01 exlk= 0.845865E+00 SSP= 0.858015E+00 SEDavg= 0.150482E+01 N= 10
3SED= 0.159025E+01 Area = 0.142857E+01 exlk= 0.845865E+00 SSP= 0.858015E+00 SEDavg= 0.150482E+01 N= 10
4SED= 0.135030E+01 Area = 0.258145E+01 exlk= 0.845865E+00 SSP= 0.858015E+00 SEDavg= 0.150482E+01 N= 10

1SED= 0.152101E+01 Area = 0.181862E+01 exlk= 0.842990E+00 SSP= 0.845865E+00 SEDavg= 0.150874E+01 N= 11
2SED= 0.144344E+01 Area = 0.142002E+01 exlk= 0.842990E+00 SSP= 0.845865E+00 SEDavg= 0.150874E+01 N= 11
3SED= 0.144893E+01 Area = 0.149131E+01 exlk= 0.842990E+00 SSP= 0.845865E+00 SEDavg= 0.150874E+01 N= 11
4SED= 0.162158E+01 Area = 0.234661E+01 exlk= 0.842990E+00 SSP= 0.845865E+00 SEDavg= 0.150874E+01 N= 11

1SED= 0.149566E+01 Area = 0.182757E+01 exlk= 0.839536E+00 SSP= 0.842989E+00 SEDavg= 0.150572E+01 N= 12
2SED= 0.154970E+01 Area = 0.136541E+01 exlk= 0.839536E+00 SSP= 0.842989E+00 SEDavg= 0.150572E+01 N= 12
3SED= 0.154651E+01 Area = 0.143855E+01 exlk= 0.839536E+00 SSP= 0.842989E+00 SEDavg= 0.150572E+01 N= 12
4SED= 0.143100E+01 Area = 0.248895E+01 exlk= 0.839536E+00 SSP= 0.842989E+00 SEDavg= 0.150572E+01 N= 12

```

1SED=	0.151299E+01	Area =	0.181575E+01	exlk=	0.839265E+00	SSP=	0.839536E+00	SEDavg=	0.150689E+01	N=	13
2SED=	0.147660E+01	Area =	0.139762E+01	exlk=	0.839265E+00	SSP=	0.839536E+00	SEDavg=	0.150689E+01	N=	13
3SED=	0.147902E+01	Area =	0.146994E+01	exlk=	0.839265E+00	SSP=	0.839536E+00	SEDavg=	0.150689E+01	N=	13
4SED=	0.155894E+01	Area =	0.238279E+01	exlk=	0.839265E+00	SSP=	0.839536E+00	SEDavg=	0.150689E+01	N=	13
1SED=	0.150188E+01	Area =	0.182117E+01	exlk=	0.838257E+00	SSP=	0.839265E+00	SEDavg=	0.150638E+01	N=	14
2SED=	0.152678E+01	Area =	0.137344E+01	exlk=	0.838257E+00	SSP=	0.839265E+00	SEDavg=	0.150638E+01	N=	14
3SED=	0.152526E+01	Area =	0.144650E+01	exlk=	0.838257E+00	SSP=	0.839265E+00	SEDavg=	0.150638E+01	N=	14
4SED=	0.147160E+01	Area =	0.245067E+01	exlk=	0.838257E+00	SSP=	0.839265E+00	SEDavg=	0.150638E+01	N=	14
1SED=	0.151031E+01	Area =	0.181628E+01	exlk=	0.838386E+00	SSP=	0.838256E+00	SEDavg=	0.150741E+01	N=	15
2SED=	0.149351E+01	Area =	0.138876E+01	exlk=	0.838386E+00	SSP=	0.838256E+00	SEDavg=	0.150741E+01	N=	15
3SED=	0.149459E+01	Area =	0.146141E+01	exlk=	0.838386E+00	SSP=	0.838256E+00	SEDavg=	0.150741E+01	N=	15
4SED=	0.153124E+01	Area =	0.240271E+01	exlk=	0.838386E+00	SSP=	0.838256E+00	SEDavg=	0.150741E+01	N=	15
1SED=	0.150325E+01	Area =	0.181904E+01	exlk=	0.838045E+00	SSP=	0.838385E+00	SEDavg=	0.150529E+01	N=	16
2SED=	0.151466E+01	Area =	0.137789E+01	exlk=	0.838045E+00	SSP=	0.838385E+00	SEDavg=	0.150529E+01	N=	16
3SED=	0.151395E+01	Area =	0.145086E+01	exlk=	0.838045E+00	SSP=	0.838385E+00	SEDavg=	0.150529E+01	N=	16
4SED=	0.148929E+01	Area =	0.243430E+01	exlk=	0.838045E+00	SSP=	0.838385E+00	SEDavg=	0.150529E+01	N=	16
1SED=	0.150878E+01	Area =	0.181691E+01	exlk=	0.838159E+00	SSP=	0.838045E+00	SEDavg=	0.150743E+01	N=	17
2SED=	0.150107E+01	Area =	0.138502E+01	exlk=	0.838159E+00	SSP=	0.838045E+00	SEDavg=	0.150743E+01	N=	17
3SED=	0.150155E+01	Area =	0.145780E+01	exlk=	0.838159E+00	SSP=	0.838045E+00	SEDavg=	0.150743E+01	N=	17
4SED=	0.151832E+01	Area =	0.241250E+01	exlk=	0.838159E+00	SSP=	0.838045E+00	SEDavg=	0.150743E+01	N=	17
1SED=	0.150455E+01	Area =	0.181824E+01	exlk=	0.838028E+00	SSP=	0.838158E+00	SEDavg=	0.150548E+01	N=	18
2SED=	0.150978E+01	Area =	0.138009E+01	exlk=	0.838028E+00	SSP=	0.838158E+00	SEDavg=	0.150548E+01	N=	18
3SED=	0.150946E+01	Area =	0.145301E+01	exlk=	0.838028E+00	SSP=	0.838158E+00	SEDavg=	0.150548E+01	N=	18
4SED=	0.149814E+01	Area =	0.242706E+01	exlk=	0.838028E+00	SSP=	0.838158E+00	SEDavg=	0.150548E+01	N=	18
1SED=	0.150628E+01	Area =	0.181728E+01	exlk=	0.838092E+00	SSP=	0.838028E+00	SEDavg=	0.150565E+01	N=	19
2SED=	0.150274E+01	Area =	0.138338E+01	exlk=	0.838092E+00	SSP=	0.838028E+00	SEDavg=	0.150565E+01	N=	19
3SED=	0.150296E+01	Area =	0.145621E+01	exlk=	0.838092E+00	SSP=	0.838028E+00	SEDavg=	0.150565E+01	N=	19
4SED=	0.151063E+01	Area =	0.241712E+01	exlk=	0.838092E+00	SSP=	0.838028E+00	SEDavg=	0.150565E+01	N=	19
1SED=	0.149165E+01	Area =	0.216836E+01	exlk=	0.100000E+01	SSP=	0.838028E+00	SEDavg=	0.149103E+01	N=	20
2SED=	0.148816E+01	Area =	0.165063E+01	exlk=	0.100000E+01	SSP=	0.838028E+00	SEDavg=	0.149103E+01	N=	20
3SED=	0.148837E+01	Area =	0.173753E+01	exlk=	0.100000E+01	SSP=	0.838028E+00	SEDavg=	0.149103E+01	N=	20
4SED=	0.149593E+01	Area =	0.288408E+01	exlk=	0.100000E+01	SSP=	0.838028E+00	SEDavg=	0.149103E+01	N=	20

fea3d2_out.txt

```

istep  exlk  appliedforce  a(14)  a(15)  it  Weight  Areal  Area2  Area3  Area4  xlie1  xlie2  finl
* 1  0.100000E+00  -0.20E+02  -5597-316  0.3908-314  3  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13419624E+03  0.18746808E+03  -22E+03
* 2  0.168218E+00  -0.34E+02  0.9180E-03  -6381E-01  3  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13419527E+03  0.18746673E+03  -38E+03
* 3  0.206585E+00  -0.41E+02  0.1523E-02  -1067E+00  3  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13419471E+03  0.18746595E+03  -47E+03

* 87  0.310484E+00  -0.62E+02  0.2785E-02  -1981E+00  2  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13419314E+03  0.18746376E+03  -72E+03
* 320  0.506051E+00  -0.10E+03  0.4808E-02  -3512E+00  2  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13418991E+03  0.18745924E+03  -12E+04
* 715  0.782859E+00  -0.16E+03  0.8372E-02  -6451E+00  2  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13418420E+03  0.18745129E+03  -22E+04

* 1376  0.999994E+00  -0.20E+03  0.1446E-01  -1259E+01  1  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13417445E+03  0.18743767E+03  -37E+04
* 1377  0.100000E+01  -0.20E+03  0.1447E-01  -1260E+01  1  0.11506603E+03  0.216836E+01  0.165063E+01  0.173753E+01  0.288408E+01  0.13417444E+03  0.18743766E+03  -37E+04

```

B.4 Optimum Khot 30 Element Star Example

Star dome 30 element truss

The input files:

Dome2_opt_mod_in.dat

```

36 3 19 1 1 1 4 0 0 0 1 12 1 1
30 0 0 0 0 0
6 12 24 4 4 4
1.e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 0. 0. 85.912

```

```

2 180. -311.769 64.662
3 360. 0. 64.662
4 180. 311.769 64.662
5 -180. 311.769 64.662
6 -360. 0. 64.662
7 -180. -311.769 64.662
8 0. -623.538 21.709
9 360. -623.538 0.
10 540. -311.769 21.709
11 720. 0. 0.
12 540. 311.769 21.709
13 360. 623.538 0.
14 0. 623.538 21.709
15 -360. 623.538 0.
16 -540. 311.769 21.709
17 -720. 0. 0.
18 -540. -311.769 21.709
19 -360. -623.538 0.

```

```

1 1 1 5
2 1 1 4
3 1 1 3
4 1 1 2
5 1 1 7
6 1 1 6
7 2 4 5
8 2 3 4
9 2 2 3
10 2 7 2
11 2 6 7
12 2 5 6
13 3 5 15
14 4 5 14
15 4 4 14
16 3 4 13
17 4 4 12
18 4 3 12
19 3 3 11
20 4 3 10
21 4 2 10
22 3 2 9
23 4 2 8
24 4 7 8
25 3 7 19
26 4 7 18
27 4 6 18
28 3 6 17
29 4 6 16
30 4 5 16
3 -2000.d0
3 1 1.0

```

Dome2_opt_mod_in_areas.dat

```

1.0d0
1.0d0
1.0d0
1.0d0

```

dome2_sup.dat

```

22 0.0
23 0.0
24 0.0
25 0.0
26 0.0
27 0.0
28 0.0
29 0.0
30 0.0
31 0.0
32 0.0
33 0.0

```

```

34  0.0
35  0.0
36  0.0
37  0.0
38  0.0
39  0.0
40  0.0
41  0.0
42  0.0
43  0.0
44  0.0
45  0.0
46  0.0
47  0.0
48  0.0
49  0.0
50  0.0
51  0.0
52  0.0
53  0.0
54  0.0
55  0.0
56  0.0
57  0.0

      open(unit=5,file='dome2_opt_mod_in.dat',status='old')
      open(unit=8,file='dome2_opt_mod_in_areas.dat',status='old')

      open(unit=5,file='dome2_opt_mod_in.dat',status='old')

      open(unit=51,file='dome2_sup.dat',status='old')

      dSEDtol=1.d0
      Amin=.1d0

C** 3D Truss , Dome_in.dat & Dome2_in.dat
      itedes=1
      dl0 = .1d0
      dlmax = .1d0
      dlmin = .01d0
      exlmax = 1.d0
      toldis = 1.d-4
      tolfor = 1.d-4

c** "Dome2_opt_mod_in_initial.dat"*****
      appliedforce = exlk * exfor(3)
      weighttotal=0.d0
      Do 55 i=1,nel
         weighttotal=weighttotal+weight(i)
55      Continue

      if(istep.eq. 1) then
         write(15,53)
53      format(' istep   exlk      appliedforce   a(2)
$ a(3)   it   Weight   Area1   Area2
$ Area3   Area4   xlie 1   xlie 2   fin1')
         endif

      write(15,50) '*',istep,exlk,appliedforce,
c      dqtot(2),dqtot(3),it,weighttotal,
c      propsect(1),propsect(2),propsect(3),propsect(4),
c      xlie(1),xlie(2),fin1(1)

50      format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
c      1x,i5,1x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,
c      e12.6,2x,e12.6,1x,e8.2)

MSC-Nastran run deck
Khot_dome_2009.dat
CEND

```



```

ECHO = NONE
DISPLACEMENT = ALL
OLOAD = ALL
SPCFORCE = ALL
FORCE = ALL
STRESS = ALL
SPC = 1
LOAD = 1
NLPARM = 1
BEGIN BULK
$ *****
$ Written by : MSC/NASTRAN for Windows
$ Version   : 5.00
$ Translator : MSC/NASTRAN
$ From Model : E:\Mscn4w30\data\PhD\Optimization\Khot_2ele_GAH_symmetric.MOD
$ Date      : Sun Feb 02 18:02:07 2003
$ Output To : E:\Mscn4w30\data\PhD\Optimization\Dome\Khot_000
$ *****
$
NLPARM      1 200      AUTO  5 200  UP  ALL+
+      0.01 0.01 1.E-7  30 25  4 0.2 0.5+
+      5      20.      20.
NLPCI      1 MRIKS  0.25 4.      12 900
PARAM,LGDISP,1
PARAM,PRGPST,NO
PARAM,AUTOSPC,YES
PARAM,K6ROT,100.
PARAM,MAXRATIO,1.E+8
PARAM,GRDPNT,0
CORD2C      1 0 0. 0. 0. 0. 0. 1.+MSC/NC1
+MSC/NC1    1. 0. 1.
CORD2S      2 0 0. 0. 0. 0. 0. 1.+MSC/NC2
+MSC/NC2    1. 0. 1.
$ MSC/NASTRAN for Windows Load Set 1 : Untitled
FORCE      1 2 0 1. 0. -200. 0.
$ MSC/NASTRAN for Windows Constraint Set 1 : Untitled
SPC      1 1 12345 0.
SPC      1 2 345 0.
SPC      1 3 12345 0.
$ MSC/NASTRAN for Windows Property 1 : Untitled
PROD      1 1 6.4999 0. 0. 0.
$ MSC/NASTRAN for Windows Property 2 : Untitled
PROD      2 1 6.4999 0. 0. 0.
$ MSC/NASTRAN for Windows Material 1 : Untitled
MAT1      1 1.E+7      0. 0. 0.
GRID      1 0 0. 0. 0. 0
GRID      2 0 125. 2.5 0. 0
GRID      3 0 250. 0. 0. 0
CROD      1 1 1 2
CROD      2 2 2 3
ENDDATA

SED_out.txt

1SED= 0.194286E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
2SED= 0.194286E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
3SED= 0.194286E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
4SED= 0.194286E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
5SED= 0.194286E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
6SED= 0.194286E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
7SED= 0.126056E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
8SED= 0.126056E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
9SED= 0.126056E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
10SED= 0.126056E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
11SED= 0.126056E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
12SED= 0.126056E+02 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
13SED= 0.740568E+00 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
14SED= 0.183099E-05 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
15SED= 0.183099E-05 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
16SED= 0.740568E+00 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
17SED= 0.183208E-05 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
18SED= 0.183349E-05 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
19SED= 0.740568E+00 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
20SED= 0.183349E-05 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1
21SED= 0.183208E-05 Area= 0.100000E+01 exlk= 0.654306E+00 SSP= 0.000000E+00 SEDavg= 0.655494E+01 N= 1

```



```

22SED= 0.161334E+02 Area = 0.231088E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
23SED= 0.430825E+01 Area = 0.100000E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
24SED= 0.430825E+01 Area = 0.100000E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
25SED= 0.161334E+02 Area = 0.231088E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
26SED= 0.430825E+01 Area = 0.100000E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
27SED= 0.430826E+01 Area = 0.100000E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
28SED= 0.161334E+02 Area = 0.231088E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
29SED= 0.430826E+01 Area = 0.100000E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7
30SED= 0.430825E+01 Area = 0.100000E+00 exlk= 0.903754E+00 SSP= 0.827755E+00 SEDavg= 0.111887E+02 N= 7

1SED= 0.156044E+02 Area = 0.168767E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
2SED= 0.156044E+02 Area = 0.168767E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
3SED= 0.156044E+02 Area = 0.168767E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
4SED= 0.156044E+02 Area = 0.168767E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
5SED= 0.156044E+02 Area = 0.168767E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
6SED= 0.156044E+02 Area = 0.168767E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
7SED= 0.156121E+02 Area = 0.136980E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
8SED= 0.156121E+02 Area = 0.136980E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
9SED= 0.156121E+02 Area = 0.136980E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
10SED= 0.156121E+02 Area = 0.136980E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
11SED= 0.156121E+02 Area = 0.136980E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
12SED= 0.156121E+02 Area = 0.136980E+01 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
13SED= 0.160748E+02 Area = 0.262472E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
14SED= 0.428412E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
15SED= 0.428412E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
16SED= 0.160748E+02 Area = 0.262472E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
17SED= 0.428411E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
18SED= 0.428413E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
19SED= 0.160748E+02 Area = 0.262472E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
20SED= 0.428413E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
21SED= 0.428411E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
22SED= 0.160748E+02 Area = 0.262472E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
23SED= 0.428412E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
24SED= 0.428412E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
25SED= 0.160748E+02 Area = 0.262472E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
26SED= 0.428411E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
27SED= 0.428413E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
28SED= 0.160748E+02 Area = 0.262472E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
29SED= 0.428413E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8
30SED= 0.428411E+01 Area = 0.100000E+00 exlk= 0.996220E+00 SSP= 0.903754E+00 SEDavg= 0.111719E+02 N= 8

```

fea3d2_out.txt

```

istep  exlk  appliedforce  a(2)  a(3)  it  Weight  Area1  Area2  Area3  Area4  xlic1  xlic2  fin1
* 1 0.100000E+00 -0.20E+03 0.1932-16 0.2112-313 3 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360614E+03 0.360614E+03 -58E+03
* 2 0.123792E+00 -0.25E+03 0.1709E-17 -4757E+00 3 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360611E+03 0.360611E+03 -72E+03
* 3 0.136007E+00 -0.27E+03 0.4762E-17 -5763E+00 3 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360610E+03 0.360610E+03 -79E+03

* 127 0.400938E+00 -0.80E+03 0.3300E-16 -1956E+01 2 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360574E+03 0.360574E+03 -25E+04
* 384 0.771478E+00 -0.15E+04 -7842E-17 -4500E+01 2 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360510E+03 0.360510E+03 -54E+04
* 527 0.901404E+00 -0.18E+04 0.2709E-16 -5919E+01 2 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360478E+03 0.360478E+03 -69E+04
* 704 0.985003E+00 -0.20E+04 -3483E-16 -7660E+01 1 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360442E+03 0.360442E+03 -86E+04
* 801 0.996220E+00 -0.20E+04 0.3495E-16 -8598E+01 1 0.762154E+03 0.168767E+01 0.136980E+01 0.262472E+00 0.100000E+00 0.360425E+03 0.360425E+03 -94E+04

```

B.5 Optimum Khot Large Shallow Truss Example

Shallow truss half-symmetry model with two point loads

The input files:

shallow_truss_in.dat

```

16 3 13 2 1 1 23 0 0 0 1 12 1 1
23 0 0 0 0 0
6 12 24 4 4 4
1e7 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23 1.23
1 -10.94 4.94 0.
2 0. 0. 0.
3 -1.19 11.94 0.
4 28.66 2.87 0.
5 56.14 17.67 0.
6 85.99 8.59 0.
7 113.5 23.41 0.
8 143.3 14.33 0.
9 170.8 29.14 0.
10 200.7 20.07 0.

```



```

37 0.0
39 0.0

fearc_opt3_shallow_truss_2009.for
  open(unit=5,file='shallow_truss_in.dat',status='old')
  open(unit=8,file='shallow_truss_areas.dat',status='old')

  open(4,file='SED_out.txt',status='unknown')

  open(unit=5,file='shallow_truss_in.dat',status='old')

  open(unit=51,file='shallow_truss_sup.dat',status='old')

  dSEDtol=1.d-1 !shallow truss
  Amin=.1d0

  Subroutine rikarc
C** Shallow_truss & Khot 4element
  itedes=1
  dl0 = .1d0
  dlmax = .10d0
  dlmin = .001d0
  exlmx = 1.d0
  toldis = 1.d-4
  tolfor = 1.d-4

  subroutine result
c**"shallow_truss_initial.dat"*****
  appliedforce = exlk * exfor(38)
  weighttotal=0.d0
  Do 55 i=1,nel
    weighttotal=weighttotal+weight(i)
55  Continue

  if(istep .eq. 1) then
    write(15,53)
53  format(' istep  exlk  appliedforce  a(28)
$ a(38)  it  Weight  Area1  Area2
$ Area3  Area4  xlie 10  xlie 15  finl')
    endif

  write(15,50) '*,istep,exlk,appliedforce,
c dqtot(26),dqtot(29),it,weighttotal,
c propsect(1),propsect(2),propsect(3),propsect(4),
c xlie(16),xlie(20),finl(20)

50  format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
c 1x,i5,1x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,
c e12.6,2x,e12.6,1x,e8.2)

MSC-Nastran run deck
shallow_Khot_truss_msc_2009.NAS
ID E:\Mscn4w30\data\PhD\Opti,FEMAP
SOL NLSTATIC
TIME 10000
CEND
ECHO = NONE
DISPLACEMENT = ALL
SPC = 1
LOAD = 1
NLPARM = 1
BEGIN BULK
$ *****
$ Written by : FEMAP
$ Version : 5.00
$ Translator : MSC/NASTRAN
$ From Model : E:\Mscn4w30\data\PhD\Optimization\shallow_Khot_final.MOD
$ Date : Sun Feb 02 18:27:29 2003
$ *****
$

```

```

NLPARM      1  900      ITER      1  900  PW  YES+
+      0.001 0.001 1.E-7  3  25  4  0.2  0.5+
+      5      20.      20.
NLPC1       1  MRIKS  0.25  4.      500  900
PARAM,LGDISP,1
PARAM,AUTOSPC,YES
PARAM,GRDPNT,0
CORD2C      1  0  0.  0.  0.  0.  0.  1.+FEMAPC1
+FEMAPC1    1.  0.  1.
CORD2S      2  0  0.  0.  0.  0.  0.  1.+FEMAPC2
+FEMAPC2    1.  0.  1.
$ FEMAP Load Set 1 : Untitled
FORCE       1  13  0  1.  0. -600.  0.
FORCE       1  7  0  1.  0. -300.  0.
$ FEMAP Constraint Set 1 : Untitled
SPC         1  1  12345  0.
SPC         1  2  345  0.
SPC         1  3  345  0.
SPC         1  4  345  0.
SPC         1  5  345  0.
SPC         1  6  345  0.
SPC         1  7  345  0.
SPC         1  8  345  0.
SPC         1  9  345  0.
SPC         1  10 345  0.
SPC         1  11 345  0.
SPC         1  12 345  0.
SPC         1  13 1345 0.
$ FEMAP Property 1 : Untitled
PROD        1  1  2.4747 0.  0.  0.
$ FEMAP Property 2 : Untitled
PROD        2  1  2.3695 0.  0.  0.
$ FEMAP Property 3 : Untitled
PROD        3  1  1.1837 0.  0.  0.
$ FEMAP Property 4 : Untitled
PROD        4  1  0.2609 0.  0.  0.
$ FEMAP Property 5 : Untitled
PROD        5  1  2.3694 0.  0.  0.
$ FEMAP Property 6 : Untitled
PROD        6  1  2.0551 0.  0.  0.
$ FEMAP Property 7 : Untitled
PROD        7  1  0.2259 0.  0.  0.
$ FEMAP Property 8 : Untitled
PROD        8  1  0.2227 0.  0.  0.
$ FEMAP Property 9 : Untitled
PROD        9  1  2.7512 0.  0.  0.
$ FEMAP Property 10 : Untitled
PROD       10  1  1.6353 0.  0.  0.
$ FEMAP Property 11 : Untitled
PROD       11  1  0.1945 0.  0.  0.
$ FEMAP Property 12 : Untitled
PROD       12  1  0.1941 0.  0.  0.
$ FEMAP Property 13 : Untitled
PROD       13  1  2.7463 0.  0.  0.
$ FEMAP Property 14 : Untitled
PROD       14  1  1.2751 0.  0.  0.
$ FEMAP Property 15 : Untitled
PROD       15  1  0.223 0.  0.  0.
$ FEMAP Property 16 : Untitled
PROD       16  1  0.2249 0.  0.  0.
$ FEMAP Property 17 : Untitled
PROD       17  1  2.3649 0.  0.  0.
$ FEMAP Property 18 : Untitled
PROD       18  1  1.6351 0.  0.  0.
$ FEMAP Property 19 : Untitled
PROD       19  1  0.259 0.  0.  0.
$ FEMAP Property 20 : Untitled
PROD       20  1  0.0524 0.  0.  0.
$ FEMAP Property 21 : Untitled
PROD       21  1  1.1756 0.  0.  0.

```

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$ FEMAP Property 22 : Untitled
PROD      22      1 2.3626  0.  0.  0.
$ FEMAP Property 23 : Untitled
PROD      23      1 2.4687  0.  0.  0.
$ FEMAP Material 1 : Untitled
MAT1      1 1.E+7      0.1  0.  0.  0.
GRID      1      0 -10.94  4.94  0.  0
GRID      2      0  0.  0.  0.  0
GRID      3      0 -1.19 11.94  0.  0
GRID      4      0 28.66  2.87  0.  0
GRID      5      0 56.14 17.67  0.  0
GRID      6      0 85.99  8.59  0.  0
GRID      7      0 113.5 23.41  0.  0
GRID      8      0 143.3 14.33  0.  0
GRID      9      0 170.8 29.14  0.  0
GRID     10      0 200.7 20.07  0.  0
GRID     11      0 228.1 34.87  0.  0
GRID     12      0 229.3 22.93  0.  0
GRID     13      0 239.1 29.94  0.  0
CROD      1      1      1      3
CROD      2      2      1      2
CROD      3      3      2      3
CROD      4      4      3      4
CROD      5      5      3      5
CROD      6      6      2      4
CROD      7      7      4      5
CROD      8      8      5      6
CROD      9      9      5      7
CROD     10     10     4      6
CROD     11     11     6      7
CROD     12     12     7      8
CROD     13     13     7      9
CROD     14     14     6      8
CROD     15     15     8      9
CROD     16     16     9     10
CROD     17     17     9     11
CROD     18     18     8     10
CROD     19     19     10     11
CROD     20     20     10     12
CROD     21     21     11     12
CROD     22     22     12     13
CROD     23     23     11     13
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SED_out.txt

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6SED= 0.183304E+01 Area= 0.194240E+01 exlk= 0.100047E+01 SSP= 0.100000E+00 SEDavg= 0.128229E+01 N= 2
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18SED= 0.169110E+01 Area = 0.161753E+01 exlk= 0.100029E+01 SSP= 0.100000E+00 SEDavg= 0.143049E+01 N= 6
19SED= 0.449480E+00 Area = 0.422165E+00 exlk= 0.100029E+01 SSP= 0.100000E+00 SEDavg= 0.143049E+01 N= 6
20SED= 0.195105E+01 Area = 0.187855E+01 exlk= 0.100029E+01 SSP= 0.100000E+00 SEDavg= 0.143049E+01 N= 6
21SED= 0.135466E+01 Area = 0.129265E+01 exlk= 0.100029E+01 SSP= 0.100000E+00 SEDavg= 0.143049E+01 N= 6
22SED= 0.214180E+01 Area = 0.206723E+01 exlk= 0.100029E+01 SSP= 0.100000E+00 SEDavg= 0.143049E+01 N= 6
23SED= 0.223812E+01 Area = 0.216654E+01 exlk= 0.100029E+01 SSP= 0.100000E+00 SEDavg= 0.143049E+01 N= 6

1SED= 0.215867E+01 Area = 0.221772E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
2SED= 0.208391E+01 Area = 0.210545E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
3SED= 0.144788E+01 Area = 0.126195E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
4SED= 0.597522E+00 Area = 0.368651E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
5SED= 0.209643E+01 Area = 0.213069E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
6SED= 0.193249E+01 Area = 0.189333E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
7SED= 0.598181E+00 Area = 0.367517E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
8SED= 0.598680E+00 Area = 0.364137E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
9SED= 0.227521E+01 Area = 0.239172E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
10SED= 0.172254E+01 Area = 0.160494E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
11SED= 0.595636E+00 Area = 0.360473E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
12SED= 0.594772E+00 Area = 0.359810E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
13SED= 0.226862E+01 Area = 0.238198E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
14SED= 0.148677E+01 Area = 0.130355E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
15SED= 0.596215E+00 Area = 0.362072E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
16SED= 0.594187E+00 Area = 0.364086E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
17SED= 0.209120E+01 Area = 0.212320E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
18SED= 0.172135E+01 Area = 0.160344E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
19SED= 0.595142E+00 Area = 0.366553E+00 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
20SED= 0.192936E+01 Area = 0.188901E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
21SED= 0.144080E+01 Area = 0.125328E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
22SED= 0.207883E+01 Area = 0.209822E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7
23SED= 0.215243E+01 Area = 0.220871E+01 exlk= 0.100031E+01 SSP= 0.100000E+00 SEDavg= 0.146334E+01 N= 7

1SED= 0.207437E+01 Area = 0.226184E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
2SED= 0.201733E+01 Area = 0.213978E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
3SED= 0.150735E+01 Area = 0.123667E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
4SED= 0.741864E+00 Area = 0.330664E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
5SED= 0.202627E+01 Area = 0.216673E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
6SED= 0.189919E+01 Area = 0.190974E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
7SED= 0.743164E+00 Area = 0.329684E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
8SED= 0.744757E+00 Area = 0.326679E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
9SED= 0.216366E+01 Area = 0.245217E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
10SED= 0.173251E+01 Area = 0.160034E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
11SED= 0.741830E+00 Area = 0.323227E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
12SED= 0.740938E+00 Area = 0.322586E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
13SED= 0.215864E+01 Area = 0.244146E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
14SED= 0.153942E+01 Area = 0.128082E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
15SED= 0.742296E+00 Area = 0.324692E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
16SED= 0.739199E+00 Area = 0.326387E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
17SED= 0.202223E+01 Area = 0.215858E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
18SED= 0.173154E+01 Area = 0.159873E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
19SED= 0.739509E+00 Area = 0.328652E+00 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
20SED= 0.189673E+01 Area = 0.190508E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
21SED= 0.150144E+01 Area = 0.122757E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
22SED= 0.201338E+01 Area = 0.213192E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8
23SED= 0.206957E+01 Area = 0.225200E+01 exlk= 0.100043E+01 SSP= 0.100000E+00 SEDavg= 0.149075E+01 N= 8

1SED= 0.199445E+01 Area = 0.230550E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
2SED= 0.195090E+01 Area = 0.217501E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
3SED= 0.154507E+01 Area = 0.122092E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
4SED= 0.875875E+00 Area = 0.304113E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
5SED= 0.195731E+01 Area = 0.220338E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
6SED= 0.185897E+01 Area = 0.192950E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
7SED= 0.877773E+00 Area = 0.303264E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
8SED= 0.880304E+00 Area = 0.300564E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
9SED= 0.206309E+01 Area = 0.251006E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
10SED= 0.172734E+01 Area = 0.160212E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
11SED= 0.877597E+00 Area = 0.297271E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
12SED= 0.876719E+00 Area = 0.296646E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
13SED= 0.205926E+01 Area = 0.249852E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
14SED= 0.157083E+01 Area = 0.126718E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
15SED= 0.877971E+00 Area = 0.298638E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
16SED= 0.874034E+00 Area = 0.300070E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
17SED= 0.195418E+01 Area = 0.219465E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
18SED= 0.172655E+01 Area = 0.160042E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
19SED= 0.873659E+00 Area = 0.302166E+00 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
20SED= 0.185703E+01 Area = 0.192455E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
21SED= 0.154022E+01 Area = 0.121147E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
22SED= 0.194785E+01 Area = 0.216659E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9
23SED= 0.199074E+01 Area = 0.229494E+01 exlk= 0.100021E+01 SSP= 0.100000E+00 SEDavg= 0.151121E+01 N= 9

1SED= 0.192441E+01 Area = 0.234725E+01 exlk= 0.100052E+01 SSP= 0.100000E+00 SEDavg= 0.152791E+01 N= 10

2SED=	0.189106E+01	Area =	0.220952E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
3SED=	0.156909E+01	Area =	0.121170E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
4SED=	0.996246E+00	Area =	0.285161E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
5SED=	0.189569E+01	Area =	0.223907E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
6SED=	0.181944E+01	Area =	0.195067E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
7SED=	0.998617E+00	Area =	0.284427E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
8SED=	0.100184E+01	Area =	0.281976E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
9SED=	0.197750E+01	Area =	0.256418E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
10SED=	0.171559E+01	Area =	0.160785E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
11SED=	0.999393E+00	Area =	0.278801E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
12SED=	0.998561E+00	Area =	0.278187E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
13SED=	0.197455E+01	Area =	0.255191E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
14SED=	0.158938E+01	Area =	0.125969E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
15SED=	0.999708E+00	Area =	0.280095E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
16SED=	0.995223E+00	Area =	0.281312E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
17SED=	0.189325E+01	Area =	0.222984E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
18SED=	0.171496E+01	Area =	0.160607E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
19SED=	0.994238E+00	Area =	0.283264E+00	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
20SED=	0.181791E+01	Area =	0.194546E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
21SED=	0.156514E+01	Area =	0.120194E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
22SED=	0.188868E+01	Area =	0.220062E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
23SED=	0.192154E+01	Area =	0.233606E+01	exlk=	0.100052E+01	SSP=	0.100000E+00	SEDavg=	0.152791E+01	N=	10
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1SED=	0.186159E+01	Area =	0.238593E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
2SED=	0.183599E+01	Area =	0.224200E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
3SED=	0.158125E+01	Area =	0.120678E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
4SED=	0.109941E+01	Area =	0.271391E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
5SED=	0.183934E+01	Area =	0.227254E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
6SED=	0.178015E+01	Area =	0.197172E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
7SED=	0.110211E+01	Area =	0.270756E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
8SED=	0.110575E+01	Area =	0.268509E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
9SED=	0.190283E+01	Area =	0.261353E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
10SED=	0.169832E+01	Area =	0.161568E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
11SED=	0.110360E+01	Area =	0.265421E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
12SED=	0.110283E+01	Area =	0.264814E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
13SED=	0.190056E+01	Area =	0.260064E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
14SED=	0.159697E+01	Area =	0.125619E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
15SED=	0.110387E+01	Area =	0.266661E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
16SED=	0.109913E+01	Area =	0.267700E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
17SED=	0.183745E+01	Area =	0.226289E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
18SED=	0.169781E+01	Area =	0.161383E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
19SED=	0.109765E+01	Area =	0.269531E+00	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
20SED=	0.177895E+01	Area =	0.196629E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
21SED=	0.157806E+01	Area =	0.119676E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
22SED=	0.183414E+01	Area =	0.223269E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
23SED=	0.185936E+01	Area =	0.237420E+01	exlk=	0.100053E+01	SSP=	0.100000E+00	SEDavg=	0.153901E+01	N=	11
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1SED=	0.180571E+01	Area =	0.242077E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
2SED=	0.178599E+01	Area =	0.227159E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
3SED=	0.158478E+01	Area =	0.120458E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
4SED=	0.118497E+01	Area =	0.261227E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
5SED=	0.178844E+01	Area =	0.230296E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
6SED=	0.174241E+01	Area =	0.199159E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
7SED=	0.118785E+01	Area =	0.260680E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
8SED=	0.19166E+01	Area =	0.258602E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
9SED=	0.183787E+01	Area =	0.265751E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
10SED=	0.167795E+01	Area =	0.162429E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
11SED=	0.118982E+01	Area =	0.255578E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
12SED=	0.118913E+01	Area =	0.254976E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
13SED=	0.183611E+01	Area =	0.264409E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
14SED=	0.159680E+01	Area =	0.125514E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
15SED=	0.119003E+01	Area =	0.256778E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
16SED=	0.118529E+01	Area =	0.257668E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
17SED=	0.178696E+01	Area =	0.229293E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
18SED=	0.167754E+01	Area =	0.162238E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
19SED=	0.118345E+01	Area =	0.259395E+00	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
20SED=	0.174147E+01	Area =	0.198596E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
21SED=	0.158222E+01	Area =	0.119433E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
22SED=	0.178455E+01	Area =	0.226193E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
23SED=	0.180397E+01	Area =	0.240858E+01	exlk=	0.100007E+01	SSP=	0.100000E+00	SEDavg=	0.154500E+01	N=	12
<hr/>											
1SED=	0.176091E+01	Area =	0.245142E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
2SED=	0.174566E+01	Area =	0.229783E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
3SED=	0.158641E+01	Area =	0.120401E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
4SED=	0.125731E+01	Area =	0.253623E+00	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
5SED=	0.174745E+01	Area =	0.232987E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
6SED=	0.171150E+01	Area =	0.200962E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
7SED=	0.126023E+01	Area =	0.253154E+00	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
8SED=	0.126401E+01	Area =	0.251216E+00	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
9SED=	0.178617E+01	Area =	0.269591E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
10SED=	0.166056E+01	Area =	0.163283E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
11SED=	0.126244E+01	Area =	0.248240E+00	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
12SED=	0.126183E+01	Area =	0.247641E+00	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
13SED=	0.178479E+01	Area =	0.268204E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
14SED=	0.159552E+01	Area =	0.125550E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
15SED=	0.126263E+01	Area =	0.249410E+00	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
16SED=	0.125806E+01	Area =	0.250174E+00	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
17SED=	0.174629E+01	Area =	0.231954E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
18SED=	0.166023E+01	Area =	0.163087E+01	exlk=	0.100027E+01	SSP=	0.100000E+00	SEDavg=	0.155075E+01	N=	13
19SED=											


```

c      call minfills(ndof,iperm)
c.....eigen-solution
c      if (iamal .eq. 1) then
c        lump=lumpmass
c        ishift=0
c        iprint=1
c        mtot=20000000
c        allocate( tempo3(mtot) )
c
c      r(mtot)=working array (in real*8) = tempo3(-)
c      iflag(1,2,3,4,5,6,7,8,9,10)=nrcord,loop_unroll,??,??,neig
c      iprint,lump,ishift,ncorf2,??
c      nrcord=0,1,2,3=no reorder,metis,nd,mmid
c
c      iflag(1)=0      ! 1,2,3 = metis,nd,mmid
c      iflag(2)=1      ! level of unroll
c      iflag(5)=necg
c      iflag(6)=iprint
c      iflag(7)=lump
c      iflag(8)=ishift
c      iflag(9)=ncorf2      ! as an output
c
c      write(6,*) 'inside *cmei*.f: ndof,ncorf1,neig,lump = '
c      write(6,*) 'ndof,ncorf1,neig,lump'
c      write(6,*) 'inside *cmei*.f: ishift,mtot = '
c      write(6,*) 'ishift,mtot'
c      write(6,*) 'inside *cmei*.f: iflag(10) = ',(iflag(i),i=1,10)
c      write(6,*) 'inside *cmei*.f: ia(-) = ',(ia(i),i=1,ndof+1)
c      write(6,*) 'inside *cmei*.f: ja(-) = ',(ja(i),i=1,ncorf1)
c      write(6,*) 'inside *cmei*.f: ad(-) = ',(ad(i),i=1,ndof)
c      write(6,*) 'inside *cmei*.f: an(-) = ',(an(i),i=1,ncorf1)
c      write(6,*) 'inside *cmei*.f: dm(-) = ',(dm(i),i=1,ndof)
c
c      if (lump .eq. 1) then
c        call eigsolver011(ndof,ncorf1,neig,lump,ishift,
c        $mtot,ia,ja,ad,an,dm, evalues,evectors,tempo3,iflag,iperm)
c      elseif (lump .eq. 0) then
c        call eigsolver022(ndof,ncorf1,neig,lump,ishift,
c        $mtot,ia,ja,ad,an,dm,am,evalues,evectors,tempo3,iflag,iperm)
c      endif
c      deallocate( tempo3 )
c      STOP
c      endif
c.....sparse "symbolic" factorization
c      ncorf2_guess=40000000
c      allocate( itempo1(ncorf2_guess) )
c
c      call symfactd(ndof,ia,ja,iu,ip,ncorf2)
c      call symfactd(ndof,ia2,ja,iu,itempo1,ip,ncorf2)
c
c      write(6,*) 'check point #03'
c      write(6,*) 'iu after symfactd=',(iu(i),i=1,ndof+1)
c      write(6,*) 'itempo1 after symfactd=',(itempo1(i),i=1,25)
c      write(6,*) 'ip after symfactd=',(ip(i),i=1,ndof)
c      stop
c
c      print *, 'ncorf2=',ncorf2
c      stop
c
c      allocate( ju(ncorf2) )
c      allocate( jut(ncorf2) )
c      allocate( un(ncorf2) )
c      call copy_int(ncorf2,itempo1,ju)
c      deallocate( itempo1 )
c
c.....transpose twice to put column numbers in order
c      call transad(ndof,ndof,iu,ju,iu,jut)
c      print *, '*** passed transa ***'
c      write(6,*) '*** passed transa ***'
c
c.....assuming to skip the "SUPER NODE" process (for unrolling purpose)
c      call supernode(ndof,isupn)
c
c.....sparse "numerical" factorization
c      call numfal1d(ndof,ia,ja,ad,an,iu,
c      $ ju,di,un,ip,iup,
c      $ isupn,iop1)
c      routine numfal1d(n,ia,ja,ad,an,iu,ju,di,un,ip,iup,isupd,iop1)
c      call numfal1d(ndof,ia2,ja,ad,an,iu,
c      $ ju,di,un,ip,iup,
c      $ isupn,iop1)
c      write(6,*) '*** passed numfal1 ***'
c
c      print *, 'b after numfal1d=',(b(i),i=1,ndof)
c
c      write(6,*) 'b before fbod=',n
c      write(6,*) 'b before fbod=',(b(i),i=1,ndof)
c      write(6,*) 'di before fbod=',(di(i),i=1,ndof)
c      write(6,*) 'iu before fbod=',(iu(i),i=1,ndof+1)
c      write(6,*) 'ju before fbod=',(ju(i),i=1,ncorf2)
c      write(6,*) 'iu before fbod=',(iu(i),i=1,ncorf2)
c      write(6,*) 'ju before fbod=',(ju(i),i=1,ncorf2)
c
c      print *, 'di before fbod=',(di(i),i=1,ndof)
c      print *, 'iu before fbod=',(iu(i),i=1,ndof+1)
c      print *, 'ju before fbod=',(ju(i),i=1,ncorf2)
c      print *, 'ncorf2=',ncorf2
c      pause
c      stop
c
c.....sparse forward/backward solution phase
c      call fbod(ndof,iu,ju,di,un,b,
c      $ tempo1,iop1,isupn,getsolve)
c
c      print *, '*** passed fbe ***'
c      print *, 'tempo1(i)=',(tempo1(i),i=1,ndof)
c      do 50 i=1,ndof
c        print *, 'disp = ',i, ' ',tempo1(i)
50      disp(i)=tempo1(i)

```



```

c AE=5.e7
c xl=2500.125
c stiff(1,1)=(AE/xl**3)*(625.d0+75.d0*u1+
c $ 1.5d0*(u1**2.))

C***Arora's nonlinear 1
c stiff(1,1)= 3.d0*u1+10.d0
c stiff(1,2)= 12.d0*u2
c stiff(2,1)= 24.d0*u2
c stiff(2,2)= 4.d0

C***Arora's nonlinear 2 soln=(-.33, -.5) **OK**
c esm(1,1)= 24.d0
c esm(1,2)= -12.d0
c esm(2,1)= -12.d0
c esm(2,2)= 8.d0

C***J. Dennis's opt. book page 172
c stiff(1,1)= 1.d0
c stiff(1,2)= 1.d0
c stiff(2,1)= u1
c stiff(2,2)= u2

C***Auroa's soln=(0,0) **OK**
c esm(1,1)= 10.d0
c esm(1,2)= 2.d0
c esm(2,1)= 2.d0
c esm(2,2)= 2.d0

C***J. Dennis opt soln=(0.00003323553246, 0.00003323553246) **OK
c esm(1,1)= 4.d0*ux(1)*ux(1)+1.d-10
c esm(1,2)= 4.d0*ux(1)*uy(1)+2.d-10
c esm(2,1)= 4.d0*ux(1)*uy(1)+3.d-10
c esm(2,2)= 4.d0*uy(1)*uy(1)+.d-10

c esm(1,1)= 4.d0*ux(1)*ux(1)+ 2.d-6
c esm(1,2)= 4.d0*ux(1)*uy(1)+ 1.d-6
c esm(2,1)= 4.d0*ux(1)*uy(1)+ 1.d-6
c esm(2,2)= 4.d0*uy(1)*uy(1)+ 2.d-6

c***Hrinda 1 (0.,20.) OK **OK**(-.7633, 1.165)
cc esm(1,1)= 24.d0*ux(1)+ 2.d-6
cc esm(1,2)= -12.d0+ 1.d-6
cc esm(2,1)= -12.d0+ 1.d-6
cc esm(2,2)= 8.d0*uy(1)+ 2.d-6

c***Hrinda 2 (1.,2.) **OK**
c print *,ux(1)='ux(1)
c print *,uy(1)='uy(1)

c esm(1,1)= 24.d0*ux(1)+ 2.d-8
c esm(1,2)= -12.d0*uy(1)+ 1.d-8
c esm(2,1)= -12.d0*uy(1)+ 1.d-8
c esm(2,2)= 8.d0*uy(1)+ 2.d-8
c print *,esm(1,1)='esm(1,1)
c print *,esm(1,2)='esm(1,2)
c print *,esm(2,1)='esm(2,1)
c print *,esm(2,2)='esm(2,2)
c pause

c***Hrinda 3 (1.,2.) **OK**
c print *,ux(1)='ux(1)
c print *,uy(1)='uy(1)

cc esm(1,1)= 24.d0*ux(1)*ux(1)+ 2.d-10
cc esm(1,2)= -16.d0
cc esm(2,1)= -36.d0
cc esm(2,2)= 6.d0*uy(1)+ 2.d-10
c print *,esm(1,1)='esm(1,1)
c print *,esm(1,2)='esm(1,2)
c print *,esm(2,1)='esm(2,1)
c print *,esm(2,2)='esm(2,2)
c pause

c**Poly Test
c print *,iel inside elstif=,iel
c If(iel.eq. 1)then
c esm(1,1)=1.d6*.0832*ux(1)**8.
c esm(2,2)=1.d6*-.7298*uy(1)**7.
c esm(3,3)=1.d6* 2.7279*uz(1)**6.
c esm(4,4)=1.d6* 5.6442*ux(2)**4.
c esm(5,5)=1.d6* 7.0200*uy(2)**3.
c esm(6,6)=1.d6* 5.3187*uz(2)**2.
c Else
c esm(1,1)=1.d6* 2.3591*ux(1)**1.
c esm(2,2)=1.d6*-.5451*uy(1)
c esm(3,3)=1.d6*-.0476*uz(1)
c esm(4,4)=0.d0
c esm(5,5)=0.d0
c esm(6,6)=0.d0
c Endif

c esm(1,1)=(1./((ux(1)-.6+(1/(ux(1)+1.d-6))))+
c (1./((ux(1)-1.8+ (.85/(ux(1)+1.d-6))))))

c esm(1,1)=(1./(((ux(1)+1.d-6)**2)*(ux(1)-.6+(1/(ux(1)+1.d-6))))+
c (1./(((ux(1)+1.d-6)**2)*(ux(1)-1.8+ (.85/(ux(1)+1.d-6))))))
cc esm(1,1)=(1./(((ux(1)+1.d-6)**2)*(ux(1)-.6+(1/(ux(1)+1.d-6))))+
c (1./(((ux(1)+1.d-6)**2)*(ux(1)-1.8+ (.85/(ux(1)+1.d-6))))))
cc c -.6.d0

c esm(1,1)= (-4.*(509.d0*ux(1)-87.d0-(22.d0/(ux(1)+1.d-6))+
c 300.d0*ux(1)**3.-
c 720.d0*ux(1)**2.)/(10.d0*ux(1)**2.-6.d0*ux(1)+1.d0)*
c (20.d0*ux(1)**2.-36.d0*ux(1)+17.d0)))+ 1.d-6

c print *,esm(1,1)='esm(1,1)
c print *,esm(2,2)='esm(2,2)
c print *,esm(3,3)='esm(3,3)
c print *,esm(4,4)='esm(4,4)

c print *,esm(5,5)='esm(5,5)
c print *,esm(6,6)='esm(6,6)
c print *,esm(1,2)='esm(1,2)
c print *,esm(2,1)='esm(2,1)
c print *,esm(1,3)='esm(1,3)
c pause

Endif

GOTO 1010

If(ityp.eq. 12)then
DO 22 I=1,6
DO 22 J=1,6
22 esm(I,J)=0.0
Do 11 I=1,2
finx(i)=0.0
finy(i)=0.0
11 finz(i)=0.0
endif

c ityp = 6 for 2-D, =12 for 3-D
c ityp = 12
c itruss = 1 for Green's, = 2 for Engineering
c itruss = 1
c itruss = 2
c itruss = 3
c POISS = .5d0

c print *,iarc inside elstif=,iarc
c print *,iarc inside elstif=,iarc
c print *,youngm inside elstif=,youngm
c print *,maxdofpe=,maxdofpe
c stop
c print *,ityp inside elstif=,ityp

c stop
c If(iarc.eq. 1.or. iarc.eq. 0)then
c*****
cxxxx If(ityp.eq.12)then ! Space truss element

c print *,'Reading in Space Truss Stiffness In elstif'

c..... Three Dimensional Truss Element Stiffness matrix
c a=dx
c e=dy

a=area
e=youngm

c print *,a='a'
c print *,e='e'
c pause
c print *,xi xj yi yj zi zj='xi,xj,yi,yj,zi,zj'

c pause

cc print *,ux(1) & ux(2)='ux(1),ux(2)
cc print *,uy(1) & uy(2)='uy(1),uy(2)
cc print *,uz(1) & uz(2)='uz(1),uz(2)
cx x(1)=xi
cx x(2)=xj
cx y(1)=yi
cx y(2)=yj
cx z(1)=zi
cx z(2)=zj
cx print *,x(1) x(2)='x(1),x(2)
cx print *,y(1) y(2)='y(1),y(2)
cx print *,z(1) z(2)='z(1),z(2)
cx pause
cx dcltax=x(2)-x(1)
cx deltax=y(2)-y(1)
cx deltax=z(2)-z(1)
cx deltax=xj-xi
deltax=yj-yi
deltax=zj-zi

c print *,dcltax='dcltax'
c pause

c deltax=x(2)+x(1)
c deltax=y(2)+y(1)
c deltax=z(2)+z(1)

c deltaxi=x(2)-ux(2)- ( x(1)-ux(1) )
c deltaxi=x(2)+ux(2)- ( x(1)+ux(1) )
cx deltaxi=x(2)-x(1)+ ux(2)-ux(1)
deltaxi=xj-xi+ ux(2)-ux(1)
cc print *,'A check'
c deltaxi=y(2)-uy(2)- ( y(1)-uy(1) )
c deltaxi=y(2)+uy(2)- ( y(1)+uy(1) )
cx deltaxi=y(2)-y(1)+ uy(2)-uy(1)
deltaxi=yj-yi+ uy(2)-uy(1)
c print *,deltaxi='deltaxi'
cc print *,y(2) y(1)='y(2)', 'y(1)
cc print *,uy(2) uy(1)='uy(2)', 'uy(1)

c deltaxi=z(2)-uz(2)- ( z(1)-uz(1) )
c deltaxi=z(2)+uz(2)- ( z(1)+uz(1) )
cx deltaxi=z(2)-z(1)+ uz(2)-uz(1)
deltaxi=zj-zi+ uz(2)-uz(1)

c print *,deltax='deltax'
c print *,deltax='deltax'
c print *,deltax='deltax'
c print *,deltaxi='deltaxi'
c print *,deltaxi='deltaxi'
c print *,deltaxi='deltaxi'

c pause
c print *,'B check'

```

```

c      pause
c      xl=dsqrt(deltax**2.d0 + deltax**2.d0 + deltax**2.d0)
c      xli=dsqrt(deltaxi**2.d0 + deltaxi**2.d0 + deltaxi**2.d0)
c
c      print *,xl =',xl
c      print *,xli=',xli
c
c      cx=deltax/xl
c      cy=deltay/xl
c      cz=deltaz/xl
c      const=e*a/xl
c
c      AN = 0.0
c      ALAM = xl/xli
c      X21D = deltaxi
c      Y21D = deltaxi
c      Z21D = deltaxi
c
c      C(1) = -X21D
c      C(2) = -Y21D
c      C(3) = -Z21D
c      C(4) = -C(1)
c      C(5) = -C(2)
c      C(6) = -C(3)
c
c      P(1)=ux(1)
c      P(2)=uy(1)
c      P(3)=uz(1)
c      P(4)=ux(2)
c      P(5)=uy(2)
c      P(6)=uz(2)
c      dx=ux(2)-ux(1)
c      dy=uy(2)-uy(1)
c      dz=uz(2)-uz(1)
c
c      ALO2=xl*xl
c      C. Glenn's modify
c      B1(1) = -deltax/ALO2
c      B1(2) = -deltay/ALO2
c      B1(3) = -deltaz/ALO2
c      B1(4) = -B1(1)
c      B1(5) = -B1(2)
c      B1(6) = -B1(3)
c
c      EGR=0.D0
c      Do 100 I=1,6
c 100 EGR=EGR+B1(I)*P(I)
c
c      EGR=EGR+.5*(dx*dx+dy*dy+dz*dz)/ALO2
c
c      EST=EGR
c      print *,EST=',est
c      stop
c      If (itruss .eq. 2)then
c        Print *,'Using Engineering Strain Element!'
c        STOP
c      Else
c        EST=2.*xI*EGR/(xli+xl)
c      Endif
c
c      If (itruss .eq. 3)then
c        Print *,'Using Log-Strain Element!'
c        STOP
c      Else
c        EST=LLOG(xli/xl)
c        print *,EST=',est
c        pause
c      Endif
c
cc      print *,EST =',est
c** "AN" is the internal force from Crisfield, vol 1, p.88
c      AN = E*A*EST
c
c      print *,E=',E
c      print *,A=',A
c
c      print *,AN =',AN
c      print *,xl =',xl
c      print *,xli =',xli
c      pause
c      stop
c
c      If (itruss .eq. 1)then
c        write(12,*)'Internal Force AN'
c      endif
c      write(12,51) AN
c 51 format(c12.4)
c      print *,AN2 =',AN2
c*****
c      Endif
c
c      EA = E*A
c      AN2 = A*E*(xl-xli)/xl
c
c      stop
c      print *,AN2 =',AN2
c      pause
cc      CON1 = 1.0D0/xlorig**3
c** EA is very large compared to AN*ALAM
c      print *,itruss inside elastif =',itruss
c
c      print *,'lm3a in elastif=',(lm(ic),ic=1,6)
c      pause
c
c      print *,'itruss=',itruss
c
c      If (itruss .eq. 1)then
c        CON1 = E*A*CON1
c      print *,E=',E
c      print *,A=',A

```

```

c      print *,CON1 =',CON1
c      pause
c      elseif (itruss .eq. 2)then
c        ALAM=xl/AN
c        CON1 = ALAM*ALAM*CON1*(EA-AN*ALAM)
c      endif
c
c      If (itruss .eq. 3) then
c        CON1=CON1*ALAM**4*(EA-(1.d0+.5d0*POISS)*AN)
c      endif
c
c      print *,'lm3b in elastif=',(lm(ic),ic=1,6)
c      pause
c
c      print *,'CON1 & CON2 =',con1,' ',con2
cc      pause
c      DO 33 J=1,6
c      DO 33 I=1,J
c      print *,'I=',i,' J=',j
c      print *,C(I) & C(J) & CON1 =',c(i),c(j),con1
c
c      print *,'lm3bc in elastif=',lm(J)
c      pause
c
c      33 csm(I,J)=CON1*C(I)*C(J)
c
c      print *,'lm3c in elastif=',(lm(ic),ic=1,6)
c      pause
c
c      If (itruss .ge. 1)then
c        If (itruss .eq. 1)then
c          CON2=AN/xl
c
c          print *,'CON2 =',con2
c          stop
c        Elseif (itruss .eq. 2)then
c          Else
c            CON2=CON2*ALAM
c          Endif
c
c          print *,'CON2 =',con2
c          pause
c          print *,xl =',xl
c          print *,xli =',xli
c
c          print *,'lm3d in elastif=',(lm(ic),ic=1,6)
c          pause
c
c          stop
c
c      con2=0.
c      C. Crisfield original..
c      csm(1,1)=csm(1,1)+CON2
c      csm(2,2)=csm(2,2)+CON2
c      csm(3,3)=csm(3,3)+CON2
c      csm(4,4)=csm(4,4)+CON2
c      csm(5,5)=csm(5,5)+CON2
c      csm(6,6)=csm(6,6)+CON2
c      csm(1,4)=csm(1,4)-CON2
c      csm(2,5)=csm(2,5)-CON2
c      csm(3,6)=csm(3,6)-CON2
c
c      D. Duc's.....
c      csm(1,1)=csm(1,1)+CON2
c      csm(2,2)=csm(2,2)+CON2
c      csm(3,3)=csm(3,3)+CON2
c      csm(4,4)=csm(4,4)+CON2
c      csm(5,5)=csm(5,5)+CON2
c      csm(6,6)=csm(6,6)+CON2
c      csm(1,4)=csm(1,4)-CON2
c      csm(2,5)=csm(2,5)-CON2
c      csm(3,6)=csm(3,6)-CON2
c
c      If (istep .eq. 440)then
c        print *,'CON2=',con2
c        print *,csm(1,1)=',csm(1,1)
c        print *,csm(2,2)=',csm(2,2)
c        print *,csm(3,3)=',csm(3,3)
c        print *,csm(4,4)=',csm(4,4)
c        print *,csm(5,5)=',csm(5,5)
c        print *,csm(6,6)=',csm(6,6)
c        print *,csm(1,4)=',csm(1,4)
c        print *,csm(2,5)=',csm(2,5)
c        print *,csm(3,6)=',csm(3,6)
c        pause
c      endif
c      print *,xl =',xl
c      stop
c      csm(1,2)=0.
c      csm(1,3)=0.
c      csm(1,5)=0.
c      csm(1,6)=0.
c      csm(2,3)=0.
c      csm(2,4)=0.
c      csm(2,6)=0.
c      csm(3,4)=0.
c      csm(3,5)=0.
c
c      C. Crisfield modified
c      csm(1,1)=csm(1,1)+CON2
c      csm(2,2)=csm(2,2)+CON2
c      csm(3,3)=csm(3,3)+CON2
c      csm(4,4)=csm(4,4)+CON2
c      csm(5,5)=csm(5,5)+CON2
c      csm(6,6)=csm(6,6)+CON2
c      csm(1,2)=csm(1,2)-CON2
c      csm(1,3)=csm(1,3)-CON2
c      csm(1,4)=csm(1,4)-CON2
c      csm(1,5)=csm(1,5)-CON2
c      csm(1,6)=csm(1,6)-CON2
c      csm(3,4)=csm(3,4)-CON2
c      csm(3,5)=csm(3,5)-CON2

```

```

c esm(3,6)=esm(3,6)-CON2
c esm(4,5)=esm(4,5)-CON2
c esm(4,6)=esm(4,6)-CON2
c esm(5,6)=esm(5,6)-CON2
c. Glenn's esm.
c esm(1,1)=esm(1,1)+CON2
c esm(1,2)=esm(1,2)-CON2
c esm(2,2)=esm(2,2)+CON2
c esm(3,3)=esm(3,3)+CON2
c esm(3,4)=esm(3,4)-CON2
c esm(4,4)=esm(4,4)+CON2
c esm(4,5)=esm(4,5)-CON2
c esm(5,5)=esm(5,5)+CON2
c esm(5,6)=esm(5,6)-CON2
c esm(6,6)=esm(6,6)+CON2
c print *,xi = ',xi
c print *,xli = ',xli

```

```

DO 344 I=1,6
DO 344 J=1,6
c print *,T,i,J,i,'esm(I,J) inside elastf= ',esm(i,j)
344 esm(J,I)=esm(I,J)
c print *,7m4 in elastf= ',(ln(ic),ic=1,6)
c pause
c pause
c print *,xi = ',xi
c print *,xli = ',xli
c stop

```

```

c34 print *,csn inside elastf= ',i','j',' ',esm(i,j)
c pause

```

```

c print *,'xli inside elastf= ',xli
c print *,'deltaxi inside elastf= ',deltaxi
c print *,'a & e inside elastf= ',a,e
c print *,'xli inside elastf= ',xli

```

```

C print *,itruss=',itruss
C PAUSE
c stop
c print *,xi = ',xi
c print *,xli = ',xli
c print *,'AN= ',AN
c print *,'X21D= ',x21d
c stop

```

```

If(itruss .eq. 1)Then
Finx(1) = -AN * (X21D/xli)
Finx(2) = -AN * (X21D/xli)
Finy(1) = -AN * (Y21D/xli)
Finy(2) = -AN * (Y21D/xli)
FinZ(1) = -AN * (Z21D/xli)
FinZ(2) = -AN * (Z21D/xli)
cvt ElseIf(itruss .gt. 1)Then
cvt ElseIf(itruss .eq. 2)Then
Else
Finx(1) = -AN * (X21D/xli) * ALAM
Finx(2) = -AN * (X21D/xli) * ALAM
Finy(1) = -AN * (Y21D/xli) * ALAM
Finy(2) = -AN * (Y21D/xli) * ALAM
FinZ(1) = -AN * (Z21D/xli) * ALAM
FinZ(2) = -AN * (Z21D/xli) * ALAM
Endif

```

```

c**Internal force for Function Tests
1010 Continue !dummy
c AE=5.e7
c xl=2500.125
c fintk(1) = (AE/xl**3)*(625.d0*u1+37.5d0*u1**2.+
c $ (u1**3)/2.)
C**Arora's nonlinear 1
c fintk(1) = (3.d0*u1+10.d0)*u1 + 12.d0*u2*u2
c fintk(2) = 24.d0*u1*u2 + 4.d0*u2

```

```

C**Arora's nonlinear 2 sol=(-.33, -.5) **OK**
cOK finx(1) = 24.d0*ux(1) - 12.d0*uy(1)
cOK finy(1) = -12.d0*ux(1) + 8.d0*uy(1)

```

```

cOK print *,'Finx(1) inside elastf= ',finx(1)
cOK print *,'Finy(1) inside elastf= ',finy(1)
c pause

```

```

C**J. Dennis's opt. book page 172
c fintk(1) = u1 + u2
c fintk(2) = u1*u1 + u2*u2

```

```

C**Arora's nonlinear soln=(0,0) **OK**
finx(1) = 10.d0*ux(1) + 2.d0*uy(1)
finy(1) = 2.d0*ux(1) + 2.d0*uy(1)

```

```

C**J. Dennis opt soln=(0.00228,0.00228)
c finx(1)=(4.d0*ux(1)*ux(1)+1.d-10)*ux(1) +
c (4.d0*ux(1)*uy(1)+2.d-10)*uy(1)
c finx(2)=(4.d0*uy(1)*ux(1)+3.d-10)*ux(1) +
c (4.d0*uy(1)*uy(1)+4.d-10)*uy(1)

```

```

c finx(1)=(4.d0*ux(1)**2.+2.d-6)*ux(1) +
c (4.d0*ux(1)*uy(1)+1.d-6)*uy(1)
c finx(2)=(4.d0*uy(1)*ux(1)+1.d-6)*ux(1) +
c (4.d0*uy(1)**2.+2.d-6)*uy(1)

```

```

c esm(1,1) = 4.d0*ux(1)*ux(1) + 1.
c esm(1,2) = 4.d0*ux(1)*uy(1) + 2.
c esm(2,1) = 4.d0*ux(1)*uy(1) + 3.
c esm(2,2) = 4.d0*uy(1)*uy(1) + 4.

```

```

c**Hrinda 1 **OK**
cc finx(1)=(24.d0*ux(1)+2.d-6)*ux(1)+(-12.d0+1.d-6)*uy(1)
cc finy(1)=(-12.d0+1.d-6)*ux(1)+(8.d0*uy(1)+2.d-6)*uy(1)

```

```

c**Hrinda 2 **OK**
c finx(1)=(24.d0*ux(1)+2.d-8)*ux(1)+(-12.d0*uy(1)+1.d-8)*uy(1)
c finy(1)=(-12.d0*uy(1)+1.d-8)*ux(1)+(8.d0*uy(1)+2.d-8)*uy(1)
c print *,'finx(1)= ',finx(1)
c print *,'finy(1)= ',finy(1)
c pause

```

```

c**Hrinda 3 **OK**
cc finx(1)=(24.d0*ux(1)*ux(1)+2.d-10)*ux(1)+
cc (-16.d0)*uy(1)

```

```

cc finy(1)=(-36.d0)*ux(1)+
cc (6.d0*uy(1)+2.d-10)*uy(1)

```

```

c print *,'finx(1)= ',finx(1)
c print *,'finy(1)= ',finy(1)

```

```

c print *,'Finx(1) inside elastf= ',finx(1)
c print *,'Finy(1) inside elastf= ',finy(1)

```

```

c**Poly Test

```

```

c If(icl .eq. 1)then
c finx(1)=(1.d6* .0832 *ux(1)**9.)
c finy(1)=(1.d6* -.7298 *uy(1)**8.)
c finz(1)=(1.d6* 2.7279 *uz(1)**7.)
c finx(2)=(1.d6* 5.6442 *ux(2)**6.)
c finy(2)=(1.d6* 7.0200 *uy(2)**5.)
c finz(2)=(1.d6* -5.3187*uz(2)**4.)
c ELSE
c finx(1)=(1.d6* 2.3591 *ux(1)**3.)
c finy(1)=(1.d6* -.5451 *uy(1)**2.)
c finz(1)=(1.d6* .0476 *uz(1)**1.)
c finx(2)=0.d0
c finy(2)=0.d0
c finz(2)=0.d0
c Endif

```

```

cc finx(1)=(1/(ux(1))-6+(1/ux(1))) +
cc c 1/(ux(1)-1.8+ (.85/ux(1))))*ux(1)

```

```

c**Matlab Example

```

```

c finx(1)=(1/(ux(1))-6+(1/ux(1)+1.d-6))) +
c (1/(ux(1)-1.8+ (.85/ux(1)+1.d-6))))*ux(1)
c finx(1)=(1/(ux(1))-6+(1/ux(1)+1.d-6))) +
c (1/(ux(1)-1.8+ (.85/ux(1)+1.d-6))))*ux(1)
c finx(1)=(1/(ux(1))-6+(1/ux(1)+1.d-6))) +
c (1/(ux(1)-1.8+ (.85/ux(1)+1.d-6))))*ux(1)

```

```

c finx(1)=(1/(ux(1)**2.)*ux(1)-.6+(1/ux(1)+1.d-6))) +
c (1/(ux(1)**2.)*ux(1)-1.8+ (.85/ux(1)+1.d-6))))*ux(1)

```

```

c finx(1)=(1/(ux(1)**2.)*ux(1)-.6+(1/ux(1)+1.d-6))) +
c (1/(ux(1)**2.)*ux(1)-1.8+ (.85/ux(1)+1.d-6))))*ux(1)

```

```

c finx(1)=(1/(ux(1)+1.d-6)**2.)*ux(1)-.6+(1/ux(1)+1.d-6)))+
c c (1/(ux(1)+1.d-6)**2.)*ux(1)-1.8+ (.85/ux(1)+1.d-6)))+
c c (ux(1))

```

```

c finx(1)=(1/(ux(1)+1.d-6)**2.)*ux(1)-.6+(1/ux(1)+1.d-6)))+
c c (1/(ux(1)+1.d-6)**2.)*ux(1)-1.8+ (.85/ux(1)+1.d-6)))+
c c (ux(1))-6.*ux(1)

```

```

cc finx(1)=(1/(ux(1)+1.d-6)**2.)*ux(1)-.6+(1/ux(1)+1.d-6)))+
cc c (1/(ux(1)+1.d-6)**2.)*ux(1)-1.8+ (.85/ux(1)+1.d-6)))+
cc c (-6.d0)*ux(1)

```

```

c print *,'ux(1)= ',ux(1)
c print *,'finx(1)= ',finx(1)
c pause

```

```

c finx(1) = (-4.*ux(1))*(509.d0*ux(1)-87.d0-(22.d0/(ux(1)+1.d-6))+
c c 300.d0*ux(1)**3.-720.d0*ux(1)**2.) /
c c (10.d0*ux(1)**2.-36.d0*ux(1)+1.d0)*
c c (20.d0*ux(1)**2.-36.d0*ux(1)+17.d0) + (1.d-6*ux(1))

```

```

c esm(1,1) = -4.*(509.d0*ux(1)-87.d0-(22.d0/(ux(1)+1.d-6))+
c c 300.d0*ux(1)**3.-
c c 720.d0*ux(1)**2.) / ((10.d0*ux(1)**2.-6.d0*ux(1)+1.d0)*
c c (20.d0*ux(1)**2.-36.d0*ux(1)+17.d0)) + 1.d-6

```

```

c pause

```

```

c pause
c Finy(1) = 1.d-6
c Finy(2) = 1.d-6
c FinZ(1) = 1.d-6
c FinZ(2) = 1.d-6

```

```

c...deltaxi=X21D...AN = E*A*EST...

```

```

c Fmx(1) = -(xl-xli)*a*c/xli * (deltaxi/xli)
c Fmx(2) = ((xl-xli)*a*c/xli * (deltaxi/xli)
cc Fmx(1) = ((xl-xli)*a*c/xli * (deltaxi/xli)
cc Fmx(2) = -(xl-xli)*a*c/xli * (deltaxi/xli)
cc print *,'AN axial load = ',AN
c print *,'Fmx(1) inside elastf= ',fmx(1)
c print *,'Fmx(2) inside elastf= ',fmx(2)
c pause
c print *,'Finy(1) inside elastf= ',finy(1)
c print *,'Finy(2) inside elastf= ',finy(2)
c print *,'Finz(1) inside elastf= ',finz(1)
c print *,'Finz(2) inside elastf= ',finz(2)
c pause

```

```

c Finy(1) = -AN * (Y21D/xli)
c Finy(2) = -AN * (Y21D/xli)
c Finy(1) = -AN * (Y21D/xli)
c Finy(2) = -AN * (Y21D/xli)
cc print *,'Finy(1) = -AN * (Y21D/xli),finy(1)
cc print *,'Finy(2) = -AN * (Y21D/xli),finy(2)

```

```

c Finy(1) = -(xl-xli)*a*c/xli * (deltaxi/xli)
c Finy(2) = ((xl-xli)*a*c/xli * (deltaxi/xli)

```

[illegible]


```

c output: iu(n+1),ju(ncocf2) structure of resulting matrix U in RR(U)U.
c working space: ip(n) of dimension N. Chained lists of rows
c associated with each column.
c The array IU is also used as the multiple
c switch array.
c print *, '*****inside symfactd*****'
c print *, 'inside symfactd: ia(-) = ', (ia(i), i=1, n+1)
c print *, 'inside symfactd: ja(-) = ', (ja(i), i=1, n+1)
c print *, 'inside symfactd: ja(-) = ', (ja(i), i=1, 3)
c pause
c print *, 'ia2 inside symfactd=', (ia2(i), i=1, n+1)
c stop

J1=0
JPP=0
MIN=0
IAA=0
IAB=0
JJ=0
JP=0
LAST=0
L=0
LH=0
IUA=0
IUB=0
NH=0
ncocf2=0
J=0
NM=0

ncocf1=ia(n+1)-1
ncocf1=ia2(n+1)-1

c print *, 'start symfactd: ia(-) = ', (ia(i), i=1, n+1)
c print *, 'inside symfactd: ja(-) = ', (ja(i), i=1, ncocf1)
c write(6,*) 'inside symfactd: ia2(-) = ', (ia2(i), i=1, n+1)
c write(6,*) 'inside symfactd: ja(-) = ', (ja(i), i=1, ncocf1)
c pause

NM=N-1
NH=N+1
DO 8 I=1, N+1
    ju(i)=0
8 ip(i)=0

DO 10 I=1, N
    IU(I)=0
10 IP(I)=0
JP=1

DO 90 I=1, NM
    JPI=JP
    JPP=N+JP-1
    MIN=NH

c print *, 'I=', i
c print *, 'JPI=', JPI
c print *, 'JPP=', JPP
c print *, 'MIN=', min
c pause
c print *, 'IA2(I) = ', IA2(I)
c print *, 'IA2(I+1) = ', IA2(I+1)
c write(6,*) 'I=', i
c write(6,*) 'JPI=', JPI
c write(6,*) 'JPP=', JPP
c write(6,*) 'MIN=', min
c pause
c write(6,*) 'IA2(I) = ', IA2(I)
c write(6,*) 'IA2(I+1) = ', IA2(I+1)

c stop

IAA=IA(I)
IAB=IA(I+1)-1
IAA=IA2(I)
IAB=IA2(I+1)-1

c print *, 'IAA=', iaa
c print *, 'IAB=', iab
c write(6,*) 'IAA=', iaa
c write(6,*) 'IAB=', iab
c pause
c write(6,*) 'SYMFAC: i,nm,jpi,jp,n,jpp,min,iaa,iab = '
c write(6,*) i,nm,jpi,jp,n,jpp,min,iaa,iab
c print *, 'SYMFAC: i,nm,jpi,jp,n,jpp,min,iaa,iab = '
c print *, i,nm,jpi,jp,n,jpp,min,iaa,iab

IF(IAB.LT.IAA) GO TO 30
c print *, 'check 1 inside symfactd'
c print *, 'IA(-) inside symfactd=', (IA(i), i=1, 3)
c print *, 'IAA=', IAA
c print *, 'IAB=', IAB
DO 20 J=IAA,IAB
    print *, 'JA(J) = ', JA(J)
JJ=JA(J)
    print *, 'chk JA(J) inside symfactd'
    JU(JP)=JJ
c print *, 'chk JU(JP) inside symfactd'
c write(6,*) 'SYMFAC: inside loop20: j,jj,jp,ju(jp),min = '
c write(6,*) j,jj,jp,ju(jp),min
c print *, 'SYMFAC: inside loop20: j,jj,jp,ju(jp),min = '
c print *, j,jj,jp,ju(jp),min
c pause
c stop

JP=JP+1
c write(6,*) 'SYMFAC: inside loop20: j,jj,jp,ju(jp),min = '
c write(6,*) j,jj,jp,ju(jp),min
c print *, 'SYMFAC: inside loop20: j,jj,jp,ju(jp),min = '
c print *, j,jj,jp,ju(jp),min

IF(JJ.LT.MIN) MIN=JJ
IF(JJ.LT.MIN) then
    min=jj

```



```

c write(6,*) 'SYMFAC: min,ip(min),i,ip(i) ='
c write(6,*) min,ip(min),i,ip(i)
90 IU(I)=JP1
c      print *,IU(I)=,IU(I)
IU(N)=JP
IU(NH)=JP
c      print *,IU(N)=,IU(N)
c      print *,IU(NH)=,IU(NH)
c write(6,*) 'SYMFAC: i,iu(i),jp1,iu(n),jp,nh,iu(nh) ='
c write(6,*) i,iu(i),jp1,iu(n),jp,nh,iu(nh)
c      print *, 'chk 5 inside sysfact'
c write(6,*) 'chk 5 inside sysfact'
c      stop
ncocf2=iu(n+1)-1
c      print *,iu(n+1) = ,iu(n+1)
c      print *, 'ncocf2 inside symfact =',ncocf2
c write(6,*) 'ncocf2=',ncocf2
c      stop
c write(6,*) 'inside symfact: ncocf2=', ncocf2
c      return
c      end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c      subroutine transad(n,m,ia,ja,iat,jat)
c      implicit real*(a-h,o-z)
c      dimension ia(*),ja(*),iat(*),jat(*)
c+++++
c.....PLEASE direct your questions to Dr. Nguyen (nguyen@cee.odu.edu)
c.....Purposes: After symbolic factorization,ja is just a merge lists
c.....WITHOUT ordering (i.e. the nonzero column numbers of a
c.....particular row are 12, 27, 14, 46, 22, 133). Upon
c.....completion, this routine will rearrange the nonzero column
c.....numbers WITH ordering, to be ready for numerical factorization
c.....phase (i.e. 12, 14, 22, 27, 46, 133)
c      input: ia,ja,an given matrix in RR(C)U.
c      n      number of rows of the matrix.
c      m      number of columns of the matrix.
c      output: iat,jat,an transposed matrix in RR(C)O.
c+++++
c      dimension iat(6), jat(7), iat(6), jat(7)
c      dimension ia(ncol+1), ja(ncocf1), iat(ncol+1), jat(ncocf1)
c      ncol=5
c      ncocf1=7
c      nrow=5
c      ncol=5
c..... x 2 0 4 5 ---> input unordered col # 2,5,4
c..... x 3 4 0 ---> input unordered col # 4,3
c..... x 0 5 ---> input col # 5
c..... x 5 ---> input col # 5
c..... x
c      ia(1)=1
c      ia(2)=4
c      ia(3)=6
c      ia(4)=7
c      ia(5)=8
c      ia(6)=8
c      ja(1)=2
c      ja(2)=5
c      ja(3)=4
c      ja(4)=4
c      ja(5)=3
c      ja(6)=5
c      ja(7)=5
c      call transad(nrows,ncols,ia,ja,iat,jat)
c write(6,*) 'after reordered, ia(-)=',(ia(i),i=1,ncol+1)
c write(6,*) 'after reordered, ja(-)=',(ja(i),i=1,ncocf1)
c      stop
c      end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c      print *,ja at start of transd =',(ja(i),i=1,15)
MH=M+1
NH=N+1
DO 10 I=2,MH
10 IAT(I)=0
IAB=IA(NH)-1
DO 20 I=1,IAB
J=JA(I)+2
IF(J.LE.MH)IAT(I)=IAT(I)+1
20 CONTINUE
IAT(1)=1
IAT(2)=1
IF(M.EQ.1)GO TO 40
DO 30 I=3,MH
30 IAT(I)=IAT(I)+IAT(I-1)
40 DO 60 I=1,N
IAA=IA(I)
IAB=IA(I+1)-1
IF(IAB.LT.IAA)GO TO 60
DO 50 JP=IAA,IAB
J=JA(JP)+1
K=IAT(J)
JAT(K)=I
c      ANT(K)=AN(JP)
50 IAT(J)=K+1
60 CONTINUE
c      print *,ja at end of transd =',(ja(i),i=1,15)
c      pause
c      call transa2d(n,m,ia,jat,ia,ja)
c      return
c      end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c      The following routines are extracted from file part2.f
c      see cd ~/cee/newfem/*completely*/

```

Table 8.7 Transposing a Sparse Matrix

```

c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c..... file = part2.o (only object codes) .....
c      subroutine transa2d(n,m,ia,ja,iat,jat)
c      dimension ia(*),ja(*),iat(*),jat(*)
c      dimension ja2(20)
c      print *, 'ia(-) inside transa2d=',(ia(i),i=1,15)
c      print *, 'ja(-) inside transa2d=',(ja(i),i=1,15)
c      pause
MH=M+1
NH=N+1
DO 10 I=2,MH
10 IAT(I)=0
IAB=IA(NH)-1
DO 20 I=1,IAB
J=JA(I)+2
IF(J.LE.MH)IAT(I)=IAT(I)+1
20 CONTINUE
IAT(1)=1
IAT(2)=1
IF(M.EQ.1)GO TO 40
DO 30 I=3,MH
30 IAT(I)=IAT(I)+IAT(I-1)
c      Do 31 I=1,20
c      ja2(i)=ja(i)
c      print *, 'ja(-) inside transa2d mid=',(ja(i),i=1,10)
c      pause
40 DO 60 I=1,N
IAA=IA(I)
IAB=IA(I+1)-1
IF(IAB.LT.IAA)GO TO 60
DO 50 JP=IAA,IAB
c      print *, 'JA(JP)=',JA(JP), '(JP)',JP
J=JA(JP)+1
K=IAT(J)
JAT(K)=I
c      ANT(K)=AN(JP)
50 IAT(J)=K+1
c      print *, 'JA(JP) 2=',JA(JP), '(JP)',JP
60 CONTINUE
c      print *, 'JA(JP) 3=',(JA(k),k=1,20)
c      nz=iat(m+1)-1
c      write(6,*) 'inside transa2: iet(-) =',(iat(i),i=1,m+1)
c      write(6,*) 'inside transa2: jet(-) =',(jat(i),i=1,mz)
c      print *, 'inside transa2 at end: iet(-) =',(iat(i),i=1,m+1)
c      print *, 'inside transa2 at end: jet(-) =',(jat(i),i=1,mz)
c      stop
c      Do 61 i=1,20
c      ja2(i)=ja2(i)
c      print *, 'ja(-) inside transa2d at end=',(ja(i),i=1,10)
c      pause
c      return
c      end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c      Table 8.2 Complete FORTRAN Code for Sparse, Symmetrical
c      Symbolic Assembly Process
c      subroutine symbass(ie,je,iet,jct,ndof,ia,ja,ncocf1)
c      subroutine symbass(ie,je,iet,jct,ndof,ia1,ia2,ja,ncocf1)
c      implicit real*(a-h,o-z)
c      dimension ie(*),je(*),iet(*),jct(*),ja(*),ia(*)
c      dimension iet(*),jet(*),iet(*),jet(*),ja1(*),ja2(*)
c+++++
c.....PLEASE direct your questions to Dr. Nguyen (nguyen@cee.odu.edu)
c.....Purposes: symmetrical, sparse symbolic assembly
c.....This code is stored under file name *symb*.f, in sub-directory
c.....cd ~/cee/newfem/complete/part2.f
c+++++
c.....Input: iet(nel+1)=locations (or pointers) of the first non-zero
c.....of each row (of element-dof connectivity info.)
c.....jet(nel*ndofpe)=global dof column number for non-zero
c.....terms of each row (of element-dof connectivity info.)
c.....iet(ndof+1)=locations (pointers) of the first non-zero
c.....of each row (of dof-element connectivity info.)
c.....jet(nel*ndofpe)=locations (pointers) of the first non-zero
c.....of each row (of dof-element connectivity info.)
c.....ia(ndof)= ndof in the positions correspond to Dirichlet b.c.
c.....if elsewhere
c.....Output:ia(ndof+1)=starting locations of the first non-zero
c.....off-diagonal terms for each row of structural stiffness
c.....matrix
c.....ja(ncocf1)=column numbers (unordered) correspond to
c.....each nonzero, off-diagonal term of each row of structural
c.....stiffness matrix
c+++++
c      "ia1" contains the supportdof from subroutine supportdof
c      "ia2" is the new "ia" that gets set to zero at the start of this
c      subroutine and is created new at the end. GAH 4-23-04
c      print *, '*** ** START SYMBASS *** **'
c      PAUSE
c      print *, '*** ** START SYMBASS *** **'
c      PAUSE
c      print *, '*** ** START SYMBASS *** **'
c      PAUSE

```



```

prop(istart+ 1)=area
prop(istart+ 2)=xi
prop(istart+ 3)=yi
prop(istart+ 4)=zi
prop(istart+ 5)=t1
prop(istart+ 6)=t2
prop(istart+ 7)=t3
prop(istart+ 8)=t4
prop(istart+ 9)=theta1
prop(istart+10)=theta2
prop(istart+11)=theta3
prop(istart+12)=theta4
1 continue

      area = prop(istart+1)

c      print *, 'area inside sectprop=', area
      return
end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%subroutine nodecoor(numnodes,xxx,yyy,zzz)
%implicit real*8(a-h,o-z)
c
c.....Purpose: Input joint coordinates
c
c      dimension xxx(1),yyy(1),zzz(1)
c
c      print *, 'numnodes inside nodecoor=', numnodes
c
c      write(6,*) 'joint,xxx(joint),yyy(joint),zzz(joint)'
c      do 21 i=1,numnodes
c        read(5,*) joint,xxx(joint),yyy(joint),zzz(joint)
c        write(*,4) joint,xxx(joint),yyy(joint),zzz(joint)
c      pause
c      write(6,4) joint,xxx(joint),yyy(joint),zzz(joint)
4      format(2x,i5,f10.2,f10.2,f10.2)
21 continue
      return
end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%subroutine elconnect(ic,jc,lm,neltype,nel,ndofpe,ndofpn)
%implicit real*8(a-h,o-z)
c
c.....Purpose: Input element connectivity information.
c.....Note: This routine can be used for any finite element type ??
c
c      dimension ic(1),jc(1),lm(1),nel(1),ndofpe(1)
c
c      icadd=0
c      locadd=0
c      ic(1)=1 ! always
c      print *, 'neltype inside elconnect=', neltype
c
c      pause
c      stop
c      do 21 k=1,neltype
c        numel='ncl(k)
c        print *, 'numel inside elconnect=', numel
c        pause
c      if (numel .eq. 0) go to 21
c      go to (31,32,33,34,34,34),k
31 continue ! 2-d truss
c      print *, 'numel=', numel
c      pause
c      do 22 i=1,numel
c        ic(i+1)=ic(i)+ndofpe(k)
c      print *, 'ic(i+1) inside elconnect =', ic(i+1)
c      pause
c
c      read(5,*) ithel,nodei,nodej
c      print *, 'Read inside elconnect'
c      write(6,*) 'ithel,nodei,nodej =', ithel,nodei,nodej
c      print *, 'ithel,nodei,nodej =', ithel,nodei,nodej
c      pause
c      Use for 2D truss
c      lm(1)=nodei*ndofpn-1
c      lm(2)=lm(1)+1
c      lm(3)=nodej*ndofpn-1
c      lm(4)=lm(3)+1
c      print *, 'nodei=', nodei
c      print *, 'ndofpn=', ndofpn
c
c      Use below for 3D Truss
c      lm(1)=nodei*ndofpn-2
c      lm(2)=lm(1)+1
c      lm(3)=lm(1)+2
c      lm(4)=nodej*ndofpn-2
c      lm(5)=lm(4)+1
c      lm(6)=lm(4)+2
c      locbegin=(ithel-1)*ndofpe(k)
c      print *, 'ithel=', ithel
c      print *, 'nodei=', nodei
c      print *, 'nodej=', nodej
c      print *, 'ndofpn=', ndofpn
c      print *, 'lm(1)=', lm(1)
c      print *, 'lm(2)=', lm(2)
c      print *, 'lm(3)=', lm(3)
c      print *, 'lm(4)=', lm(4)
c      print *, 'lm(5)=', lm(5)
c      print *, 'lm(6)=', lm(6)
c      print *, 'locbegin=', locbegin
c      pause
c      do 23 j=1,ndofpe(k)
c        locate=locbegin+j
c        jc(locate)=lm(j)
c
c      print *, 'locate=', locate
c      print *, 'jc(locate)=', jc(locate)
c      pause
c
c      print *, 'lm(j)=', lm(j)
c      print *, 'jc(locate)=', jc(locate)
c
c      pause
23 continue
22 continue
go to 21
32 continue ! 3-d beam
icadd=icadd+nel(k-1) ! to include previous 2-d truss elements
locadd=locadd+nel(k-1)*4
go to 21
33 continue ! 4-node (24 dofpe) rect. plate bending+membrane
icadd=icadd+nel(k-1) ! to include previous 3-d beam elements
locadd=locadd+nel(k-1)*12
c      print *, 'numel=', numel
c      pause
c      do 42 i=1,numel
c        ic(i+1+icadd)=ic(i+icadd)+ndofpe(k)
c
c      read(5,*) ithel,nodei,nodej,nodek,nodej
c      write(6,*) 'ithel,nodei,nodej,nodek,nodej'
c      write(6,*) 'ithel,nodei,nodej,nodek,nodej'
c
c      lm(1)=nodei*ndofpn-5
c      lm(2)=lm(1)+1
c      lm(3)=lm(2)+1
c      lm(4)=lm(3)+1
c      lm(5)=lm(4)+1
c      lm(6)=lm(5)+1
c
c      lm(7)=nodej*ndofpn-5
c      lm(8)=lm(7)+1
c      lm(9)=lm(8)+1
c      lm(10)=lm(9)+1
c      lm(11)=lm(10)+1
c      lm(12)=lm(11)+1
c
c      lm(13)=nodek*ndofpn-5
c      lm(14)=lm(13)+1
c      lm(15)=lm(14)+1
c      lm(16)=lm(15)+1
c      lm(17)=lm(16)+1
c      lm(18)=lm(17)+1
c
c      lm(19)=nodek*ndofpn-5
c      lm(20)=lm(19)+1
c      lm(21)=lm(20)+1
c      lm(22)=lm(21)+1
c      lm(23)=lm(22)+1
c      lm(24)=lm(23)+1
c
c      locbegin=(ithel-1)*ndofpe(k)
c      do 43 j=1,ndofpe(k)
c        locate=locbegin+j
c        jc(locate+locadd)=lm(j)
43 continue
42 continue
go to 21
34 continue ! other f.e. type
go to 21
21 continue
c      icall=nel(1)+nel(2)+nel(3)+nel(4)+nel(5)+nel(6)
cc      jeall=nel(1)*4 + nel(2)*12 + nel(3)*24
c      jeall=nel(1)*6 + nel(2)*12 + nel(3)*24
c      print *, 'jeall=', jeall
c      pause
c
c      write(6,*) 'jeall = sum all el types =', jeall
c      write(6,*) 'je =', (je(i),i=1,jeall+1)
c      write(6,*) 'je =', (je(i),i=1,jeall)
c      print *, 'jeall = sum all el types =', jeall
c      print *, 'jeall =', jeall
c      print *, 'je =', (je(i),i=1,jeall+1)
c      print *, 'je =', (je(i),i=1,jeall)
c      pause
c      return
end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%subroutine loads(ndof,b,loadof,exfor)
%implicit real*8(a-h,o-z)
c
c.....Purpose: Input applied loads at the joints
c
c      dimension b(1),exfor(*)
c
c      write(6,*) 'inside loads: ndof =', ndof
c      print *, 'inside loads'
c
c      do 1 i=1,ndof
c        b(i)=0.0 ! load vector
1 continue
c
c      do 18 i=1,loadof
c        read(5,*) loadof, value
c        write(6,*) 'loadof, value'
c        write(6,*) 'loadof, value'
c
c      print *, 'loadof=', loadof
c      print *, 'value=', value
c      pause
c
c      b(loadof)=value
c      exfor(loadof)=value
18 continue
c      print *, 'exfor inside load=', (exfor(i),i=1,ndof)
c      stop
c      return
end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%subroutine supportdof(iboundc,nboundc,b,ndof,ia)
%implicit real*8(a-h,o-z)
c

```

```

c.....Purpose: input support dof information
c
    dimension iboundc(1),    b(1),ia(1)

    do 18 i=1,ndof
    iboundc(i)=0
18  continue
c.....input the boundary condition flag
    do 19 i=1,nboundc
    read(5,*) ibcdof, settlem
    write(6,*) 'ibcdof, settlem = ',ibcdof,settlem
    iboundc(ibcdof)=1
    b(ibcdof)=settlem
    print *,b(i) inside supportdof=b(i)
19  continue
c
c    pause
c    write(6,*) 'ibcdof = ', ibcdof
c    write(6,*) 'load and settlement b(-) = ', (b(i),i=1,ndof)
c.....copy boundary flag for later usage in Duc's sparse symbolic assembly
    do 3 i=1,ndof
    if ( iboundc(i) .eq. 0 ) ia(i)=0
    if ( iboundc(i) .eq. 1 ) ia(i)=ndof
3  continue
    return
end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
subroutine assembly(ip,ad,an,lm,ie,jc,propmat,
c $    propsect,elk,bc,b,iboundc,
c $    propsect,bc,b,iboundc,
c $    ae,ia,ja,xx,yy,zz,ncocf1,maxdofpc,
c $    ae,ia,ja,ncocf1,maxdofpc,
c $    ae,ia2,ja,xx,yy,zz,ncocf1,maxdofpc,
c $    ndof,neltype,nel,ndofpc,ianal,lumpmass,dm,am,elm,
c $    tempo1,disp,iarc,it,area,youngm,esm,qk,itnrmilon)
c $    tempo1,disp,iarc,it,area,youngm,qk,itnrmilon,istep,icheck,
c $    zec,dlen,cm,ex)

    implicit real*8(a-h,o-z)

c
c    Purpose: perform sparse numerical assembly
c
c
    dimension ip(1),ad(1),an(1),lm(1),ie(1),jc(1),propmat(1)
c $,    propsect(1),bc(1),b(1),iboundc(1)
c $,    propsect(1),elk(maxdofpc,maxdofpc),bc(1),b(1),iboundc(1)
c $,    ae(1),ia(1),ja(1),xx(500),yy(500),zz(500),nel(1),ndofpc(1)
c $,    ac(1),ia2(1),ja2(1),xx(1),yy(1),zz(1),nel(1),ndofpc(1)
    dimension dm(1),am(1),elm(maxdofpc,1),tempo1(1)

    common/infor/getforce,finx(2),finy(2),finz(2),getstiff,getsolve
    common/isp/ux(2),uy(2),uz(2),P(6),B(1(6)

    common/jam/ja2(100)
c    common/detype/ityp,itruss    !ityp = 6 for 2-D, =12(3D truss)

c
c    dimension ux(2),uy(2),finx(2),finy(2)
c    dimension disp(*),qk(*)

c
c    dimension lm2(6)

c
c    dimension elk(6,6)

c
c    print *,'je start assembly=',(jc(ic),ic=1,10)
c    pause
c    print *,'B(-) start assembly=',(b(ic),ic=1,ndof)
c    pause

c    double precision, allocatable:: b(-,:)
c    allocate elk(maxdofpc,maxdofpc)

c
c    dimension ja(1)

c
c    print *,'Getstiff start assembly=',getstiff
c    print *,'Getforce start assembly=',getforce
c    print *,'Getsolve start assembly=',getsolve
c    pause

c
c    If(getsolve .eq. 1)Then
c    Goto 670
c    Endif

c
c    If(getforce .eq. 1)Then !Skip ad & ae =0,just getforce
c    Goto 699
c    Endif

c
c    print *,'S T A R T O F A S S E M B L Y'
c    print
c    *,'XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX'
c    print *,'Setting ad, an & ae to zero'
c    Do 701 ic=1,ndof
c    ad(ic)=0.0 !Stiffness diagonal

c
c    an(ic)=0.0 !Stiffness off diagonal

701  continue

c
c    Do 702 ic=1,10000
c    an(ic)=0.d0

702  continue

c
c    print *,'b(-) at start2 of assembly=',(b(ic),ic=1,ndof)
c    pause
c    Do 702 ic=1,100
c    ac(ic)=0.0
c702  continue
c    print
c    *,'XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX'
c    pause
c699  Continue

c
c    print *,'idir at start of assembly=',(idir(ic),ic=1,ndof)
c    pause

c
c    print *,'qk(-) at start of assembly=',(qk(ic),ic=1,ndof)
c    print *,'b(-) at start of assembly=',(b(ic),ic=1,ndof)
c    pause
c    print *,'ia start of assembly=',(ia(i),i=1,15)
c    print *,'ja2(i)=',(ja2(ic),ic=1,10)
c    print *,'ja(1)=',ja(1)
c    print *,'ja start of assembly=',(ja(i),i=1,1)
c    print *,'ndofpc = ',ndofpc
c    stop

c
c    If(getforce .eq. 1)then
c    Do 777 i = 1,10
c    ja(i)=ja2(i)
c    Print *,'ja2(i) inside start assembly=',ja2(i)
c777  Continue
c    pause
c    Endif

c
c    if(it .eq. 2)then
c    print *,'it =2'
c    print *,'ianal=',ianal
c    stop
c    endif
c
c    print *,'getforce=',getforce
c    stop
c
c    print *,'chk inside assembly at start'
c    print *,'getstiff=',getstiff
c    print *,'getforce=',getforce
c    pause
c
c    print *,'xx inside assembly =',(xx(i),i=1,42)
c    print *,'yy inside assembly =',(yy(i),i=1,42)
c    print *,'zz inside assembly =',(zz(i),i=1,42)
c    print *,'lm inside assembly =',(lm(i),i=1,6)
c    print *,'_____
c    pause
c    stop

c
c    pause

c
c    If(getforce .eq. 1)then
c    print *,'getforce=1 at start of assembly'
c    stop
c    endif

c
c    write(6,*)'ia2 start of assembly=',(ia2(i),i=1,ndof+1)
c    print *,'chk inside assembly'
c    print *,'iarc inside assembly=',iarc
c    print *,'ianal inside assembly=',ianal
c    print *,'neltype=',neltype
c    print *,'ncocf1=',ncocf1
c    print *,'ndof=',ndof
c    ncocf2=ncocf1
c    print *,'ip=',(ip(i),i=1,ndof)
c    stop
c    print *,'b=',(b(i),i=1,ndof)
c    pause
c    print *,'ia2 start assembly=',(ia2(i),i=1,ndof+1)
c    stop

c.....initialize before numerical sparse assembling
    do 96 j=1,ndof
96  ip(j)=0
cccc  blanked out below don't need dynamics
cccc  if (ianal .eq. 1) dm(j)=0.
cccc 96  ad(j)=0.
c 96  continue
cccc  something not write with ncocf1???
cc    ncocf1=ncocf2

c
c    write(6,*)'ncocf1 start assembly=',ncocf1
c    print *,'ncocf1=',ncocf1
c    stop
cccc  do 95 j=1,ncocf1
cccc  if (ianal .eq. 1 .and. lumpmass .eq. 0) then
cccc  am(j)=0.
cccc  endif
cccc 95  an(j)=0.
c
c    print *,'neltype=',neltype
c    stop

c
c    if(it .eq. 2)then
c    print *,'it =2'
c    print *,'neltype=',neltype
c    stop
c    endif

c
c    write(6,*)',neltype in assembly=',neltype
c    stop

c670  Continue !skipped above when getsolve=1
c**** START OF DO 98 *****
DO 98 k=1,neltype

c
c    numel=nd(k)
c
c    print *,'numel=',numel
c
c    pause
c
c    if(it .eq. 2)then
c    print *,'it =2'
c    print *,'ianal=',ianal
c    print *,'numel=',numel
c    stop
c    endif

c
c    stop

```

```

      if (numel .eq. 0) go to 98
c.....loop for all elements
c      print *, 'start loop for all elements'
c      print *, 'ncoef1=', ncoef1
c      print *, 'numel =', numel
c      pause
c      stop

      DO 4 iel=1,numel
c      print *, 'iel =', iel
c      print *, '*****'

c      If (getforce .eq. 1) then
c      goto 400
c      endif

c      pause
c      print *, 'numel=', numel
c      pause
c      stop

c      write(6,*) 'inside assembly: truss el #, nel(1) =', iel, nel(1)
c.....get the global dof associated with each element
c      print *, 'ndofpe(k)=', ndofpe(k)
c      iend=iel*ndofpe(k)
c      istart=iend-ndofpe(k)
c      print *, 'iend=', iend
c      print *, 'istart=', istart
c      print *, 'ndofpe(k)=', ndofpe(k)
c      pause

      do 76 j=1,ndofpe(k)
c      print *, 'j=', j
c      print *, 'j*(istart+j)-', j*(istart+j)
c      write(6,*) 'lm(j)=', lm(j)

      lm(j)=j*(istart+j)
c      continue
c      print *, 'j*(istart+j)-', j*(istart+j)
c      print *, 'lm 2 inside assembly =', (lm(i), i=1,6)
c      pause

c      print *, 'iarc=', iarc
c      pause
c      stop

      if (iarc .eq. 1) then
c      ix1dof=lm(1)
c      iy1dof=lm(2)
c      iz1dof=lm(3)
c      ix2dof=lm(4)
c      iy2dof=lm(5)
c      iz2dof=lm(6)
c      print *, 'lm(6)=', lm(6)

c      ux(1)=ux(1)+disp(ix1dof)
c      uy(1)=uy(1)+disp(iy1dof)
c      uz(1)=uz(1)+disp(iz1dof)
c      ux(2)=ux(2)+disp(ix2dof)
c      uy(2)=uy(2)+disp(iy2dof)
c      uz(2)=uz(2)+disp(iz2dof)

c      ux(1)=ux(1)+qk(ix1dof)
c      uy(1)=uy(1)+qk(iy1dof)
c      uz(1)=uz(1)+qk(iz1dof)
c      ux(2)=ux(2)+qk(ix2dof)
c      uy(2)=uy(2)+qk(iy2dof)
c      uz(2)=uz(2)+qk(iz2dof)
c      print *, 'qk(ix1dof)=', qk(ix1dof)
c      stop
c      ux(1)=qk(ix1dof)
c      uy(1)=qk(iy1dof)
c      uz(1)=qk(iz1dof)
c      ux(2)=qk(ix2dof)
c      uy(2)=qk(iy2dof)
c      uz(2)=qk(iz2dof)
c      print *, 'ix1dof=', ix1dof

c      print *, 'iy1dof=', iy1dof
c      print *, 'iz1dof=', iz1dof
c      print *, 'ix2dof=', ix2dof
c      print *, 'iy2dof=', iy2dof
c      print *, 'iz2dof=', iz2dof
c      print *, 'ux(1)=', ux(1)
c      print *, 'uy(1)=', uy(1)
c      print *, 'uz(1)=', uz(1)
c      print *, 'ux(2)=', ux(2)
c      print *, 'uy(2)=', uy(2)
c      print *, 'uz(2)=', uz(2)
c      pause
c      stop

      If (getforce .eq. 1) then
c      print *, 'ix1dof=', ix1dof

c      print *, 'iy1dof=', iy1dof
c      print *, 'iz1dof=', iz1dof
c      print *, 'ix2dof=', ix2dof
c      print *, 'iy2dof=', iy2dof
c      print *, 'iz1dof=', iz1dof
c      print *, 'ux(1)=', ux(1)
c      print *, 'uy(1)=', uy(1)
c      print *, 'uz(1)=', uz(1)
c      print *, 'ux(2)=', ux(2)
c      print *, 'uy(2)=', uy(2)
c      print *, 'uz(2)=', uz(2)
c      write(6,*) 'ix1dof=', ix1dof
c      write(6,*) 'iy1dof=', iy1dof
c      write(6,*) 'iz1dof=', iz1dof
c      write(6,*) 'ix2dof=', ix2dof
c      write(6,*) 'iy2dof=', iy2dof
c      write(6,*) 'iz2dof=', iz2dof
c      write(6,*) 'ux(1)=', ux(1)
c      write(6,*) 'uy(1)=', uy(1)
c      write(6,*) 'uz(1)=', uz(1)
c      write(6,*) 'ux(2)=', ux(2)
c      write(6,*) 'uy(2)=', uy(2)
c      write(6,*) 'uz(2)=', uz(2)

```

```

c      stop
c      endif

c      print *, 'chk 2 inside assembly'
c      stop
c      pause

c      if (it .eq. 2) then
c      print *, 'it = 2'
c      print *, 'ianal=', ianal
c      stop
c      endif

c      print *, 'chk before info_elstif inside assembly'
c      pause
c      print *, 'lm 3 inside assembly =', (lm(i), i=1,6)

c      print *, 'xx inside assembly before info_ =', (xx(i), i=1,42)
c      print *, 'yy inside assembly before info_ =', (yy(i), i=1,42)
c      print *, 'zz inside assembly before info_ =', (zz(i), i=1,42)
c      pause
c      print *, '*****'
c      print *, 'before "call info_elstif" '
c      pause

c      print *, 'xlengh before info_elstif=', xlengh
c      print *, 'xli before info_elstif=', xli
c      pause
c      print *, 'je before info_elstif=', (j(ic), ic=1,10)
c      pause
c      print *, 'B( ) before info_elstif in assembly=', (b(ic), ic=1,ndof)
c      pause
c      If (cx .eq. 10) then
c      goto 1900
c      call info_ex(iel, xlengh, xl, cx, cy, cz, xx, yy, zz, ic, je
c      $, propmat, propsect, youngm, arca, rho,
c      $ deltaxi, deltaxi, deltaxi, xli,
c      $ xi, xi, yi, yi, zi, zi, AE, zee, dLength)
c      Else
c      call info_elstif(iel, xlengh, xl, cx, cy, cz, xx, yy, zz, ic, je
c      $, propmat, propsect, youngm, arca, rho,
c      $ deltaxi, deltaxi, deltaxi, xli,
c      $ xi, xi, yi, yi, zi, zi)
c      Endif

1900 CONTINUE Idummy

c      print *, 'xx inside assembly after info_ =', (xx(i), i=1,42)
c      print *, 'yy inside assembly after info_ =', (yy(i), i=1,42)
c      print *, 'zz inside assembly after info_ =', (zz(i), i=1,42)
c      pause
c      print *, '*****'
c      print *, 'after "call info_elstif" '
c      print *, 'B( ) after info_elstif in assembly=', (b(ic), ic=1,ndof)
c      pause

c      print *, 'xlengh after info_elstif=', xlengh
c      print *, 'xli after info_elstif=', xli
c      pause

      ndofped=ndofpe(k)
c      write(6,*) 'inside assembly: ndofped =', ndofped
c      print *, 'chk before elstif inside assembly'
c      stop
c      print *, 'lm 3a inside assembly =', (lm(i), i=1,6)

c      pause
c      call elstif(ndofped, el, k, bc,
c      $ arca, youngm, xlengh, cx, cy, cz, maxdofpe,
c      $ ityp, xl, xli, deltaxi, deltaxi, deltaxi, xx, yy, zz,
c      $ finx, finy, finz, iarc)
c      call elstif(ndofpe, esm, bc,

c      print *, 'xx inside assembly before elstif= ', (xx(i), i=1,42)
c      print *, 'yy inside assembly before elstif= ', (yy(i), i=1,42)
c      print *, 'zz inside assembly before elstif= ', (zz(i), i=1,42)
c      print *, '*****'
c      print *, 'Before elstif inside assembly'
c      pause
c      print *, 'xlengh before elstif=', xlengh
c      print *, 'xli before elstif=', xli
c      pause

c      print *, 'iel before call elstif=', iel
c      pause

      call elstif(ndofpe, el, k, bc,
c      $ arca, youngm, xlengh, cx, cy, cz, maxdofpe,
c      $ xl, xli, deltaxi, deltaxi, deltaxi, xx, yy, zz,
c      $ iarc, xi, xi, yi, yi, zi, zi, ityp, lm, istop, iel, icheck, rex)

c      print *, 'xlengh after elstif=', xlengh
c      print *, 'xli after elstif=', xli
c      pause

c      print *, 'xx inside assembly after elstif= ', (xx(i), i=1,4)
c      print *, 'yy inside assembly after elstif= ', (yy(i), i=1,4)
c      print *, 'zz inside assembly after elstif= ', (zz(i), i=1,4)
c      print *, '*****'
c      print *, 'After elstif inside assembly'
c      pause

c      print *, 'lm 3b inside assembly =', (lm(i), i=1,6)
c      pause
c      print *, 'Check after elstif'

c      print *, 'idir after elstif in assembly=', (idir(ic), ic=1,ndof)
c      pause

```



```

C*** resk = residual force at load step k (or i),
C*** FRk (or FRi), (real, vector)
C*** scali = scale factor for load step i, Si, (real, vector)
C*** stifi = tangent stiffness at i, KTi, (real, matrix)
C*** stik = tangent stiffness at k, KTK, (real, matrix)
C***
C*****
*
implicit real*8(a-h,o-z)
c parameter (nq=2)

common/RIK/ stifi(20,20),dqk(5000),dqk1(5000),
$ dqk2(5000),fintk(5000),
$ resk(5000),scali(5000),work1(5000),indx(5000),neq

c common/deltaq/dqk(500)

common/av/a(1500),jgfcjgsm,np,nbw,np2,nbw2
c common/disp/ux(2),uy(2),uz(2),disp(500)
common/mfor/getforce,finx(2),finy(2),finz(2),getstiff,getsolve
common/testing/toldis,tolfor,exlmax,iconv
common/nodefor/bstor(500),bvtor(500)

common/jam/ja2(100)

c common/etype/ityp,itruss !ityp = 6 for 2-D, =12(3D truss)

c double precision, allocatable: dqtot(:),dqic(:),dqim1(:),qk(:)
double precision, allocatable: dqtot(:),dqic(:),dqim1(:)
integer, allocatable: itempo2(:)
c double precision, allocatable: ja(:)

c dimension disp(*),b(*),ia(*),iperi(*),qk(*)
c dimension disp(*),b(*),ia1(*),ia2(*),iperi(*)
c dimension ic(*),ie(*),iet(*),iet(*),ae(*),ad(*)
c dimension iboundc(*),an(*),ux(*),uy(*),di(*),exfor(*)
c dimension x(*),y(*),z(*),ip(*),lm(1),ju(*)
c dimension ja(*),x(*),y(*),z(*),ip(*),lm(1),ju(*)

c dimension elk(maxdofpe,maxdofpe)

c ... open files for output
c open(15,file='fearc_out.txt',status='old')
c open(12,file='fearc_out_F.txt',status='old')
c open(13,file='fearc_out_q1.txt',status='old')

c open(15,file='fea3d2_out.txt',status='old')
c open(12,file='fea3d2_out_F.txt',status='old')
c open(13,file='fea3d2_out_q1.txt',status='old')

c open(14,file='fea3d2_out_q2.txt',status='old')

c allocate (ja(50))

c neq=ndof
c print *, 'numnodes=', numnodes
c print *, 'x start rik =',(x(i),i=1,numnodes)
c print *, 'y start rik =',(y(i),i=1,numnodes)
c print *, 'z start rik =',(z(i),i=1,numnodes)
c stop
c print *, 'b start rikarc =',(b(i),i=1,ndof)
c stop
c print *, 'jgsm =', jgsm
cc print *, 'np =', np
c print *, 'neq inside Rikarc =', neq
c print *, 'a at start of RIK =', a
c print *, 'dq1 at start of RIK =', dq1
c print *, 'start of RIK'
c print *, 'ityp start RIK =', ityp
c print *, 'ndof start RIK =', ndof
c stop
c print *, 'maxdofpe =', maxdofpe

c stop
c pause
c ... define user input
c** d10 = starting incremental external load multiplier
c d10 = 2.5d-2
ccccc d10 = 1.d-2
c d10 = 1.d-1
c4 d10 = 1.d0
cc d10 = 1.d-3
ccc d10 = .001
C*** dlmax = maximum allowable incremental external load
C*** multiplier, delta lambda max, (real, scalar)
C*** dlmin = minimum allowable incremental external load
C*** multiplier, delta lambda min, (real, scalar)
c dlmax = 2.6d-2
ccccc dlmax = 1.d-2
ccccc dlmin = 1.d-3
ccc dlmax = 1.d-3
ccc dlmin = 1.d-4
cc dlmax = 1.d-4
cc dlmin = 1.d-5
ccccc dlmax = .1
ccccc dlmin = .01
ccccc dlmax = 1.
ccccc dlmin = .1
c4 dlmax = 1000.
c4 dlmin = 10.
c4 dlmin = 1.
c** Use below for truss1
c dlmax = 1.d-0
c dlmin = 1.d-1
c** Use below for truss2
c dlmax = 1.d+1
c dlmin = 1.d-0
c** read in the initial forces from big "a"
cc print *, 'jgfc =', jgfc
c stop
cc print *, 'exfor at start of RikArc =', exfor

c stop
c exfor(1) = 1.55d0
c exfor(2) = 1.45d0
C*** exlmax = maximum allowable total external load
C*** multiplier, lambda max, (real, scalar)
ccccc exlmax = 1.d0
ccccc exlmax = 5.d0
cc exlmax = .2d0
cc exlmax = .1d0
c4 exlmax = 100.d0

c itedes = 4
c itedes = 1
c itemax = 20000
c itemax = 999999
c itemax = 1500
c itemax = 900000

itemax = 1000000

cc mxstp = 60
czzz mxstp = 1500
ccc mxstp = 25000

mxstp = 1000000 !step

ccccc toldis = 1.d-3
ccccc tolfor = 1.d-3
c4x toldis = 1.d-2
c4x tolfor = 1.d-2
ccccc toldis = .5
ccccc tolfor = .5
c4 toldis = 1.d-1
c4 tolfor = 1.d-1
c toldis = 1.5d0
c tolfor = 1.5d0
C*****
c** Truss_2bay_3D.dat
C** Symmetric
C** This is 6 nodes, 11 element
c itedes = 1
c d10 = .01d0
c dlmax = .001d0
c dlmin = .0001d0
c exlmax = 1.d0
c toldis = 1.d-6
c tolfor = 1.d-6
C*****
C** Two Bar Truss
C** Symmetric
C** This is 3 nodes, 2 element
cc itedes = 1
cc d10 = .01d0
cc dlmax = .01d0
cc dlmin = .001d0
cc exlmax = 1.d0
cc toldis = 1.d-6
cc tolfor = 1.d-6
c print *, 'Check After input'
c pause
C*****
C** Tripod
C** Crisfield 3.10.2
C** This is 4 nodes, 2 element
cpod itedes = 1
cpod d10 = .1d0
cpod dlmax = .001d0
cpod dlmin = .0001d0
cpod exlmax = 1.d0
cpod toldis = 1.d-6
cpod tolfor = 1.d-6
c toldis = 1.d-12
c tolfor = 1.d-12
C*****
C** Crisfield truss, ex 22.4a, vol2 chap 22.4, page 407
C** cris_22_4a_in.dat 6nodes, 9 elements
c itedes=1
c d10 = .1d0
c dlmax = .01d0
c dlmin = .001d0
c exlmax = 1.d0
c toldis = 1.d-6
c tolfor = 1.d-6
C*****
C** Duc truss, truss11_3d_in.dat
C** Duc truss, truss11_3d_xz_in.dat
C** This is a 6 nodes, 11 elements,
c itedes=1
c d10 = .01d0
c dlmax = .0001d0
c dlmin = .00001d0
c exlmax = 1.d0
c toldis = 1.d-6
c tolfor = 1.d-6
C*****
C** Duc truss, truss10_3d_in.dat
C** This is a 6 nodes, 10 elements,
c itedes=1
c d10 = .01d0
c dlmax = .001d0
c dlmin = .0001d0
c exlmax = 1.d0
c toldis = 1.d-6
c tolfor = 1.d-6
C*****
C** Duc truss, truss7_3d_in.dat

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C** This is a 5 nodes, 7 elements,
ctruss      itedes=1
ctruss      d0 = .01d0
ctruss      d0max = .001d0
ctruss      d0min = .0001d0
ctruss      exlmax = 1.d0
ctruss      toldis = 1.d-4
ctruss      tolfir = 1.d-4
C*****
C** The following are used for test problem Truss3in.dat & T4in.dat
C** This is a 2 ele, 3 node problem, results agree with Crisfield
c      d0 = .1d0
c      d0max = .001
c      d0min = .0001
c      exlmax = 1.d0
c      toldis = .00001
c      tolfir = .00001d0
C*****
C** The following are used for test problem T3in.dat
C** This is a 3 ele, 3 node problem, results agree with Crisfield
c      d0 = .1d0
c      d0max = .01
c      d0min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfir = .01d0
C*****
C** The following are used for test problem T3xin.dat & T3ain.dat
C** This is a 6 ele, 4 node problem, results agree with Crisfield
c      d0 = .1d0
c      d0max = .01
c      d0min = .001
c      exlmax = 1.d0
c      toldis = .00001d0
c      tolfir = .00001d0
C*****
C** The following are used for test problem T3xin.dat
C** This is a 6 ele, 4 node problem, results agree with nastran
c      d0 = .1d0
c      d0max = .1
c      d0min = .01
c      exlmax = 1.d0
c      toldis = .000001d0
c      tolfir = .01d0
C*****
C** The following are used for test problem T4xxin.dat GOOD
C** This is a 10 ele, 7 node problem, results agree with nastran
c      d0 = .1d0
c      d0max = .1d0
c      d0min = .01d0
c      exlmax = 1.d0
c      toldis = 1.d-9
c      tolfir = 1.d-9
C*****
C** Crisfield small arch, arch20in.dat
C** This is a 10 nodes, 20 element,
c      d0 = .1d0
c      d0max = .001d0
c      d0min = .0001d0
c      exlmax = 1.d0
c      toldis = 1.d-7
c      tolfir = 1.d-7
C*****
C** Crisfield small arch, arch18in.dat
C** This is a 18 nodes, 41 element,
c      d0 = .01d0
c      d0max = .001d0
c      d0min = .0001d0
c      exlmax = 1.d0
c      toldis = 1.d-5
c      tolfir = 1.d-5
C*****
C** Crisfield small arch, arch10_3D_in.dat
C** This is a 10 nodes, 21 element,
c      itedes=1
c      d0 = .001d0
c      d0max = .001d0
c      d0min = .0001d0
c      exlmax = 1.d0
c      toldis = 1.d-6
c      tolfir = 1.d-6
C*****
C** Crisfield small arch, arch18_3D_in.dat
C** This is a 18 nodes, 41 element,
c      itedes=5
c      d0 = .01d0
c      d0max = .005d0
c      d0min = .0005d0
c      exlmax = 1.d0
c      toldis = 1.d-6
c      tolfir = 1.d-6
C*****
C** Crisfield large symmetry arch, arch22in.dat
C** This is a 22 nodes, 51 elements,
cc      d0 = .1d0
cc      d0max = .1d0
cc      d0min = .01d0
cc      exlmax = 1.d0
cc      toldis = 1.d-3
cc      tolfir = 1.d-4
C*****
C** Crisfield small arch, arch42_3D_in.dat
C** arch3din.dat
C** This is a 42 nodes, 101 element,
c      itedes=1
c      d0 = .1d0
c      d0max = .01d0
c      d0min = .0001d0
c      exlmax = 1.d0
c      toldis = 1.d-4
c      tolfir = 1.d-4
C*****
C*****
C** Crisfield small arch, arch42in.dat
C** arch10_3D_in.dat
C** This is a 21 nodes, 10 element,
carch      itedes=1
carch      d0 = .01d0
carch      d0max = .01d0
carch      d0min = .001d0
carch      exlmax = 1.d0
carch      toldis = 1.d-4
carch      tolfir = 1.d-4
C*****
C** Duc frame example frame_in.dat
C**
C** This is a 4 nodes, 5 element,
c      itedes=1
c      d0 = .01d0
c      d0max = .001d0
c      d0min = .0001d0
c      exlmax = 1.d0
c      toldis = 1.d-6
c      tolfir = 1.d-6
C*****
c      itedes=2
c      d0 = .025d0
c      d0max = 8.d-3
c      d0min = 5.d-3
c      exlmax = 1.d0
c      toldis = 1.d-3
c      tolfir = 1.d-4
C*****
C*****
C** t3a_in.dat
C** This is a 3 nodes, 3 element,
ct3a      itedes=1
ct3a      d0 = .00001d0
ct3a      d0max = 1.d-3
ct3a      d0min = 1.d-4
ct3a      exlmax = 1.d0
ct3a      toldis = 1.d-6
ct3a      tolfir = 1.d-6
C*****
C** 3D Truss , Td3_in.dat
C** This is a 4 nodes, 3 elements,
c      d0 = .1d0
c      d0max = .01d0
c      d0min = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-5
c      tolfir = 1.d-5
C*****
C** 3D Truss , Dome_in.dat & Dome2_in.dat
C** This is a 13 nodes, 24 elements,
cdome      itedes=1
cdome      d0 = .1d0
cdome      d0max = .1d0
cdome      d0min = .001d0
cdome      exlmax = 1.d0
cdome      toldis = 1.d-6
cdome      tolfir = 1.d-6
C*****
C** Khot_shallow_truss
C**
ckhot      itedes=1
ckhot      d0 = .001d0
ckhot      d0max = .001d0
ckhot      d0min = .0001d0
ckhot      exlmax = 1.d0
ckhot      toldis = 1.d-4
ckhot      tolfir = 1.d-4
C*****
C** snap_in.dat
C** This is a 4 nodes, 3 elements,
csnap      itedes=1
csnap      d0 = .01d0
c      d0 = .5d0
csnap      d0max = .1d0
csnap      d0min = .00001d0
csnap      exlmax = 1.d0
csnap      toldis = 1.d-4
csnap      tolfir = 1.d-4
C*****
C*****
C** 3D Truss , twobar_in.dat !Similar to Crisfield 22.1
C** large bifurcation
C** This is a 3 nodes, 2 elements,
ctwo      itedes=1
ctwo      d0 = .001d0
c      d0 = .5d0
ctwo      d0max = .001d0
ctwo      d0min = .0001d0
ctwo      exlmax = 1.d0
ctwo      toldis = 1.d-6
ctwo      tolfir = 1.d-6
C*****
C*****
C** The following are used for test problem T4xin.dat & T4xxin.dat & T4in.dat
C** This is a 10 ele, 7 node problem, results agree with nastran
c      d0 = .1d0
c      d0max = .01d0
c      d0min = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-6
c      tolfir = 1.d-6
C*****
C** The following are used for test problem T5xxin.dat & T4xxin.dat
C** This is a 10 ele, 7 node problem, results agree with nastran
c      d0 = .1d0
c      d0max = .01d0

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c      d0 = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-5
c      tolfor = 1.d-4
C*****
C** The following are used for test problem T7in.dat
C** This is a 4 ele, 5 node problem, results agree with Crisfield
c      d0 = .01d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfor = .01d0
C*****
C** The following are used for test problem T7Ain.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
C** using these variables, this takes a long time 30+ min
c      d0 = .1d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfor = .01d0
C** The following are used for test problem T7Bin.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
C** try using different variables for faster
c      d0 = 1.d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfor = .01d0
C** The following are used for test problem T7Cin.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
C** try using different variables for faster
c      d0 = 1.d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfor = .01d0
C** The following are used for test problem T7Din.dat
C** This is a 6 ele, 5 node, 3 support problem, results agree with Crisfield
c      d0 = .01d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .001d0
c      tolfor = .001d0
C** The following are used for test problem T7Ein.dat
C** This is same as T7D above but use 2 supports instead of 3
C** This is a 6 ele, 5 node, 2 support problem
C** Trying to get a solution, do I need right bracketing or is program wrong?
c      d0 = .01d0
c      d1max = .01d0
c      d1min = .001d0
c      exlmax = 1.d0
c      9 works, try smaller
c      toldis = .9d0
c      tolfor = .9d0
C*****
C** The following are used for test problem T11in.dat
C** This is a 4 ele, 5 node problem, results agree with Crisfield
c      d0 = 1.d0
c      d1max = 1.
c      d1min = .1
c      exlmax = 100.d0
c      toldis = .99d0
c      tolfor = .99d0
C*****
C** The following are used for test problem T11m.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
c      d0 = 1.d0
c      d1max = .1
c      d1min = .01
c      exlmax = 1000.d0
c      toldis = .9d0
c      tolfor = .9d0
C*****
C** The following are used for test problem T11in.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
c      d0 = 1.d0
c      d1max = .1
c      d1min = .01
c      exlmax = 100.d0
c      toldis = .99d0
c      tolfor = .99d0
C*****
c ... end user input

C***Crisfield sdf
c      d0 = 1.0d-4
c      d1max = 1.0d-3
c      d1min = 1.0d-4
c      exfor(1) = -100.d0
C***Crisfield sdf

c      exfor(1) = 1.55d0
c      exfor(2) = 1.45d0
c>>> Arora's exact solution = {-397975,0.540417} <<<
c      d0 = 1.0d-5
c      d1max = 1.0d-5
c      d1min = 1.0d-6
c      exfor(1) = 0.d0
c      exfor(2) = -3.d0

c>>> Arora's nonlinear 2 ex = {-1/3, -1/2} <<<      OK

c      d0 = 1.0d-1
c      d1max = 1.0d-1
c      d1min = 1.0d-2
c      exlmax = 1.d0
c      itodes = 2
c      itemax = 100000
c      mxstp = 100000
c      toldis = 1.d-3
c      tolfor = 1.d-4

C***J. Dennis's opt. book page 172
c      d0 = 1.0d-6
c      d1max = 1.0d-3
c      d1min = 1.0d-4
c      exfor(1) = 3.d0
c      exfor(2) = 9.d0
c      exlmax = 1.d0
c      itodes = 2
c      itemax = 10000
c      mxstp = 10000
c      toldis = 1.d-3
c      tolfor = 1.d-4

C***Arora's nonlinear page 331 soln=(0,0)
c      d0 = 1.0d-1
c      d1max = 1.0d-1
c      d1min = 1.0d-2
c      exlmax = 1.d0
c      itodes = 2
c      toldis = 1.d-3
c      tolfor = 1.d-4

C***J. Dennis's opt book
c      d0 = 1.0d-9
c      d1max = 1.0d-10
c      d1min = 1.0d-11
c      exlmax = 1.d0
c      itodes = 2
c      toldis = 1.d-3
c      tolfor = 1.d-4
c      exfor(1) = 1.0d-10
c      exfor(2) = 1.0d-10

C***Hrinda 1      **OK**
c      d0 = 1.d-2
c      d1max = 1.d-3
c      d1min = 1.d-4
c      exlmax = 1.d0
c      itodes = 2
c      toldis = 1.d-3
c      tolfor = 1.d-4

C***Hrinda 2      **OK**
c      d0 = 1.d-10
c      d1max = 1.d-10
c      d1min = 1.d-11
c      exlmax = 1.d0
c      itodes = 2
c      toldis = 1.d-4
c      tolfor = 1.d-5

C***Hrinda 3      **OK**
c      d0 = 1.d-1
c      d1max = 1.d-2
c      d1min = 1.d-3
c      exlmax = 1.d0
c      itodes = 2
c      toldis = 1.d-4
c      tolfor = 1.d-5
c
C***POLY TEST      OK
c      d0 = 1.d-8
c      d1max = 1.d-8
c      d1min = 1.d-9
c      exlmax = 1.d0
c      itodes = 2
c      toldis = 1.d-3
c      tolfor = 1.d-4
C***Matlab ex
c      d0 = 1.d-3
c      d1max = 1.d-3
c      d1min = 1.d-4
c      exlmax = 1.d0
c      itodes = 2
c      toldis = 1.d-3
c      tolfor = 1.d-4

c      allocate (dqtot(ndof),dq1(ndof),dqim1(ndof),qk(ndof))
c      allocate (dqtot(ndof),dq1(ndof),dqim1(ndof))

c      ncoef1_guess=20000000
c      allocate ( itempo2(ncoef1_guess) )

c      print *, 'check BB'
c      pause

c ... initialize required variables
c
c      d0 = 0.d0
c      d1min1 = 0.d0
c      d1sq = 0.d0
c      d10 = 0.d0
c      d1 = 0.d0
c      d1m1 = 0.d0
c      d1max = 0.d0
c      d1min = 0.d0
c      exl = 0
c      istep = 1
c      it = 1
c
c      do 20 i=1,nex
c      do 10 j=1,nex

```

```

c          print *, 'chk before stiff'
c          pause
c          stiff(j,i) = 0.d0
c 10 continue
c
c          print *, 'check zz'
c          pause
c
c          dq(i) = 0.d0
c
c          print *, 'Check after dq'
c
c          pause
c          dqim1(i) = 0.d0
c          dqtot(i) = 0.d0
c          fintk(i) = 0.d0
c          qk(i) = 0.d0
c          resk(i) = 0.d0
c          scali(i) = 0.d0
c          work1(i) = 0.d0
20 continue
c
c          print *, 'exfor = ', (exfor(ic), ic=1, ndof)
c          pause
c          print *, 'iarc = ', iarc
c          print *, 'maxdofpe = ', maxdofpe
c          print *, 'iboundc = ', (iboundc(i), i=1, ndof)
c          stop
c
c          iskip = 0 ! When zero will go thru symfactd, 1 will skip symfactd
c          iturnon = 0 ! When zero not going thru "iturn1"
c          When one, inside "iturn1" telling sysqcn & assembly
c 999 if (exlk .le. exlms and. istep .le. mxstp) then
c
c          If(istep.eq.910)Then
c          itedes=1
c
c          dl0 = .01d0
c          dlmax = .000001d0
c          dlmin = .00000001d0
c          exlms = 1.d0
c          toldis = 1.d-8
c          tolfar = 1.d-8
c
c          print *, 'Change starting arc variables'
c          Endif
c
c          write(*,*) 'Beginning Load Step Number in RIKARC:', istep
c          print *, 'exlk start Rik = ', exlk
c          pause
c          stop
c          it = 1
c          if (istep .eq. 1) then
c          print *, '** CHECK A **'
c          pause
c          print *, 'je start istep=1 = ', (je(i), i=1, 20)
c
c          print *, 'getstiff = ', getstiff
c          print *, 'getforce = ', getforce
c          print *, 'getsolve = ', getsolve
c          pause
c
c          stop
c ... compute Kt0 for eqn. 4.107
c          print *, 'b before sysqcn = ', (b(i), i=1, ndof)
c          pause
c          stop
c          print *, 'maxdofpe = ', maxdofpe
c          print *, 'check before 1st sysqcn'
c          pause
c          stop
c          getstiff=1
c
c          call sysqcn(ne, ip1, b, ndof, disp, iarc, qk,
c          $ iearl, re, je, iet, iet, jearl, ia, ac, maxdofpe,
c          $ neltype, nel, ndofpe, x, y, z, propmat, propsect, lm,
c          $ iboundc, ad, an, iperm, ru, ip, iut, dqtot, dq, dqim1,
c          $ ux, uy, uz, di, it, area, youngm,
c          $ ianal, lumpmass, iskip, itempo2, iturnon, exfor, istep,
c          $ zee, dLength, icx)
c
c          write(6,*) 'ia2 after sysqcn = ', (ia2(i), i=1, ndof+1)
c          $ja, iboundc, ndofpe, be, lm, ndofpe, ad, ip, tempo1, dm, am, ianal, lumpmass)
c          print *, 'chk after sysqcn in rikarc'
c          print *, '*****'
c          print *, '*****'
c          print *, 'disp after 1st sysqcn = ', (disp(i), i=1, ndof)
c          print *, '*****'
c          print *, '*****'
c          pause
c          print *, 'iskip = ', iskip
c          print *, 'itempo2(1) after 1st sysqcn = ', itempo2(1)
c          pause
c
c          print *, 'b after 1st sysqcn = ', (b(i), i=1, ndof)
c          pause
c          stop
c          write(6,*) 'disp after 1st sysqcn = ', (disp(i), i=1, ndof)
c          write(6,*) 'ac stiff after 1st sysqcn = ', (ac(i), i=1, maxdofpe**2)
c          print *, 'ad stiff after 1st sysqcn = ', (ad(ic), ic=1, maxdofpe**2)
c          print *, 'an stiff after 1st sysqcn = ', (an(ic), ic=1, 50)
c          print *, 'ae stiff after 1st sysqcn = ', (ae(ic), ic=1, maxdofpe**2)
c          pause
c          stop
c
c          do 704 i=1, noq
c          scali(i) = 1.d0/stiff(i,i)
c          print *, 'a(neq**2+i) = ', a(neq**2+i)
c          scali(i) = 1.d0/a(neq**2+i) !!! Get diagonal
cc          scali(i) = 1.d0/ad(i) !!! Get diagonal
c
c          print *, 'scali = ', scali(i)
704 continue
c
c          stop
c          print *, 'a after sysqcn = ', a
c          stop
c          getstiff = 0
c          getforce = 0
c          ~~~~~~
c          print *, 'a = ', a
c          stop
c
c          stop
c
c          do 44 i=1, ndof
c          dqtot(i) = disp(i)
c          print *, 'dqtot(i) = ', (dqtot(i), i=1, ndof)
c          pause
c          write(6,*) 'dqtot( ) = ', (dqtot(i), i=1, ndof)
c          stop
c ... compute dqtot**2 for eqn. 4.109
c          dprdl = 0.d0
c          do 50 i=1, noq
c          dprdl = dprdl + dqtot(i)**2
c          print *, 'dprdl = ', dprdl
50 continue
c          write(6,*) 'dprdl = ', dprdl
cc          print *, 'dprdl = ', dprdl
c          stop
c ... compute ds0 using eqn. 4.109
c          ds0 = dl0*dsqrt(dprdl+1.d0)
c ... compute dsmax using user specified max load inc
c          dsmax = dlmax*dsqrt(dprdl+1.d0)
c ... compute dsmin using user specified min load inc
c          dsmin = dlmin*dsqrt(dprdl+1.d0)
c ... compute and store ds(i-1) for eqn. 4.110
c          dsim1 = ds0
c
c          print *, 'dsmax = ', dsmax
c          print *, 'dsmin = ', dsmin
c          print *, 'dsim1 = ', dsim1
c          pause
c          stop
c
c ... compute dq0 using eqn. 4.106, and store in dq0
c ... store dq0 in dqim1 for next load step
c ... update the total displacements qk
c          print *, 'dl0 & dqtot(i) = ', dl0, dqtot
c          print *, 'noq = ', noq
c
c          write(6,*) 'qk(i) before = ', (qk(i), i=1, noq)
c
c          print *, 'dl0 = ', dl0
c          print *, 'dqtot( ) = ', (dqtot(ic), ic=1, noq)
c          pause
c
c          do 60 i=1, noq
c          dq(i) = dl0*dqtot(i)
c          print *, 'dq(i) = ', dq(i)
c          dqim1(i) = dq(i)
c          print *, 'qk(i) before = ', qk
c          disp(i) = disp(i) + dq(i)
c          print *, 'dq(i) = ', dq(i)
c          print *, 'disp(i) = disp(i) + dq(i)', disp(i)
c          pause
c          qk(i) = qk(i) + dq(i)
c          print *, 'qk(i) after = ', qk(i)
c          pause
60 continue
c          write(6,*) 'dl0 = ', dl0
c          write(6,*) 'dqtot(i) = ', (dqtot(i), i=1, noq)
c          write(6,*) 'dq(i) = ', (dq(i), i=1, noq)
c          write(6,*) 'qk(i) = ', (qk(i), i=1, noq)
c          stop
c          print *, 'dqtot(i) = ', dqtot
c          print *, 'qk(i) = ', qk
c          pause
c          stop
c
c?? not sure ??
c** Put qk in "a"
ccc Do 61 i=qk = 1, noq
ccc a(iqk) = qk(iqk)
ccc 61 continue
c** Put qk in "disp"
ccc Do 61 i=qk = 1, noq
ccc disp(iqk) = qk(iqk)
61 continue
c          print *, '@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@'
c          print *, 'disp(i)=qk(k)', (disp(ic), ic=1, noq)
c          print *, '@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@'
c          pause
c
c          print *, 'a after insert qk = ', a
c          stop
c ... update the total external load multiplier totlk
c          exlk = exlk + dl0
c          print *, 'exlk = ', exlk
c ... store dl0 in dlim1 for next load step
c          dlim1 = dl0
c          print *, 'dlim1 = ', dlim1
c          pause
c ... compute the internal forces, fintk, at qk
c          getforce = 1 !!! Yes get internal force
c          print *, 'getforce = ', getforce
c          write(6,*) 'getforce = ', getforce
c          write(6,*) 'exlk = ', exlk
c          write(6,*) 'dl0 = ', dl0
c          write(6,*) 'b before 2nd sysqcn = ', (b(i), i=1, ndof)
c          stop
c          print *, 'a before 2nd sysqcn to getforce = ', a
c          stop
c          print *, 'b before 2nd sysqcn in RIK = ', it

```



```

c      do 71 i=1,nq
c        scali(i) = 1.d0/stifi(i)
c      c c print *,a(nq*2+i) = ,a(nq*2+i)
c        scali(i) = 1.d0/a(nq*3+i) !!!Get diagonal
c 71 continue
c      Endif
c~~~~~
c      print *,scali(i) check = ,(scali(kk),i=1,nq)
c      stop
c      do 70 i=1,nq
c        scali(i) = 1.d0/stifi(i)
c 70 continue
c ... solve eqn. 4.113 for dqtot
c      do 80 i=1,nq
c        dqtot(i) = exfor(i)
c 80 continue

c      print *,exfor(_)=,(exfor(ic),ic=1,ndof)
c      pause
c**Only solve
  Getstiff=0
    Getforce=0
    Getsolve=1
    call sysseqn(ne,iplvl,b,ndof,disp,iarc,qk,
$      icall,ic,je,je,je,je,call,ia,ac,maxdofpe,
$      neltpe,nel,ndofpe,x,y,z,propmat,propsect,lm,
$      iboundc,ad,an,iperm,iu,ip,iut,dqtot,dqi,dqim1,
$      ux,uy,uz,di,it,area,youngm,
$      ianal,lumpmass,iskap,itimep2,imrmlon,exfor,istep,
$      zoc,dlength,icx)

    Getsolve=0

    Do 82 i=1,nq
    dqtot(i)=disp(i) !get new disp(_) & set equal to dqtot(_)
82 continue

c      print *,dqtot(_)=,(dqtot(ic),ic=1,nq)
c      pause
c      put dqtot(i) into "a(i)" in place of force
c      jay=0
c~~~~~
c      If(ityp .eq. 6)Then
c        do 81 i=nq+1,nq*2
c          do 81 i=1,nq
c            jay=jay+1
c            a(i)=dqtot(jay)
c            b(i)=dqtot(jay)
c          print *,b(i)=,b(i)
c 81 continue
c          pause
c        Endif
c      If(ityp .eq. 12)Then
c        do 82 i=nq+1,nq*3
c          jay=jay+1
c          a(i)=dqtot(jay)
c 82 continue
c        Endif
c~~~~~
cc      print *,a w/dqtot=,a
c      stop
c      call solve(dqtot)
cc c      print *,stifi before ludcmp = ,stifi
c      call ludcmp(stifi,n,np,indx,x)
cc c      print *,stifi after ludcmp = ,stifi
c      stop
c      call lubksb(stifi,n,np,indx,dqtot)
cc c      print *,stifi after ludcmp = ,stifi

c      write(*,*) 'Before dcmpbd inside rikarc'
c      stop
cc      ipick = 3
c      call dcmpbd
c      stop
c      write(*,*) 'After dcmpbd inside rikarc'
c      stop
cc      call slvbd
c      write(*,*) 'After slvbd & ipick=3 inside rikarc'
cc      print *,a after slvbd=,a
c      stop

c ... compute dqtot**2 for eqn. 4.109
c      dprd1 = 0.d0
c      do 90 i=1,nq
c        dprd1 = dprd1 + dqtot(i)**2
c 90 continue
c ... dli using eqn. 4.112
c      dli = dsi/dsqrt(1.d0 + dprd1)
c      If(dprd1.lt.0.)Then
c        print *,dli inside RIK=,dli
c      stop
c      Endif
c      pause
c      stop
c ... test for sign of dli using eqn. 4.117
c      dprd2 = 0.d0
c      do 100 i=1,nq
c        dprd2 = dprd2 + dqtot(i)*dqim1(i)
c        dprd2 = dprd2 + a(i)*dqim1(i)
c        dprd2 = dprd2 + b(i)*dqim1(i)
c 100 continue
c      print *,istep=,istep
c      print *,dqtot(_)=,(dqtot(ic),ic=1,nq)
c      print *,dqim(_)=,(dqim1(ic),ic=1,nq)
c      pause

c      If(dprd2.lt.0.)Then
c        print *,dprd2 negative=,dprd2
c      pause
c      stop
c      Endif

c      If(dli1.lt.0.)Then
c        print *,istep=,istep
c      print *,dli1 negative=,dli1
c      pause
c      stop
c      Endif

c      print *,dprd1=,dprd1
c      print *,dprd2=,dprd2
c      pause

c      stop
c      testv = dli*(dprd2 + dli1)
c      print *,testv=,testv
c      print *,istep=,istep
c      pause

c~~~~~
c      if (testv .lt. 0.D0) then
c        if (testv .lt. 0.D0) then
c          dli = -1.d0*dli
c          dli = 1.d0*dli
c          print *,test for negative sign'
c          pause
c        stop
c~~~~~
c      dli = 1.d0*dli
c      dli = -1.d0*dli
c      print *,test for positive sign'
c      stop
c      end if

c      If(istep .eq. 914)then
c        print *,it=,it
c        pause
c      If(it .gt. 4)then
c        If(ad(6).lt.0.)then
c          dli = -1.d0*dli
c        exlk=-exlk
c      Endif

c      pause

c ... compute dqi using eqn. 4.114
c ... store dqi in dqim1 for next load step
c ... update the total displacements qk
c      do 112 i=1,nq
c        dq(i) = dli*dqtot(i)
c        dq(i) = dli*a(i)
c        dq(i) = dli*b(i)
c        dqim1(i) = dq(i)
c        qk(i) = qk(i) + dq(i)

c** Need to put qk into "a" at displacement locations
c      a(i) = qk(i)
c          b(i) = qk(i)
c          dqtot(i)=qk(i)
c 112 continue
c      print *,qk(i) = ,qk
cc      print *,a w/qk update added =,a

c      stop
c ... update the total external load multiplier exlk
c      print *,exlk before update =,exlk
c      stop
c      If(istep .eq. 561) then
c        dli=abs(dli)
c        endif
c        exlk = exlk + dli

c      If(istep .eq. 561) then
c        exlk=-exlk
c      endif

c      print *,dli = ,dli
c      print *,exlk after update =,exlk
c      stop
c      print *,exlk BBBBBBBBB = ,exlk
c      stop
c ... store dli in dli1 for next load step
c      dli1 = dli

c ... compute the internal forces, fintk, at qk
c      call forces
c      getforce = 1 !!!Yes get internal force
c      print *,getforce = ,getforce
c      stop
c~~~~~
c      print *, "a" before 2nd sysseqn to getforce = ,a
c      print *,fa(_)=,(fa(ic),ic=1,ndof)
c      pause
c      print *, "***** after 2nd sysseqn after Else in Rikarc *****"
c      pause
c      print *, "***** after 2nd sysseqn after Else in Rikarc *****"
c      pause
c      print *, "***** after 2nd sysseqn after Else in Rikarc *****"
c      pause
c      print *, "***** after 2nd sysseqn after Else in Rikarc *****"
c      pause
c      stop
c      call sysseqn(ne,iplvl,b,ndof,disp,iarc,qk,
$      icall,ic,je,je,je,je,call,ia,ac,maxdofpe,
$      neltpe,nel,ndofpe,x,y,z,propmat,propsect,lm,
$      iboundc,ad,an,iperm,iu,ip,iut,dqtot,dqi,dqim1,
$      ux,uy,uz,di,it,area,youngm,
$      ianal,lumpmass,iskap,itimep2,imrmlon,exfor,istep,
$      zoc,dlength,icx)

```



```

common/nodes/umtl(500),xc(500),yc(500),zc(500)
c dimension dx(5),dy(5),g(5),q(5),grdc(5,2)

c common/RJK/ stiff(20,20),dq(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scal(50),work1(500),indx(50),neq
c common/RJK/ stiff(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scal(50),work1(50),indx(50),neq
c common/RJK/ stiff(20,20),dqk(5000),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scal(5000),work1(5000),indx(5000),neq

c common/deltaq/dqi(500)

c common/disp/ux(2),uy(2),uz(2),disp(500)

c common/disp/ux(2),uy(2),disp(10)
c common/disp/ux(2),uy(2)
c common ns(6),phi(6),gdx(6),gdu(6),gdy(6)
c common/disp/qk(500)
c common/infor/getforce,finx(2),finy(2),finz(2),getstiff,getsolve
c common/clctype/typ !ityp = 6 for 2-D problems
c common/spring/springK
c common/testing/toldis,tolfor,exlk,iconv

common/jam/ja2(100)

c integer, allocatable:: ja(:),itempo1(:),itempo2(:)
c integer, allocatable:: ja(:),itempo1(:),juc(:),jut(:)
c integer, allocatable:: itempo1(:)

c integer, allocatable:: itempo1(:)
ccc double precision, allocatable:: an(:)

c double precision, allocatable:: tempo1(:),an(:),juc(:),jut(:),un(:)
c double precision, allocatable:: tempo1(:),un(:)
c double precision, allocatable:: jut(:),jut(:),un(:)
c dimension b(*) ,disp(*) ,ux(*) ,uy(*) ,uz(*) ,x(*) ,y(*) ,z(*)
c dimension iet(*) ,iet(*) ,iet(*) ,iet(*) ,iet(*) ,ia(*)
c dimension iet(*) ,iet(*) ,iet(*) ,iet(*) ,iet(*) ,ad(*)
c dimension iet(*) ,iet(*) ,iet(*) ,iet(*) ,iet(*) ,ad(*) ,am(*)
c dimension iut(*) ,ip(*) ,iut(*) ,iperm(*)
c dimension dqtot(*) ,dq(*) ,dqim1(*) ,di(*) ,ia(*) ,qk(*)
c dimension dqtot(*) ,dq(*) ,dqim1(*) ,qk(*) ,di(*) ,ia1(*) ,ia2(*)
c dimension iboundc(*) ,clK(maxdofpc,1),ja(*) ,am(*) ,lm(1)
c dimension iboundc(*) ,lm(1)
c dimension iboundc(*) ,clK(maxdofpc,maxdofpc),lm(1)
c dimension itempo2(*) ,exfor(*)
c dimension ja(*)
c $ja,iboundc,ndofpc,bc,lm,ndofpc,ad,ip,tempo1,dm,am,ianal,lumpmass)
c dimension be(*) ,ad(*) ,dm(*) ,am(*)

c dimension ja(19)

c dimension tempo1(10)
c print *, 'S T A R T O F S Y S E Q N'
c pause
c print *, 'iskip at start sysqcn=',iskip
c print *, 'getstiff at start sysqcn=',getstiff
c print *, 'getforce at start sysqcn=',getforce
c print *, 'getsolve at start sysqcn=',getsolve
c pause
c print *, 'qk( ) at start of sysqcn=',(qk(ic),ic=1,n,q)
c pause

c print *, 'b( ) inside start sysqcn=',(b(ic),ic=1,n,q)
c pause
c print *, 'disp( ) inside start sysqcn=',(disp(ic),ic=1,n,q)
c pause
c print *, 'ad( ) inside start sysqcn=',(ad(ic),ic=1,n,q)
c pause
c print *, 'iskip start sysqcn=',iskip
c pause

c...Solver needed, no update to stiff or forces required
c print *, 'getsolve start sysqcn=',getsolve
c pause
c if(getsolve.eq. 1)Then
c Goto 1111
c Endif

c if(getforce.eq. 1)then
c print *, 'getforce = 1 start sysqcn, goto 32'
c pause

c Do 28 i=1,ndof
28 b(i)=0.
c goto 32
c Endif

c allocate (tempo1(ndof))

c print *, 'itrmlon start sysqcn=',itrmlon
c pause
c .....
c if(itrmlon.eq. 1)then
c do 27 i=1,n,q
c* dqk1(i) = exfor(i)
c* dqk2(i) = resk(i)
c print *, dqk1( )=,dqk1(i)
c print *, dqk2( )=,dqk2(i)
c*27 continue
c* j=0 !???????
c* do 29 i=1,n,q
c* b(i)=dqk1(i)
c* print *, 'b( ) in sysqcn & itrmlon=',b(i)
c*29 continue
c* Endif
c .....
c pause

c print *, 'ianal at start of sysqcn=',ianal

c print *, 'lumpmass at start of sysqcn=',lumpmass
c stop

c print *, 'x start sysqcn =',(x(i),i=1,ndof)
c print *, 'y start sysqcn =',(y(i),i=1,ndof)
c print *, 'z start sysqcn =',(z(i),i=1,ndof)
c print *, 'ndof=',ndof
c stop
c print *, 'chk start of sysqcn'
c pause
c print *, 'iarc=',iarc
c print *, 'iboundc=',(iboundc(i),i=1,ndof)
c print *, 'it = ',it
c stop

c print *, 'maxdofpc =',maxdofpc
c stop
c print *, 'b start of sysqcn =',(b(i),i=1,ndof)
c pause
c print *, 'je start of sysqcn =',(je(i),i=1,20)
c stop

c if(it.eq. 2)then
c print *, 'it = 2'
c stop
c Endif

c if(getforce.eq. 1)then
c print *, 'getforce=1 at start of sysqcn'
c stop
c** Get ready for internal forces, set all forces to zero
c .....
c if(ityp.eq. 6)Then
c Do 28 i=1,ndof
c 28 b(i)=0.
c .....
c stop
c goto 30
c Endif

c** Get ready for new stiffness terms.
c** set only stiff & force terms to zero
c .....
c DO 29 i=1,ndof
c 29 b(i)=0. !set loads to zero
c print *, 'b =',(b(i),i=1,ndof)
c stop
c ndof2=ndof**2
c print *, 'ndof2=',ndof2
c Do 31 i=1,ndof2-10
c 31 an(i)=0. !set stiff to zero
c print *, 'chk 2 inside sysqcn'
c stop

30 continue !just a blank, no Do associated
c.....input boundary dof
c call supportdof(iboundc,nboundc,b,ndof,ia)
c print *, 'b inside sysqcn =',(b(i),i=1,ndof)
c stop
c.....
c.....
c if(getforce.eq. 1)then !skip transa2d, symbass, copy_int
c "Go to assembly2"
c print *, 'ja(1)='ja(1)
c print *, 'getforce goto 32'
c pause
c stop
c print *, 'ieall=',ieall
c print *, 'ndof=',ndof
c print *, 'je =',(je(i),i=1,ieall*4)
c print *, 'iet =',(iet(i),i=1,ndof+1)
c print *, 'ie =',(ie(i),i=1,ieall*1)
c print *, 'je =',(je(i),i=1,jeall)
c stop
c goto 32
c Endif
c.....
c if(it.eq. 2)then
c print *, 'it = 2'
c stop
c Endif
c print *, 'chk before transa2d'
c print *, 'getstiff=',getstiff
c print *, 'getforce=',getforce
c pause
c print *, 'je inside sysqcn before transa2d=',(je(i),i=1,20)
c stop
c print *, 'chk before transa2d'
c pause
c call transa2d(ieall,ndof,ie,je,iet,jct)

cc32 continue !dummy line from "if(getforce.eq. 1) above
c write(6,*) '*** passed transa2d ***'
c print *, 'after transa2d'
c pause
c stop
c print *, 'ndof=',ndof
c print *, 'jeall=',jeall
c print *, 'ieall=',ieall
c print *, 'ie =',(ie(i),i=1,ieall+1)
c print *, 'je =',(je(i),i=1,jeall)

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c      print *,je = '(ic(i),i=1,ndof*4)
c      print *,ic = '(ic(i),i=1,ndof+1)
c      print *,jc = '(jc(i),i=1,jcall)
c      print *,jct = '(jct(i),i=1,jcall*4)
c      print *,ial = '(ial(i),i=1,ndof+1)
c      stop
c      if(it.eq. 2)then
c      print *,it = 2'
c      stop
c      endif

c      if(getforce.eq. 1)then
c      print *,'getforce = 1 before symbass'
c      print *,'ndof=' ,ndof
c      stop
c      endif

c.....sparse "symbolic" assembly
c      ncoef1_guess=20000000
c      deallocate (itempo1)

c      allocate ( itempo1(ncoef1_guess) )
c      print *,'is skip before allocate itempo2=',is skip
c      pause
c      if(iskip.eq. 1)Then
c      itempo1(1)=itempo2(1)
c      print *,'itempo1(1)=itempo2(1)',itempo1(1)
c      Else
c      Endif

c      print *,'ndof=' ,ndof
c      stop
c      print *,'chk before symbass'
c      print *,'getstiff=',getstiff
c      print *,'getforce=',getforce
c      print *,'icall before symbass=',icall
c      print *,'jcall before symbass=',jcall
c      print *,'je before symbass=',(ic(ic),ic=1,jcall+1)
c      print *,'je inside syseqn before symbass=',(ic(i),i=1,30)
c      print *,'jct before symbass=',(jct(ic),ic=1,jcall+1)
c      print *,'jct before symbass=',(jct(ic),ic=1,jcall+1)
c      print *,'ja before symbass=',(ja(i),i=1,jcall+1)
c      print *,'ja before symbass=',(ja(i),i=1,jcall+1)
c      stop
c      pause
c      print *,'is skip before if = ' ,is skip
c      pause
c      if(iskip.eq. 1)Then !only do symbass one time, skip after 1st time
c      Go To 799
c      Else
c      call symbass(ic,je,jct,jct,ndof,ial,ja2,
c      $      itempo1,ncoef1)
c      iskip = 1 !This causes symbass to be skipped, only need to go once
c      itempo2(1)=itempo1(1) !Need this because itempo1 gets re-allocated
c      call symbass(ic,jct,jct,ndof,ial,ja2,
c      $      itempo1,ncoef1)
c      Endif

799 CONTINUE !dummy line for abv "If" statement
c      print *,'is skip after symbass = ' ,is skip
c      print *,'*** After symbass ***'
c      print *,'je after syseqn = '(je(i),i=1,20)
c      print *,'itempo1=' ,itempo1(1)
c      print *,'itempo2=' ,itempo2(1)
c      pause

c      stop
c      pause

c      if(getforce.eq. 1)then
c      print *,'getforce = 1 before symbass'
c      print *,'ncoef1 =',ncoef1
c      stop
c      endif

c      print *,'ncoef1 =',ncoef1
c      pause
c      print *,'icall = ' ,icall
c      print *,'je = '(je(i),i=1,jcall)
c      print *,'jct = '(jct(i),i=1,ndof+1)
c      stop
c      print *,'jcall=' ,jcall
c      print *,'ndof=' ,ndof
c      print *,'ncoef1=' ,ncoef1
c      print *,'jct after symbass=' ,jct(i),i=1,jcall)
c      print *,'ial after symbass=' ,ial(i),i=1,ndof+1)
c      stop
c      print *,'ja2 after symbass=' ,ja2(i),i=1,ndof+1)
c      print *,'itempo1 after symbass=' ,itempo1(i),i=1,ncoef1)
c      pause
c      stop

c      if(getforce.eq. 1)then
c      stop
c      endif

c      if(it.eq. 2)then
c      print *,'it = 2'
c      print *,'STOP'
c      stop
c      endif

c      stop
c      print *,'ncoef1=' ,ncoef1
c      stop
c      do 111 i=1,ncoef1_guess
c      print *,'itempo1 = ' ,itempo1(ncoef1_guess)
c      stop
c      print *,'ncoef1 = ' ,ncoef1

c      stop
c      allocate ( ja2(ncoef1) )

c      stop
c.....not sure, "ja" is also needed in assembly2
c      print *,' ??????????????????????????????'
c.....iturnlon means call was done in subroutine iturnlon
c      print *,'iturnlon=' ,iturnlon
c      pause
c      if(iturnlon.eq. 1)Then !skip allocation, already done
c      goto 790
c      Endif
c      if(getstiff.eq. 0)then
c      print *,'ncoef1=' ,ncoef1
c      pause
c      allocate ( ja(ncoef1) )
c      print *,'allocate -ja- when getstiff=0 inside syseqn'
c      pause
c      allocate ( ja2(ncoef1) )
c      can allocate ( an(ncoef1) )
c      print *,'allocate -an- when getstiff=0 inside syseqn'
c      pause
c      Endif
790 Continue !dummy line

c      allocate (tempo1(ndof))
c      print *,'***chk before copy_int***'
c      pause
c      print *,'getstiff=',getstiff
c      print *,'getforce=',getforce
c      print *,'getsolve=',getsolve
c      print *,'ncoef1=',ncoef1
c      print *,'itempo1=',itempo1
c      print *,'ja=' ,ja(ic),ic=1,ncoef1)
c      pause
c      print *,'is skip before 1st copy_int=' ,is skip
c      pause

c      if(iskip.eq. 1)Then !only do symbass one time, skip after 1st time
c      goto 798
c      Else
c      call copy_int(ncoef1,itempo1,ja)
c      Endif
798 CONTINUE !dummy line for abv "If" statement
c      print *,'passed 1st copy_int'
c      print *,'ja( ) after copy_int in syseqn=' ,ja(ic),ic=1,ncoef1)
c      print *,'#####'
c      pause
c      Endif
c788 continue !dummy line for skip=1
c      print *,'ncoef1=' ,ncoef1
c      stop

c      if(getforce.eq. 1)then !skip, ja is already=ja2
c      goto 112
c      Else

c      print *,'ncoef1=' ,ncoef1
c      allocate ja2(ncoef1)
c      do 111 i=1,ncoef1
c      print *,'ja(i)=' ,ja(i)
c      ja2(i)=ja(i)
c111

c      Endif
c      print *,'ja2 just after setting ja=' ,ja2(ic),ic=1,10)
c      print *,'ja2(1) =',ja2(1)
c      pause
c      print *,'#####'
c      pause
c112 Continue !dummy

c      print *,'ja2 after set to ja =',ja2(i),i=1,ncoef1)
c      pause
c      stop
c      deallocate (itempo1)

c.....sparse "numerical" assembly
c      print *,'iamal=' ,iamal
c      print *,'lumpmass=' ,lumpmass
c      if (iamal.eq. 1) then
cc      allocate ( evalues(neig) )
cc      allocate ( vectors(ndof*neig) )
cc      allocate ( dm(ndof) )
cc      allocate ( elm(maxdofpc,maxdofpc) )
c      if (lumpmass.eq. 0) then
cc      allocate ( am(ncoef1) )
cc      Endif
c      Endif

c      print *,'check point #01'
c      write(6,*) 'check point #01'
c      print *,'ncoef1 before assembly=' ,ncoef1
c      stop

c      if(it.eq. 2)then
c      print *,'it = 2'
c      print *,'before assembly2'
c      stop
c      Endif

32 continue
c32 print *,'dummy line' !dummy line from "if(getforce.eq. 1) above
c.....
c      write(6,*) '*** passed symbass ***'
c      if(getforce.eq. 1)then
c      print *,'getforce = 1 before assembly'
c      print *,'ja2(i)=' ,ja2(ic),ic=1,10)
c      Endif
c      pause

c      if(getforce.eq. 1)then
c      stop
c      pause
c      print *,'ncoef1=' ,ncoef1
c      write(6,*)ja( ) before assembly2=(,ja(i),i=1,ncoef1)
c      print *,'ja( ) before assembly2=' ,ja(i),i=1,ncoef1)

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```

c      stop
c      call assembly2(ip,ad,an,lm,ie,je,propmat
c $,   propsect,elk,bc,b,iboundc,ux,uy
c $,   ac,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c $ndof,neltype,nel,ndofpe,ianal,lumpmass,dm,am,elm,tempo1,disp,
c $iarc,ityp,getforce,it)
c      print *,'ia2 before assembly=',(ia2(i),i=1,ndof+1)
c      stop
c      If(getforce .eq. 1)then
c      print *,'ja2 before assembly & getforce=1',(ja2(ic),ic=1,10)
c      endif
c      pause

c      print *,'ad stiff before assembly=',(ad(i),i=1,maxdofpe**2)
c      print *,'ae stiff before assembly=',(ae(i),i=1,maxdofpe**2)
c      pause
c      print *,'skip call assembly'
c      pause
c      call assembly(ip,ad,an,lm,ie,je,propmat,
c $   propsect,bc,b,iboundc,
c $   ac,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c $   ae,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c $ndof,neltype,nel,ndofpe,ianal,lumpmass,dm,am,elm,
c $ tempo1,disp,iarc,it,area,youngm,esm,qk,imrmlon)
c $ tempo1,disp,iarc,it,area,youngm,qk,imrmlon,istep,icheck,
c $ zcc,dLength,jex)

c      print *,'ia2 after assembly=',(ia2(i),i=1,ndof+1)
c      print *,'*** Passed assembly ***'

c      print *,'ad stiff after assembly=',(ad(i),i=1,maxdofpe**2)
c      print *,'ae stiff after assembly=',(ae(i),i=1,maxdofpe**2)
c      pause

c      STOP

c      else
c      print *,'chk before assembly'
c      print *,'getstiff=',getstiff
c      print *,'getforce=',getforce
c      print *,'Check before assembly'
c      stop
c      pause

c      call assembly(ip,ad,an,lm,ie,je,propmat
c $,   propsect,elk,bc,b,iboundc,ux,uy
c $,   ac,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c $ndof,neltype,nel,ndofpe,ianal,lumpmass,dm,am,elm,tempo1,disp,
c $iarc,ityp,getforce,it)

c      print *,'***ia2 before assembly***',(ia2(i),i=1,ndof+1)
c      stop
c      print *,'going to assembly 2'
c      print *,'ndofpe=',ndofpe
c      print *,'chk before assembly'
c      pause
c      print *,'B( ) before assembly=',(b(ic),ic=1,ndof)
c      pause
c      call assembly(ip,ad,an,lm,ie,je,propmat,
c $   propsect,bc,b,iboundc,
c $   ac,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c $   ae,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c $ndof,neltype,nel,ndofpe,ianal,lumpmass,dm,am,elm,
c $ tempo1,disp,iarc,it,area,youngm,esm,qk,imrmlon)
c $ tempo1,disp,iarc,it,area,youngm,qk,imrmlon,istep,icheck,
c $ zcc,dLength,jex)

c      print *,'***Passed assembly***'
c      print *,'ad stiff after assembly=',(ad(ic),ic=1,maxdofpe**2)
c      print *,'an stiff after assembly=',(an(ic),ic=1,50)
c      print *,'ae stiff after assembly=',(ae(i),i=1,maxdofpe**2)
c      pause
c      stop
c      write(6,*)'***Passed assembly***'

c      stop
c      endif

c-----
c... Only used when solving, getsolve=1
c      print *,getforce=?,getforce
c      print *,getstiff=?,getstiff
c      print *,getsolve=?,getsolve
c      pause
c      print *,'B( )=',(b(ic),ic=1,ndof)
c      pause
1111  If(getsolve .eq. 1)Then
c      goto 797
cx  call assembly(ip,ad,an,lm,ic,je,propmat,
cx $   propsect,bc,b,iboundc,
cx $   ac,ia2,ja,x,y,z,ncoeff1,maxdofpe,
cx $ndof,neltype,nel,ndofpe,ianal,lumpmass,dm,am,elm,
cx $ tempo1,disp,iarc,it,area,youngm,qk,imrmlon)
c-----
c      print *,'b after assembly getsolve=1 ',(b(i),i=1,ndof)
c      print *,'ad after assembly getsolve=1',(ad(i),i=1,maxdofpe**2)
c      print *,'ae after assembly getsolve=1',(ae(i),i=1,maxdofpe**2)
c      stop
c      pause
c      Endif

c      write(6,*)ae=(ae(i),i=1,maxdofpe*2)
c      write(6,*)disp=(disp(i),i=1,ndof)
c      write(6,*)ae=(ae(i),i=1,20)
c      write(6,*)disp=(disp(i),i=1,10)
c      stop
c      print *,'Getforce after assembly2 =',getforce
c      stop
c      If(getforce .eq. 1)then

c      print *,'b after assembly getforce is 1 ',(b(i),i=1,ndof)
c      print *,'elk after assembly getforce is 1 ',(elk(i),i=1,ndof)
c      print *,'iboundc=',(iboundc(i),i=1,ndof)
c***need to get support dof into "b"
c      Do 449 i=1,ndof
c      If(iboundc(i) .eq. 1)Then
c      b(i)=0.0
c      Endif
449  Continue
c      b(1)=0.0
c      b(2)=0.0
c      b(3)=0.0
c      b(4)=0.0
c      b(6)=0.0
c      b(7)=0.0
c      b(8)=0.0
c      b(9)=0.0
c      print *,'b modify for support dof=',(b(i),i=1,ndof)
c      pause
c      goto 45 !this goes to the end of subroutine when we want internal forces
c      stop
c      endif

c*****
c      print *,'ae =',(ae(i),i=1,maxdofpe**2)
c      stop

c      write(6,*)'check point #02'
c      print *,'check point #02'
c      stop
cc  if (ianal .eq. 1) then
cc  write(6,*)'diag-mass = dm(-) =',(dm(i),i=1,ndof)
cc  endif
cc  if (ianal .eq. 1 .and. lumpmass .eq. 0) then
cc  write(6,*)'old diag-mass = am(-) =',(am(i),i=1,ncoeff1)
cc  endif

c.....assuming to skip the "REORDERING" process (minimize "fills-in" terms)
c
c      print *,'***before minfills***'
c      print *,'iperm before minfills=',(iperm(i),i=1,ndof)
c      pause
c      stop

c      print *,'iskip inside syseqn=',iskip
c      pause

c      If(iskip .eq. 1)Then !only do sybmass one time, skip after 1st time
c      print *,'iskip=1 goto 797'
c      pause
c      goto 797
c      Else
c      call minfills(ndof,iperm)
c      print *,'iperm after minfills=',(iperm(i),i=1,ndof)
c      pause
c      iskip = !This causes sybmass to be skipped, only need to go once
c      save for other iterations!!!

c      print *,'passed minfills'
c      print *,'iperm after minfills=',(iperm(i),i=1,ndof)
c      Endif

797  Continue !dummy statement
c      stop
c.....eigen-solution
cc  if (ianal .eq. 1) then
cc  lump=lumpmass
cc  ishift=0
cc  iprint=1
cc  mtot=20000000
cc  allocate( tempo3(mtot) )
c      r(mtot)=working array (in real*8) = tempo3(-)
c      iflag(1,2,3,4,5,6,7,8,9,10)=nreord,loop_unroll,?,?,?,neig
c      =iprint,lump,ishift,ncoeff2,??
c      nreord=0,1,2,3=no reorder,metis,nd,mmd
c
c      iflag(1)=0 ! 1,2,3 = metis,nd,mmd
cc  iflag(2)=1 ! level of unroll
cc  iflag(5)=neig
cc  iflag(6)=iprint
cc  iflag(7)=lump
cc  iflag(8)=ishift
c      iflag(9)=ncoeff2 ! as an output
c
cc  write(6,*)'inside *cmei*.f: ndof,ncoeff1,neig,lump ='
cc  write(6,*)'ndof,ncoeff1,neig,lump'
cc  write(6,*)'inside *cmei*.f: ishift,mtot ='
cc  write(6,*)'ishift,mtot'
cc  write(6,*)'inside *cmei*.f: iflag(10) =',(iflag(i),i=1,10)
cc  write(6,*)'inside *cmei*.f: ia(-) =',(ia(i),i=1,ndof+1)
cc  write(6,*)'inside *cmei*.f: ja(-) =',(ja(i),i=1,ncoeff1)
cc  write(6,*)'inside *cmei*.f: ad(-) =',(ad(i),i=1,ndof)
cc  write(6,*)'inside *cmei*.f: an(-) =',(an(i),i=1,ncoeff1)
cc  write(6,*)'inside *cmei*.f: dm(-) =',(dm(i),i=1,ndof)
c
cc  if (lump .eq. 1) then
ccc  call eigsolver01(ndof,ncoeff1,neig,lump,ishift,
ccc  smtot,ia,ja,ad,an,dm, evalues,evectors,tempo3,iflag,iperm)
ccc  elseif (lump .eq. 0) then
ccc  call eigsolver022(ndof,ncoeff1,neig,lump,ishift,
ccc  smtot,ia,ja,ad,an,dm,am,evalues,evectors,tempo3,iflag,iperm)
ccc  endif
cc  deallocate( tempo3 )
cc  STOP
cc  endif

c      If(getstiff .eq. 1)Then
c      goto 674
c      Endif

c.....sparse "symbolic" factorization
ncoeff2_guess=1000

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c      print *, '~~~~~Chk before allocate itempo1~~~~~'
c      pause
c      allocate ( itempo1(ncocf2_gucss) )
c      print *, 'ia before symfactd=', (ia(ic), ic=1, 12)
c      print *, 'ja before symfactd=', (ja(ic), ic=1, 3)
c      print *, '++++ Chk before symfactd +++++'
c      print *, 'getstiff=', getstiff
c      print *, 'getforce=', getforce
c      print *, 'getsolve=', getsolve
c      pause
c      print *, 'ndof before symfactd=', ndof
c      pause
c      call symfactd(ndof, ia, ja, iu, itempo1, ip, ncocf2)
c      call symfactd(ndof, ia2, ja, iu, itempo1, ip, ncocf2)

c      print *, '*****passed symfactd*****'
c      print *, 'after symfactd: IU(-) = ', (iu(ic), ic=1, ndof+1)
c      pause
c      pause

c      write(6, *) 'passed symfactd'
c      stop
c      write(6, *) 'check point #03'

c      print *, 'ncocf2=', ncocf2
c      print *, 'NNNNNNNNNNNN ncocf2 NNNNNNNNNNNNNN'
c      pause
c      stop

c      allocate ( ju(ncocf2) )
c      allocate ( iu(ncocf2) )
c      allocate ( un(ncocf2) )

c      print *, 'itempo1 before copy_int=', (itempo1(ic), ic=1, 12)
c      pause
c      call copy_int(ncocf2, itempo1, iu)
c      print *, 'passed copy_int'
c      print *, 'getsolve=1, getsolve'
c      print *, 'itempo1 after copy_int=', (itempo1(ic), ic=1, 12)
c      pause
c      pause

c      print *, '***Passed copy_int***'
c      print *, 'ad stiff after copy_int=', (ad(i), i=1, maxdofpe**2)
c      print *, 'an off-stiff after copy_int=', (an(ic), ic=1, 3)
c      print *, 'ae stiff after copy_int=', (ae(i), i=1, maxdofpe**2)
c      pause

c      if (getsolve.eq.1) then !skip, deallocate
c      allocate (tempo1(10000))
c      deallocate (itempo1)
c      goto 781
c      Endif
c      deallocate (itempo1)
781 continue

c      c.....transpose twice to put column numbers in order
c      call transad(ndof, ndof, iu, ju, iu, iu)
c      print *, '*** passed transa ***'
c      write(6, *) '*** passed transa ***'
c      print *, 'iu after transad=', (iu(i), i=1, ndof+1)
c      write(6, *) 'ju after transad=', (ju(i), i=1, ndof+1)
c      pause
c      stop

c      c.....assuming to skip the "SUPER NODE" process (for unrolling purpose)
c      call supernode(ndof, isupn)
c      print *, '*** passed supernode ***'
c      stop

c      c.....sparse "numerical" factorization
c      print *, 'ia2 before numfa1d=', (ia2(i), i=1, ndof+1)
c      write(6, *) 'ia2 before numfa1d=', (ia2(i), i=1, ndof+1)
c      stop
c      print *, 'ndof before numfa1d=', ndof
c      pause

c      print *, 'getstiff before numfa1d=', getstiff
c      print *, 'chk before numfa1c'
c      pause
674 if (getstiff .eq. 1) Then !skip, only need stiff
c      Goto 793
c      Endif

c      call numfa1d(ndof, ia, ja, ad, an, iu,
c      $ ju, di, un, ip, iup,
c      $ isupn, iopf)
c      routine numfa1d(n, ia, ja, ad, an, iu, ju, di, un, ip, iup, isupd, iopf)
c      call numfa1d(ndof, ia2, ja, ad, an, iu,
c      $ ju, di, un, ip, iup,
c      $ isupn, iopf)

793 Continue !dummy line
c      print *, 'getstiff after numfa1d=', getstiff
c      pause

c      if (getstiff .eq. 1) Then !skip, only need stiff
c      Goto 675
c      Endif

c      print *, '*** PASSED NUMFA1d ***'
c      pause
c      STOP
c      write(6, *) '*** passed numfa1d ***'
c      c.....sparse forward/backward solution phase

c      write(6, *) 'ndof before fbed=', ndof
c      write(6, *) 'b before fbed=', (b(i), i=1, ndof)
c      write(6, *) 'di before fbed=', (di(i), i=1, ndof)
c      write(6, *) 'iu before fbed=', (iu(i), i=1, ndof+1)
c      write(6, *) 'ju before fbed=', (ju(i), i=1, ncocf2)
c      write(6, *) 'un before fbed=', (un(i), i=1, ncocf2)

```

```

      return
    end
c *****
c *** SUBROUTINE: TEST ***
c *****
c subroutine test(toldis,tolfor,exlk,iconv)
c subroutine test(dqtot,dqi,dqim1,qk,exfor,b,iturnmlon)
c implicit real*8(a-h,o-z)
c common/RIK/ stifi(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqk(5000),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c
c common/deltaqi/dqi(500)
c
c common/testing/toldis,tolfor,exlk,iconv
c
c dimension dqtot(*),dqi(*),dqim1(*),exfor(*),qk(*),b(*)
c
c dimension dqk(neq),qk(neq),exfor(neq),resk(neq),scali(neq)
c
c print *,',iturnmlon in test=',iturnmlon
cc print *,',exlk inside TEST=',exlk
c print *,',tolfor inside TEST=',tolfor
c stop
c iconv = 0
c
c if (tolfor .lt. 1.d0) then
c print *,',tolfor = ',tolfor
c print *,',goto unbal'
cc print *,',tolfor, exlk, iconv inside test = ',tolfor,exlk,iconv
c pause
c stop
c call unbal(tolfor,exlk,iconv)
c print *,',exlk before unbal = ',exlk
c stop
c pause
c print *,',chk before unbal in test'
c pause
c call unbal(dqtot,dqi,dqim1,qk,exfor,b)
c end if
c print *,',toldis after unbal = ',toldis
c pause
c stop
c
c if (toldis .lt. 1.d0) then
c print *,',toldis = ',toldis
c print *,',goto displ'
c STOP
c call displ(toldis,iconv)
c call displ(dqtot,dqi,dqim1,qk,h,iturnmlon)
c end if
c
c return
c end
c *****
c *** SUBROUTINE: UNBALF ***
c *****
c subroutine unbalf(tolfor,exlk,iconv)
c subroutine unbalf(dqtot,dqi,dqim1,qk,exfor,b)
c implicit real*8(a-h,o-z)
c common/RIK/ stifi(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqk(5000),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c
c common/deltaqi/dqi(500)
c
c common/testing/toldis,tolfor,exlk,iconv
c
c dimension dqtot(*),dqi(*),dqim1(*),exfor(*),qk(*),b(*)
c
c dimension exfor(neq),resk(neq),scali(neq)
c
c print *,',Start of "UNBALF"'
c print *,',exlk inside UNBALF=',exlk
c stop
c unbfi = 0.d0
c unbfe = 0.d0
c
c ... compute numerator of eqn. 4.133
c ... compute denominator of eqn. 4.133
c print *,',scali(i) inside UNBALF"',(scali(i),i=1,neq)
c print *,',resk(i) inside UNBALF"',(resk(i),i=1,neq)
c pause
c print *,',exfor(i) inside UNBALF"',(exfor(i),i=1,neq)
c stop
c do 10 i=1,neq
c unbfi = unbfi + dabs(scali(i))*resk(i)**2
c unbfe = unbfe + dabs(scali(i))*exfor(i)**2
10 continue
c
c ... compute eqn. 4.133
c print *,',unbfi=',unbfi
c print *,',unbfe=',unbfe
c print *,',scali( )=',(scali(i),i=1,neq)
c print *,',exlk=',exlk
c delf = dsqrt(unbfi)/dsqrt(unbfe)/exlk
c print *,',delf inside unbal = ',delf
c pause
c stop
c
c ... test to see if delf is greater than tolfor
c if (dabs(delf) .gt. tolfor) then
c iconv = iconv + 100
c end if
c print *,',iconv inside unbal = ',iconv
c stop
c
c return
c end
c *****
c *** SUBROUTINE: DISPL ***
c *****
c subroutine displ(toldis,iconv)
c subroutine displ(dqtot,dqi,dqim1,qk,h,iturnmlon)
c implicit real*8(a-h,o-z)
c common/RIK/ stifi(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqk(5000),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c
c common/deltaqi/dqi(500)
c
c common/testing/toldis,tolfor,exlk,iconv
c common/av/a(1500),jgfgsm,np,nbw,np2,nbw2
c
c dimension dqtot(*),dqi(*),dqim1(*),qk(*),b(*)
c
c dimension dqk(neq),qk(neq)
c
c print *,',neq inside displ=',neq
c stop
c dqsq = 0.d0
c qsq = 0.d0
c
c ... compute deld using eqn. 4.132
c do 10 i=1,neq
c
c if(iturnmlon .eq. 0)then
c print *,',dqi(i)=',dqi(i)
c dqsq = dqsq + dqi(i)**2
c Else iteration on normal
c print *,',dqk(i)=',dqk(i)
c dqsq = dqsq + dqk(i)**2
c End if
c qsq = qsq + qk(i)**2
c qsq = qsq + b(i)**2
c qsq = qsq + a(i)**2
10 continue
c print *,',dqsq inside displ =',dqsq
c print *,',qsq inside displ =',qsq
c stop
c deld = dsqrt(dqsq)/dsqrt(qsq)
c print *,',deld inside displ = ',deld
c pause
c stop
c
c ... test to see if deld is greater than toldis
c if (deld .gt. toldis) then
c iconv = iconv + 10
c end if
c print *,',iconv inside displ = ',iconv
c stop
c
c return
c end
c *****
c *** SUBROUTINE: RESULT ***
c *****
c subroutine result(istep,it,dqtot,dqi,dqim1,qk,exfor,ad)
c implicit real*8(a-h,o-z)
c common/RIK/ stifi(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqk(5000),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c
c common/deltaqi/dqi(500)
c
c common/av/a(1500),jgfgsm,np,nbw,np2,nbw2
c common/testing/toldis,tolfor,exlk,iconv
c
c dimension dqtot(*),dqi(*),dqim1(*),exfor(*),qk(*),ad(*)
ccc common/disp/ux(2),uy(2),disp(500)
cccc print *,',ux(1) & ux(2) =',ux(1),ux(2)
cc print *,',In Result'
cc pause
c stop
c dimension exfor(neq),qk(neq)
c
c if (istep .eq. 1) then
c c write(*,10)
c c write(*,20)
c c write(11,10)
c c write(11,20)
c end if
c
c open(15,file='fea3d2_out.txt',status='unknown')
c open(12,file='fea3d2_out_F.txt',status='unknown')
c open(13,file='fea3d2_out_q1.txt',status='unknown')
c open(14,file='fea3d2_out_q2.txt',status='unknown')
c write(*,50) *,',istep,exlk,qk(1),qk(2),it

```



```

cshail c 1x,i5)

c write(20,60) dqtot(20)
c60 format(e14.6)
cc if(ipnrat.eq. 0)then 'do this first time only
c write(19,61) exlk,dqtot(20),dqtot(38)
c61 format(e14.6,2x,e14.6,2x,e14.6)
cc iprint=1
cc iprt=1
cc endif

c if(iprint/10 .eq. 10*iprt/100)then
c...output every 10th data point
cc if(ipnrat .eq. iprt)then
cc write(19,62) exlk,dqtot(20),dqtot(38)
cc62 format(e14.6,2x,e14.6,2x,e14.6)
c print *,iprint=,iprint
c print *,iprint/10=,iprint/10
c print *,iprt=,iprt
c print *,10*iprt/100=,10*iprt/100
c pause
cc if(iprint.gt. 1)then
cc iprt=iprint+10
cc Else
cc iprt=iprint+9
cc Endif
cc print *,iprint 2=,iprint
c print *,iprt 2=,iprt
c pause
cc iprint=iprint+1

c*****
c** "3a_in.dat" 3 member truss *****
c appliedforce = exlk * exfor(4)
c if(istep .eq. 1) then
c write(15,53)
c53 format(' istep exlk appliedforce dqtot(4)
c $ dqtot(5) dqtot(6) dqtot(7) dqtot(8) dqtot(9)
c $ it')
c endif
c write(15,50) *,istep,exlk,appliedforce,
c c dqtot(4),dqtot(5),dqtot(6),dqtot(7),dqtot(8),dqtot(9),it
c50 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,3x,e10.4,
c c 3x,e10.4,3x, e10.4,3X e10.4,4x,i5)
c*****

c if(istep .eq. 1) then
c write(15,53) *,istep,exlk,appliedforce,
c c dqtot(61),dqtot(62),it
c53 format(a1,2x,i3,5x,f10.6,3x,f10.6,6x,f10.8,6x,f12.8,
c c 6x,i3)
c endif
c write(15,50) *,istep,exlk,appliedforce,
c c dqtot(61),dqtot(62),it
c50 format(a1,2x,i3,5x,f10.6,3x,f10.6,6x,f10.8,6x,f12.8,
c c 6x,i3)
c** "Tripodin.dat using 3d element"*****
c appliedforce1 = exlk * exfor(10)
c appliedforce2 = exlk * exfor(12)
c if(istep .eq. 1) then
c write(15,53)
c53 format(' istep exlk appfor ex appfor ex
c c a(10) a(11) a(12) it')
c endif
c write(15,50) *,istep,exlk,appliedforce1,appliedforce2,
c c dqtot(10),dqtot(11),dqtot(12),it
c50 format(a1,2x,i4,5x,f10.6,3x,e10.3,3x,e10.4,6x,e10.4,6x,
c c e10.4,4x,i5)
c** "twohar_in.dat"*****
c two appliedforce = exlk * exfor(7)
c two if(istep .eq. 1) then
c two write(15,53)
c two53 format(' istep exlk appliedforce a(5)
c two $ a(7) it ad(5) ad(7)')
c two endif
c two write(15,50) *,istep,exlk,appliedforce,
c two c dqtot(5),dqtot(7),it,
c two c ad(5),ad(7)
c two50 format(a1,2x,i4,5x,e14.6,3x,e10.4,6x,e10.4,4x,e10.4
c two c 4x,i5,4x,e10.4,3x,e10.4)
c*****
c** "snap4_in.dat"*****
c snap4 appliedforce = exlk * exfor(11)
c snap4 if(istep .eq. 1) then
c snap4 write(15,53)
c snap453 format(' istep exlk appliedforce a(1)
c snap4 $ a(2) a(11) it ad(3) ad(4)')
c snap4 endif
c snap4 write(15,50) *,istep,exlk,appliedforce,
c snap4 c dqtot(1),dqtot(2),dqtot(11),it,
c snap4 c ad(1),ad(2)
c snap450 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3X,e10.4,
c snap4 c 4x,i5,4x,e10.4,3x,e10.4)
c*****
c** "snap_in.dat"*****
c snap appliedforce = exlk * exfor(11)
c snap if(istep .eq. 1) then
c snap write(15,53)
c snap53 format(' istep exlk appliedforce a(1)
c snap $ a(2) a(11) it ad(3) ad(4)')
c snap endif
c snap write(15,50) *,istep,exlk,appliedforce,
c snap c dqtot(1),dqtot(2),dqtot(11),it,
c snap c ad(1),ad(2)
c snap50 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3X,e10.4,
c snap c 4x,i5,4x,e10.4,3x,e10.4)
c*****
c** "domein.dat"*****
c dome appliedforce = exlk * exfor(3)
c dome if(istep .eq. 1) then
c dome write(15,53)
c dome53 format(' istep exlk appliedforce a(1)
c dome $ it ad(3) ad(4)')
c dome endif
c dome write(15,50) *,istep,exlk,appliedforce,
c dome c dqtot(1),dqtot(2),dqtot(3),dqtot(4),dqtot(5),dqtot(6),it,
c dome c ad(3),ad(4)
c dome50 format(a1,2x,i4,5x,e10.2,6x,e10.4,6x,e10.4,3X,e10.4,
c dome c 3x,e10.4,3x, e10.4,3X e10.4,4x,i5)
c*****
c** "truss7_3d_in.dat using 3d element"*****
c** "truss11_3d_in.dat using 3d element"*****
c truss appliedforce = exlk * exfor(8)
c truss if(istep .eq. 1) then
c truss write(15,53)
c truss53 format(' istep exlk appliedforce a(1)
c truss $ a(2) a(4) a(5) a(7) a(8)
c truss $ it')
c truss endif
c truss write(15,50) *,istep,exlk,appliedforce,
c truss c dqtot(1),dqtot(2),dqtot(4),dqtot(5),dqtot(7),dqtot(8),it
c truss50 format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,3X,f10.4,
c truss c f10.4,3x, f10.4,3X f10.4,4x,i5)

c write(15,50) *,istep,exlk,appliedforce,
c c a(6),a(9),a(3),it
c50 format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,
c c 6x,i3)
c50 format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,f10.4,
c c 6x,i3)
c print *,'check 3 inside result'
c write(*,50) *,istep,exlk,appliedforce,
c c a(3),a(4),a(5),a(6),a(13),a(14),it
c Below IS FOR T3y
c write(15,50) *,istep,exlk,appliedforce,
c c a(1),a(2),a(3),a(4),it,a(12)
c write(15,50) *,istep,exlk,xinternalforce,yinternalforce,
c c a(3),a(4),it

c stop
ccc write(12,51) xinternalforce,yinternalforce
ccc51 format(f12.2,1x,f12.2)
c write(12,51) appliedforce
c51 format(f12.2)

c write(13,52) a(3)
cc write(13,52) a(5)
c18 write(13,52) a(20)
carch write(13,52) a(44)
cc52 format(f10.6)

c51 continue
c
cc10 format('t5,'Load','t13,'Load',
cc $ t28,'External','t62,'No. of')
cc20 format('t5,'Step','t13,'Multiplier',
cc $ t28,'Load','t45,'Displacement',
cc $ t62,'Iter.')
cc30 format('t5,i3,t13,f10.6,t28,f10.6,t45,f12.6,t62,i3)

c print *,'end of result'
c pause
c stop
c** "func_in.dat"*****
c appliedforce1 = exlk * exfor(1)
c appliedforce2 = exlk * exfor(2)
c print *,'result'
c print *,exlk=,exlk
c print *,exfor(1)=,exfor(1)
c print *,exfor(2)=,exfor(2)
c pause
c if(istep .eq. 1) then
c write(15,53)
c53 format(' istep exlk appliedforce1 appliedforce2
c $ a(1) a(2) it ad(5) ad(7)')
c endif
c write(15,50) *,istep,exlk,appliedforce1,appliedforce2,
c c dqtot(1),dqtot(2),it,
c c ad(5),ad(7)
c50 format(a1,2x,i6,5x,e16.8,3x,e10.4,6x,e10.4,4x,e10.4
c c 4x,e10.4,4x,i5,4x,e10.4,3x,e10.4)
c*****
c return
c end

C*****
C** SUBROUTINE: ITNRML **
C*****
c subroutine itrml(itmax,toldis,tolfor,dli,dlim1,
c $ exlk,iconv,iflag,it,ne,ipvl)
c subroutine itrml(itmax,dli,dlim1,b,exfor,ad,nctype,qk,
c $ iflag,it,ne,ipvl,ndof,ia,nel,ncoef1,jcall,
c $ icall,icj,icj,icj,maxdofpc,dqtot,dqi,dqim1,
c $ ja,an,propmat,prosect,x,y,z,ndofpn,numnodes,
c $ ip,iu,disp,ianal,ndofpc,iskip,itempo2,iarc,lm,
c $ itrmlon,iboundc,esin,elk)
c
c use
c
c implicit real*(a-h,o-z)
c common/RJK/ stih(20,20),dqk(500),dqim1(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),finitk(50),
c $ resk(50),scal1(50),work1(50),indx(50),neq
c common/RJK/ stih(20,20),dqim1(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),finitk(50),
c $ resk(50),scal1(50),work1(50),indx(50),neq
c common/RJK/ stih(20,20),dqk(5000),dqk1(5000),
c $ dqk2(5000),finitk(5000),

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$ resk(5000),scali(5000),work1(5000),indx(5000),neq
c      common/deltaqi/dqi(500)

common/av/a(1500),jgf,jgsm,np,nbw,np2,nbw2
common/disp/ux(2),uy(2),uz(2)
common/infor/getforce,finx(2),finy(2),finz(2),getstiff,getsolve
common/zvector/za(1500),zai(1500),za2(1500),za3(1500),jpick
common/testing/toldis,tolfor,exlk,iconv

dimension ic(*),je(*),jet(*),jst(*),b(*),exfor(*),nci(*)
dimension dqtor(*),dqi(*),dqim1(*),ad(*),qk(*)
c dimension dqtor(*),dqi(*),dqim1(*),qk(*),ia2(*),ad(*)
dimension ja(*),an(*),disp(*)
c dimension an(*),disp(*)
dimension propmat(1),propsect(1),x(*),y(*),ip(*),iu(*)
dimension itempo2(*),lm(1),ae(1)
dimension iboundc(*)
c dimension itempo2(*),lm(1),elk(maxdofpc,maxdofpc)

c dimension stiff(neq,neq),dqi(neq),dqim1(neq),dqk(neq),
c $ dqk1(neq),dqk2(neq),exfor(neq),fintk(neq),qk(neq),
c $ resk(neq),scali(neq),work1(neq)

c
c      deallocate (ja)

itrnml=1 !Let everyone know we are going thru "itrnml"
c      "sysqcn" "&" "assembly" need to do something more

c print *,!!!!!!!!!!!!!! starting itrnml !!!!!!!!!!!!!!!
c      pause
c      print *,'itempo2(1) inside itrnml=',itempo2(1)
c      pause

c      print *,'ad stiff=',(ad(i),i=1,maxdofpc**2)
c      pause

c print *,'ipick =',ipick
c print *,'istep =',istep
c print *,'it =',it
c print *,'getforce =',getforce
c print *,'getstiff =',getstiff
c      print *,'qk(-) start of itrnml=',(qk(i),i=1,ndof)
c print *,'b start of itrnml=',(b(i),i=1,ndof)
c print *,'ad(-) start itrnml=',(ad(ic),ic=1,ndof)
c print *,'an(-) start itrnml=',(an(ic),ic=1,50)
c      pause
c      stop
c print *,'a at start of itrnml =',a
c print *,'exlk at start of itrnml =',exlk
c print *,'dqi at start of itrnml =',(dqi(i),i=1,ndof)
c print *,'exfor at start of itrnml =',(exfor(i),i=1,ndof)
c      pause
c      stop
c      dlk = 0.d0
c      iconv = 1
c      iflag = 0
c      it = 0

c      do 20 i=1,neq
c      do 10 j=1,neq
c      stiff(i,j) = 0.d0
c 10 continue
c      print *,'exfor(i) start =',exfor(i)
c      dqk(i) = 0.d0
c      dqk1(i) = 0.d0
c      dqk2(i) = 0.d0
c      fintk(i) = 0.d0
c      work1(i) = 0.d0
c      print *,'exfor(i) end =',exfor(i)
c 20 continue
c** set counter equal to zero for next "it"
iam = 0
c print *,'exfor =',exfor
c      stop
c print *,'iconv =',iconv
c print *,'itemax =',itemax
c print *,'it =',it
c++++++
c 1002 if (iconv .ne. 0 .and. it .le. itemax) then
c      print *,'iconv =',iconv
c      print *,'it =',it
c      print *,'itemax =',itemax
c      stop
c      it = it + 1
c      write(*,*) 'Beginning Iteration Number:',it
c      stop
c ... compute Kik for eqn. 4.97
cc print *,'ne & ipvl inside itrnml =',ne,ipvl
c print *,'qk inside itrnml=',qk
c c      pause
c      stop
c      Getforce=1
c**Only get stiffness
c      Getsolve=0
c      Getforce=0
c      Getstiff=1
c      print *,'exfor =',exfor
c      print *,'chk before sysqcn inside itrnml'
c      write(6,*)'chk before sysqcn inside itrnml'
c      stop

c      deallocate (ja)
c      deallocate (itempo1)
c      deallocate (an)
c      print *,'***** iskip in itrnml *****'
c      print *,'***** iskip in itrnml *****'
c      pause
c      print *,'iskip in itrnml before 1st sysqcn=',iskip
c      pause
c      print *,'iskip in itrnml before 1st sysqcn=',iskip

c      pause
c      print *,'iskip in itrnml before 1st sysqcn=',iskip
c      pause
c      print *,'getforce in itrnml before 1st sysqcn=',getforce
c      print *,'getstiff in itrnml before 1st sysqcn=',getstiff

c      pause
c      print *,'*****'
c      print *,'*****'
c      print *,'disp before 1st sysqcn in itrnml=',(disp(i),i=1,ndof)
c      print *,'*****'
c      print *,'*****'
c      pause
c      print *,'ad stiff before=',(ad(i),i=1,ndof)
c      pause
c      print *,'an stiff=',(an(i),i=1,maxdofpc**2)
c      print *,'ae(-) before 1st sysqcn in itrnml=',(ae(ic),ic=1,18)
c      print *,'b(-) before=',(b(ic),ic=1,ndof)
c      pause
c      print *,'exfor(-) =',(exfor(ic),ic=1,ndof)
c      pause
c      pause

c      call sysqcn(ne,ipvl,b,ndof,disp,iarc,qk,
c      $ reall,ic,je,jet,jst,call,ia,ae,maxdofpc,
c      $ neltpe,nel,ndofpc,x,y,z,propmat,propsect,lm,
c      $ iboundc,ad,an,iperm,iu,ip,iut,dqtor,dqi,dqim1,
c      $ ux,uy,uz,di,ita,area,youngm,
c      $ ialan,lumpmass,iskip,itempo2,itrnmlon,exfor,istep,
c      $ zvec,dlength,ixex)

c $ja,iboundc,ndofpod,be,lm,ndofpod,ad,ip,tempo1,dm,am,ialan,lumpmass)
c print *,'dqk1 after sysqcn in itrnml=',dqk1
c print *,'*****'
c print *,'*****'
c print *,'disp after 1st sysqcn in itrnml=',(disp(i),i=1,ndof)
c      pause
c print *,'b after 1st sysqcn in itrnml=',(b(i),i=1,ndof)
c      pause
c print *,'ad stiff after 1st sysqcn=',(ad(i),i=1,ndof)
c      pause
c print *,'an(-) after 1st sysqcn in itrnml=',(an(ic),ic=1,50)
c print *,'ae stiff after 1st sysqcn=',(ae(ic),ic=1,maxdofpc**2)
c print *,'*****'
c print *,'*****'
c      pause

c print *,'exfor(-) =',(exfor(ic),ic=1,ndof)
c      pause

c      if (it .eq. 2) then
c      print *,'it =',it
c      print *,'disp after 1st sysqcn in itrnml=',(disp(ic),ic=1,ndof)
c      print *,'b(-) after 1st sysqcn in itrnml=',(b(ic),ic=1,ndof)
c      print *,'ad stiff after 1st sysqcn=',(ad(ic),ic=1,maxdofpc**2)
c      print *,'an(-) after 1st sysqcn in itrnml=',(an(ic),ic=1,50)
c      stop
c      endif

c      stop

c      pause
c      print *,'chk after sysqcn inside itrnml'
c      write(6,*)'chk after sysqcn inside itrnml'
c      write(6,*)'b after 1st sysqcn in itrnml=',(b(i),i=1,neq)
c      write(6,*)'disp after 1st sysqcn in itrnml=',(disp(i),i=1,neq)

c      stop

c print *,'exfor(-) =',(exfor(ic),ic=1,ndof)
c      pause

c~~~~~ SETTING ZERO DIAGONAL VALUES TO ONE ~~~~~
c      do 1014 i=neq**2+1,neq**3
c      do 1014 i=1,neq
c      if (ad(i).GT..00001) GoTo 1014
c      if (ad(i).GT.1.e-8) GoTo 1014
c      ad(i)=1.e-8
c      ad(i)=0.d0
c 1014 continue

c      print *,'exfor(-) =',(exfor(ic),ic=1,ndof)
c      pause

c??? do 702 i=1,neq
c      scali(i) = 1.d0/stiff(i,i)
c c c print *,'a(neq**2+i) =',a(neq**2+i)
cc scali(i) = 1.d0/a(neq**2+i) !!!Get diagonal
c??? scali(i) = 1.d0/ad(i) !!!Get diagonal

c??? print *,'scali =',scali(i)
c??? write(6,*)scali =,scali(i)
c??? 702 continue

c** call modify to get the stiffness w/deleted rows/columns
cc call modify
c print *,'dqk1 after modify in itrnml=',dqk1
c      stop
c print *,'Check after fifth modify'
c print *,'a" after 5th modify =',a
c      pause
c c print *,'ibstor =',ibstor
c c print *,'bvstor =',bvstor
c      stop

c      Getstiff = 0 ! set getting just stiff back to zero

cc print *,'a after sysqcn inside itrnml =',a
c      if (it .eq. 2) then
c      print *,'it =',it
c      print *,'a at it=2 =',a
c      stop

```

```

c      endif
c      call stiff

cc      print *, 'stiff inside itnrm1 = ', stiff
c ... compute (dqk1)1 using eqn. 4.97
c ... compute (dqk1)2 using eqn. 4.99
c      print *, 'exfor( ) = ', (exfor(ic), ic=1, ndof)
c      pause
c      stop

      do 30 i=1, ncoq
        dqk1(i) = exfor(i)
c      dqk1(i) = b(i)
c      dqk2(i) = resk(i)
c      print *, 'exfor(i) = ', exfor(i)
c      print *, 'dqk1(i) & i = ', dqk1(i), i
c      print *, 'resk(i) & i = ', resk(i), i
c      print *, 'dqk2(i) & i = ', dqk2(i), i
30      continue
c      pause
c      print *, 'dqk1( ) = ', (dqk1(ic), ic=1, ncoq)
c      pause
c      print *, 'dqk2( ) = ', (dqk2(ic), ic=1, ncoq)
c      pause
c      stop

c c      print *, 'resk = ', resk

c put dqk1(i) into big "a(i) as a force, get out as displacement"
      j=0
cc      print *, 'neq, neq2, np2 = ', ncoq, ncoq2, np2
c      stop
c      print *, 'a = ', a
c      stop
c .....
c      If (ityp .eq. 6) Then
cc      do 31 i=ncoq+1, ncoq*2

      do 31 i=1, ncoq
cc      j=j+1
c      a(i)=dqk1(j)

      b(i)=dqk1(i)
c      print *, 'b(i) before new 2nd sysqcn = ', b(i)
c      pause
c c      print *, 'a(i) i = ', a(i), i
c      print *, 'dqk1(i) = ', dqk1(i)
31      continue
c      print *, 'b( ) after dqk1( ) = ', (b(ic), ic=1, ncoq)
c      pause

CXX      write(6, *) 'b(i) inside itnrm1 = ', (b(i), i=1, ncoq)
c      Endif
c      If (ityp .eq. 12) Then
c      do 34 i=ncoq+1, ncoq*3
c      j=j+1
c      a(i)=dqk1(j)
c      print *, 'a(i) i = ', a(i), i
c c      print *, 'dqk1(j) j = ', dqk1(j), j
c 34      continue
c      Endif
c .....

c      print *, 'dqk1 = ', dqk1
c      stop
c      call solve(dqk1)
cc c      print *, 'n before ludecmp = ', n
c      stop
cc c      print *, '****ludecmp 3****'
c      pause

cc      write(*, *) 'Before dcmphd inside itnrm1'
c      print *, 'a = ', a
c      stop
c** solve for new "dqk1"

      ipick = 1

cc      call dcmphd
cc      print *, 'after dcmphd'
c      print *, 'a after dcmphd inside itnrm1 = ', a
c      stop
cc      write(*, *) 'After dcmphd inside itnrm1'
cc      call slvbd
c      write(*, *) 'After slvbd1 & ipick=1 inside itnrm1'
c      stop
c      print *, '##### NEW SYSEQN ADDED itnrm1 #####'
c      print *, '##### 2nd Sysseqn in itnrm1 #####'
c      pause

c      print *, '*****'
c      print *, '*****'
c      print *, 'disp before 2nd sysseqn in itnrm1 = ', (disp(i), i=1, ndof)
c      pause
c      print *, 'b before 2nd sysseqn in itnrm1 = ', (b(i), i=1, ndof)
c      pause
c      print *, 'ad stiff before 2nd sysseqn = ', (ad(i), i=1, maxdofpe**2)
c      pause
c      print *, 'an( ) before 2nd sysseqn in itnrm1 = ', (an(ic), ic=1, 50)
c      pause
c      print *, 'ac stiff after 1st sysseqn = ', (ac(i), i=1, maxdofpe**2)
c      print *, '*****'
c      print *, '*****'

c ... I only want to solve, I don't want update forces or stiff
      getforce=0
      getstiff=0
      getsolve=1
c      print *, 'getsolve=1 inside itnrm1 before 2nd sysseqn'
c      pause
c ... Need to solve eqns only, no new loads or stiff!
      call sysseqn(ne, ipvl, bndof, disp, iarc, qk,

```

```

S      reall, ic, ic, jet, jet, ja, ac, maxdofpe,
S      neltypc, nel, ndofpe, x, y, z, propmat, prosect, lm,
S      iboundc, ad, am, iperm, iu, ip, iut, dqtot, dq1, dqm1,
S      ux, uy, uz, di, t, ar, ea, youngm,
S      ianal, lumpmass, iskip, itempo2, itnrm1on, exfor, istep,
S      zeed, dLength, iex)

c      print *, '##### END SYSEQN #####'
c      pause
c      print *, '##### After 2nd Sysseqn in itnrm1 #####'
c      pause
c      pause
c      pause
c      print *, 'neq = ', neq
c      print *, 'disp( ) after 2nd sysseqn solve = ', (disp(ic), ic=1, ndof)
c      pause
c      print *, 'b(i) after new 2nd sysseqn = ', (b(ic), ic=1, ndof)
c      pause
c      print *, 'ad after 2nd sysseqn solve = ', (ad(i), i=1, maxdofpe**2)
c      print *, 'an after 2nd sysseqn solve = ', (an(i), i=1, 50)
c      pause
c      If (it .eq. 2) then
c      print *, 'i = ', it
c      print *, 'disp after 2nd sysseqn in itnrm1 = ', (disp(ic), ic=1, ndof)
c      print *, 'b( ) after 2nd sysseqn in itnrm1 = ', (b(ic), ic=1, ndof)
c      print *, 'ad stiff after 2nd sysseqn = ', (ad(ic), ic=1, maxdofpe**2)
c      print *, 'an( ) after 2nd sysseqn in itnrm1 = ', (an(ic), ic=1, 50)
c      stop
c      endif

c      stop
c      print *, 'ae after 2nd sysseqn = ', (ae(i), i=1, maxdofpe**2)
c      pause
c      pause
c      print *, 'dqk1( ) = ', (dqk1(ic), ic=1, 9)
c      pause

c** set "dqk1" equal to the solution displ stored in "a"
      DO 178 LL=1, ncoq
cc      dqk1(LL) = a(LL)
c      dqk1(LL) = disp(LL)
c      print *, 'dqk1( ) after new sysseqn = ', dqk1(LL)
178      continue
c      pause
c      write(6, *) 'dqk1(LL) inside itnrm1 = ', (dqk1(LL), i=1, ncoq)
c      print *, 'a = ', a
c      print *, 'dqk1 = ', dqk1
c      stop
c** new dqk1 from big "a"
cc      print *, 'neq = ', neq
c      stop
c** get out "dqk1" as displacement, now put back into "a" at displace
c** NO leave dqk1 in own vector, donot put into "a"
c      do 177 ink=1, ncoq
c      dqk1(ink)=a(ink)
c c      print *, 'a(ink) = ', a(ink)
c c      print *, 'dqk1(ink) & ink = ', dqk1(ink), ink
c 177      continue
c      stop

cc      call ludecmp(stiff, n, np, indx, X)
cc c      print *, 'n after ludecmp = ', n
c      stop
c      call lubksb(stiff, n, np, indx, dqk1)
c      print *, 'np = ', np
c      print *, 'neq = ', neq
c      pause
c      do 12 i=1, np
c      do 12 i=1, ncoq
12      indx(i)=0

c** Now do the same for dqk2

c      call solve(dqk2)

c put dqk2(i) into big "a(i) as a force, get out as displacement"
      j=0
cc      print *, 'neq, neq2, np2 = ', ncoq, ncoq2, np2
c      stop
c .....
c      If (ityp .eq. 6) then
c      do 32 i=1, ncoq
c      j=j+1
c      a(i)=dqk2(j)

      b(i)=dqk2(i)
c c      print *, 'a(i) = ', a(i)
c      print *, 'dqk2(i) = ', dqk2(i)
32      continue
c      print *, '##### After 3rd Sysseqn inside itnrm1 #####'
c      pause

c      If (istep.gt.900) Then
c      print *, 'dqk2( ) inside itnrm1 = ', (dqk2(ic), ic=1, ncoq)
c      print *, 'b( ) inside itnrm1 = ', (b(ic), ic=1, ncoq)
c      pause
c      Endif

c      write(6, *) 'dqk2( ) inside itnrm1 = ', (dqk2(ic), ic=1, ncoq)
c      Endif

c      If (ityp .eq. 12) then
c      do 33 i=ncoq+1, ncoq*3
c      j=j+1
c      a(i)=dqk2(j)
c c      print *, 'a(i) = ', a(i)
c c      print *, 'dqk2(j) = ', dqk2(j)
c 33      continue
c      Endif
c .....

c      stop

cc      write(*, *) 'Before dcmphd inside itnrm1 2nd time'
c      stop

```



```

        ipick = 2
*****

* Not sure if "a" is getting rewritten and used properly????

*****
cc print *, 'a before dcmprbd =', a
c print *, 'dqj before dcmprbd =', dqj
c print *, 'dqk1( ) inside intml =', (dqk1(ic), ic=1, nreq)
c pause
c stop
cc call dcmprbd
c stop
c write(*,*) 'After dcmprbd inside intml 2nd time'
cc call slvbd
c write(*,*) 'After slvbd & ipick=2 inside intml 2nd time'
c print *, '##### END SYSEQN 3 #####'
c... I only want to solve, I don't want update forces or stiff
        getforce=0
        getstiff=0
        getsolve=1
c print *, 'getsolve=1 inside itnrm1 before 3rd sysqcn'
c pause
c print *, 'b(i) before new 3rd sysqcn=', (b(ic), ic=1, ndof)
c pause
c print *, 'ad before 3rd sysqcn solve=', (ad(i), i=1, maxdofpe**2)
c pause
c print *, 'disp( ) before 3rd sysqcn solve only=', (disp(ic), ic=1, ndof)
c pause
c... Need to solve eqns only, no new loads or stiff!
        call sysqcn(nc, plvl, h, ndof, disp, aarc, qk,
$         read, ic, ic, ic, call, ia, ae, maxdofpe,
$         nelype, nely, ndofpe, x, y, z, propmat, propsect, lm,
$         rboundc, ad, an, iperm, iu, ip, iut, dgetor, dqj, dqim1,
$         ux, uy, uz, di, it, area, youngm,
$         ialal, lumpmass, iskip, itempo2, itnrm1on, cxfor, istep,
$         zee, dlength, iex)
c print *, '##### END SYSEQN 3 #####'
c pause
c print *, 'neq=', neq
c
c print *, 'b(i) after new 3rd sysqcn=', (b(ic), ic=1, ndof)
c pause
c print *, 'ad after 3rd sysqcn solve=', (ad(i), i=1, maxdofpe**2)
c pause
c print *, 'an after 2nd sysqcn solve=', (an(i), i=1, 50)
c stop
c
c If( it .eq. 2) then
c print *, 'it =', it
c print *, 'disp after 3rd sysqcn in itnrm1=', (disp(ic), ic=1, ndof)
c print *, 'b( ) after 3rd sysqcn in itnrm1=', (b(ic), ic=1, ndof)
c print *, 'ad stiff after 3rd sysqcn=', (ad(ic), ic=1, maxdofpe**2)
c print *, 'an( ) after 3rd sysqcn in itnrm1=', (an(ic), ic=1, 50)
c stop
c endif
c
c print *, 'disp( ) after 3rd sysqcn solve only=', (disp(ic), ic=1, ndof)
c pause
c** set "dqk1" equal to the solution displ stored in "a"
DO 179 LL=1, neq
cc dqk2(LL) = a(LL)
dqk2(LL) = disp(LL)
c print *, 'dqk2 =', dqk2(LL)
179 continue
cc print *, 'a after slvbd =', a
c print *, 'dqk1 =', dqk1
c print *, 'dqk2 =', dqk2
c stop
c call stiff
ccccc call sysqcn(nc, plvl)
c stop
do 13 i=1, np
indx(i)=0
c ... compute dlk using eqn. 4.101
dprd1 = 0.d0
dprd2 = 0.d0
do 40 i=1, nreq
c print *, 'dqj( ) dqk1( ) dqk2( ) =', dqj(i), dqk1(i), dqk2(i)
dprd1 = dprd1 + dqj(i)*dqk2(i)
dprd2 = dprd2 + dqj(i)*dqk1(i)
40 continue
c write(6,*) dprd1 inside itnrm1=, dprd1
c write(6,*) dprd2 inside itnrm1=, dprd2
c
c If(istep.gt.900)Then
c print *, 'dqj(i)=', dqj
c print *, 'istep=', istep
c print *, 'dqk1(i)=', (dqk1(ic), ic=1, ndof)
c print *, 'dqk2(i)=', (dqk2(ic), ic=1, ndof)
c print *, 'dprd1=', dprd1
c print *, 'dprd2=', dprd2
c print *, 'ad( )=', (ad(ic), ic=1, ndof)
c pause
c Endif
c
c Testv2=dlk*(dprd2+dlim1)
c print *, 'istep=', istep
c print *, 'Testv2=', testv2
c pause
c
c If(Testv2.lt.-1.6e-5)Then
c dli=-1.*dli
c Else
c dli=1.*dli
c Endif
c
c If(dprd1.lt.0.0.and.dprd2.lt.0.0)Then
c If(dprd1.gt.-.00001.and.dprd2.gt.-.1)Then
c dli=-1.*dli
c Endif
c Else
c dli=1.*dli
c Endif
c
c print *, 'dprd1 =', dprd1
c print *, 'dprd2 inside itnrm1= ', dprd2
c pause
c print *, 'dli inside itnrm1= ', dli
c stop
c dlk = (dprd1)/(dprd2 + dli)
c print *, 'dlk inside itnrm1 = ', dlk
c stop
c ... update the external load multiplier exlk
c print *, 'exlk before = ', exlk
c
c If(istep.gt.561)then
c dlk = -1.d0*dlk
c Endif
c
c exlk = exlk - dlk
c
c If(istep.eq.561)then
c exlk = -1.d0*exlk
c Endif
c
c print *, '1st exlk in itnrm1 = ', exlk
c pause
c print *, 'dlk in itnrm1= ', dlk
c pause
c write(6,*) '1st exlk in itnrm1 = ', exlk
c write(6,*) 'dlk in itnrm1= ', dlk
c stop
ccc pause
c stop
c ... update dlim1 for next load step
dlim1 = dlim1 - dlk
c stop
c ... compute dqk using eqn. 4.94
c ... update dqim1 for next load step
c ... update the total displacements using eqn. 4.103
c print *, 'neq = ', neq
c stop
do 50 i=1, nreq
c If(istep.eq.914)Then
c dqk(i) = dqk2(i) + dlk*dqk1(i)
c Else
c dqk(i) = dqk2(i) - dlk*dqk1(i)
c Endif
c If(dqk1(i).lt.0.0)Then
c print *, 'istep=', istep
c print *, 'dqk(11)=', dqk(11)
c pause
c Endif
c stop
c dlim1(i) = dlim1(i) + dqk(i)
c dqim1(i) = dqim1(i) + dqk(i)
c print *, 'dqim1(i) & i =', dqim1(i), i
c print *, 'qk(11) before=', qk(11)
c qk(i) = qk(i) + dqk(i) !Update Total Displacements
c print *, 'qk(11) after=', qk(11)
50 continue
c
c print *, 'istep=', istep
c print *, 'dqk(11)=', dqk(11)
c print *, 'qk(11)=', qk(11)
c pause
c
c If(istep.gt.900)Then
c print *, 'istep=', istep
c print *, 'dqj( )=', (dqj(ic), ic=1, nreq)
c print *, 'dqk( )=', (dqk(ic), ic=1, nreq)
c print *, 'qk( )=', (qk(ic), ic=1, nreq)
c print *, 'dli( )=', (dli(ic), ic=1, nreq)
c print *, 'dlk( )=', (dlk(ic), ic=1, nreq)
c print *, 'ad( )=', (ad(ic), ic=1, nreq)
c pause
c
c Do 5050 ii=1, nreq
c dqim1(ii) = dqim1(ii) + dqk(ii)
c5050 continue
cc If(istep.gt.911)Then
c If(istep.gt.136)Then
cc print *, 'istep=', istep
cc print *, 'dqk1(i)=', (dqk1(ic), ic=1, nreq)
cc print *, 'dlk=', dlk
cc print *, 'dqk2(i)=', (dqk2(ic), ic=1, nreq)
cc print *, 'dqk(i)=', (dqk(ic), ic=1, nreq)
cc print *, 'qk(i)=', (qk(ic), ic=1, nreq)
cc print *, 'ad(ic)=', (ad(ic), ic=1, nreq)
cc pause
cc Endif
cc write(6,*) qk(i)=, (qk(i), i=1, nreq)
cc print *, 'qk(i)=', (qk(ic), ic=1, nreq)
cc pause
c stop
c
c print *, 'exlk =', exlk
cc print *, 'dlim1 =', dlim1
cc print *, 'dqk=', dqk
cc print *, 'qk=', qk
cc print *, 'dqim1(1)=', dqim1
c ... compute the internal forces, fink, at qk
c call forces

```



```

1 continue
f(1)=3*d0*u(1)**2+12.d0*u(2)**2-10.d0*u(1)
f(2)=24.d0*u(1)*u(2)+4.d0*u(2)+3.d0
print *,f(1) inside funct = ',f(1)
print *,f(2) inside funct = ',f(2)
pause
go to 999
c.....Arora's nonlinear example, page 331
c.....Minimize phi = 5X1**2+2X1X2+X2**2+7
c.....correct (exact) solution = {0, 0}
13 continue
f(1)=10.d0*u(1)+2.d0*u(2)
f(2)=2.d0*u(1)+2.d0*u(2)
go to 999
c.....Arora's nonlinear example, page ???
c.....correct (exact) solution = {-1/3, -1/2}
14 continue
f(1)=24.d0*u(1)-12.d0*u(2)+2.d0
f(2)=8.d0*u(2)-12.d0*u(1)
go to 999
15 continue
c.....J. Dennis's optimization book, page 172
c.....(hard time for BFGS ??) example
c.....correct (exact) solution = {0,3}, and also {3,0}
f(1)=u(1)+u(2)-3.0
f(2)=u(1)**2+u(2)**2-3.0
go to 999
16 continue
c.....J. Dennis's optimization book, page 201
c.....correct exact solution = {2,-1}
f(1)=4.d0*(u(1)-2.d0)**3+3.d0*(u(1)-2.d0)*u(2)**2
f(2)=2.d0*(u(1)-2.d0)**2*u(2)+2.d0*(u(2)+1.d0)
go to 999
17 continue
c.....J. Dennis's optimization book, page ???
c.....correct exact solution = {0.00228, 0.00228}
f(1)=4.d0*u(1)**3+4.d0*u(1)*u(2)**2
f(2)=4.d0*u(2)**2+4.d0*u(2)**3
go to 999
18 continue
c.....Osman's nonlinear hydraulic example
c.....correct solution = {-10.0, 40.0, 30.0, 157.1}
c1=-0.02057
f(1)=c1*u(1)*dabs(u(1)) - u(4) + 155.0
f(2)=c1*u(2)*dabs(u(2)) - u(4) + 190.0
f(3)=c1*u(3)*dabs(u(3)) + u(4) - 138.6
f(4)=u(1)+u(2)-u(3)
go to 999
c.....Mathcad Indefinite case
c.....correct (exact) solution = {1.089, 839}
c19 continue
c f(1)=u(1)+u(1)*u(2)-2.d0
c f(2)=u(1)**2+4.d0*u(2)**2-4.d0
c go to 999
c.....Nonlinear Truss example
19 continue
f(1)=0.d0
A = 1.d0
E = 1.d7
sprk = 3.d0
hgt = 1.d0
print *, 'A, E, sprk, hgt inside funct = ', A, E, sprk, hgt
print *, f(1) inside funct = ', f(1)
c stop
c L1 = dsqrt((100.d0)**2 + (hgt)**2)
c L1i = dsqrt((100.d0)**2 + (hgt-u1)**2)
c L = 10.d0
c L1=14.1421d0
c L2=10.d0
c L1i=0.d0
c L2i=0.d0
c D = 14.142d0
c
c u2 = u(2)
c print *, 'u1 = ', u1
c print *, 'u2 = ', u2
c pause
c L1i = dsqrt((10.d0+u1)**2 + (L2+u2)**2)
c print *, 'L1i = ', L1i
c L2i = dsqrt((L2+u2)**2 + u1**2)
c print *, 'L2i = ', L2i
c pause
c Rcos1 = (10.d0+u1)/L1i
c Rcos1a = 10.d0/L1
c Rsin1 = (L2 + u2)/L1i
c Rsin1a = L2/L1
c Rcos2 = u1/L2i
c Rcos2a = 0.d0
c Rsin2 = (L2 + u2)/L2i
c Rsin2a = 1.d0
c
c P1 = (A/E/L1) * (L1i-L1)
c P2 = (A/E/L2) * (L2i-L2)
c print *, 'P1 = ', P1
cc print *, 'P2 = ', P2
c pause
c print *, 'u1 inside funct = ', u1
c print *, 'u2 inside funct = ', u2
c print *, 'f(1) & f(2), f(1), f(2)
c...u1 is the incremental displacements from previous step
u1 = u(1)
print *, 'u1 inside funct = ', u1
print *, 'force = ', force
c stop
c f(force.eq,1)then
L1 = dsqrt((100.d0)**2 + (hgt)**2)
Else
c.....The new deformed geometry ready for next step
L1 = dsqrt((100.d0)**2.d0 + (hgt-u1)**2.d0)
print *, 'New starting length L1 inside funct = ', L1
c....get next guess using old u1 plus .1
c u1=u1+.1

```

C.2 Hrinda Rikarc Optimization

```

implicit real*8(a-h,o-z)
dimension nel(6),ndofpe(6),iflag(100)! assuming 6 finite element types
dimension dqk(5000),dqk(5000)

common/infor/getforce,finx(2),finy(2),finz(2),getstiff,getsolve
common/disp/ux(2),uy(2),uz(2),P(6),B1(6)

common/RIK/ stiff(60,60),dqk1(5000),
$ dqk2(5000),fintk(5000),
$ resk(5000),scal(5000),workl(5000),indx(5000),neq

common/testing/toldis,tolfor,endk,iconv

integer, allocatable:: iet(:),jct(:),ibound(:),iet(:),jct(:)
$jpc(:),iut(:),iuf(:),iup(:),ismc(:),lm(:),ipom(:),iat(:),jat(:)
$jju(:),jut(:),itempol(:),iareac(:),ilimit(:),kprop(:),
$ISEDchk(:),minareac(:)

double precision, allocatable:: b(:),bef(:),aef(:),ad(:)
$,x(:),y(:),z(:),propmat(:),propsoe(:),dqtoft(:)
$,tempo1(:),tempo2(:)
$,di(:),am(:),um(:),evalues(:),evectors(:),dm(:),lam(:)
$,elm(:);
$.disp(:),qk(:),exfor(:)
$,strainel(:),strainE(:),strainD(:),weight(:),Anew(:)
$,Anew2(:),Anew3(:),VED(:),VEDoid(:),Apart(:),SEDSum(:)
$,Fin1(:),Fin2(:),WF(:),Dimitt(:),xlief(:),SED(:)

double precision, allocatable:: tempo3(:)

c
c open(unit=5,file='input3.dat',status='old')
c open(unit=6,file='output3.dat',status='old')
cbar open(unit=5,file='barc.dat',status='old')
carch open(unit=5,file='arch3dim.dat',status='old')
carch2 open(unit=5,file='arch2dim.dat',status='old')

```

```

carch3      open(unit=5,file='arch3in.dat',status='old')
cframe2     open(unit=5,file='frame_in.dat',status='old')
             open(unit=5,file='frame2_in.dat',status='old')

ct3a        open(unit=5,file='t3a_in.dat',status='old')!3mem truss triangle
cpod        open(unit=5,file='tpod_in.dat',status='old')
c            open(unit=5,file='tpod2_in.dat',status='old')
ctwo        open(unit=5,file='twobar_in.dat',status='old')

csdof       open(unit=5,file='cris_s dof_in.dat',status='old')
ckhot       open(unit=5,file='khot_2ele_in.dat',status='old')
             open(unit=5,file='khot_2ele_mod_in_unsym.dat',status='old')
             open(unit=8,file='khot_2ele_mod_in_unsym_areas.dat',status='old')

ckhot2_sym  open(unit=5,file='khot_2ele_mod_in_sym.dat',status='old')
ckhot2_sym  open(unit=8,file='khot_2ele_mod_in_sym_areas.dat',status='old')
ckhot2_sym  c status='old')

ckhot4      open(unit=5,file='khot_4ele_mod_in.dat',status='old')
ckhot4      open(unit=8,file='khot_4ele_mod_in_areas.dat',status='old')

cdome       open(unit=5,file='dome2_opt_mod_in.dat',status='old')
cdome       open(unit=8,file='dome2_opt_mod_in_areas.dat',status='old')

cshallow    open(unit=5,file='shallow_truss_in.dat',status='old')
cshallow    open(unit=8,file='shallow_truss_areas.dat',status='old')

c            open(4,file='SED_out.txt',status='unknown')
c            open(3,file='SED_out.txt',status='unknown')
c            open(2,file='SED.txt',status='unknown')

c            open(unit=5,file='khot_6ele_mod_in.dat',status='old')
c            open(unit=5,file='khot_10ele_mod_in.dat',status='old')
c            open(unit=5,file='khot_11ele_mod_in.dat',status='old')
c            open(unit=5,file='khot_12ele_mod_in.dat',status='old')
c            open(unit=5,file='khot_18ele_mod_in.dat',status='old')
c            open(unit=5,file='khot_20ele_mod_in.dat',status='old')

cxxx        open(unit=5,file='dome2_opt_mod_in.dat',status='old')
cdome2      open(unit=5,file='dome2_opt_mod_in_initial.dat',status='old')

carch3d     open(unit=5,file='arch3d_opt_mod_half_in_initial.dat',status='old')

carch3d_half open(unit=5,file='arch3d_opt_mod_half_in_initial.dat',status='old')

carch41     open(unit=5,file='arch41_opt_mod_half_in_initial.dat',status='old')

c            open(unit=5,file='dome_in.dat',status='old')

csnap       open(unit=5,file='snap_in.dat',status='old')

csnap4      open(unit=5,file='snap4_in.dat',status='old')

c            open(unit=5,file='snap5_in.dat',status='old')

cdome7      open(unit=5,file='dome7_in.dat',status='old')
ctruss      open(unit=5,file='truss7_3d_in.dat',status='old')

c            open(unit=5,file='bar2a.dat',status='old')
c            open(unit=5,file='bar2b.dat',status='old')
c            open(unit=6,file='bar2out.dat',status='old')
carch       open(unit=6,file='arch3dot.dat',status='old')
cframe      open(unit=6,file='frame_out.dat',status='old')
ctwo        open(unit=6,file='twobar_out.dat',status='old')

csdof       open(unit=6,file='cris_s dof_out.dat',status='old')
ckhot       open(unit=6,file='khot_2ele_out.dat',status='old')
cdome2      open(unit=6,file='dome2_opt_out.dat',status='old')
cdome       open(unit=6,file='dome_out.dat',status='old')

csnap       open(unit=6,file='snap_out.dat',status='old')
ct3a        open(unit=6,file='t3a_out.dat',status='old')
cpod        open(unit=6,file='tpod_out.dat',status='old')
ctruss      open(unit=6,file='truss7_3d_out.dat',status='old')
             open(unit=7,file='data_out.dat',status='old')

c+++++++
c
c      write(6,*) 'Version Date = 03-01-2004'
c.....input general information
netype=6
             ! assuming 6 finite element types
             itype=12 ! type ele is 3d from GAII
             iopt=0 !if=1 then going thru rik again for optimizer!
             N=1 !counter for times thru rikarc

c...area ratio=1 means section areas have been ratioed after rikarc
iratio=0 !area ratio
weighttotal=0.d0
weightold=0.d0

c...below used in determining (SSP)step size parameter
ie1k=0!this is 1 if exkld0, 2 if exkld1 & 3 if exkldk

c            allocate(VED(100),VEDold(100),iarea(100))!100 = num elements

1000        Continue !Dummy statement
rewind (5)
c            open(unit=4,file='dome2_opt_mod_in_uni.dat',status='old')

cdome2      open(unit=5,file='dome2_opt_mod_in2.dat',status='old')

carch3d     open(unit=5,file='arch3d_opt_mod_in2.dat',status='old')

carch3d_half open(unit=5,file='arch3d_opt_mod_half_in2.dat',status='old')
carch41     open(unit=5,file='arch41_opt_mod_half_in2.dat',status='old')

cshallow    open(unit=5,file='shallow_truss_in2.dat',status='old')

ckhot2_sym  open(unit=5,file='khot_2ele_mod_in_sym.dat',status='old')
ckhot4      open(unit=5,file='khot_4ele_mod_in_sym.dat',status='old')
ckhot4      open(unit=5,file='khot_4ele_mod_in_unsym.dat',status='old')
ckhot4      open(unit=5,file='khot_4ele_mod_in_applied.dat',status='old')
ckhot4      Endif

             print *, 'check start N= ',N
             call generalip(nel,ndofpe,netype,maxdofpe,nboundc
$ , ndofpn,numnodes,loadof,nummat,nlayers,nsect
$ , lumpmass,ndof,ieall,jeall,iarea,neig,irarc
$ , itype,numlim)

             inumel=nel(1)

ccc         iopt=0 !if=1 then going thru rik again for optimizer!
ccc         N=1 !counter for times thru rikarc

c.....dynamic storage memory allocation
             allocate ( ie(ieall+1),je(jeall),ibound(ndof),iet(ndof+1),
c..changed ip(ndof) to ip(ndof+1)
$   jet(jeall),ip(ndof+1),iu(ndof+1),iut(ndof),iup(ndof),
$   isupn(ndof),lm(maxdofpe),iperm(ndof),ia(ndof+1))

             allocate (ja(ndof+1))

             allocate ( b(ndof),be(maxdofpe),ae(maxdofpe**2),ad(ndof),
$   an(10000),dqtot(ndof),
$   x(numnodes),y(numnodes),z(numnodes),
$   propmat(nummat*11),tempo1(ndof),
$   tempo2(ndof),di(ndof),exfor(ndof) )

             allocate ( strain(ndof),strainE(ndof),strainD(ndof),
$   weight(ndof) )

             allocate (Anew(ndof),Anew2(ndof),Anew3(ndof),
$   A$part(ndof),SEDsum(ndof),Fin1(ndof),Fin2(ndof))
cccccccccccccccc

             If(N .eq. 1)then
                 allocate(VED(ndof),VEDold(ndof),iarea(inumel),propsect(nsect))
                 allocate(minarea(nsect))
                 allocate(WF(inumel),ilimit(ndof),dlimit(ndof),kprop(inumel))
                 allocate(xlie(inumel))
                 allocate(SED(inumel))
                 allocate(iSEDchk(inumel))
                 Endif

cccccccccccccccc
c.....input material properties

             call materprop(nummat,propmat,youngm)

c.....input cross-sectional properties
             print *, 'N before sectprop=',N
             If(N .eq. 1)then
                 call sectprop(nsect,prosect,area)
c...set to zero, after rikarc is run, minarea may change to 1
c...minarea is either 0 or 1, when it is 1, means that the min
c...area value has been reached in the design and the area may
c...not go below this value.
                 Do 444 i=1,nsect
                     minarea(i)=0
                 Endif

c.....input joint coordinates
             call nodecoor(numnodes,x,y,z)

c.....input connectivity information
             call elconect(ie,je,lm,netype,nel,ndofpe,ndofpn,iarca)
c.....input applied loads at the joints
             call loads(ndof,b,loadof,exfor)
c            print *, 'exfor =', (exfor(i),i=1,ndof)

c            call limits(ndof,numlim,dlimit,ilimit)
c            print *, 'b after loads=', (b(i),i=1,ndof)
c.....input boundary dof
             print *, 'chk1 before supportdof'

cc         iopt=0 !if=1 then going thru rik again for optimizer!
cc         N=1 !counter for times thru rikarc
             AEDsum=0.d0 !sum strain energy density, set to zero

555         Do 555 j=1,inumel
             SEDsum(j)=0.d0

1100        Continue
c            print *, 'chk2 before supportdof'
c            open(unit=51,file='dome_sup.dat',status='old')

carch3d     open(unit=51,file='arch3d_opt_mod_sup.dat',status='old')

carch3d_half open(unit=51,file='arch3d_opt_mod_half_sup.dat',status='old')

carch41     open(unit=51,file='arch41_opt_mod_half_sup.dat',status='old')

ckhot_sym  open(unit=51,file='khot_2ele_mod_sym_sup.dat',status='old')
ckhot_sym  open(unit=51,file='khot_2ele_mod_unsym_sup.dat',status='old')

ckhot4      open(unit=51,file='khot_4ele_mod_sup.dat',status='old')

cdome       open(unit=51,file='dome2_sup.dat',status='old')

cshallow    open(unit=51,file='shallow_truss_sup.dat',status='old')

c            open(unit=51,file='sdof_sup.dat',status='old')
c            open(unit=51,file='Khot_4ele_sup.dat',status='old')
c            open(unit=51,file='Khot_6ele_sup.dat',status='old')
c            open(unit=51,file='Khot_10ele_sup.dat',status='old')

```



```

cx      deltax=y(2)-y(1)
cx      deltaz=z(2)-z(1)
      deltax=xj-xi
      deltax=yj-yi
      deltax=zj-zi

c      print *,deltax=deltax
c      pause

c      deltax=x(2)+x(1)
c      deltax=y(2)+y(1)
c      deltaz=z(2)+z(1)

c      deltaxi=x(2)-ux(2) - ( x(1)-ux(1) )
c      deltaxi=x(2)+ux(2) - ( x(1)+ux(1) )
cx      deltaxi=x(2)-x(1) + ux(2)-ux(1)
      deltaxi=xj-xi + ux(2)-ux(1)
cc      print *,'A check'
c      deltaxi=y(2)-uy(2) - ( y(1)-uy(1) )
c      deltaxi=y(2)+uy(2) - ( y(1)+uy(1) )
cx      deltaxi=y(2)-y(1) + uy(2)-uy(1)
      deltaxi=yj-yi + uy(2)-uy(1)
c      print *,deltaxi=deltaxi
c      print *,y(2) y(1) = ',y(2)',',y(1)'
cc      print *,uy(2) uy(1) = ',uy(2)',',uy(1)'

c      deltazi=z(2)-uz(2) - ( z(1)-uz(1) )
c      deltazi=z(2)+uz(2) - ( z(1)+uz(1) )
cx      deltazi=z(2)-z(1) + uz(2)-uz(1)
      deltazi=zj-zi + uz(2)-uz(1)
c      print *,deltax=deltax
c      print *,deltaxi=deltaxi
c      print *,deltaz=deltaz
c      print *,deltazi=deltazi
c      print *,deltaxi=deltaxi
c      print *,deltazi=deltazi
c      pause
c      print *,'B check'
c      pause
      x1=dsqrt(deltax**2.d0 + deltax**2.d0 + deltaz**2.d0)
      x1=dsqrt(deltaxi**2.d0 + deltaxi**2.d0 + deltazi**2.d0)
c      print *,x1 inside elstif=',x1'
c      pause

      xlie(iel)=x1
c      print *,xlie(iel)=',xlie(iel)'
      density=.1d0
      wciht(iel)=density*A*x1
c      print *,x1 inside elstif=',x1'
c      print *,wciht(iel)=',wciht(iel)'
c      pause

c...Strain in element
c      strainel(iel)=(x1-x1)/x1
      strainel(iel)=(x1**2.-x1**2.)/(2.d0*x1)

c...Strain Energy
      strainE(iel)=.5*A*E*((strainel(iel))**2.d0)*x1
cc.. Strain Energy=(1/2)EAL(strain**2)
      strainE(iel)=.5*((A*E)/x1)*(x1-x1)**2.

c...Strain Energy Density of i-th element
cc      strainD(iel)=strainE(iel)/(density*A*x1)
ccc      strainD(iel)=strainE(iel)/(density)
ccc      strainD(iel)=(strainE(iel)/(A*x1))/density

      strainD(iel)=strainE(iel)/wciht(iel)

      SED(iel)=(.5*E/density) * ((x1-x1)/x1)**2.0
c      print *,'iel inside elstif=',iel
c      print *,SED(iel) inside elstif=',SED(iel)'
c      pause
c      Anew(iel)=A*(1+(x1-x1)/x1)
c      Apart(iel)=(x1-x1)/x1

c      print *,strainel(iel)=',strainel(iel)'
c      print *,strainE(iel)=',strainE(iel)'
c      print *,strainD(iel)=',strainD(iel)'

c      deltaxi2=x(2)-ux(2) - ( x(1)-ux(1) )
c      deltaxi2=y(2)-uy(2) - ( y(1)-uy(1) )
c      deltazi2=z(2)-uz(2) - ( z(1)-uz(1) )
c      x12=dsqrt(deltaxi2**2.d0 + deltaxi2**2.d0 + deltazi2**2.d0)
cc      print *,'iel =',iel
c      print *,x1=',x1'
c      print *,x12=',x12'
c      stop
c      print *,x12=',x12'

c      print *,'x =',x(ic),ic=1,4)
c      print *,'y =',y(ic),ic=1,4)
c      print *,'z =',z(ic),ic=1,4)
c      pause

c      print *,'lm2 in elstif=',(lm(ic),ic=1,6)
c      pause

c      stop

c      print *,x1=',x1'
c      print *,x12=',x12'
c      print *,deltax =',deltax'
c      print *,deltay =',deltay'
c      print *,deltaz =',deltaz'
c      print *,deltaxi =',deltaxi'
c      print *,deltayi =',deltayi'
c      print *,deltazi =',deltazi'
c      pause
cc      print *,'check el 1'

c      pause
c      stop

c      print *,'lm2a in elstif=',(lm(ic),ic=1,6)
c      pause

c      pause
c      stop
cx      deltax=x1
cy      deltax=y1
cz      deltax=z1
const=c**a/x1
c      print *,cx cy e a const,cx,cy,e,a,const
c      stop
AN = 0.0
ALAM = x1/x1i
X21D = deltaxi
Y21D = deltaxi
Z21D = deltaxi
c      print *,X21D=X21D
c      print *,Y21D=Y21D
c      print *,Z21D=Z21D

c      print *,'lm2a in elstif=',(lm(ic),ic=1,6)
c      pause

c      pause
c      ifityp .eq. 12) then
      C(1) = -X21D
      C(2) = -Y21D
      C(3) = -Z21D
      C(4) = -C(1)
      C(5) = -C(2)
      C(6) = -C(3)
c      print *,C(1)=',C(1)'
c      print *,C(2)=',C(2)'
c      print *,C(3)=',C(3)'
c      print *,C(4)=',C(4)'
c      print *,C(5)=',C(5)'
c      print *,C(6)=',C(6)'

c      print *,'lm2b in elstif=',(lm(ic),ic=1,6)
c      pause

c      pause
c      C(1) = X21D
c      C(2) = Y21D
c      C(3) = Z21D
c      C(4) = -C(1)
c      C(5) = -C(2)
c      C(6) = -C(3)

c*****
c      P(1)=ux(1)
c      P(2)=uy(1)
c      P(3)=uz(1)
c      P(4)=ux(2)
c      P(5)=uy(2)
c      P(6)=uz(2)
      P(1)=ux(1)
      P(2)=uy(1)
      P(3)=uz(1)
      P(4)=ux(2)
      P(5)=uy(2)
      P(6)=uz(2)
      dx=ux(2)-ux(1)
      dy=uy(2)-uy(1)
      dz=uz(2)-uz(1)

c      print *,'lm2c in elstif=',(lm(ic),ic=1,6)
c      pause

c      print *,'dx=',dx
c      print *,'dy=',dy
c      print *,'dz=',dz
      ALO2=x1*x1
c      B1(1) = X21D/ALO2
c      B1(2) = Y21D/ALO2
c      B1(3) = Z21D/ALO2
c      B1(4) = B1(1)
c      B1(5) = B1(2)
c      B1(6) = B1(3)
C..Glenn's modify
      B1(1) = -deltax/ALO2
      B1(2) = -deltay/ALO2
      B1(3) = -deltaz/ALO2
      B1(4) = -B1(1)
      B1(5) = -B1(2)
      B1(6) = -B1(3)

c      print *,'lm2d in elstif=',(lm(ic),ic=1,6)
c      pause

c      print *,'B1( )=',B1
c      print *,'P( )=',P
c      pause
c      stop

      EGR=0.D0
      Do 100 I=1,6
100 EGR=EGR+B1(I)*P(I)
c      print *,EGR1 =',egr'
c      EGR = B1(1)*P(1)+B1(2)*P(2)+B1(3)*P(3)+B1(4)*P(4)
c      +B1(5)*P(5)+B1(6)*P(6)
c      print *,EGR =',egr'
c      pause
c      print *,'dx=',dx
c      print *,'dy=',dy
c      print *,'dz=',dz

c      print *,'lm3 in elstif=',(lm(ic),ic=1,6)
c      pause

c      pause
      EGR=EGR+.5*(dx*dx+dy*dy+dz*dz)/ALO2
      EST=EGR
c      print *,EST=',est'

```

```

c          pause
c          stop
c      If (itruss .eq. 2)then
c          Print *,'Using Engineering Strain Element!'
c          STOP
c
c      EST=2.*xl*EGR/(xli-xl)
c
c      Endif
c
c      If (itruss .eq. 3)then
c          Print *,'Using Log-Strain Element!'
c          STOP
c
c      EST=LOG(xli/xl)
c          print *,'EST=',est
c          pause
c
c      Endif
c
cc      print *,'EST =' ,est
c** "AN" is the internal force from Crisfield, vol I, p.88
c      AN = E*A*EST
c
c      Fin1(iel)=AN !This puts element Internal Force in array "Fin"
c
c      If(N .eq. 1 .or. N .eq. 3 .or. N .eq. 5 .or. N .eq. 7)then
c          VED(iel)=fin1(iel)/(E*A**2.)
c          print *,'VED(iel)=' ,VED(iel)
c          Endif
c
c          print *,'E=' ,E
c          print *,'A=' ,A
c      print *,'AN =' ,AN
c      print *,'xl =' ,xl
c      print *,'xli =' ,xli
c          pause
c          stop
c
c      If(1first .eq. 1)then
c          write(c12,*)'Internal Force AN'
c          endif
c      write(c12,51) AN
c51 format(c12,4)
c      print *,'AN2 =' ,AN2
c*****
c      Endif
c
c      EA = E*A
c      AN2 = A*E*(xl-xli)/xl
c
c          stop
c      print *,'AN2 =' ,AN2
c      pause
cc      CON1 = 1.0D0/xlorig**3
c      CON1 = 1.0D0/xl**3
c** EA is very large compared to AN*ALAM
c      print *,'itruss inside elstif =' ,itruss
c          pause
c
c      print *,'lm3a in elstif=' , (lm(ic),ic=1,6)
c          pause
c
c      print *,'itruss=' ,itruss
c
c      If(itruss .eq. 1)then
c          CON1 = E*A*CON1
c          print *,'E=' ,E
c          print *,'A=' ,A
c          print *,'CON1 =' ,CON1
c          pause
c      elseif(itruss .eq. 2)then
c          ALAM=xl/AN
c          CON1 = ALAM*ALAM*CON1*(EA-AN*ALAM)
c          endif
c
c          If(itruss .eq. 3) then
c              CON1=CON1*ALAM**4*(EA-(1.d0+.5d0*POISS)*AN)
c              endif
c
c          print *,'lm3b in elstif=' , (lm(ic),ic=1,6)
c          pause
c
c      print *,'CON1 & CON2 =' ,con1, ' ,con2
cc      pause
c      DO 33 J=1,6
c      DO 33 I=1,J
c
c          print *,'I=' ,i, ' J=' ,j
c      print *,'C(I) & C(J) & CON1 =' ,c(i),c(j),con1
c
c          print *,'lm3bc in elstif=' ,lm(J)
c          pause
c
c      33 esm(I,J)=CON1*C(I)*C(J)
c
c          print *,'lm3c in elstif=' , (lm(icc),icc=1,6)
c          pause
c
c** If(itruss .ge. 1)then
c** If(itruss .eq. 1)then
c      CON2=AN/xl
c          print *,'CON2 =' ,con2
c          stop
c** Elseif(itruss .eq. 2)then
c      Else
c      CON2=CON2*ALAM
c      Endif
c          print *,'CON2 =' ,con2
c          pause
c      print *,'xl =' ,xl
c      print *,'xli =' ,xli

```

```

c          print *,'lm3d in elstif=' , (lm(ic),ic=1,6)
c          pause
c
c          stop
c
c      con2=0.
c..Crisfield original..
c      esm(1,1)=esm(1,1)+CON2
c      esm(2,2)=esm(2,2)+CON2
c      esm(3,3)=esm(3,3)+CON2
c      esm(4,4)=esm(4,4)+CON2
c      esm(5,5)=esm(5,5)+CON2
c      esm(6,6)=esm(6,6)+CON2
c      esm(1,4)=esm(1,4)+CON2
c      esm(2,5)=esm(2,5)+CON2
c      esm(3,6)=esm(3,6)+CON2
c
c..Duc's.....
c      esm(1,1)=esm(1,1)+CON2
c      esm(2,2)=esm(2,2)+CON2
c      esm(3,3)=esm(3,3)+CON2
c      esm(4,4)=esm(4,4)+CON2
c      esm(5,5)=esm(5,5)+CON2
c      esm(6,6)=esm(6,6)+CON2
c      esm(1,4)=esm(1,4)+CON2
c      esm(2,5)=esm(2,5)+CON2
c      esm(3,6)=esm(3,6)+CON2
c
c      If(istep .eq. 440)then
c          print *,'CON2=' ,con2
c          print *,'esm(1,1)=' ,esm(1,1)
c          print *,'esm(2,2)=' ,esm(2,2)
c          print *,'esm(3,3)=' ,esm(3,3)
c          print *,'esm(4,4)=' ,esm(4,4)
c          print *,'esm(5,5)=' ,esm(5,5)
c          print *,'esm(6,6)=' ,esm(6,6)
c          print *,'esm(1,4)=' ,esm(1,4)
c          print *,'esm(2,5)=' ,esm(2,5)
c          print *,'esm(3,6)=' ,esm(3,6)
c          pause
c          endif
c          print *,'xl =' ,xl
c          print *,'xli =' ,xli
c          stop
c      esm(1,2)=0.
c      esm(1,3)=0.
c      esm(1,5)=0.
c      esm(1,6)=0.
c      esm(2,3)=0.
c      esm(2,4)=0.
c      esm(2,6)=0.
c      esm(3,4)=0.
c      esm(3,5)=0.
c
c..Crisfield modified
c      esm(1,1)=esm(1,1)+CON2
c      esm(2,2)=esm(2,2)+CON2
c      esm(3,3)=esm(3,3)+CON2
c      esm(4,4)=esm(4,4)+CON2
c      esm(5,5)=esm(5,5)+CON2
c      esm(6,6)=esm(6,6)+CON2
c      esm(1,2)=esm(1,2)+CON2
c      esm(1,3)=esm(1,3)+CON2
c      esm(1,4)=esm(1,4)+CON2
c      esm(1,5)=esm(1,5)+CON2
c      esm(1,6)=esm(1,6)+CON2
c      esm(3,4)=esm(3,4)+CON2
c      esm(3,5)=esm(3,5)+CON2
c      esm(3,6)=esm(3,6)+CON2
c      esm(4,5)=esm(4,5)+CON2
c      esm(4,6)=esm(4,6)+CON2
c      esm(5,6)=esm(5,6)+CON2
c..Glenn's esm..
c      esm(1,1)=esm(1,1)+CON2
c      esm(1,2)=esm(1,2)+CON2
c      esm(2,2)=esm(2,2)+CON2
c      esm(3,3)=esm(3,3)+CON2
c      esm(3,4)=esm(3,4)+CON2
c      esm(4,4)=esm(4,4)+CON2
c      esm(4,5)=esm(4,5)+CON2
c      esm(5,5)=esm(5,5)+CON2
c      esm(5,6)=esm(5,6)+CON2
c      esm(6,6)=esm(6,6)+CON2
c          print *,'xl =' ,xl
c          print *,'xli =' ,xli
c
c      DO 344 I=1,6
c      DO 344 J=1,6
c          print *,'T,i,j,j','esm(I,J) inside elstif=' ,esm(i,j)
c344 esm(I,J)=esm(I,J)
c
c          print *,'lm4 in elstif=' , (lm(icc),icc=1,6)
c          pause
c
c          print *,'xl =' ,xl
c          print *,'xli =' ,xli
c          stop
c34      print *,'esm inside elstif=' , 'i','j',' ,esm(i,j)
c          pause
c
c      print *,'xli inside elstif=' ,xli
c      print *,'deltaxi inside elstif=' ,deltaxi
c      print *,'a & e inside elstif=' ,a,e
c      print *,'xl inside elstif=' ,xl
c
c          print *,'itruss=' ,itruss
c          PAUSE
c          stop

```



```

c          do 9 k=1,ndof+1
c          ia1(k)=0.
c          ia2(k)=0.
c9         continue
c          stop
c          do 30 i=1,nm1          !003 last row (= eq) will be skipped
c          jpi=jp                !004 delayed counter for ia(-) array
c          if ( ia2(i) .eq. n ) go to 30          !005 skip row which correspond to Dirichlet b.c.
c          if ( ia(i) .eq. n ) go to 30          !005 skip row which correspond to Dirichlet b.c.

c          ieta=ieta(i)          !006 begin index (to find how many elements)
c          ietb=ieta(i+1)-1      !007 end index (to find how many elements)
c          do 20 ip=ieta,ietb     !008 loop covering ALL elements attached to row i
c          j=jeta(ip)             !009 actual "element number" attached to row i
c          ic=iet(i)              !010 begin index (to find how many nodes attached to
element j)
c          print *, 'ic(j) inside symbass=', ic(j)
c          print *, 'ic(j+1)=', ic(j+1)
c          ieb=ieta(i+1)-1       !011 end index (to find how many nodes attached to
element j)
c          print *, 'iea & ieb=', iea, ieb
c          do 10 kp=iea,ieb       !012 loop covering ALL nodes attached to element j
c          k=jeta(kp)             !013 actual "node, or column number" attached to element j
c          print *, 'k in symbass=', k
c          print *, 'i=', i
c          print *, 'ia2(k)=', ia2(k)
c          pause
c          if (k .le. i) go to 10    !014 skip, if it involves with LOWER triangular portion
c          if ( ia(k) .ge. i ) go to 10 !015 skip, if same node already been accounted by earlier
elements
c          if ( ia2(k) .ge. i ) go to 10 !015 skip, if same node already been accounted by
earlier elements
c          ja(ip)=k               !016 record "column number" associated with non-zero off-
diag. term
c          jp=jp+1                !017 increase "counter" for column number array ja(-)
c          ia(k)=i                !018 record node (or column number) k already contributed
to row i
c          ia2(k)=i               !018 record node (or column number) k already
contributed to row i

c          print *, 'ia2(k)=', ia2(k)
c          !019
c          !020
c          print *, 'jpi =', jpi
c          pause
c          ia(i)=jpi              !021 record "starting location" of non-zero off-diag.
c          ia2(i)=jpi             !021 record "starting location" of non-zero off-diag.

c          ! terms associated with row i
c          print *, 'jp inside symbass=', jp
c          pause
c          ia(n)=jp               !022 record "starting location" of non-zero term of LAST
ROW
c          ia(n+1)=jp             !023 record "starting location" of non-zero term of LAST
ROW + 1
c          ia2(n)=jp              !022 record "starting location" of non-zero term of LAST
ROW
c          ia2(n+1)=jp            !023 record "starting location" of non-zero term of LAST
ROW + 1

c          ncoeff=ia(n+1)-1
c          ncoeff=ia2(n+1)-1

c          if (istep .eq. 1) then
c          print *, 'ia(n)=', ia(n)
c          print *, 'ia(n+1)=', ia(n+1)
c          print *, 'ncoeff inside symbass=', ncoeff
c          pause
c          endif

c          pause
c          print *, 'ia(-) at end of symbass=', (ia(i), i=1, ndof+1)
c          pause
c          write(6, *) 'ia(-) array =', (ia(i), i=1, n+1)
c          write(6, *) 'ja(-) array =', (ja(i), i=1, ncoeff)
c
c          return
c          end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
c          Table 8.4 Complete FORTRAN Code for Sparse, Symmetrical
c          Numerical Assembly Process

c          subroutine numass(ia, ja, idir, ac, bc, lm, ndofpe, an, ad, b, ip,
c          $elmass, dm, am, ianal, lumpmass, ndof, ncoeff, inc, istcp)
c          !000 Subroutine numass(ia2, ja, idir, ac, bc, lm, ndofpe, an, ad, b, ip,
c          $elmass, dm, am, ianal, lumpmass, ndof, ncoeff)
c          implicit real*8(a-h, o-z)
c          dimension ia(*), idir(*), ac(*), bc(*), lm(*), an(*)
c          dimension ia(*), ja(*), idir(*), ac(*), bc(*), lm(1), an(*)
c          dimension ia(*), idir(*), ac(*), bc(*), lm(*), an(*)
c          dimension ia2(*), ja(*), idir(*), ac(*), bc(*), lm(*), an(*)
c          dimension ad(*), b(*), ip(*)
c          dimension elmass(1), dm(1), am(1)
c          ++++++
c          ++++++
c          !001 PLEASE direct your questions to Dr. Nguyen (nguyen@cee.odu.edu)
c          !002 Purposes: symmetrical, sparse numerical assembly
c          !003 This code is stored under file name "symb*.f", in sub-directory
c          ++++++
c          ++++++
c          !004 Input: ia(ndof+1)=starting locations of the first non-zero
c          !005 off-diagonal terms for each row of structural stiffness
c          !006 matrix
c          !007 ja(ncoeff)=column numbers (unordered) correspond to
c          !008 each nonzero, off-diagonal term of each row of structural
c          !009 stiffness matrix
c          !010 idir(ndof)= 1 in the positions correspond to Dirichlet b.c.
c          !011 0 elsewhere
c          !012 ac(ndofpe**2), bc(ndofpe)= element (stiffness) matrix,
c          !013 and element (load) vector
c          !014 lm(ndofpe)= global dof associated with a finite element
c          !015 ndofpe= number of dof per element
c          !016 b(ndof)= before using this routine, values of b(-) should
c          !017 be initialized to:
c          !018 C1, values of prescribed Dirichlet bc at proper locations
c          !019 or values of applied nodal loads
c          !020
c          !021 Output: an(ncoeff)= values of nonzero, off-diagonal terms of
c          !022 structural stiffness matrix
c          !023 ad(ndof)= values of diagonal terms of structural stiffness
c          !024 matrix
c          !025 b(ndof)= right-hand-side (load) vector of system of linear
c          !026 equations
c          !027 Temporary Arrays:
c          !028 ip(ndof)= initialized to 0
c          !029 then IP(-) is used and reset to 0
c          !030
c          !031 ***** chk start numass *****
c          !032 pause
c          !033 ***** chk start numass *****
c          !034 pause
c          !035 ***** chk start numass *****
c          !036 pause
c          !037
c          !038 If (istep .eq. 1) then
c          !039 print *, '***** chk start numass *****'
c          !040 pause
c          !041
c          !042 print *, 'lm(i) start numass=', (lm(i), i=1, ndofpe)
c          !043 pause
c          !044 print *, 'ndofpe inside numass=', ndofpe
c          !045 print *, 'ndof inside numass=', ndof
c          !046
c          !047 print *, 'ad diag stiff start numass=', (ad(i), i=1, ndof)
c          !048 print *, 'ac off diag stiff start numass=', (ac(i), i=1, ncoeff)
c          !049 print *, 'an(i) array start numass =', (an(i), i=1, 50)
c          !050 pause
c          !051 print *, 'ja(-) start of numass =', (ja(i), i=1, 15+1)
c          !052 print *, 'ja(-) start in numass =', (ja(i), i=1, 15+1)
c          !053 pause
c          !054 endif
c          !055
c          !056 stop
c          !057 print *, 'ac start of numass =', (ac(i), i=1, 16)
c          !058 stop
c          !059 print *, 'an start on numass =', (an(i), i=1, 20)
c          !060 print *, 'ad start on numass =', (ad(i), i=1, 20)
c          !061 print *, 'ip start in numass =', (ip(i), i=1, 20)
c          !062 pause
c          !063
c          !064 print *, 'ia2(-) start of numass =', (ia2(i), i=1, 9+1)
c          !065 stop
c          !066 print *, 'ndofpe=ndofpe'
c          !067 print *, 'idir=', (idir(ic), ic=1, ndof)
c          !068 pause
c          !069
c          !070 print *, 'ia2(-) array =', (ia2(i), i=1, ndof+1)
c          !071 print *, 'ncoeff1=', ncoeff1
c          !072 print *, 'ja(-) array inside numass =', (ja(ic), ic=1, ncoeff1)
c          !073 print *, 'imal inside numass =', ianal
c          !074 print *, 'idir=', (idir(i), i=1, ndof)
c          !075 print *, 'b at start numass=', (b(i), i=1, ndof)
c          !076 pause
c          !077 print *, 'be in numass=', (be(i), i=1, ndofpe)
c          !078 print *, 'ia2=', (ia2(i), i=1, ndof)
c          !079 print *, 'an=', (an(i), i=1, 30)
c          !080 stop
c          !081 write(*, *) 'ia2(-) start of numass =', (ia2(i), i=1, ndof+1)
c          !082 write(*, *) 'inside numass: b(-) =', (b(i), i=1, 10)
c          !083 stop
c          !084 write(6, *) 'ia2(-) start of numass =', (ia2(i), i=1, ndof+1)
c          !085 print *, 'ia2(i) start numass=', (ia2(i), i=1, ndof+1)
c          !086 pause
c          !087 stop
c          !088 write(6, *) 'inside numass: b(-) =', (b(i), i=1, 10)
c          !089 do 40 L=1, ndofpe          !001 local "row" dof
c          !090 i=lm(L)                !002 global "row" dof
c          !091 print *, 'lm(L)=', lm(L), ' L=', L
c          !092 print *, 'i=', i
c          !093 print *, 'idir(i) in numass=', idir(i)
c          !094 pause
c          !095 if ( idir(i) .ne. 0 ) go to 401          !003 skip, if DIRICHLET b.c.
c          !096 print *, '*** idir=0 ***'
c          !097 k=L-ndofpe          !004 to find location of element k-dia
c          !098 print *, 'L=', L
c          !099 print *, 'ndofpe=ndofpe'
c          !100 print *, 'k=L-ndofpe', k
c          !101 print *, 'ac(k+L*ndofpe)=', ac(k+L*ndofpe)
c          !102 pause
c          !103 ad(i)=ad(i)+ac(k+L*ndofpe)          !005 assemble K-dia
c          !104
c          !105 print *, 'ad in numass=', ad(i)
c          !106 pause
c          !107 if (ianal .eq. 1) then
c          !108 dm(i)=dm(i)+elmass(k+L*ndofpe)          ! assemble M-dia
c          !109 endif
c          !110 print *, 'assemble element rhs Load Vector in numass'
c          !111 b(i)=b(i)+bc(L)          !006 assemble element rhs load vector
c          !112 print *, 'bc(L) =', bc(L)
c          !113 print *, 'b(i) =', (b(ic), ic=1, ndof)
c          !114 stop
c          !115 pause
c          !116
c          !117 kk=0          !007 flag, to skip contribution of entire
c          !118 ! global row i if all global col #
c          !119 ! j < i, or if entire row i belongs
c          !120 ! to LOWER triangle

```



```

cc      print *, 'prop( )=' ,prop(i)
c      prop(istart+ 2)=xi
c      prop(istart+ 3)=yi
c      prop(istart+ 4)=zi
c      prop(istart+ 5)=1
c      prop(istart+ 6)=2
c      prop(istart+ 7)=3
c      prop(istart+ 8)=4
c      prop(istart+ 9)=thcta1
c      prop(istart+10)=thcta2
c      prop(istart+11)=thcta3
c      prop(istart+12)=thcta4

1      continue

c      area = prop(istart+1)

cc      print *, 'area inside sectprop=' ,area

return
end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
subroutine nodecoor(numnodes,xxx,yyy,zzz)
implicit real*8(a-h,o-z)
c.....Purpose: Input joint coordinates
c
c      dimension xxx(1),yyy(1),zzz(1)
c
c      print *, 'numnodes inside nodecoor=' ,numnodes
c      pause
c
c      write(6,*) 'joint,xxx(joint),yyy(joint),zzz(joint)'
c      do 21 i=1,numnodes
c      read(5,*) joint,xxx(joint),yyy(joint),zzz(joint)
c      write(*,4) joint,xxx(joint),yyy(joint),zzz(joint)
c      pause
c      write(6,4) joint,xxx(joint),yyy(joint),zzz(joint)
c      format(2x,i5,1f0.2,1f0.2,1f0.2)
c      21 continue
c
c      return
c      end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
subroutine elconnect(ie,ie,lm,neltype,nel,n dofpe,n dofpn,iarea)
implicit real*8(a-h,o-z)
c.....Purpose: Input element connectivity information.
c.....Note: This routine can be used for any finite element type ??
c
c      dimension ie(1),ie(1),lm(1),nel(1),n dofpe(1)
c      dimension iarea(*)
c
c      itharea=0
c
c      icadd=0
c      locadd=0
c      ie(1)=1
c      print *, 'neltype inside elconnect=' ,neltype
c
c      pause
c      stop
c      do 21 k=1,neltype
c      numel=nel(k)
c      print *, 'numel inside elconnect=' ,numel
c      pause
c      if (numel .eq. 0) go to 21
c      go to (31,32,33,34,34,34),k
c      31 continue
c      print *, 'numel=' ,numel
c      pause
c      do 22 i=1,numel
c      ie(i+1)=ie(i)+n dofpe(k)
c      print *, 'ie(i+1) inside elconnect=' ,ie(i+1)
c      pause
c
c      read(5,*) ithel,nodei,nodej
c      read(5,*) ithel,itharea,nodei,nodej
cc      print *, 'itharea=' ,itharea
c      print *, 'ithel inside elconnect=' ,ithel
c      iarea(i)=itharea
c      print *, 'i=' ,i, ' iarea(i) inside elconnect=' ,iarea(i)
c      print *, 'Read inside elconnect'
c      write(6,*) 'ithel,nodei,nodej = ' ,ithel,nodei,nodej
c      print *, 'ithel,nodei,nodej = ' ,ithel,nodei,nodej
c      pause
c
c      Use for 2D truss
c      lm(1)=nodei*n dofpn-1
c      lm(2)=lm(1)+1
c      lm(3)=nodej*n dofpn-1
c      lm(4)=lm(3)+1
c
c      print *, 'nodei=' ,nodei
c      print *, 'n dofpn=' ,n dofpn
c
c      Use below for 3D Truss
c      lm(1)=nodei*n dofpn-2
c      lm(2)=lm(1)+1
c      lm(3)=lm(1)+2
c      lm(4)=nodej*n dofpn-2
c      lm(5)=lm(4)+1
c      lm(6)=lm(4)+2
c      locbegin=(ithel-1)*n dofpe(k)
c
c      print *, 'ithel=' ,ithel
c      print *, 'nodei=' ,nodei
c      print *, 'nodej=' ,nodej
c      print *, 'n dofpn=' ,n dofpn
c      print *, 'lm(1)=' ,lm(1)
c      print *, 'lm(2)=' ,lm(2)
c      print *, 'lm(3)=' ,lm(3)
c      print *, 'lm(4)=' ,lm(4)
c      print *, 'lm(5)=' ,lm(5)
c      print *, 'lm(6)=' ,lm(6)
c
c      print *, 'locbegin=' ,locbegin
c      pause
c
c      do 23 j=1,n dofpe(k)
c      locater=locbegin+j
c      je(locate)=lm(j)
c
c      print *, 'locate=' ,locate
c      print *, 'je(locate)=' ,je(locate)
c      pause
c      print *, 'lm(j)=' ,lm(j)
c      print *, 'je(locate)=' ,je(locate)
c      pause
c
c      23 continue
c      22 continue
c      go to 21
c      32 continue
c      ! 3-d beam
c      icadd=icadd+n el(k-1) ! to include previous 2-d truss elements
c      locadd=locadd+n el(k-1)*4
c      go to 21
c      33 continue
c      ! 4-node (24 dofpe) rect. plate bonding+membrane
c      icadd=icadd+n el(k-1) ! to include previous 3-d beam elements
c      locadd=locadd+n el(k-1)*12
c
c      print *, 'numel=' ,numel
c      pause
c      do 42 i=1,numel
c      ie(i+1+icadd)=ie(i+icadd)+n dofpe(k)
c
c      read(5,*) ithel,nodei,nodej,nodck,nodel
c      write(6,*) 'ithel,nodei,nodej,nodck,nodel'
c      write(6,*) 'ithel,nodei,nodej,nodck,nodel'
c
c      lm(1)=nodei*n dofpn-5
c      lm(2)=lm(1)+1
c      lm(3)=lm(2)+1
c      lm(4)=lm(3)+1
c      lm(5)=lm(4)+1
c      lm(6)=lm(5)+1
c
c      lm( 7)=nodej*n dofpn-5
c      lm( 8)=lm( 7)+1
c      lm( 9)=lm( 8)+1
c      lm(10)=lm( 9)+1
c      lm(11)=lm(10)+1
c      lm(12)=lm(11)+1
c
c      lm(13)=nodck*n dofpn-5
c      lm(14)=lm(13)+1
c      lm(15)=lm(14)+1
c      lm(16)=lm(15)+1
c      lm(17)=lm(16)+1
c      lm(18)=lm(17)+1
c
c      lm(19)=nodel*n dofpn-5
c      lm(20)=lm(19)+1
c      lm(21)=lm(20)+1
c      lm(22)=lm(21)+1
c      lm(23)=lm(22)+1
c      lm(24)=lm(23)+1
c
c      locbegin=(ithel-1)*n dofpe(k)
c      do 43 j=1,n dofpe(k)
c      locater=locbegin+j
c      je(locate+locadd)=lm(j)
c      43 continue
c      42 continue
c      go to 21
c      34 continue
c      ! other f.e. type
c      go to 21
c
c      21 continue
c
c      icall=nel(1)+nel(2)+nel(3)+nel(4)+nel(5)+nel(6)
cc      jeall=nel(1)*4 + nel(2)*12 + nel(3)*24
c      jeall=nel(1)*6 + nel(2)*12 + nel(3)*24
c      print *, 'jeall=' ,jeall
c      pause
c
c      write(6,*) 'icall = sum all el types = ' ,icall
c      write(6,*) 'ie=' , (ie(i),i=1,icall+1)
c      write(6,*) 'je=' , (je(i),i=1,jeall)
c      print *, 'icall = sum all el types = ' ,icall
c      print *, 'jeall = ' ,jeall
c      print *, 'ie=' , (ie(i),i=1,icall+1)
c      print *, 'iarea( )=' , (iarea(i),i=1,numel)
c      print *, 'je=' , (je(i),i=1,jeall)
c      pause
c
c      return
c      end
c%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
subroutine loads(ndof,h,loadof,exfor)
implicit real*8(a-h,o-z)
c.....Purpose: Input applied loads at the joints
c
c      dimension b(1),exfor(*)
c
c      write(6,*) 'inside loads: ndof = ' ,ndof
c      print *, 'inside loads'
c      do 1 i=1,ndof
c      exfor(i)=0.0
c      b(i)=0.0 ! load vector
c      1 continue
c
c      do 18 i=1,loadof
c      read(5,*) loadofdo, value
c      write(6,*) loadofdo, value
c      write(6,*) loadofdo, value
c
c      print *, 'loadof=' ,loadof
c      print *, 'value=' ,value
c      pause

```

	b(loadedof)=value				dimension strainE(*),strainE(*),strainD(*),weight(*),xlic(*)
	exfor(loadedof)=value				dimension Anew(*),Apart(*),Fin1(*),Fin2(*),VED(*),VEDold(*),SED(*)
18	continue	c			print *,'je start assembly=',j(cic),ic=1,10)
c	print *,'exfor inside loads=',(exfor(i),i=1,n dof)	c			pause
	stop	c			print *,'B() start assembly=',(b(ic),ic=1,n dof)
	return	c			pause
	end	c			print *,'Start assembly'
c%	%%%%%%%%%%	c			print *,'ux(1)=' ,ux(1)
c%	%%%%%%%%%%	c			print *,'uy(1)=' ,uy(1)
c%	%%%%%%%%%%	c			print *,'uz(1)=' ,uz(1)
c%	%%%%%%%%%%	c			print *,'ux(2)=' ,ux(2)
c%	%%%%%%%%%%	c			print *,'uy(2)=' ,uy(2)
c%	%%%%%%%%%%	c			print *,'uz(2)=' ,uz(2)
c%	%%%%%%%%%%	c			pause
c.....	Purpose: Reads in constraints, number, dof & max allow disp	c			
c		c			
	dimension dlimit(*),ilimit(*)	c			
c		c			
	do 1 i=1,n dof	c			double precision, allocatable:: b(:,)
	ilimit(i)=0.0	c			allocate elk(maxdofpe,maxdofpe)
dlimit(i)=0.0					
1	continue	c			dimension ja(1)
		c			
	do 18 i=1,numlim !numlim is the number of optimizer constraints	c			print *,'Getstiff start assembly=' ,getstiff
read(5,*) limitdof, ivalue, dvalue		c			print *,'Getforce start assembly=' ,getforce
c	write(6,*) 'loadedof, value'	c			print *,'Getsolve start assembly=' ,getsolve
c	write(6,*) loadedof, value	c			pause
	print *,'loadof=' ,loadof				
	print *,'value=' ,value				
	pause				
	ilimit(limitdof)=ivalue !dof of optimizer constraint				If(getsolve .eq. 1)Then
	dlimit(limitdof)=dvalue !value of optimizer constraint				Goto 670
					Endif
18	continue				
c	print *,'exfor inside loads=',(exfor(i),i=1,n dof)	c			If(getforce .eq. 1)Then !Skip ad & ae =0,just getforce
c	stop	c			Goto 699
	return	c			Endif
	end	c			
c%	%%%%%%%%%%	c			print *,'S T A R T O F A S S E M B L Y '
c%	%%%%%%%%%%	c			print *,'XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX'
c%	%%%%%%%%%%	c			print *,'Setting ad, an & ae to zero'
	subroutine supportdof(iboundc,nboundc,h,n dof,ia)				Do 701 ic=1,n dof
	implicit real*8(a-h,o-z)				ad(ic)=0.0 !Stiffness diagonal
c					
c.....	Purpose: input support dof information	c			an(ic)=0.0 !Stiffness off diagonal
	dimension iboundc(1), b(1),ia(1)	701	continuc		
	do 18 i=1,n dof				
	iboundc(i)=0				
18	continue				Do 702 ic=1,10000
c	print *,'nboundc inside supportdof=' ,nboundc	702	continuc		an(ic)=0.d0
c.....	input the boundary condition flag				
	do 19 i=1,n boundc				
	read(51,*) ibcdof, settlem				
c	write(6,*) 'ibcdof, settlem = ',ibcdof,settlem	c			print *,'b_) at start2 of assembly=' ,(b(ic),ic=1,n dof)
	iboundc(ibcdof)=1	c			pause
	b(ibcdof)=settlem	c			Do 702 ic=1,100
	print *,'b(i) inside supportdof=' ,b(i)	c			ae(ic)=0.0
e		c702	continuc		
19	continue	c			print *,'XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX'
c	pause	c			pause
c	write(6,*) 'ibcdof = ', ibcdof	c			Continue
c	write(6,*) 'load and settlement b(-) = ', (b(i),i=1,n dof)	c			
c.....	copy boundary flag for later usage in Duc's sparse symbolic assembly	c			print *,'idir at start of assembly=' ,(idir(ic),ic=1,n dof)
	do 3 i=1,n dof	c			pause
	if (iboundc(i) .eq. 0) ia(i)=0				
	if (iboundc(i) .eq. 1) ia(i)=n dof	c			print *,'qk_) at start of assembly=' ,(qk(ic),ic=1,n dof)
cc	print *,'ia_) inside supportdof=' ,ia(i)	c			print *,'b_) at start of assembly=' ,(b(ic),ic=1,n dof)
3	continue	c			pause
		c			print *,'ia start of assembly=' ,(ia(i),i=1,15)
		c			print *,'ja2(i)=' ,(ja2(ic),ic=1,10)
		c			print *,'ja(1)=' ,ja(1)
		c			print *,'ja start of assembly=' ,(ja(i),i=1,1)
		c			print *,'ndofpe = ',ndofpe
		c			stop
	rewind 51				
cc	pause				
	end	c			If(getforce .eq. 1)then
c%	%%%%%%%%%%	c			Do 777 i= 1,10
c%	%%%%%%%%%%	c			ja(i)=ja2(i)
c	\$ prospect,elk,bc,b,iboundc,iarea,	c			Print *,ja2(i) inside start assembly=' ,ja2(i)
c	\$ prospect,bc,b,iboundc,iarea,	c			pause
c	\$ ac,ia,ja,xx,yy,zz,ncoef1,maxdofpe,	c777			Continue
c	\$ ac,ia,jancoef1,maxdofpe,	c			pause
c	\$ ac,ia2,ja,xx,yy,zz,ncoef1,maxdofpe,	c			Endif
	\$ ndof,netype,ncl,ndofpe,ianal,lumpmass,dm,am,elm,				
c	\$ tempo1,disp,iarc,it,area,youngm,esm,qk,itrmlon)	c			if(it .eq. 2)then
c					

```

c          print *,ndof=1,ndof
cc         ncoef2=ncoef1
c          print *,'ip=',(ip(i),i=1,ndof)
c          stop
c          print *,'b=',(b(i),i=1,ndof)
c          pause
c          print *,'ia2 start assembly=',(ia2(i),i=1,ndof-1)
c          stop

c.....initialize before numerical sparse assembling
do 96 j=1,ndof
96  ip(j)=0
cccc blanked out below don't need dynamics
cccc  if (ianal .eq. 1) dm(j)=0.
cccc 96  ad(j)=0.
c 96  continue
c
cccc something not write with ncoef1 ???
cc      ncoef1=ncoef2

c          write(6,*)'ncoef1 start assembly=',ncoef1
c          print *,'ncoef1=',ncoef1
c          stop
cccc  do 95 j=1,ncoef1
cccc  if (ianal .eq. 1 .and. lumpmass .eq. 0) then
cccc  am(j)=0.
cccc  endif
cccc 95  an(j)=0.
c          print *,'neltype=',neltype
c          stop

c          if(it .eq. 2)then
c          print *,'it =2'
c          print *,'neltype=',neltype
c          stop
c          endif

c          write(6,*)'neltype in assembly=',neltype
c          stop

670      Continue !skipped above when getsolve=1
c***** START OF DO 98 *****
DO 98 k=1,neltype

      If(getsolve .eq. 1)Then
      Goto 671
      Endif

      numel=nel(k)
c          print *,'numel=',numel
c          pause
c          if(it .eq. 2)then
c          print *,'it =2'
c          print *,'ianal=',ianal
c          print *,'numel=',numel
c          stop
c          endif

c          stop
c          if (numel .eq. 0) go to 98
c.....loop for all elements
c          print *,'start loop for all elements'
c          print *,'ncoef1=',ncoef1
c          print *,'numel=',numel
c          pause
c          stop
c          print *,'Before DO 4'
c          print *,'ux(1)=-,ux(1)'
c          print *,'uy(1)=-,uy(1)'
c          print *,'uz(1)=-,uz(1)'
c          print *,'ux(2)=-,ux(2)'
c          print *,'uy(2)=-,uy(2)'
c          print *,'uz(2)=-,uz(2)'
c          pause

      DO 4 iet=1,numel
c          print *,'iel = ',iel
c          print *,'*****'

c          If(getforce .eq. 1)then
c          goto 400
c          endif

c          pause
c          print *,'numel=',numel
c          pause
c          stop
c          write(6,*) 'inside assembly: truss el #,nel(1) = ',iel,nel(1)
c.....get the global dof associated with each element
c          print *,'ndofpe(k)=-,ndofpe(k)'
c          iend=iel*ndofpe(k)
c          istart=iend-ndofpe(k)
c          print *,'iend=',iend
c          print *,'istart=',istart
c          print *,'ndofpe(k)=-,ndofpe(k)'
c          pause

      do 76 j=1,ndofpe(k)
c          print *,'j=',j
c          print *,'je(istart+j)=-je(istart+j)'
c          write(6,*)'lm(j)=-,lm(j)'
c          lm(j)=je(istart+j)
c          continue
c 76  print *,'je(istart+j)=-je(istart+j)'
c          print *,'lm 2 inside assembly =',(lm(i),i=1,6)
c          pause

c          print *,'iarc=-,iarc'
c          pause
c          stop

c          if(iarc .eq. 1)then

ix1dof=1lm(1)
iy1dof=1lm(2)
iz1dof=1lm(3)
ix2dof=1lm(4)
iy2dof=1lm(5)
iz2dof=1lm(6)
c          print *,'lm(6)=-,lm(6)'
c          ux(1)=ux(1)+disp(ix1dof)
c          uy(1)=uy(1)+disp(iy1dof)
c          uz(1)=uz(1)+disp(iz1dof)
c          ux(2)=ux(2)+disp(ix2dof)
c          uy(2)=uy(2)+disp(iy2dof)
c          uz(2)=uz(2)+disp(iz2dof)
c          ux(1)=ux(1)+qk(ix1dof)
c          uy(1)=uy(1)+qk(iy1dof)
c          uz(1)=uz(1)+qk(iz1dof)
c          ux(2)=ux(2)+qk(ix2dof)
c          uy(2)=uy(2)+qk(iy2dof)
c          uz(2)=uz(2)+qk(iz2dof)
c          print *,'qk(ix1dof)=-,qk(ix1dof)'
c          pause
c          stop
c          ux(1)=qk(ix1dof)
c          uy(1)=qk(iy1dof)
c          uz(1)=qk(iz1dof)
c          ux(2)=qk(ix2dof)
c          uy(2)=qk(iy2dof)
c          uz(2)=qk(iz2dof)
c          print *,'ix1dof=-,ix1dof'
c          print *,'iy1dof=-,iy1dof'
c          print *,'iz1dof=-,iz1dof'
c          print *,'ix2dof=-,ix2dof'
c          print *,'iy2dof=-,iy2dof'
c          print *,'iz2dof=-,iz2dof'
c          print *,'checking ux uy uz'
c          print *,'ux(1)=-,ux(1)'
c          print *,'uy(1)=-,uy(1)'
c          print *,'uz(1)=-,uz(1)'
c          print *,'ux(2)=-,ux(2)'
c          print *,'uy(2)=-,uy(2)'
c          print *,'uz(2)=-,uz(2)'
c          pause
c          stop

      If(getforce .eq. 1)then
c          print *,'ix1dof=-,ix1dof'
c          print *,'iy1dof=-,iy1dof'
c          print *,'iz1dof=-,iz1dof'
c          print *,'ix2dof=-,ix2dof'
c          print *,'iy2dof=-,iy2dof'
c          print *,'iz1dof=-,iz1dof'
c          print *,'ux(1)=-,ux(1)'
c          print *,'uy(1)=-,uy(1)'
c          print *,'uz(1)=-,uz(1)'
c          print *,'ux(2)=-,ux(2)'
c          print *,'uy(2)=-,uy(2)'
c          print *,'uz(2)=-,uz(2)'
c          write(6,*)'ix1dof=-,ix1dof'
c          write(6,*)'iy1dof=-,iy1dof'
c          write(6,*)'iz1dof=-,iz1dof'
c          write(6,*)'ix2dof=-,ix2dof'
c          write(6,*)'iy2dof=-,iy2dof'
c          write(6,*)'iz2dof=-,iz2dof'
c          write(6,*)'ux(1)=-,ux(1)'
c          write(6,*)'uy(1)=-,uy(1)'
c          write(6,*)'uz(1)=-,uz(1)'
c          write(6,*)'ux(2)=-,ux(2)'
c          write(6,*)'uy(2)=-,uy(2)'
c          write(6,*)'uz(2)=-,uz(2)'
c          stop
c          endif

c          print *,'chk 2 inside assembly'
c          stop
c          pause

c          if(it .eq. 2)then
c          print *,'it =2'
c          print *,'ianal=',ianal
c          stop
c          endif

c          print *,'chk before info_elstif inside assembly'
c          pause
c          print *,'lm 3 inside assembly =',(lm(i),i=1,6)

c          print *,'xx inside assembly before info_ =',(xx(i),i=1,42)
c          print *,'yy inside assembly before info_ =',(yy(i),i=1,42)
c          print *,'zz inside assembly before info_ =',(zz(i),i=1,42)
c          pause
c          print *,'*****'
c          print *,'before "call info_elstif" '
c          pause

c          print *,'xlength before info_elstif=-,xlength'
c          print *,'xli before info_elstif=-,xli'
c          pause
c          print *,'je before info_elstif=-,(je(ic),ic=1,10)'
c          pause
c          print *,'B( ) before info_elstif in assembly=-,(b(ic),ic=1,ndof)'
c          pause

c          call info_elstif(iel,xlength,xli,cx,cy,cz,xx,yy,zz,ie,je
$ ,propmat,propsect,youngm,area,rho,
$ deltaxi,deltayi,deltazi,xli,
$ xi,xj,yi,zi,zi)

c          print *,'xx inside assembly after info_ =',(xx(i),i=1,42)
c          print *,'yy inside assembly after info_ =',(yy(i),i=1,42)
c          print *,'zz inside assembly after info_ =',(zz(i),i=1,42)

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c      pause
c      print *,*****
c      print *,after "call info_elstif"
c      print *,('B') after info_elstif in assembly=,(b(ic),ic=1,ndof)
c      pause

c      print *,xlength after into_elstif=xlength
c      print *,xli after info_elstif=xli
c      pause

      ndofped=ndofpe(k)
c      write(6,*) inside assembly: ndofped = 'ndofped
c      print *,chk before elstif inside assembly'
c      stop
c      print *,lm 3a inside assembly =,(lm(i),i=1,6)

c      pause
c      call elstif(ndofped,elk,be,
c      $      arca,youngm,xlength,cx,cy,cz,maxdofpe,
c      $      ityp,xl,xli,deltaxi,deltayi,deltazi,
c      $      finx,finy,finz,iarc)
c      call elstif(ndofpe,esm,be,

c      print *,xx inside assembly before elstif=,(xx(i),i=1,42)
c      print *,yy inside assembly before elstif=,(yy(i),i=1,42)
c      print *,zz inside assembly before elstif=,(zz(i),i=1,42)
c      print *,'++++++'
c      print *,Before elstif inside assembly'
c      pause
c      print *,xlength before elstif=xlength
c      print *,xli before elstif=xli
c      pause

c      print *,iel before call elstif=iel
c      pause
c      print *,iarc( )=,(iarc(i),i=1,iel)
c      pause
c      call elstif(ndofpe,elk,be,prospect,iarc,
c      $      area,youngm,xlength,cx,cy,cz,maxdofpe,
c      $      xl,xli,deltaxi,deltayi,deltazi,xx,yy,zz,
c      $      iarc,xi,xj,yj,zj,zj,ityp,lm,istep,iel,check,
c      $      strainel,strainE,strainD,weight,Ancw,Apert,FinI,
c      $      VED,VEDold,xlie,SED)

c      print *,xlength after elstif=xlength
c      print *,xli after elstif=xli
c      pause

c      print *,xx inside assembly after elstif=,(xx(i),i=1,4)
c      print *,yy inside assembly after elstif=,(yy(i),i=1,4)
c      print *,zz inside assembly after elstif=,(zz(i),i=1,4)
c      print *,'++++++'
c      print *,After elstif inside assembly'
c      pause

c      print *,lm 3b inside assembly =,(lm(i),i=1,6)
c      pause
c      print *,Check after elstif

c      print *,idir after elstif in assembly=,(idir(ic),ic=1,ndof)
c      pause

c      DO 919 i=1,6
c      DO 919 j=1,6
c919      print *,elk after elstif = ,elk(i,j)
c      pause

c      stop

c      print *,getforce=,getforce
c      print *,finx(1)=,finx(1)
c      print *,finy(1)=,finy(1)
c      print *,finz(1)=,finz(1)
c      print *,finx(2)=,finx(2)
c      print *,finy(2)=,finy(2)
c      print *,finz(2)=,finz(2)
c      pause
c      stop

      If(getforce.eq.1)then
        b(x1dof)=finx(1)+b(x1dof)
        b(y1dof)=finy(1)+b(y1dof)
        b(z1dof)=finz(1)+b(z1dof)
        b(x2dof)=finx(2)+b(x2dof)
        b(y2dof)=finy(2)+b(y2dof)
        b(z2dof)=finz(2)+b(z2dof)

c      write(6,*)b x&y=,(b(i),i=1,ndof)
c      print *,b x,y,z=,(b(i),i=1,ndof)
c      pause
c      stop
c      goto 4
c      endif

c      print *,lm 4 inside assembly =,(lm(i),i=1,6)
c      pause
c      if(it.eq.2)then
c      print *,it -2'
c      print *,ianal=,ianal
c      stop
c      endif
c      print *,ianal =,ianal

      if (ianal .eq. 1) then
        call elmass(rho,arca,xlength,lumpmass,elm,ndofped,maxdofpe,
        $cx,cy)
c      endif

c      write(6,*) *** passed elstif ***
c      print *,*** passed elstif ***
c      print *,ndofpe(k)=,ndofpe(k)
c      pause
c      stop

```

```

c      DO 920 i=1,6
c      DO 920 j=1,6
c920      print *,elk after elstif = ,elk(i,j)

c      print *,zz 1 inside assembly after elstif= ,(zz(ic),ic=1,3)
c      pause

c677      Continue !skip to here from start if getsolve=1, just solving

c.....convert element [k] & [m] from 2-D array into 1-D array (column-wise)
      do 78 j=1,ndofpe(k)
c      print *,lm 5 inside assembly =,(lm(ic),ic=1,6)

c      print *,zz 1a inside assembly after elstif= ,(zz(ic),ic=1,3)
c      pause
      do 77 ij=1,ndofpe(k)
c      print *,lm 6 inside assembly =,(lm(ic),ic=1,6)
      locate=jj+(j-1)*ndofpe(k)
c      print *,lm 6a inside assembly =,(lm(ic),ic=1,6)

c      print *,zz 1b inside assembly after elstif= ,(zz(ic),ic=1,3)
c      pause
cc      print *,ae(locate)=,ae(locate)

ccc      Something wrong with lm ??????????????????????
c      do 812 im=1,6
c812      lm2(im)=lm(im)

c      print *,zz 1c inside assembly after elstif= ,(zz(id),id=1,3)
c      pause
c      print *,jj, j, elk(ij,j)=,jj, 'j', 'j', elk(ij,j)
c      pause
c      print *,locate, ae(locate) before=,locate, 'ae(locate)
c      pause
c      ae(locate)=elk(ij,j)
c      print *,locate, ae(locate) after=,locate, 'ae(locate)
c      pause
c      print *,zz 1d inside assembly after ae( )=,(zz(ic),ic=1,3)

c      DO 922 id=1,3
c      zz(id)=0.0 !Force zz to zero, something wrong above!!!
c922      continue
c      print *,zz 1d forcing to zero= ,(zz(ic),ic=1,3)

c      pause

c      do 813 im=1,6
c813      lm(im)=lm2(im)
          ! for [k]
cc      print *,lm 6b inside assembly =,(lm(ic),ic=1,6)
c      write(6,*)locate=,locate
c      write(6,*)ae(locate)=,ae(locate)
c      print *,locate end assembly=,locate
c      print *,ae(locate) end assembly=,ae(locate)
c      pause
c      print *,jj, j = ,jj, 'j'
c      print *,elk(ij,j)=,elk(ij,j)
c      pause
c      write(6,*)      'jj, j, locate      = ,jj, 'j', 'j', locate
c      write(6,*)elk(ij,j)=,elk(ij,j)
c      pause

      if (ianal .eq. 1) then
        tempo1(locate)=elm(ij,j)      ! for [m]
c      write(6,*)tempo1=,tempo1

c      ondif
cc      print *,lm 7 inside assembly =,(lm(ic),ic=1,6)
c      pause
c      print *,zz 2 inside assembly lm 7= ,(zz(ic),ic=1,3)
c      pause

77      continue
78      continue

c      print *,ae( )=,(ae(ic),ic=1,20)
c      pause

c      print *,lm 8 inside assembly =,(lm(ic),ic=1,6)
c      stop
c      print *,going to numass'
c      print *,ncoef1=,ncoef1
c      print *,ia before numass in assembly=,(ia(ic),ic=1,10+1)
c      pause

c      not correct...something wrong with ncoef1, again
c      ncoef2=ncoef1
c      stop

c.....sparse "numerical" assembly
c      print *,ia1 before numass in assembly=,(ia1(i),i=1,ndof+1)
c      print *,ia2 before numass in assembly=,(ia2(i),i=1,ndof+1)
c      write(6,*)ia2 before numass in assembly=,(ia2(i),i=1,ndof+1)
c      stop
c      print *,ja(1) before numass in assembly=,ja(1)
c      pause
c      print *,lm inside assembly before numass =,(lm(i),i=1,6)

c      print *,iboundc before numass in aibly=,(iboundc(ic),ic=1,ndof)
c      pause
c.....iboundc=idir in subroutine numass
c.....tempo1=elmass in subroutine numass

c      print *,xx inside assembly before numass=,(xx(i),i=1,42)
c      print *,yy inside assembly before numass=,(yy(i),i=1,42)
c      print *,zz inside assembly before numass=,(zz(i),i=1,42)
c      print *,'++++++'
c      print *,'++++++'
c      print *,Before numass inside assembly'
c      pause

c      print *, 'b(-) before numass in assembly= ,( b(i),i=1,ndof)
c      pause
c      print *,getforce=,getforce
c      pause

```



```

C*** Program to trace the equilibrium path for a geometrically
C*** nonlinear single degree of freedom truss.
C***
C*** Input Variables:
C*** dfl0 = starting incremental external load multiplier,
C*** delta lambda 0, (real, scalar)
C*** dlmx = maximum allowable incremental external load
C*** multiplier, delta lambda max, (real, scalar)
C*** dlmn = minimum allowable incremental external load
C*** multiplier, delta lambda min, (real, scalar)
C*** exfor = external force, Q, (real, vector)
C*** exlmax = maximum allowable total external load
C*** multiplier, lambda max, (real, scalar)
C*** itedes = number of desired iterations for
C*** convergence, (integer, scalar)
C*** itemax = maximum allowable number of iterations,
C*** (integer, scalar)
C*** mxstp = maximum allowable number of load steps,
C*** (integer, scalar)
C*** toldis = convergence tolerance for displacements,
C*** (real, scalar)
C*** tolfor = convergence tolerance for residual forces,
C*** (real, scalar)
C***
C*** Output Variables:
C*** cxlk = total external load multiplier at step k (or i),
C*** lambda k (or lambda i), (real, scalar)
C*** qk = total displacements at step k (or i),
C*** qk (or qi), (real, vector)
C***
C*** Intermediate Variables:
C*** dli = incremental external load multiplier at step i,
C*** delta lambda i, (real, scalar)
C*** dlim1 = incremental external load multiplier at step i-1,
C*** delta lambda i-1, (real, scalar)
C*** dlk = incremental external load multiplier at step k,
C*** delta lambda k, (real, scalar)
C*** dq1 = incremental displacements at step i, delta qi,
C*** (real, vector)
C*** dqim1 = incremental displacements at step i-1, delta qi-1,
C*** (real, vector)
C*** dqk = incremental displacements at step k, delta qk,
C*** (real, vector)
C*** dqk1 = part 1 of delta qk, delta qk1, (real, vector)
C*** dqk2 = part 2 of delta qk, delta qk2, (real, vector)
C*** dqtot = total displacements at load step i, delta qtot,
C*** (real, vector)
C*** dqsq = storage for dqtot*dqtot, (real, scalar)
C*** ds0 = magnitude of initial tangent vector, delta s0,
C*** (real, scalar)
C*** dsi = magnitude of the tangent vector at load step i,
C*** delta si, (real, scalar)
C*** dsim1 = magnitude of the tangent vector at load step i-1,
C*** delta si-1, (real, scalar)
C*** dsmax = maximum allowable magnitude of the tangent
C*** vector, delta smax, (real, scalar)
C*** dsmin = minimum allowable magnitude of the tangent
C*** vector, delta smn, (real, scalar)
C*** fintk = internal force at load step k (or i),
C*** Fk (or Fi), (real, vector)
C*** iconv = convergence flag, iconv=0 means toldis and
C*** and tolfor have been met, (integer, scalar)
C*** iflag = error flag for iteration on the normal
C*** plane, iflag.ne.0 means maximum iterations
C*** have been exceeded, (integer, scalar)
C*** istep = load step counter (integer, scalar)
C*** it = iteration counter (integer, scalar)
C*** resk = residual force at load step k (or i),
C*** FRk (or FRi), (real, vector)
C*** scali = scale factor for load step i, Si, (real, vector)
C*** stifi = tangent stiffness at i, KTi, (real, matrix)
C*** stifik = tangent stiffness at k, KTk, (real, matrix)
C***
C*****
*
implicit real*8(a-h,o-z)
c parameter (nq=2)

common/RIK/ stifi(60,60),dqk1(5000),
$ dqk2(5000),fintk(5000),
$ resk(5000),scali(5000),work1(5000),indx(5000),neq

c common/deltaqi/dqi(500)

common/av/a(1500),jgf,jgsm,np,nb,np2,nbw2
c common/disp/ux(2),uy(2),uz(2),disp(500)
common/infor/getforce,finx(2),finy(2),finz(2),getstiff,getsolve
common/testing/toldis,tolfor,exlk,iconv
common/nodetor/bstor(500),bstor(500)

common/jam/ja2(2000)

c common/elctype/ityp,itruss ityp = 6 for 2-D, =12(3D truss)

double precision, allocatable: dq1(:),dqim1(:)
integer, allocatable: itempo2(:)

dimension dqtot(*)

c double precision, allocatable: ja(:)

dimension disp(*),b(*),ia(*),iperm(*),qk(*)
dimension disp(*),b(*),ia1(*),ia2(*),iperm(*)
dimension ic(*),jet(*),ict(*),jet(*),ac(*),ad(*)
dimension ibound(*),an(*),ux(*),uy(*),di(*),exfor(*)
dimension x(*),y(*),z(*),ip(*),lm(1),iu(*),iarea(*)
dimension ja(*),x(*),y(*),z(*),ip(*),lm(1),iu(*)

dimension ja(*)

dimension strainel(*),strainE(*),strainD(*),weight(*)

dimension Anew(*),Fin1(*),Fin2(*),VED(*),VEDold(*)

c if(iopt .eq. 1) goto 2 !skip, going thru rikarc again in optimizer
c double precision, allocatable: dqtot(:),dq1(:),dqim1(:)
c integer, allocatable: itempo2(:)
c2 continue

c dimension elk(maxdofpe,maxdofpe)

c ... open files for output
c open(15,file='fearc_out.txt',status='old')
c open(12,file='fearc_out_F.txt',status='old')
c open(13,file='fearc_out_q1.txt',status='old')

c open(15,file='fea3d2_out.txt',status='old')
c open(12,file='fea3d2_out_F.txt',status='old')
c open(13,file='fea3d2_out_q1.txt',status='old')

c open(14,file='fea3d2_out_q2.txt',status='old')

c allocate (ja(50))

c print *, 'Start Rik'

neq=ndof
c print *, 'numnodes=', numnodes
c print *, 'x start rik =',(x(i),i=1,numnodes)
c print *, 'y start rik =',(y(i),i=1,numnodes)
c print *, 'z start rik =',(z(i),i=1,numnodes)
c stop
c print *, 'b start rikarc =',(b(i),i=1,ndof)
c stop
c print *, 'jgsm =', jgsm
cc print *, 'np =', np
c print *, 'neq inside Rikarc =', neq
c print *, 'a at start of RIK =', a
c print *, 'dq1 at start of RIK =', dq1
c print *, 'start of RIK'
c print *, 'ityp start RIK =', ityp
c print *, 'ndof start RIK =', ndof
c stop
c print *, 'maxdofpe=', maxdofpe

c stop
c c pause
c ... define user input
C*** dfl0 = starting incremental external load multiplier
c dfl0 = 2.5d-2
cccccc dfl0 = 1.d-2
c dfl0 = 1.d-1
c4 dfl0 = 1.d0
cc dfl0 = 1.d-3
ccc dfl0 = .001
C*** dlmx = maximum allowable incremental external load
C*** multiplier, delta lambda max, (real, scalar)
C*** dlmn = minimum allowable incremental external load
C*** multiplier, delta lambda min, (real, scalar)
c dlmx = 2.6d-2
cccccc dlmx = 1.d-2
cccccc dlmn = 1.d-3
ccc dlmx = 1.d-3
ccc dlmn = 1.d-4
cc dlmx = 1.d-4
ccc dlmn = 1.d-5
cccccccc dlmx = .1
cccccccc dlmn = .01
cccccccc dlmx = .1
cccccccc dlmn = .1
c4 dlmx = 1000.
c4 dlmn = 10.
cxx dlmn = 1.
C*** Use below for truss1
c dlmx = 1.d-0
c dlmn = 1.d-1
C*** Use below for truss2
c dlmx = 1.d+1
c dlmn = 1.d-0
C*** read in the initial forces from big "a"
cc print *, 'jgf =', jgf
c stop
cc print *, 'exfor at start of RikArc =', exfor
c stop
c exfor(1) = 1.55d0
c exfor(2) = 1.45d0
C*** exlmax = maximum allowable total external load
C*** multiplier, lambda max, (real, scalar)
cccccc exlmax = 1.d0
cccccc exlmax = .5d0
cc exlmax = .2d0
cc exlmax = .1d0
c4 exlmax = 100.d0

c itedes = 4
c itedes = 1
c itemax = 20000
c itemax = 999999
c itemax = 1500
c itemax = 900000
c itemax = 100000
cc mxstp = 60
czzz mxstp = 1500
ccc mxstp = 25000
mxstp = 1000000 !step
cccccc toldis = 1.d-3
cccccc tolfor = 1.d-3
cxx toldis = 1.d-2
cxx tolfor = 1.d-2
cccc toldis = .5
cccc tolfor = .5
c4 toldis = 1.d-1
c4 tolfor = 1.d-1

```

```

c   toldis = 1.5d0
c   tolfor = 1.5d0
C*****
C** Truss_2bay_3D.dat
C** Symmetric
C** This is 6 nodes, 11 element
c   itedes = 1
c   d0 = .01d0
c   dlmx = .001d0
c   dlmin = .0001d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-6
C*****
C** Two Bar Truss
C** Symmetric
C** This is 3 nodes, 2 element
cc  itedes = 1
cc  d0 = .01d0
cc  dlmx = .01d0
cc  dlmin = .001d0
cc  exlmx = 1.d0
cc  toldis = 1.d-6
cc  tolfor = 1.d-6
c   print *, 'Check After input'
c   pause
C*****
C** Tripod
C** Crisfield 3,10,2
C** This is 4 nodes, 2 element
cpod itedes = 1
cpod d0 = .1d0
cpod dlmx = .001d0
cpod dlmin = .0001d0
cpod exlmx = 1.d0
cpod toldis = 1.d-6
cpod tolfor = 1.d-6
c   toldis = 1.d-12
c   tolfor = 1.d-12
C*****
C** Crisfield truss, ex 22.4a, vol2 chap 22.4, page 407
C** cris_22_4a_in.dat 6nodes, 9 elements
c   itedes=1
c   d0 = .1d0
c   dlmx = .01d0
c   dlmin = .001d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-6
C*****
C** Duc truss, truss11_3d_in.dat
C** Duc truss, truss11_3d_xz_in.dat
C** This is a 6 nodes, 11 elements,
c   itedes=1
c   d0 = .01d0
c   dlmx = .0001d0
c   dlmin = .00001d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-6
C*****
C** Duc truss, truss10_3d_in.dat
C** This is a 6 nodes, 10 elements,
c   itedes=1
c   d0 = .01d0
c   dlmx = .001d0
c   dlmin = .0001d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-6
C*****
C** Duc truss, truss7_3d_in.dat
C** This is a 5 nodes, 7 elements,
ctruss itedes=1
ctruss d0 = .01d0
ctruss dlmx = .001d0
ctruss dlmin = .0001d0
ctruss exlmx = 1.d0
ctruss toldis = 1.d-4
ctruss tolfor = 1.d-4
C*****
C** The following are used for test problem Truss3in.dat & T4in.dat
C** This is a 2 ele, 3 node problem, results agree with Crisfield
c   d0 = .1d0
c   dlmx = .001
c   dlmin = .0001
c   exlmx = 1.d0
c   toldis = .00001
c   tolfor = .00001d0
C*****
C** The following are used for test problem T3in.dat
C** This is a 3 ele, 3 node problem, results agree with Crisfield
c   d0 = .1d0
c   dlmx = .01
c   dlmin = .001
c   exlmx = 1.d0
c   toldis = .01d0
c   tolfor = .01d0
C*****
C** The following are used for test problem T3in.dat & T3ain.dat
C** This is a 6 ele, 4 node problem, results agree with Crisfield
c   d0 = .1d0
c   dlmx = .01
c   dlmin = .001
c   exlmx = 1.d0
c   toldis = .0001d0

```

```

c   tolfor = .0001d0
C*****
C** The following are used for test problem T3xin.dat
C** This is a 6 ele, 4 node problem, results agree with nastran
c   d0 = .1d0
c   dlmx = .1
c   dlmin = .01
c   exlmx = 1.d0
c   toldis = .00001d0
c   tolfor = .01d0
C*****
C** The following are used for test problem T4xxcin.dat GOOD
C** This is a 10 ele, 7 node problem, results agree with nastran
c   d0 = .1d0
c   dlmx = .1d0
c   dlmin = .01d0
c   exlmx = 1.d0
c   toldis = 1.d-9
c   tolfor = 1.d-9
C*****
C** Crisfield small arch, arch20in.dat
C** This is a 10 nodes, 20 element,
c   d0 = .1d0
c   dlmx = .001d0
c   dlmin = .0001d0
c   exlmx = 1.d0
c   toldis = 1.d-5
c   tolfor = 1.d-5
C*****
C** Crisfield small arch, arch10_3D_in.dat
C** This is a 10 nodes, 21 element,
c   itedes=1
c   d0 = .001d0
c   dlmx = .001d0
c   dlmin = .0001d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-6
C*****
C** Crisfield small arch, arch18_3D_in.dat
C** This is a 18 nodes, 41 element,
c   d0 = .01d0
c   dlmx = .001d0
c   dlmin = .0001d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-6
C*****
C** Crisfield small arch, arch18_3D_in.dat
C** This is a 18 nodes, 41 element,
c   itedes=5
c   d0 = .01d0
c   dlmx = .005d0
c   dlmin = .0005d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-6
C*****
C** Crisfield large symmetry arch, arch22in.dat
C** This is a 22 nodes, 51 elements,
cc  d0 = .1d0
cc  dlmx = .1d0
cc  dlmin = .01d0
cc  exlmx = 1.d0
cc  toldis = 1.d-3
cc  tolfor = 1.d-4
C*****
C** Crisfield small arch, arch42_3D_in.dat
C** arch3din.dat
C** This is a 42 nodes, 101 element,
c   itedes=1
c   d0 = .1d0
c   dlmx = .01d0
c   dlmin = .0001d0
c   exlmx = 1.d0
c   toldis = 1.d-4
c   tolfor = 1.d-4
C*****
C** Crisfield small arch, arch42in.dat
C** arch10_3D_in.dat
C** This is a 21 nodes, 10 element,
c   itedes=1
c   d0 = .01d0
c   dlmx = .01d0
c   dlmin = .001d0
c   exlmx = 1.d0
c   toldis = 1.d-6
c   tolfor = 1.d-4
C*****
carch itedes=1
carch d0 = .1d0
carch dlmx = .1d0
carch dlmin = .001d0
carch exlmx = 1.d0
carch toldis = 1.d-6
carch tolfor = 1.d-6
C*****
c   itedes=1
c   d0 = .01d0
c   dlmx = .01d0
c   dlmin = .001d0
c   exlmx = 1.d0
c   toldis = 1.d-4
c   tolfor = 1.d-4
C*****
C** Shallow truss & Khot 4element
C** Khot paper
C** This is a 13 nodes, 23 elements,
c   itedes=1

```

```

c      d10 = .01d0
c      d1max = .01d0
c      d1min = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-4
c      tolfir = 1.d-4

      itodes=1
      d10 = .1d0
      d1max = .10d0
      d1min = .001d0
      exlmax = 1.d0
      toldis = 1.d-4
      tolfir = 1.d-4

c      itodes=1
c      d10 = .01d0
c      d1max = .01d0
c      d1min = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-4
c      tolfir = 1.d-4

C*****

C** Duc frame example frame_in.dat
C**
C** This is a 4 nodes, 5 element,
c      itodes=1
c      d10 = .01d0
c      d1max = .001d0
c      d1min = .0001d0
c      exlmax = 1.d0
c      toldis = 1.d-6
c      tolfir = 1.d-6

c      itodes=2
c      d10 = .025d0
c      d1max = 8.d-3
c      d1min = 5.d-3
c      exlmax = 1.d0
c      toldis = 1.d-3
c      tolfir = 1.d-4
C*****

C*****
C** t3a_in.dat
C** This is a 3 nodes, 3 element,
ct3a      itodes=1
ct3a      d10 = .00001d0
ct3a      d1max = 1.d-3
ct3a      d1min = 1.d-4
ct3a      exlmax = 1.d0
ct3a      toldis = 1.d-6
ct3a      tolfir = 1.d-6
C*****

C** 3D Truss , Td3_in.dat
C** This is a 4 nodes, 3 elements,
c      d10 = .1d0
c      d1max = .01d0
c      d1min = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-5
c      tolfir = 1.d-5
C*****

C** 3D Truss , Dome_in.dat & Dome2_in.dat
C** This is a 13 nodes, 24 elements,
cc      if (exlk.gt. .99.and. exlk.lt. 1.0)then
cc          print *,'exlk .gt. .99 at start rik=',exlk
cc      d10 = .00001d0
cc      d1max = .00001d0
cc      d1min = .000001d0
cc          pause
cc      Else
cdome      itodes=1
cdome      d10 = .1d0
cdome      d1max = .1d0
cdome      d1min = .01d0
cdome      exlmax = 1.d0
cdome      toldis = 1.d-4
cdome      tolfir = 1.d-4
C*****
C** Crisfield 2.2 Truss , Cris_sodf_in.dat
C** This is a 2 nodes, 1 element,
csdof      itodes=1
csdof      d10 = .01d0
csdof      d1max = .001d0
csdof      d1min = .001d0
csdof      exlmax = 1.d0
csdof      toldis = 1.d-4
csdof      tolfir = 1.d-4

C*****
C*****
C** Khot 2 ele unsymmetric Truss , Khot_2ele_in.dat
C** This is a 3 nodes, 2 element,

ckhot2      itodes=1
ckhot2      d10 = .01d0
ckhot2      d1max = .01d0
ckhot2      d1min = .001d0
ckhot2      exlmax = 1.d0
ckhot2      toldis = 1.d-4
ckhot2      tolfir = 1.d-4

cc      itodes=1
cc      d10 = .0001d0
cc      d1max = .0001d0
cc      d1min = .00001d0

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cc      exlmax = 1.d0
cc      toldis = 1.d-4
cc      tolfir = 1.d-4

C*****
C** snap_in.dat
C** This is a 4 nodes, 3 elements,
csnap      itodes=1
csnap      d10 = .01d0
c      d10 = .5d0
csnap      d1max = .1d0
csnap      d1min = .00001d0
csnap      exlmax = 1.d0
csnap      toldis = 1.d-4
csnap      tolfir = 1.d-4

C*****
C** 3D Truss , twobar_in.dat !Similar to Crisfield 22.1
C** large bifurcation
C** This is a 3 nodes, 2 elements,
ctwo      itodes=1
ctwo      d10 = .001d0
c      d10 = .5d0
ctwo      d1max = .001d0
ctwo      d1min = .0001d0
ctwo      exlmax = 1.d0
ctwo      toldis = 1.d-6
ctwo      tolfir = 1.d-6

C*****
C** The following are used for test problem T4xin.dat & T4xxin.dat & T4in.dat
C** This is a 10 ele, 7 node problem, results agree with nastran
c      d10 = .1d0
c      d1max = .01d0
c      d1min = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-6
c      tolfir = 1.d-6
C*****
C** The following are used for test problem T5xxin.dat & T4xxin.dat
C** This is a 10 ele, 7 node problem, results agree with nastran
c      d10 = .1d0
c      d1max = .01d0
c      d1min = .001d0
c      exlmax = 1.d0
c      toldis = 1.d-5
c      tolfir = 1.d-4
C*****
C** The following are used for test problem T7in.dat
C** This is a 4 ele, 5 node problem, results agree with Crisfield
c      d10 = .01d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfir = .01d0
C*****
C** The following are used for test problem T7Ain.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
C** using these variables, this takes a long time 30+ min
c      d10 = .1d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfir = .01d0
C** The following are used for test problem T7Bin.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
C** try using different variables for faster
c      d10 = 1.d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfir = .01d0
C** The following are used for test problem T7Cin.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
C** try using different variables for faster
c      d10 = 1.d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .01d0
c      tolfir = .01d0
C** The following are used for test problem T7Din.dat
C** This is a 6 ele, 5 node, 3 support problem, results agree with Crisfield
c      d10 = .01d0
c      d1max = .01
c      d1min = .001
c      exlmax = 1.d0
c      toldis = .001d0
c      tolfir = .001d0
C** The following are used for test problem T7iEn.dat
C** This is same as T7D above but use 2 supports instead of 3
C** This is a 6 ele, 5 node, 2 support problem
C** Trying to get a solution, do I need right bracketing or is program wrong?
c      d10 = .01d0
c      d1max = .01d0
c      d1min = .001d0
c      exlmax = 1.d0
c      tolfir = .9d0
c      toldis = .9d0
C*****
C** The following are used for test problem T11in.dat
C** This is a 4 ele, 5 node problem, results agree with Crisfield
c      d10 = 1.d0
c      d1max = 1.
c      d1min = .1

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c      exlmax = 100.d0
c      toldis = .99d0
c      tolfor = .99d0
C*****
c
C*****
C** The following are used for test problem T11.in.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
c      d0 = 1.d0
c      d1max = .1
c      d1min = .01
c      exlmax = 1000.d0
c      toldis = 9d0
c      tolfor = .98d0
C*****
C** The following are used for test problem T11.in.dat
C** This is a 4 ele, 4 node problem, results agree with Crisfield
c      d0 = 1.d0
c      d1max = .1
c      d1min = .01
c      exlmax = 100.d0
c      toldis = .99d0
c      tolfor = .99d0
C*****
c ... end user input
c
c      allocate (dqtot(ndof),dqj(ndof),dqim1(ndof),qk(ndof))
c
c      If(iopt .eq. 1)then
c      deallocate (dqtot)
c      deallocate (dqj)
c      deallocate (dqim1)
c      print *, 'deallocate'
c      endif
c
c      allocate (dqj(ndof),dqim1(ndof))
c
c      ncoef1_guess=20000000
c      allocate ( itempo2(ncoef1_guess) )
c
c      print *, 'check BB'
c      pause
c
c      common/RJK/ stifi(60,60),dqk1(5000),
c      $ dqk2(5000),fintk(5000),
c      $ resk(5000),scal(5000),work1(5000),indx(5000),neq
c
c      allocate ( iet(jeall+1),je(jeall),iboundc(ndof),iet(ndof+1),
c      $ iet(jeall),ip(ndof),iu(ndof+1),iut(ndof+1),iup(ndof),
c      $ isupn(ndof),lm(maxdofpe),iperm(ndof),ia(ndof+1),iarea(ndof))
c      allocate (ja(ndof+1))
c      allocate ( b(ndof),be(maxdofpe),ae(maxdofpe**2),ad(ndof),
c      $ an(10000),dqtot(ndof),
c      $ x(numnodes),y(numnodes),z(numnodes),
c      $ propmat(nummat*11),propsect(nsect),tempo1(ndof),
c      $ tempo2(ndof),di(ndof),exfor(ndof))
c      allocate ( disp(ndof),qk(ndof) )
c
c      Do 7070 i=1,jeall
c      jct(i)=0.d0
c7070 continue
c
c      itnrm1on = 0
c
c      Do 7070 i=1,maxdofpe**2
c      ae(i)=0.d0
c7070 continue
c
c      Do 6060 i=1,ndof+1
c      ia(i)=0.d0
c      ja(i)=0.d0
c6060 continue
c
c      Do 5050 i=1,10000
c      an(i)=0.d0
c5050 continue
c
c      Do 4040 i=1,1000
c      ja2(i)=0.d0
c4040 continue
c
c      Do 3030 j=1,60
c      Do 3031 k=1,60
c      stifi(j,k)=0.d0
c3031 continue
c3030 continue
c
c      Do 2020 i=1,5000
c      dqk1(i)=0.d0
c      dqk2(i)=0.d0
c      fintk(i)=0.d0
c      resk(i)=0.d0
c      scal(i)=0.d0
c      work1(i)=0.d0
c      indx(i)=0.d0
c2020 continue
c
c      Do 1010 i=1,1500
c      a(i)=0.d0
c1010 continue
c
c ... initialize required variables
c
c      dli = 0.d0      dlk = 0.d0
c
c      dlim1 = 0.d0
c      dqsq = 0.d0
c      ds0 = 0.d0
c      dsi = 0.d0
c      dsim1 = 0.d0
c
c      dsmax = 0.d0
c      dsmin = 0.d0
c      exlk = 0.d0
c      iconv = 0
c      istep = 1
c      it = 1
c
c      do 20 i=1,neq
c      do 10 j=1,neq
c      print *, 'chk before stiff'
c      pause
c      stifi(j,i) = 0.d0
c10 continue
c
c      print *, 'check zz'
c      pause
c      dqj(i) = 0.d0      print *, 'Check after dqj'
c
c      pause
c      dqim1(i) = 0.d0
c      dqtot(i) = 0.d0
c
c      disp(i) = 0.d0
c
c      fintk(i) = 0.d0
c      qk(i) = 0.d0
c      resk(i) = 0.d0
c      scal(i) = 0.d0
c      work1(i) = 0.d0
c
c      exfor(i) = 0.d0
c      b(i) = 0.d0
c      disp(i)=0.d0
c      ad(i)=0.d0
c      tempo1(i)=0.d0
c      tempo2(i)=0.d0
c20 continue
c
c      print *, 'exfor at start rikarc = ',(exfor(ic),ic=1,ndof)
c      pause
c      print *, 'iarc=',iarc
c      print *, 'maxdofpe=',maxdofpe
c      print *, 'iboundc=',(iboundc(i),i=1,ndof)
c      pause
c
c      stop
c
c      iskip = 0 !When zero will go thru symfactd, 1 will skip symfactd
c
c      itnrm1on = 0 !When zero not going thru "itnrm1"
c      When one, inside "itnrm1" telling syscon & assembly
c
c      ... [ja] allocation in syscon...if jallo=0 then allocate
c      ... if jallo=1 then skip allocation is sysconF
c
c      If(iopt .eq. 0)then
c      print *, 'iopt is zero at start Rikarc=',iopt
c      pause
c      jallo=0
c      endif
c
c      print *, 'exlk before 999=',exlk
c      pause
c
c999 if(exlk .le. exlmax .and. istep .le. mxstp) then
c
c      If(istep .eq. 910)Then
c      itides=1
c
c      d0 = .01d0
c      d1max = .000001d0
c      d1min = .00000001d0
c      exlmax = 1.d0
c      toldis = 1.d-8
c      tolfor = 1.d-8
c
c      print *, 'Change starting are variables'
c      Endif
c
c      write(*,*) 'Beginning Load Step Number in RIKARC:',istep
c      print *, 'exlk start Rik= ',exlk
c      pause
c      stop
c      it = 1
c      if (istep .eq. 1) then
c      print *, '** CHECK A **'
c      pause
c      print *, 'je start istep=1 = ',(je(i),i=1,20)
c
c      print *, 'getstiff=',getstiff
c      print *, 'getforce=',getforce
c      print *, 'getsolve=',getsolve
c      pause
c
c      stop
c      ... compute K10 for eqn. 4,107
c      print *, 'ndof=',ndof
c      pause
c      print *, 'b before syscon = ',(b(i),i=1,ndof)
c      pause
c      stop
c      print *, 'maxdofpe=',maxdofpe
c      print *, 'check before 1st syscon'
c
c      stop
c      getstiff=1
c
c      call syscon(nc,iplvl,b,ndof,disp,iarc,qk,
c      $ ietall,ie,je,iut,jeall,ia,ae,maxdofpe,
c      $ ndtype,nel,maxdofpe,x,y,z,propmat,propsect,lm,
c      $ iboundc,ad,an,iperm,iu,ip,iut,dqtot,dqj,dqim1,
c      $ ux,uy,uz,di,ie,area,young,grn,iarea,
c      $ ianal,lumpmass,iskip,itempo2,itnrm1on,exfor,istep,
c      $ jallo,
c      $ strainel,strainE,strainD,weight,iopt,Anew,Apert,Fin1,

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c          print *,it=2'
c          stop
c          endif

c          If(getforce.eq. 1)then
c            print *,getforce=1 at start of syseqn'
c            stop
c** Get ready for internal forces, set all forces to zero
c*****
c          If(ityp .eq. 6)Then
c            Do 28 i=1,ndof
c 28       b(i)=0.
c*****
c          stop
c          goto 30
c          endif

c** Get ready for new stiffness terms,
c** set only stiff & force terms to zero
c*****
c          DO 29 i=1,ndof
c 29       b(i)=0. !set loads to zero
c          print *,b =',(b(i),i=1,ndof)
c          stop
c          ndof2=ndof**2
c          print *,ndof2=','ndof2
c          Do 31 i=1,ndof2-10
c 31       an(i)=0. !set stiff to zero
c          print *,chk 2 inside syseqn'
c          stop

30       continue !just a blank, no Do associated
c.....input boundary dof
c          call supportdof(iboundc,nboundc,b,ndof,ia)
c          print *,b inside syseqn =',(b(i),i=1,ndof)
c          pause
c          stop
c.....
c          print *,getforce=','getforce
c*****
c          If(getforce .eq. 1)then !skip transa2d, symbass, copy_int
c            'Go to assembly2'
c            print *,ja(1)=','ja(1)
c            print *,getforce goto 32'
c            pause
c            stop
c            print *,ical=','ical
c            print *,ndof=','ndof
c            print *,jct =',(jct(i),i=1,jeall*4)
c            print *,iet =',(iet(i),i=1,ndof+1)
c            print *,ie =',(ie(i),i=1,jeall+1)
c            print *,je =',(je(i),i=1,jeall)
c            stop
c            goto 32
c          Endif
c*****
c          If(it .eq. 2)then
c            print *,it=2'
c            stop
c            endif
c            print *,chk before transa2d'
c            print *,getstiff=','getstiff
c            print *,getforce=','getforce
c            pause
c            print *,je inside syseqn before transa2d=',(je(i),i=1,20)
c            stop
c            print *,chk before transa2d'
c            pause
c            call transa2d(ical,ndof,ie,je,iet,jct)

cc32 continue !dummy line from "If(getforce .eq. 1) above
c          write(6,*) '*** passed transa2 ***'
c          print *,after transa2d'
c          pause
c          stop
c          print *,ndof=','ndof
c          print *,jeall=','jeall
c          print *,ical=','ical
c          print *,ie =',(ie(i),i=1,jeall+1)
c          print *,je =',(je(i),i=1,jeall)
c          print *,je =',(je(i),i=1,ndof*4)
c          print *,iet =',(iet(i),i=1,ndof+1)
c          print *,jct =',(jct(i),i=1,jeall)
c          print *,jct =',(jct(i),i=1,jeall*4)
c          print *,ia1 =',(ia1(i),i=1,ndof+1)
c          stop
c          If(it .eq. 2)then
c            print *,it=2'
c            stop
c            endif

c          If(getforce .eq. 1)then
c            print *,getforce=1 before symbass'
c            print *,ndof=','ndof
c            stop
c            endif
c.....sparse "symbolic" assembly
c          ncoef1_guess=20000000
c          dallocate (itempo1)

c          allocate ( itempo1(ncoef1_guess) )
c          print *,!skip before allocate itempo2=','!skip
c          pause
c          If(!skip .eq. 1)Then
c            itempo1(1)=itempo2(1)
c            print *,itempo1(1)=itempo2(1)=','itempo1(1)
c          Else
c            Endif
c          print *,ndof=','ndof
c          stop

c          print *,chk before symbass'
c          print *,getstiff=','getstiff
c          print *,getforce=','getforce
c          print *,jeall before symbass=','jeall
c          print *,je before symbass=','(je(i),ic=1,jeall+1)
c          print *,je inside syseqn before symbass=','(je(i),i=1,30)
c          print *,iet before symbass=','(iet(ic),ic=1,jeall+1)
c          print *,iet before symbass=','(iet(ic),ic=1,jeall+1)
c          print *,ja before symbass=','(ja(i),i=1,jeall+1)
c          print *,ja before symbass=','(ja(i),i=1,jeall+1)
c          stop
c          pause
c          print *,!skip before if =','!skip
c          pause
c          If(!skip .eq. 1)Then !only do symbass one time, skip after 1st time
c            Go To 799
c          Else
c            call symbass(ie,je,iet,jct,ndof,ia,
c              $ itempo1,ncoef1,itempo1)
c          $
c          !skip = 1!This causes symbass to be skipped, only need to go once
c          itempo2(1)=itempo1(1)!Need this because itempo1 gets re-allocated
c          call symbass(ie,je,iet,jct,ndof,ia1,ia2,
c            $ itempo1,ncoef1)
c          Endif
c          CONTINUE !dummy line for abv "If" statement
c          print *,!skip after symbass =','!skip
c          print *,*** After symbass ***'
c          print *,je after syseqn =','(je(i),i=1,20)
c          print *,itempo1=','itempo1(1)
c          print *,itempo2=','itempo2(1)
c          pause

c          stop
c          pause

c          If(getforce .eq. 1)then
c            print *,getforce =1 before symbass'
c            print *,ncoef1 =','ncoef1
c            stop
c            endif

c          print *,ncoef1 =','ncoef1
c          pause
c          stop
c          print *,jeall =','jeall
c          print *,ie =','(ie(i),i=1,jeall+1)
c          print *,je =','(je(i),i=1,jeall)
c          print *,iet =','(iet(i),i=1,ndof+1)
c          stop
c          print *,jeall=','jeall
c          print *,ndof=','ndof
c          print *,ncoef1=','ncoef1
c          print *,jct after symbass=','(jct(i),i=1,jeall)
c          print *,ia1 after symbass=','(ia1(i),i=1,ndof+1)
c          stop
c          print *,ia2 after symbass=','(ia2(i),i=1,ndof+1)
c          print *,itempo1 after symbass=','(itempo1(i),i=1,ncoef1)
c          stop

c          If(getforce .eq. 1)then
c            stop
c            endif

c          If(it .eq. 2)then
c            print *,it=2'
c            print *,STOP'
c            stop
c            endif

c          stop
c          print *,ncoef1=','ncoef1
c          stop
c          do 111 i=1,ncoef1_guess
c 111       print *,itempo1 =','itempo1(ncoef1_guess)
c          stop
c          print *,ncoef1 =','ncoef1
c          stop
c          allocate ( ja2(ncoef1) )
c          stop
c          c...not sure, "ja" is also needed in assembly2
c          print *, '?????????????????????????????'
c          c...!turnlon means call was done in subroutine !turnlon
c          print *,!turnlon=','!turnlon
c          pause
c          If(!turnlon .eq. 1)Then !skip allocation, already done
c            goto 790
c          Endif

c          print *,getstiff=','getstiff
c          pause

c          If(getstiff .eq. 0)then
c            c... when jallo=0, allocate [ja]
c            c... don't allocate when jallo=1
c            c... added for multiple loads for dynamics
c            print *,jallo=','jallo
c            If(jallo .eq. 0) then
c              If(!loadyn .eq. 1 .or. idyn .ne. 99)then
c                print *,chk before allocate (ja)'
c                print *,jallo before allocate=','jallo
c                pause
c                allocate (ja(ncoef1) )
c                print *,chk after allocate (ja)'
c                jallo=1
c                Endif
c              Endif
c            print *,ncoef1=','ncoef1

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c          pause
c          If(iopt.eq. 1)then !skip allocation
c          print *,iopt='!',iopt
c          pause
c          goto 790
c          Endif
c          allocate (ja(ncoeff))
c          print *,'allocate -ja- when getstiff=0 inside sysqp'
c          pause
c          allocate (ja2(ncoeff))
c          allocate (am(ncoeff))
c          print *,'allocate -am- when getstiff=0 inside sysqp'
c          pause
c          Endif
790      Continue !dummy line
c          allocate (tempol(ndof))
c          print *,'***chk before copy_int***'
c          pause
c          print *,'getstiff=',getstiff
c          print *,'getforce=',getforce
c          print *,'getsolve=',getsolve
c          print *,'ncoeff1=',ncoeff1
c          print *,'tempol=',tempol
c          print *,'ja=',(ja(ic),ic=1,ncoeff1)
c          pause
c          print *,'skip before 1st copy_int=',iskip
c          pause
c          print *,'larea( ) before 1st copy_int=',(larea(i),i=1,nel)
c          pause
c          If(iskip.eq. 1)Then !only do symbass one time, skip after 1st time
c          goto 798
c          Else
c          print *,'chk 1 before copy_int'
c          pause
c          call copy_int(ncoeff1,tempol,ja)
c          Endif
798      CONTINUE !dummy line for abv "If" statement
c          print *,'passed 1st copy_int'
c          print *,'ja( ) after copy_int in sysqp=',(ja(ic),ic=1,ncoeff1)
c          print *,'#####'
c          pause
c          Endif
c788      continue !dummy line for skip=1
c          print *,'ncoeff1=',ncoeff1
c          stop
c          If(getforce.eq. 1)then !skip, ja is already=ja2
c          goto 112
c          Else
c          print *,'ncoeff1=',ncoeff1
c          allocate ja2(ncoeff1)
c          do 111 i=1,ncoeff1
c          print *,'ja(i)=' ja(i)
c111      ja2(i)=ja(i)
c          Endif
c          print *,'ja2 just after setting ja=',(ja2(ic),ic=1,10)
c          print *,'ja2(1)=' ja2(1)
c          pause
c          print *,'#####'
c          pause
c112      Continue !dummy
c          print *,'ja2 after set to ja =' ,(ja2(i),i=1,ncoeff1)
c          pause
c          stop
c          deallocate (tempol)
c          c.....sparse "numerical" assembly
c          print *,'lanel=',lanel
c          print *,'lumpmass=',lumpmass
c          if (lanel .eq. 1) then
c          allocate ( evalues(ncig) )
c          allocate ( evecs(ncig) )
c          allocate ( dm(ndof) )
c          allocate ( elm(maxdofpe,maxdofpe) )
c          if (lumpmass .eq. 0) then
c          allocate ( am(ncoeff1) )
c          Endif
c          Endif
c          print *,'check point #01'
c          write(6,*) 'check point #01'
c          print *,'ncoeff1 before assembly=',ncoeff1
c          stop
c          if(it.eq. 2)then
c          print *,'it =2'
c          print *,'before assembly2'
c          stop
c          Endif
32      continue
c32      print *,'dummy line' !dummy line from "If(getforce .eq. 1) above
c          write(6,*) '*** passed symbass ***'
c          If(getforce.eq. 1)then
c          print *,'getforce=1 before assembly'
c          print *,'ja2(i)=' ,(ja2(ic),ic=1,10)
c          Endif
c          pause
c          print *,'getforce=',getforce
c          If(getforce.eq. 1)then
c          stop
c          pause
c          print *,'ncoeff1=',ncoeff1
c          write(6,*) ja( ) before assembly2=( ja(i),i=1,ncoeff1)
c          print *,'ja( ) before assembly2=',(ja(i),i=1,ncoeff1)
c          stop
c          call assembly2(ip,ad,an,lm,ic,jc,propmat
c          $, propsect,elk,be,b,iboundc,ux,uy
c          $, ae,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c          $ ndof,neltype,nel,ndofpe,lanal,lumpmass,dm,am,elm,tempol,disp,
c          $ larc,ityp,getforce,it)
c          print *,'ia2 before assembly=',(ia2(i),i=1,ndof+1)
c          stop
c          If(getforce .eq. 1)then
c          print *,'ja2 before assembly & getforce=1',(ja2(ic),ic=1,10)
c          Endif
c          pause
c          print *,'ad stiff before assembly=',(ad(i),i=1,maxdofpe**2)
c          print *,'ae stiff before assembly=',(ae(i),i=1,maxdofpe**2)
c          pause
c          print *,'skip call assembly'
c          print *,'Before assembly 1 in sys'
c          pause
c          call assembly(ip,ad,an,lm,ic,jc,propmat,
c          $ propsect,be,b,iboundc,larea,
c          $ ae,ia,ja,x,y,z,ncoeff1,maxdofpe,
c          $ ae,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c          $ ndof,neltype,nel,ndofpe,lanal,lumpmass,dm,am,elm,
c          $ tempol,disp,larc,it,area,youngm,esm,qk,itmrmton)
c          $ tempol,disp,larc,it,area,youngm,qk,itmrmton,istep,check,
c          $ strainel,strainE,strainD,weight,Anew,Apart,Fin1,
c          $ Fin2,VED,VEDold,xlic,SED)
c          print *,'ia2 after assembly=',(ia2(i),i=1,ndof+1)
c          print *,'*** Passed assembly ***'
c          print *,'ad stiff after assembly=',(ad(i),i=1,maxdofpe**2)
c          print *,'ae stiff after assembly=',(ae(i),i=1,maxdofpe**2)
c          pause
c          STOP
c          else
c          print *,'chk before assembly'
c          print *,'getstiff=',getstiff
c          print *,'getforce=',getforce
c          print *,'Check before assembly'
c          stop
c          pause
c          call assembly(ip,ad,an,lm,ic,jc,propmat
c          $, propsect,elk,be,b,iboundc,ux,uy
c          $, ae,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c          $ ndof,neltype,nel,ndofpe,lanal,lumpmass,dm,am,elm,tempol,disp,
c          $ larc,ityp,getforce,it)
c          print *,'***ia2 before assembly***',(ia2(i),i=1,ndof+1)
c          stop
c          print *,'going to assembly 2'
c          print *,'ndofpe=',ndofpe
c          print *,'chk before assembly'
c          pause
c          print *,'B( ) before assembly=',(b(ic),ic=1,ndof)
c          pause
c          call assembly(ip,ad,an,lm,ic,jc,propmat,
c          $ propsect,be,b,iboundc,larea,
c          $ ae,ia,ja,x,y,z,ncoeff1,maxdofpe,
c          $ ae,ia2,ja,x,y,z,ncoeff1,maxdofpe,
c          $ ndof,neltype,nel,ndofpe,lanal,lumpmass,dm,am,elm,
c          $ tempol,disp,larc,it,area,youngm,qk,itmrmton,istep,check,
c          $ strainel,strainE,strainD,weight,Anew,Apart,Fin1,
c          $ Fin2,VED,VEDold,xlic,SED)
c          print *,'***Passed assembly***'
c          print *,'maxdofpe=',maxdofpe
c          print *,'ad stiff after assembly=',(ad(ic),ic=1,maxdofpe**3)
c          print *,'an stiff after assembly=',(an(ic),ic=1,50)
c          print *,'ae stiff after assembly=',(ae(i),i=1,maxdofpe**2)
c          pause
c          stop
c          write(6,*) '***Passed assembly***'
c          stop
c          Endif
c----- Only used when solving, getsolve=1
c          print *,'getforce=',getforce
c          print *,'getstiff=',getstiff
c          print *,'getsolve=',getsolve
c          pause
c          print *,'B( )=',(b(ic),ic=1,ndof)
c          pause
1111      If(getsolve .eq. 1)Then
c          goto 797
cx      call assembly(ip,ad,an,lm,ic,jc,propmat,
cx      $ propsect,be,b,iboundc,
cx      $ ae,ia,ja,x,y,z,ncoeff1,maxdofpe,
cx      $ ndof,neltype,nel,ndofpe,lanal,lumpmass,dm,am,elm,
cx      $ tempol,disp,larc,it,area,youngm,qk,itmrmton)
c          print *,'b after assembly getsolve=1 =' ,(b(i),i=1,ndof)
c          print *,'ad after assembly getsolve=1',(ad(i),i=1,maxdofpe**2)
c          print *,'ae after assembly getsolve=1',(ae(i),i=1,maxdofpe**2)
c          stop
c          pause
c          Endif
c          write(6,*) 'ae=',(ae(i),i=1,maxdofpe**2)
c          write(6,*) 'disp=',(disp(i),i=1,ndof)
c          write(6,*) 'ae=',(ae(i),i=1,20)
c          write(6,*) 'disp=',(disp(i),i=1,10)
c          stop

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c      print *,Getforce after assembly2 = ',getforce
c      stop
c      If(getforce.eq. 1)then

c      print *,'b after assembly getforce is 1 =',(b(i),i=1,ndof)
c      print *,'clk after assembly getforce is 1 =',(clk(i),i=1,ndof)
c      print *,'iboundc=',(iboundc(i),i=1,ndof)
c***need to get support dof into "b"
c      Do 449 I=1,ndof
c      If(iboundc(i).eq. 1)Then
c      b(i)=0.0
c      Endif
449 Continue
c      b(1)=0.0
c      b(2)=0.0
c      b(3)=0.0
c      b(4)=0.0
c      b(6)=0.0
c      b(7)=0.0
c      b(8)=0.0
c      b(9)=0.0
c      print *,'b modify for support dof =',(b(i),i=1,ndof)
c      pause
c      goto 45 'this goes to the end of subroutine when we want internal
forces
c      stop
c      endif
c*****
c      print *,'ae =',(ae(i),i=1,maxdofc**2)
c      stop
c      write(6,*) 'check point #02'
c      print *,'check point #02'
c      stop
cc      if (ianal .eq. 1) then
cc      write(6,*) 'diag-mass = dm(-) =',(dm(i),i=1,ndof)
cc      endif
cc      if (ianal .eq. 1 .and. lumpmass .eq. 0) then
cc      write(6,*) 'bdiag-mass = am(-) =',(am(i),i=1,ncoeff)
cc      endif
c
c.....assuming to skip the "REORDERING" process (minimize "fills-in" terms)
c      print *,'***before minfills***'
c      print *,'iperm before minfills=',(iperm(i),i=1,ndof)
c      pause
c      stop
c
c      print *,'iskip inside sysseqn=',iskip
c      pause
c
c      If(iskip .eq. 1)Then !only do symbass one time, skip after 1st time
c      print *,'iskip=1 goto 797'
c      pause
c      goto 797
c      Else
c      call minfills(ndof,iperm)
c      print *,'iperm after minfills=',(iperm(i),i=1,ndof)
c      pause
c
c      iskip = 1!This causes symbass to be skipped, only need to go once
c      save for other iterations!!!
c
c      print *,'passed minfills'
c      print *,'iperm after minfills=',(iperm(i),i=1,ndof)
c      Endif
797 Continue 'dummy statement
c      stop
c.....eigen-solution
cc      if (ianal .eq. 1) then
cc      lump=lumpmass
cc      ishift=0
cc      iprint=1
cc      mtot=20000000
cc      allocate( tempo3(mtot) )
c
c      r(mtot)=working array (in real*8) = tempo3(-)
c      iflag(1,2,3,4,5,6,7,8,9,10)=nrecord,loop_unroll,??,??,neig
c      =>print,lump,ishift,ncoeff2,??
c      nrecord=0,1,2,3=no reorder,metis,nd,mmid
c
cc      iflag(1)=0      ! 1,2,3 = metis,nd,mmid
cc      iflag(2)=1      ! level of unroll
cc      iflag(5)=neig
cc      iflag(6)=iprint
cc      iflag(7)=lump
cc      iflag(8)=nshift
c      iflag(9)=ncoeff2      ! as an output
c
cc      write(6,*) 'inside *cmei*.f: ndof,ncoeff1,neig,lump = '
cc      write(6,*)      ndof,ncoeff1,neig,lump
cc      write(6,*) 'inside *cmei*.f: ishift,mtot = '
cc      write(6,*)      ishift,mtot
cc      write(6,*) 'inside *cmei*.f: iflag(10) =',(iflag(i),i=1,10)
cc      write(6,*) 'inside *cmei*.f: ia(-) =',(ia(i),i=1,ndof+1)
cc      write(6,*) 'inside *cmei*.f: ja(-) =',(ja(i),i=1,ncoeff1)
cc      write(6,*) 'inside *cmei*.f: ad(-) =',(ad(i),i=1,ndof)
cc      write(6,*) 'inside *cmei*.f: an(-) =',(an(i),i=1,ncoeff1)
cc      write(6,*) 'inside *cmei*.f: dm(-) =',(dm(i),i=1,ndof)
c
ccc      if (lump .eq. 1) then
ccc      call eigsolver011(ndof,ncoeff1,neig,lump,ishift,
ccc      $mtot,ia,ja,ad,an,dm, evalues,evectors,tempo3,iflag,iperm)
ccc      elseif (lump .eq. 0) then
ccc      call eigsolver022(ndof,ncoeff1,neig,lump,ishift,
ccc      $mtot,ia,ja,ad,an,dm,an,evalues,evectors,tempo3,iflag,iperm)
ccc      endif
cc      deallocate( tempo3 )
cc      STOP
cc      endif

c      If(getstiff.eq.1)Then

c      goto 674
c      Endif

c.....sparse "symbolic" factorization
ncoeff2_gucss=1000
c      print *,'~~~~~Chk before allocate itempo1~~~~~'
c      pause
c      allocate ( itempo1(ncoeff2_gucss) )
c      print *,'ia before symfactd=',(ia(i),ic=1,12)
c      print *,'ja before symfactd=',(ja(i),ic=1,3)
c      print *,'++++ Chk before symfactd +++++'
c      print *,'getstiff=',getstiff
c      print *,'getforce=',getforce
c      print *,'getsolve=',getsolve
c      pause
c      print *,'ndof before symfactd=',ndof
c      pause
c      call symfactd(ndof,ia,ja,iu,itempo1,ip,ncoeff2)
c      call symfactd(ndof,ia2,ja,iu,itempo1,ip,ncoeff2)
c
c      print *,'*****passed symfactd*****'
c      print *,'after symfactd: IU(-) =',(iu(ic),ic=1,ndof+1)
c      pause
c      pause
c
c      write(6,*) 'passed symfactd'
c      stop
c      write(6,*) 'check point #03'
c
c      print *,'ncoeff2=',ncoeff2
c      print *,'NNNNNNNNNNNNNNNN ncoeff2 NNNNNNNNNNNNNNNNN'
c      pause
c      stop
c      allocate ( ju(ncoeff2) )
c      allocate ( jut(ncoeff2) )
c      allocate ( un(ncoeff2) )
c      print *,'itempo1 before copy_int=',(itempo1(ic),ic=1,28)
c      pause
c      print *,'chk 2 before copy_int'
c      call copy_int(ncoeff2,itempo1,ju)
c      subroutine copy_int(n,ianay,icopy)
c
c      print *,'passed copy_int'
c      print *,'getsolve=',1,getsolve
c      print *,'itempo1 after copy_int=',(itempo1(ic),ic=1,28)
c      print *,'ju after copy_int=',(ju(ic),ic=1,28)
c
c      pause
c      pause
c
c      print *,'***Passed copy_int***'
c      print *,'ad stiff after copy_int=',(ad(i),i=1,maxdofc**2)
c      print *,'an off-stiff after copy_int=',(an(ic),ic=1,3)
c      print *,'ae stiff after copy_int=',(ae(i),i=1,maxdofc**2)
c      pause
c      print *,'getsolve=',getsolve
c      If(getsolve.eq.1)then 'skip, deallocate
c      allocate (tempo1(10000) )
c
c      deallocate (itempo1)
c      print *,'chk after allocate'
c      goto 781
c      Endif
c      deallocate (itempo1)
781 continue
c      print *,'Chk after 781'
c
c.....transpose twice to put column numbers in order
c      call transad(ndof,ndof,iu,ju,iut,jut)
c      subroutine transad(n,m,ja,ia,iat,jat)
c
c      print *,'*** passed transa ***'
c      write(6,*) '*** passed transa ***'
c
c      print *,'iu after transad=',(iu(i),i=1,ndof+1)
c      write(6,*) 'ju after transad=',(ju(i),i=1,ndof+1)
c      pause
c      stop
c
c.....assuming to skip the "SUPER NODE" process (for unrolling purpose)
c      call supernode(ndof,isupn)
c
c      print *,'*** passed supernode ***'
c      stop
c
c.....sparse "numerical" factorization
c      print *,'ia2 before numfalld=',(ia2(i),i=1,ndof+1)
c      write(6,*) 'ia2 before numfalld=',(ia2(i),i=1,ndof+1)
c      stop
c      print *,'ndof before numfalld=',ndof
c      pause
c
c      print *,'getstiff before numfalld=',getstiff
c      print *,'chk before numfalld'
c      pause
674 If(getstiff .eq. 1)Then 'skip, only need stiff
c      Goto 793
c      Endif
c
c      call numfalld(ndof,ia,ja,ad,an,iu,
c      $ ju,di,un,ip,iup,
c      $ isupn,iopf,istep)
c      routine numfalld(n,ia,ja,ad,an,iu,ju,di,un,ip,iup,isupd,iopf)
c      call numfalld(ndof,ia2,ja,ad,an,iu,
c      $ ju,di,un,ip,iup,
c      $ isupn,iopf)
793 Continue 'dummy line
c      print *,'getstiff after numfalld=',getstiff
c      pause
c
c      If(getstiff .eq. 1)Then 'skip, only need stiff
c      Goto 675
c      Endif

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c          print *, "*** PASSED NUMFA1d ***"
c          pause
c          STOP
c       write(6,*) "*** passed numfa1d ***"
c.....sparse forward/backward solution phase

c          write(6,*)ndof before fbed=,ndof
c          write(6,*)b before fbed=,(b(i),i=1,ndof)
c          write(6,*)di before fbed=,(di(i),i=1,ndof)
c          write(6,*)iu before fbed=,(iu(i),i=1,ndof+1)
c          write(6,*)ju before fbed=,(ju(i),i=1,ncoe2)
c          write(6,*)un before fbed=,(un(i),i=1,ncoe2)
c          print *,ndof before fbed=,ndof
c          print *,b before fbed=,(b(i),i=1,ndof)
c          print *,di before fbed=,(di(i),i=1,ndof)
c          print *,iu before fbed=,(iu(i),i=1,ndof+1)
c          print *,ncoe2=,ncoe2
c          print *,ju before fbed=,(ju(i),i=1,ncoe2)
c          pause
c          print *,un before fbed=,(un(i),i=1,ncoe2)
c          stop

c       print *, '//////////'
c       print *, 'disp @ before fbed =',(disp(i),i=1,neq)
c       pause
c       print *, '//////////'
c       pause
c       print *, 'going to fbed'
c       pause
c       call fbed(ndof,iu,ju,di,un,b,
$         tempol,ioph,isupn,getsolve)

c.....tempol are displacements!
c       print *,tempol=,(tempol(i),i=1,neq)
c       print *, "*** passed fbed ***"
c       pause

c       write(6,*) "*** passed fbed ***"
c       .....
c       deallocate (jn)
c       deallocate (ju)
c       .....
c       stop

c       do 40 i=1,ndof
c         qk(i)=tempol(i)
c       40   disp(i)=tempol(i)
c       print *,tempol, disp =,tempol
c       print *,b =,(b(i),i=1,ndof)
c       print *,b after assembly getforce is 1 =,(b(i),i=1,20)
c***need to get support dof into "b"
c       b(8)=0.0
c       b(9)=0.0
c       b(10)=0.0
c       write(6,*)b end of syseqn =,(b(i),i=1,ndof)
c       print *,b end of syseqn =,(b(i),i=1,20)
c       stop
c       print *, '//////////'
c       print *, 'disp @ end of syseqn =',(disp(i),i=1,12)
c       pause
c       print *, '//////////'
c       pause
c       pause
c       pause
c       pause
c       pause
c       stop
c       if getforce .eq. 1)then
c         print *,disp and syseqn&getforce is 1 =,(disp(i),i=1,ndof)
c       stop
c       endif
c75 continue !blank line used when getstiff=1
c45 continue !blank line used to go if only getting internal forces
c793 continue! dummy,used to go if only get stiffness

c       return
c       end
c*****
c*** SUBROUTINE: RESID ***
c*****
c       subroutine resid(dqtot,dqi,dqim1,qk,b,exfor)
c       implicit real*8(a-h,o-z)
c       common/RIK/ stiff(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c       $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c       $ resk(50),scali(50),work1(50),mdx(50),neq
c       common/RIK/ stiff(20,20),dqim1(50),dqk(50),dqk1(50),
c       $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c       $ resk(50),scali(50),work1(50),mdx(50),neq
c       common/RIK/ stiff(60,60),dqk1(5000),
c       $ dqk2(5000),fintk(5000),
c       $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c       common/deltaqi/dqi(500)
c       common/av/a(1500),jg,fjgsm,np,nbw,np2,nbw2
c       common/testing/toldis,tolfor,exlk,iconv
c       dimension dqtot(*),dqim1(*),b(*),exfor(*),qk(*)
c       dimension exfor(neq),fintk(neq),resk(neq)
c       ccc print *,a inside resid=,a
c       print *,exlk inside resid=,exlk
c       print *,exfor inside resid=,(exfor(i),i=1,neq)
c       print *,b inside resid=,(b(i),i=1,neq)
c       print *,neq inside resid=,neq
c       stop
c       do 10 i=1,neq
c       resk(i) = exlk*exfor(i) - a(neq+i) !!!For 2D truss only

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resk(i) = exlk*exfor(i) - b(i)
c       print *,i=,i,exlk inside resid =,exlk
c       resk(i) = exlk*exfor(i) - fintk(i)
c       10 continue
ccc print *,exlk inside resid =,exlk
ccc print *,exfor(i) inside resid =,exfor
c       print *,resk(i) inside resid =,resk
c       print *,exlk inside resid =,exlk
c       print *,exfor(i) inside resid =,(exfor(i),i=1,neq)
c       print *,resk(i) inside resid =,(resk(i),i=1,neq)
c       pause
c       stop
c       stop
c       return
c       end
c*****
c*** SUBROUTINE: TEST ***
c*****
c       subroutine test(toldis,tolfor,exlk,iconv)
c       subroutine test(dqtot,dqim1,qk,exfor,b)
c       implicit real*8(a-h,o-z)
c       common/RIK/ stiff(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c       $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c       $ resk(50),scali(50),work1(50),indx(50),neq
c       common/RIK/ stiff(20,20),dqim1(50),dqk(50),dqk1(50),
c       $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c       $ resk(50),scali(50),work1(50),indx(50),neq
c       common/RIK/ stiff(60,60),dqk1(5000),
c       $ dqk2(5000),fintk(5000),
c       $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c       common/deltaqi/dqi(500)
c       common/testing/toldis,tolfor,exlk,iconv
c       dimension dqtot(*),dqim1(*),exfor(*),qk(*),b(*)
c       dimension dqk(5000)
c       dimension dqk(neq),qk(neq),exfor(neq),resk(neq),scali(neq)
c       ccc print *,exlk inside TEST=,exlk
c       print *,tolfor inside TEST=,tolfor
c       print *,dqtot inside TEST=,(dqtot(i),i=1,neq)
c       pause
c       print *,qk(i) inside resid =,(qk(i),i=1,neq)
c       pause
c       stop
c       iconv = 0
c       if (tolfor .lt. 1.d0) then
c       print *,tolfor =,tolfor
c       print *,goto unbalf
ccc print *,tolfor, exlk, iconv inside test =,tolfor,exlk,iconv
c       pause
c       stop
c       call unbalf(tolfor,exlk,iconv)
c       print *,exlk before unbalf =,exlk
c       stop
c       pause
c       print *,'chk before unbalf in test'
c       pause
c       call unbalf(dqtot,dqim1,qk,exfor,b)
c       end if
c       print *,toldis after unbalf =,toldis
c       stop
c       if (toldis .lt. 1.d0) then
c       print *,toldis =,toldis
c       print *,goto displ
c       STOP
c       call displ(toldis,iconv)
c       call displ(dqtot,dqk,dqim1,qk,b)
c       end if
c       return
c       end
c*****
c*** SUBROUTINE: UNBALF ***
c*****
c       subroutine unbalf(tolfor,exlk,iconv)
c       subroutine unbalf(dqtot,dqim1,qk,exfor,b)
c       implicit real*8(a-h,o-z)
c       common/RIK/ stiff(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c       $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c       $ resk(50),scali(50),work1(50),indx(50),neq
c       common/RIK/ stiff(20,20),dqim1(50),dqk(50),dqk1(50),
c       $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c       $ resk(50),scali(50),work1(50),mdx(50),neq
c       common/RIK/ stiff(60,60),dqk1(5000),
c       $ dqk2(5000),fintk(5000),
c       $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c       common/deltaqi/dqi(500)
c       common/testing/toldis,tolfor,exlk,iconv
c       dimension dqtot(*),dqim1(*),exfor(*),qk(*),b(*)
c       dimension exfor(neq),resk(neq),scali(neq)
c       print *,Start of "UNBALF"
c       print *,exlk inside UNBALF=,exlk
c       stop
c       unbf = 0.d0
c       unbfc = 0.d0

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c ... compute numerator of eqn. 4.133
c ... compute denominator of eqn. 4.133
c print *,scali(i) inside UNBALF="",(scali(i),i=1,neq)
c print *,resk(i) inside UNBALF="",(resk(i),i=1,neq)
c pause
c print *,'exfor(i) inside UNBALF="',(exfor(i),i=1,neq)
c stop
do 10 i=1,neq
  unbfi = unbfi + dabs(scali(i))*resk(i)**2
  unbfc = unbfc + dabs(scali(i))*exfor(i)**2
10 continue
c
c ... compute eqn. 4.133
c print *,'unbfi=',unbfi
c print *,'unbfc=',unbfc
c print *,'scali( )=',(scali(ic),ic=1,neq)
c print *,'exlk=',exlk
c delf = dsqrt(unbfi)/dsqrt(unbfc)/extk
c print *,'delf inside unbal =',delf
c pause
c stop
c
c ... test to see if delf is greater than tolf for
if (dabs(delf) .gt. tolf) then
  iconv = iconv + 100
end if
c print *,'iconv inside unbal =',iconv
c stop
c
c return
c end
c *****
c *** SUBROUTINE: DISPL ***
c *****
c subroutine displ(toldis,iconv)
c subroutine displ(dqtot,dqi,dqim1,qk,b)
c implicit real*8(a-h,o-z)
c common/RIK/ stifi(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(60,60),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c
c common/deltaq/dqi(500)
c
c common/testing/toldis,tolf,exlk,iconv
c common/av/a(1500),jgfgsm,np,nbw,np2,nbw2
c
c dimension dqtot(*),dqim1(*),qk(*),b(*)
c
c dimension dqk(5000)
c
c dimension dqk(neq),qk(neq)
c
c print *,'neq inside displ=',neq
c stop
c dqsq = 0.d0
c qsq = 0.d0
c
c ... compute deld using eqn. 4.132
do 10 i=1,neq
  dqsq = dqsq + dqk(i)**2
  dqsq = dqsq + dqk(i)**2
  qsq = qsq + qk(i)**2
  qsq = qsq + b(i)**2
  qsq = qsq + a(i)**2
10 continue
c print *,'dqsq inside displ =',dqsq
c print *,'qsq inside displ =',qsq
c stop
c deld = dsqrt(dqsq)/dsqrt(qsq)
c print *,'deld inside displ =',deld
c PAUSE
c stop
c
c ... test to see if deld is greater than toldis
if (deld .gt. toldis) then
  iconv = iconv + 10
end if
c print *,'iconv inside displ =',iconv
c stop
c
c return
c end
c *****
c *** SUBROUTINE: RESULT ***
c *****
c subroutine result(istep,it,dqtot,dqi,dqim1,qk,exfor,ad,
c $ strain,strainE,strainD)
c subroutine result(istep,it,dqtot,dqim1,qk,exfor,propsect,ad,
c $ strainE,strainE,strainD,weight,ncl,Anew,Fin1,
c $ xlie,weightTotal,Nevenodd,N)
c
c call result(istep,it,dqtot,dqi,dqim1,qk,exfor,ad,
c $ strainE,strainE,strainD)
c
c implicit real*8(a-h,o-z)
c common/RIK/ stifi(20,20),dqi(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stifi(60,60),dqk1(5000),
c $ dqk2(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c common/RIK/ stifi(60,60),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq
c common/deltaq/dqi(500)
c
c common/testing/toldis,tolf,exlk,iconv
c common/av/a(1500),jgfgsm,np,nbw,np2,nbw2
c
c dimension dqtot(*),dqim1(*),dqim1(*),exfor(*),qk(*),ad(*)
c
c dimension dqtot(*),dqim1(*),exfor(*),qk(*),ad(*)
c
c dimension dqk(5000)
c
c dimension strainE(*),strainE(*),strainD(*),weight(*)
c
c dimension propsect(*) !Area of members
c
c dimension SEDratio(100)
c
c dimension Anew(*),Fin1(*),xlief(*)
c
ccc common/disp/ux(2),uy(2),disp(500)
cccc print *,'ux(1) & ux(2) =',ux(1),ux(2)
c print *,'stop in result'
c stop
c dimension exfor(neq),qk(neq)
c
c if (istep .eq. 1) then
c c write(*,10)
c c write(*,20)
c c write(11,10)
c c write(11,20)
c c and if
c
c open(15,file='fea3d2_out.txt',status='unknown')
c open(21,file='Stiffout.txt',status='unknown')
c open(16,file='strainD.txt',status='new')
c open(17,file='strainE.txt',status='unknown')
c open(18,file='strainD.txt',status='unknown')
c open(19,file='resk.txt',status='unknown')
c open(19,file='Fin.txt',status='unknown')
c
c open(22,file='SEDratio.txt',status='unknown')
c open(25,file='AreaNew.txt',status='unknown')
c
c If(Nevenodd.eq.2)then ?N is now even number so print!
c If(N.eq.3)then
c
c print *,'Nevenodd=',Nevenodd
c
c open(20,file='displacement.txt',status='unknown')
c write(*,50) *,istep,exlk,qk(1),qk(2),it
c
c print *,'***** Inside Result *****'
c print *,istep=istep
c pause
c
c Do 51 i=1,neq
c xinternalforce = exlk * exfor(3)
c yinternalforce = exlk * exfor(4)
c caa appliedforce = exlk * exfor(5)
c arch appliedforce = exlk * exfor(62) !arch
c print *,'exlk=',exlk
c print *,'exfor(62)=',exfor(62)
c pause
c appliedforce = exlk * exfor(6)
c
c aforce=a(12)
c appliedforce = exlk * exfor(15)
c appliedforce = exlk * exfor(3)
c18 appliedforce = exlk * exfor(20)
c arch appliedforce = exlk * exfor(44)
c print *,'exlk inside result =',exlk
cccc print *,'exfor(12) inside result =',exfor(12)
ccc print *,'exfor(15) inside result =',exfor(15)
c print *,'exfor(3) inside result =',exfor(3)
c print *,'appliedforce inside result=',appliedforce
cc print *,'a(4) displacement =',a(4)
cc print *,'a(3) displacement =',a(3)
c pause
c stop
cccc write(*,50) *,istep,exlk,xinternalforce,yinternalforce,
cccc c a(3),a(4),it
ccc write(*,50) *,istep,exlk,xinternalforce,yinternalforce,
ccc c a(3),a(4),it
ccc write(*,50) *,istep,exlk,appliedforce,
ccc c a(3),a(4),it
c
c write(12,55) appliedforce
c55 format(f12.4)
c write(14,56) a(6)
c56 format(f12.4)
c write(15,50) *,istep,exlk,appliedforce,a(3),it
c50 format(a1,1x,i3,1x,f10.6,1x,f10.6,1x,f10.6,1x,f10.6,1x,f10.6,1x,
c c 1x,i3)
c50 format(a1,1x,i3,1x,f12.4,1x,f12.4,1x,f12.4,1x,f12.4,1x,f12.4,1x,
c c f12.4,1x,f12.4,1x,i3)
c below for T3
c50 format(a1,1x,i3,1x,f12.4,1x,f12.4,1x,f12.4,1x,f12.4,1x,f12.4,1x,
c c f12.4,1x,f12.4,1x,i3,1x,f12.4)
c below for T3x
ccc50 format(a1,1x,i5,1x,f12.4,1x,f16.0,1x,f12.4,1x,f12.4,1x,
ccc c f12.4,1x,f12.4,1x,f12.4,1x,f12.4,2x,i5)
c50 format(a1,1x,i3,1x,f10.6,1x,f12.4,1x,f10.6,1x,f10.6,1x,
c c f10.6,1x,f10.6,1x,f10.6,1x,f10.6,1x,i3)
c50 format(a1,1x,i3,1x,f10.6,1x,f10.6,1x,f10.6,1x,f10.6,1x,f10.6,
c c 1x,i3)
c print *,'check inside result'
c
c if(istep .eq. 1) then
c c write(12,55)
c55 format('Appliedforce')
c write(13,56)

```

```

c 56 format('Two ele Truss')

carch write(15,53)
carch 53 format(' istep exlk appliedforce dqtot(61)
carch $ dqtot(62) it')

c 53 format(' istep exlk appliedforce dqtot(4)
c $ dqtot(5) it')

c 53 format(' istep exlk appliedforce a(3) a(4)
c $a(5) a(6) it')
c 53 format(' istep exlk appliedforce a(1)
c $ a(2) a(3) a(4) a(5) a(6) it')

c write(*,53)
c 53 format(' istep exlk appliedforce a(3) a(4)
c $a(5) a(6) a(9) a(10) it')
c 53 format(' istep exlk appliedforce a(5) a(6)
c $ a(13) a(14) a(11) a(12) it')
c18 53 format(' istep exlk appliedforce a(15)
c18 $ a(16) a(17) a(18) a(19) a(20) it')
CCC 53 format(' istep exlk appliedforce a(19)
CCC $ a(20) a(41) a(42) a(43) a(44) it')
carch 53 format(' istep exlk appliedforce a(47)
carch $ a(48) a(39) a(40) a(43) a(44) it')
ccc 53 format(' istep exlk appliedforce a(10)
ccc $ a(11) a(12) it')
c 53 format(' istep exlk appliedforce a(13)
c $ a(14) a(15) it')
cc 53 format(' istep exlk appliedforce a(1)
cc $ a(2) a(3) it')
cdome 53 format(' istep exlk appliedforce a(6)
cdome $ a(9) a(3) it')
c 53 format(' istep exlk appliedforce a(3) a(4)
c $a(5) a(6) it')
cc below for T3
cc 53 format(' istep exlk appliedforce a(3) a(4)
cc $ a(5) a(6) it a(12)')
c below for T3x
cxxx 53 format(' istep exlk appliedforce a(3) a(4)
cxxx $ a(5) a(6) a(9) a(10) it')
c below for T3y
c 53 format(' istep exlk appliedforce a(1) a(2)
c $ a(3) a(4) it a(12)')
c 53 format(' istep exlk xinfo yinfo a(3) a(4)
c $ it')
c endif

c print *, 'check 2 inside result'
c write(15,50) '**,istep,exlk,appliedforce,
c c a(3),a(4),a(5),a(6),a(11),a(12),it
c Below IS FOR T3
c write(15,50) '**,istep,exlk,appliedforce,
c c a(3),a(4),a(5),a(6),it,a(12)
c write(15,50) '**,istep,exlk,appliedforce,
c c a(4),a(5),a(6),it
c6 write(15,50) '**,istep,exlk,appliedforce,
c6 c a(1),a(2),a(3),a(4),a(5),a(6),it

c Below IS FOR T3x
c write(15,50) '**,istep,exlk,appliedforce,
c c a(5),a(6),a(13),a(14),a(11),a(12),it
c18 write(15,50) '**,istep,exlk,appliedforce,
c18 c a(15),a(16),a(17),a(18),a(19),a(20),it
c18 50 format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,f10.4,
c18 c f10.4,6x,f10.4,f10.4,6x,i3)
CCC write(15,50) '**,istep,exlk,appliedforce,
CCC c a(19),a(20),a(41),a(42),a(43),a(44),it
carch write(15,50) '**,istep,exlk,appliedforce,
carch c a(39),a(40),a(47),a(48),a(43),a(44),it
carch 50 format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,3X,f10.4,
carch c f10.4,3x,f10.4,3X,f10.4,4x,i5)
cc print *,istep,exlk,appliedforce,
cc c a(10),a(11),a(12),it
ccc write(15,50) '**,istep,exlk,appliedforce,
ccc c a(10),a(11),a(12),it

c 50 format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,f10.4,
c c 6x,i3)
c6 50 format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,4x,f10.4,
c6 c f10.4,f10.4,f10.4,4x,i3)

c write(15,50) '**,istep,exlk,appliedforce,
c c a(13),a(14),a(15),it
cc write(15,50) '**,istep,exlk,appliedforce,
cc c a(1),a(2),a(3),it
caa write(15,50) '**,istep,exlk,appliedforce,
caa c dqtot(4),dqtot(5),it
c*****
c** "Khot_2ele_mod_in.dat"*****
cx weighttotal=0,d0
cx appliedforce = exlk * exfor(3)
cx appliedforce = exlk * exfor(5)
cx appliedforce = exlk * exfor(15)
cx Do 55 i=1,ncl
cx print *, 'istep=', istep
cx print *, 'i=', i
cx print *, 'weighttotal=', weighttotal
cx print *, 'weight(i)=', weight(i)
cx pause
cx weighttotal=weighttotal+weight(i)
cx55 Continue
cx print *, 'weighttotal final=', weighttotal
cx pause

cx if(istep.eq.1) then
cx write(15,53)
c 53 format(' istep exlk appliedforce a(1)
c $ a(2) a(5) it ad(3) ad(4)')

cx write(15,53)

cx53 format(' istep exlk appliedforce a(1)
cx $ a(2) a(3) it Weight Area')

c 53 format(' istep exlk appliedforce a(13)
c $ a(14) a(15) it Weight Area')

c write(15,53)
c 53 format(' istep exlk appliedforce a(5)
c $ Strain S_energy SE_density it resk(4)
c $ resk(5)')

c write(16,62)
c62 format('STRAIN')
c write(17,63)
c63 format('STRAIN ENERGY')
c write(18,64)
c64 format('STRAIN ENERGY DENSITY')
c write(19,65)
c65 format('Appliedforce')
c write(20,66)
c66 format('Displacement')

cx endif

c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(4),dqtot(5),it,weighttotal,propsect(1)
c50 format(a1,2x,i4,5x,c14.6,3x,e10.4,3X,e10.4,3X,e10.4,
c c 4x,i5,3x,e10.4,3x,e10.4)

c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(1),dqtot(2),dqtot(5),it,
c c ad(1),ad(2)
c50 format(a1,2x,i4,5x,c14.6,3x,e10.2,6x,e10.4,3X,e10.4,
c c 4x,i5,4x,e10.4,3x,e10.4)

c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(3),dqtot(4),dqtot(5),it,weighttotal
c 50 format(a1,1x,i4,1x,e14.6,1x,e10.2,2x,e10.4,2x,e10.4,1X,e10.4,
c c 1x,i5,1x,e10.4,1x,e10.4,1x,e10.4)

cx write(15,50) '**,istep,exlk,appliedforce,
cx c dqtot(1),dqtot(2),dqtot(3),it,weighttotal,propsect(1)
cx50 format(a1,1x,i4,1x,e14.6,1x,e10.2,2x,e10.4,2x,e10.4,1X,e10.4,
cx c 1x,i5,1x,e10.4,1x,e10.4,1x,e10.4)

c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(14),dqtot(15),it,weighttotal,propsect(1)
c50 format(a1,1x,i4,1x,e14.6,1x,e10.2,2x,e10.4,2x,e10.4,1X,e10.4,
c c 1x,i5,1x,e10.4,1x,e10.4,1x,e10.4)

c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(5),strain(1),strainE(1),strainD(1),it,
c c resk(4),resk(5)
c50 format(a1,2x,i4,5x,c14.6,3x,e10.2,6x,e10.4,
c c 3x,e12.6,3x,e12.6,3X,e12.6,4x,i5,
c c 2x,e12.6,2x,e12.6)

c write(16,72) strainel(1)
c72 format(e12.6)
c write(17,72) strainE(1)
c write(18,72) strainD(1)
c write(19,72) appliedforce
c write(20,72) dqtot(5)

c If(Nevenodd.eq.2)then !N is now even number so print!
c If(N.eq.3)then

c** "Khot_2ele_mod_in.dat"*****
appliedforce = exlk * exfor(5)
weighttotal=0,d0
Do 55 i=1,ncl
print *, 'istep=', istep
print *, 'i=', i
print *, 'weighttotal=', weighttotal
print *, 'weight(i)=', weight(i)
pause
cd SEDratio(i)=strainD(i)/weight(i)
weighttotal=weighttotal+weight(i)
55 Continue

if(istep.eq.1) then
write(15,63)N='N'
c 63 format(i4)
write(15,53)
53 format(' istep exlk appliedforce a(4)
$ a(5) it Weight Area1 Area2
$ xlic 1 xlic 2 finl N Nevenodd')
endif

c If(Nevenodd.eq.2.or.Nevenodd.eq.0)then

write(15,50) '**,istep,exlk,appliedforce,
c dqtot(4),dqtot(5),it,weighttotal,
c propsect(1),propsect(2),xlic(2),xlic(1),finl(1),N,
c Nevenodd

c endif

50 format(a1,2x,i4,6x,e14.6,2x,e10.2,4x,e10.4,4x,e10.4,
c 1x,i5,1x,e14.6,2x,e12.6,2x,e12.6,2x,e14.8,2X,e14.8,1x,e8.2,
c i4,2x,i4)

c** "Khot_4ele_mod_in_initial.dat"*****
cKhot4 appliedforce = exlk * exfor(15)
cKhot4 weighttotal=0,d0
cKhot4 Do 55 i=1,ncl
c print *, 'istep=', istep
c print *, 'i=', i
c print *, 'weighttotal=', weighttotal
c print *, 'weight(i)=', weight(i)
c pause
c** "Khot_4ele_mod_in_initial.dat"*****

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cd SEDratio(i)=strainD(i)/weight(i)
cKhot4 weighttotal=weighttotal+weight(i)
cKhot455 Continue

cKhot4 if(istep.eq.1) then
cKhot4 write(15,53)
cKhot4 53 format(' istep exlk appliedforce a(14)
cKhot4 $ a(15) it Weight Area1 Area2
cKhot4 $ Area3 Area4 xlie 1 xlie 2 fin1')
cKhot4 endif

cKhot4 write(15,50) '**,istep,exlk,appliedforce,
cKhot4 c dqtot(14),dqtot(15),it,weighttotal,
cKhot4 c propsct(1),propsct(2),propsct(3),propsct(4),
cKhot4 c xlie(1),xlief(2),fin1(1)

cKhot450 format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
cKhot4 c 1x,i5,1x,e14.8,2x,e12.6,2x,e12.6,2x,e12.6,2x,
cKhot4 c e14.8,2X,e14.8,1x,e8.2)

c**
"Dome2_opt_mod_in_initial.dat"*****
****
cdome appliedforce = exlk * cxf(3)
cdome weighttotal=0.d0
cdome Do 55 i=1,nel
c print *,istep=,istep
c print *,i=,i
c print *,weighttotal=,weighttotal
c print *,weight( )=,weight(i)
c pause
cd SEDratio(i)=strainD(i)/weight(i)
cdome weighttotal=weighttotal+weight(i)
cdome55 Continue

cdome if(istep.eq.1) then
cdome write(15,53)
cdome 53 format(' istep exlk appliedforce a(2)
cdome $ a(3) it Weight Area1 Area2
cdome $ Area3 Area4 xlie 1 xlie 2 fin1')
cdome endif

cdome write(15,50) '**,istep,exlk,appliedforce,
cdome c dqtot(2),dqtot(3),it,weighttotal,
cdome c propsct(1),propsct(2),propsct(3),propsct(4),
cdome c xlie(1),xlief(2),fin1(1)

cdome50 format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
cdome c 1x,i5,1x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,
cdome c e12.6,2X,e12.6,1x,e8.2)
c*****

c**
"Arch3d_opt_mod_in_initial.dat"*****
****
cArch3d appliedforce = exlk * cxf(65)
cArch3d weighttotal=0.d0
cArch3d Do 55 i=1,nel
c print *,istep=,istep
c print *,i=,i
c print *,weighttotal=,weighttotal
c print *,weight( )=,weight(i)
c pause
cd SEDratio(i)=strainD(i)/weight(i)
cArch3d weighttotal=weighttotal+weight(i)
cArch3d55 Continue

cArch3d if(istep.eq.1) then
cArch3d write(15,53)
cArch3d 53 format(' istep exlk appliedforce a(64)
cArch3d $ a(65) it Weight Area1 Area2
cArch3d $ Area3 Area4 xlie 50 xlie 51 fin1')
cArch3d endif

cArch3d write(15,50) '**,istep,exlk,appliedforce,
cArch3d c dqtot(64),dqtot(65),it,weighttotal,
cArch3d c propsct(1),propsct(2),propsct(3),propsct(4),
cArch3d c xlie(50),xlief(51),fin1(50)

cArch3d50 format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
cArch3d c 1x,i5,1x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,
cArch3d c e12.6,2X,e12.6,1x,e8.2)
c*****

c**
"Arch41_opt_mod_in_initial.dat"*****
****
cArch41 appliedforce = exlk * cxf(29)
cArch41 weighttotal=0.d0
cArch41 Do 55 i=1,nel
c print *,istep=,istep
c print *,i=,i
c print *,weighttotal=,weighttotal
c print *,weight( )=,weight(i)
c pause
cd SEDratio(i)=strainD(i)/weight(i)
cArch41 weighttotal=weighttotal+weight(i)
cArch4155 Continue

cArch41 if(istep.eq.1) then
cArch41 write(15,53)
cArch41 53 format(' istep exlk appliedforce a(26)
cArch41 $ a(29) it Weight Area1 Area2
cArch41 $ Area3 Area4 xlie 10 xlie 15 fin1')
cArch41 endif

cArch41 write(15,50) '**,istep,exlk,appliedforce,
cArch41 c dqtot(26),dqtot(29),it,weighttotal,
cArch41 c propsct(1),propsct(2),propsct(3),propsct(4),
cArch41 c xlie(10),xlief(15),fin1(20)

cArch4150 format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
cArch41 c 1x,i5,1x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,
cArch41 c e12.6,2X,e12.6,1x,e8.2)
c*****

c** "shallow_truss_initial.dat"*****
cshallow appliedforce = exlk * cxf(38)
cshallow weighttotal=0.d0
cshallow Do 55 i=1,nel
c print *,istep=,istep
c print *,i=,i
c print *,weighttotal=,weighttotal
c print *,weight( )=,weight(i)
c pause
cd SEDratio(i)=strainD(i)/weight(i)
cshallow weighttotal=weighttotal+weight(i)
cshallow55 Continue

cshallow if(istep.eq.1) then
cshallow write(15,53)
cshallow 53 format(' istep exlk appliedforce a(28)
cshallow $ a(38) it Weight Area1 Area2
cshallow $ Area3 Area4 xlie 10 xlie 15 fin1')
cshallow endif

cshallow write(15,50) '**,istep,exlk,appliedforce,
cshallow c dqtot(26),dqtot(29),it,weighttotal,
cshallow c propsct(1),propsct(2),propsct(3),propsct(4),
cshallow c xlie(16),xlief(20),fin1(20)

cshallow50 format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,
cshallow c 1x,i5,1x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,
cshallow c e12.6,2X,e12.6,1x,e8.2)
c*****

c*** frame ***
c** "frame_in.dat" & "frame_out.dat"*****
cf totald=sqrt(dqtot(1)**2+dqtot(2)**2) !total nodal displ.

cframe appliedforce = exlk * cxf(1)

cframe if(istep.eq.1) then
cframe write(15,53)
c 53 format(' istep exlk appliedforce dqtot(1)
c $ dqtot(2) dqtot(4) dqtot(5) it')
cframe 53 format(' istep exlk appliedforce dqtot(1)
cframe $ dqtot(2) dqtot(4) dqtot(5) it')

cframe endif

c write(15,50) '**,dqtot(1)

cframe write(15,50) '**,istep,exlk,appliedforce,
cframe c dqtot(1),dqtot(2),dqtot(4),dqtot(5),it
cframe 50 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,
cframe c e10.4,6x,e10.4,3X,i5)

c** Arch ***
c** "arch42_in.dat" & "arch42_3D_in.dat"*****
c appliedforce = exlk * cxf(11)
c if(istep.eq.1) then
c write(15,53)
c 53 format(' istep exlk appliedforce dqtot(11)
c $ it')
c endif
c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(11),it
c 50 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,4x,i5)

ccc write(15,50) exlk
ccc 50 format(c14.6)

ca 53 format(' istep exlk appliedforce dqtot(61)
ca $ dqtot(62) dqtot(64) dqtot(65) dqtot(85) dqtot(86)
ca $ it ad(61) ad(62)')
ca endif
ca write(15,50) '**,istep,exlk,appliedforce,
ca c dqtot(61),dqtot(62),dqtot(64),dqtot(65),dqtot(85),dqtot(86),it,
ca c ad(62),ad(65)
ca 50 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3X,e10.4,
ca c 3x,e10.4,3x,e10.4,3X,e10.4,4x,i5,4x,e10.4,3x,e10.4)

c*****
c** "t3a_in.dat" 3 member truss *****
c appliedforce = exlk * cxf(4)
c if(istep.eq.1) then
c write(15,53)
c 53 format(' istep exlk appliedforce dqtot(4)
c $ dqtot(5) dqtot(6) dqtot(7) dqtot(8) dqtot(9)
c $ it')
c endif
c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(61),dqtot(62),it
c 50 format(a1,2x,i3,5x,e10.6,3x,e10.6,6x,e10.8,6x,e12.8,
c c 6x,i3)
c endif
c write(15,50) '**,istep,exlk,appliedforce,
c c dqtot(61),dqtot(62),it
c 50 format(a1,2x,i3,5x,e10.6,3x,e10.6,6x,e10.8,6x,e12.8,
c c 6x,i3)
c** "Tripodin.dat using 3d element"*****
c appliedforce1 = exlk * cxf(10)

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```

c    appliedforce2 = exlk * exfor(12)
c    if(istep.eq. 1) then
c      write(15,53)
c 53 format(' istep    exlk    appliedforce    appliedforce2
c    a(10)    a(11)    a(12)    it')
c    endif
c    write(15,50) '**,istep,exlk,appliedforce1,appliedforce2,
c    c    dqdt(10),dqdt(11),dqdt(12),it
c 50 format(a1,2x,i4,5x,f10.6,3x,e10.3,3x,e10.4,6x,e10.4,6x,e10.4,6x,
c    c    e10.4,4x,i5)
c** "twobar_in.dat"*****
ctwo    appliedforce = exlk * exfor(7)
ctwo    if(istep.eq. 1) then
ctwo      write(15,53)
ctwo 53 format(' istep    exlk    appliedforce    a(5)
ctwo    $    a(7)    it    ad(5)    ad(7))
ctwo    endif
ctwo    write(15,50) '**,istep,exlk,appliedforce,
ctwo    c    dqdt(5),dqdt(7),it,
ctwo    c    ad(5),ad(7)
ctwo 50 format(a1,2x,i4,5x,e14.6,3x,e10.4,6x,e10.4,4x,e10.4
ctwo    c    4x,i5,4x,e10.4,3x,e10.4)
c*****
c** "snap4_in.dat"*****
csnap4    appliedforce = exlk * exfor(11)
csnap4    if(istep.eq. 1) then
csnap4      write(15,53)
csnap4 53 format(' istep    exlk    appliedforce    a(1)
csnap4    $    a(2)    a(11)    it    ad(3)    ad(4)')
csnap4    endif
csnap4    write(15,50) '**,istep,exlk,appliedforce,
csnap4    c    dqdt(1),dqdt(2),dqdt(11),it,
csnap4    c    ad(1),ad(2)
csnap4 50 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3x,e10.4,
csnap4    c    4x,i5,4x,e10.4,3x,e10.4)
c*****
c** "snap_in.dat"*****
csnap    appliedforce = exlk * exfor(11)
csnap    if(istep.eq. 1) then
csnap      write(15,53)
csnap 53 format(' istep    exlk    appliedforce    a(1)
csnap    $    a(2)    a(11)    it    ad(3)    ad(4)')
csnap    endif
csnap    write(15,50) '**,istep,exlk,appliedforce,
csnap    c    dqdt(1),dqdt(2),dqdt(11),it,
csnap    c    ad(1),ad(2)
csnap 50 format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3x,e10.4,
csnap    c    4x,i5,4x,e10.4,3x,e10.4)
c*****
c** "domain.dat"*****
cd    appliedforce = exlk * exfor(3)
cd    weighttotal=0.d0
cd    Do 55 i=1,nel
c      print *,istep=,istep
c      print *,i=i
c      print *,weighttotal=,weighttotal
c      print *,weight(i)=,weight(i)
c      pause
cd    SEDratio(i)=strainD(i)/weight(i)
cd    weighttotal=weighttotal+weight(i)
cd 55    Continue

cd    if(istep.eq. 1) then
cd      write(15,53)
c 53 format(' istep    exlk    appliedforce    a(1)
c    $    a(2)    a(3)    a(4)    a(5)    a(6)
c    $    it    ad(3)    ad(4)')
cd    write(15,53)
cd 53 format(' istep    exlk    appliedforce    a(1)
cd    $    a(2)    a(3)    it    Weight    Area1    Area2
cd    $    Area3    Area4')

cd    write(22,60)
cd 60    format('SDratio(1) SDratio(2) SDratio(3) SDratio(4)
cd    $ SDratio(5) SDratio(6) SDratio(7) SDratio(8) SDratio(9)
cd    $ SDratio(10) SDratio(11) SDratio(12) SDratio(13)
cd    $ SDratio(14) SDratio(15)')

cd    write(22,58) SEDratio(1),SEDratio(2),SEDratio(3),SEDratio(4),
cd    $ SEDratio(5),SEDratio(6),SEDratio(7),SEDratio(8),SEDratio(9),
cd    $ SEDratio(10),SEDratio(11),SEDratio(12),SEDratio(13),
cd    $ SEDratio(14),SEDratio(15)

c    write(18,59)
c 59    format('strainD(1) strainD(2) strainD(3) strainD(4)
c    $ strainD(5) strainD(6) strainD(7) strainD(8) strainD(9)
c    $ strainD(10) strainD(11) strainD(12) strainD(13) strainD(14)
c    $ strainD(15)')

c    write(18,58) strainD(1),strainD(2),strainD(3),strainD(4),
c    $ strainD(5),strainD(6),strainD(7),strainD(8),strainD(9),strainD(10)
c    $ strainD(11),strainD(12),strainD(13),strainD(14),strainD(15)

cd 58    format('e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,
cd    $ e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,
cd    $ 2x,e10.2,2x,e10.2)

cd    write(21,54)
cd 54 format(' istep    exlk    ad(1)    ad(2)    ad(3)
cd    $    ad(4)    ad(5)    ad(6)    ad(7)    ad(8)
cd    $    ad(9)    ad(10)    ad(11)    ad(12)    ad(13)
cd    $    ad(14)    ad(15)    resk(1)    resk(2)    resk(3)')

cd    write(21,56) istep,exlk,ad(1),ad(2),ad(3),ad(4),ad(5),ad(6),
cd    $ ad(7),ad(8),ad(9),ad(10),ad(11),ad(12),ad(13),ad(14),
cd    $ ad(15),resk(1),resk(2),resk(3)
cd 56    format('14,2x,e14.6,2x,e10.2,2x,e10.2,2x,e10.2,2x,
cd    $ e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,
cd    $ e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,
cd    $ e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2,2x,e10.2)

cd    write(25,68) istep,exlk,Anew(1),Anew(7),Anew(13),Anew(14)
cd 68    format('i4,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6)

cd    endif

cd    write(15,50) '**,istep,exlk,appliedforce,
cd    c    dqdt(1),dqdt(2),dqdt(3),it,weighttotal,
cd    c    prospect(1),prospect(2),prospect(3),prospect(4)

cd 50    format(a1,2x,i4,2x,e14.6,4x,e10.2,4x,e10.4,4x,e10.4,4x,e10.2,
cd    c    2x,i5,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4)

c      print *,resk(3) inside result=,resk(3)
c      pause

cd    write(22,58) SEDratio(1),SEDratio(2),SEDratio(3),SEDratio(4),
cd    $ SEDratio(5),SEDratio(6),SEDratio(7),SEDratio(8),SEDratio(9),
cd    $ SEDratio(10),SEDratio(11),SEDratio(12),SEDratio(13),
cd    $ SEDratio(14),SEDratio(15)

c    write(19,57) resk(1),resk(2),resk(3),resk(4),
c    $ resk(5),resk(6),resk(7),resk(8),resk(9),resk(10)
c    $ resk(11),resk(12),resk(13),resk(14),resk(15)

cd    write(19,57) Fin(1),Fin(2),Fin(3),Fin(4),
cd    $ Fin(5),Fin(6),Fin(7),Fin(8),Fin(9),Fin(10)
cd    $ Fin(11),Fin(12),Fin(13),Fin(14),Fin(15)

cd    write(17,57) strainE(1),strainE(2),strainE(3),strainE(4),
cd    $ strainE(5),strainE(6),strainE(7),strainE(8),strainE(9),strainE(10)
cd    $ strainE(11),strainE(12),strainE(13),strainE(14),strainE(15)

c    write(16,57) strainD(1),strainD(2),strainD(3),strainD(4),
c    $ strainD(5),strainD(6),strainD(7),strainD(8),strainD(9),strainD(10)
c    $ strainD(11),strainD(12),strainD(13),strainD(14),strainD(15)

cd 57    format('e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,
cd    $ e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,
cd    $ 2x,e10.4,2x,e10.4)

cc      if(istep.eq. 7920)then
c      if(istep.eq. 7420)then

cd    write(18,67) exlk,strainD(1),strainD(2),strainD(3),strainD(4),
cd    $ strainD(5),strainD(6),strainD(7),strainD(8),strainD(9),strainD(10)
cd    $ strainD(11),strainD(12),strainD(13),strainD(14),strainD(15)
cd 67    format('e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,
cd    $ e10.4,2x,
cd    $ e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,2x,e10.4,
cd    $ 2x,e10.4,2x,e10.4)

c    write(25,68) istep,exlk,Anew(1),Anew(7),Anew(13),Anew(14)
c 68    format('i4,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6,2x,e12.6)

cc      Endif

cdome    write(15,50) '**,istep,exlk,appliedforce,
cdome    c    dqdt(1),dqdt(2),dqdt(3),dqdt(4),dqdt(5),dqdt(6),it,
cdome    c    ad(3),ad(4)
cdome 50    format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3x,e10.4,
c*****
c** "truss7_3d_in.dat using 3d element"*****
C** "truss11_3d_in.dat using 3d element"*****
ctruss    appliedforce = exlk * exfor(8)
ctruss    if(istep.eq. 1) then
ctruss      write(15,53)
ctruss 53 format(' istep    exlk    appliedforce    a(1)
ctruss    $    a(2)    a(4)    a(5)    a(7)    a(8)
ctruss    $    it')
ctruss    endif
ctruss    write(15,50) '**,istep,exlk,appliedforce,
ctruss    c    dqdt(1),dqdt(2),dqdt(4),dqdt(5),dqdt(7),dqdt(8),it
ctruss 50    format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,3x,f10.4,
ctruss    c    f10.4,3x, f10.4,3x f10.4,4x,i5)

c    write(15,50) '**,istep,exlk,appliedforce,
c    c    a(6),a(9),a(3),it
c 50    format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,
c    c    6x,i3)
cc 50    format(a1,2x,i3,5x,f10.6,3x,f10.2,6x,f10.4,6x,f10.4,f10.4,
cc    c    6x,i3)
c    print *,'check 3 inside result'
c    write(*,50) '**,istep,exlk,appliedforce,
c    c    a(3),a(4),a(5),a(6),a(13),a(14),it
c    Below IS FOR T3y
c    write(15,50) '**,istep,exlk,appliedforce,
c    c    a(1),a(2),a(3),a(4),a(12)
c    write(15,50) '**,istep,exlk,xinternalforce,yinternalforce,
c    c    a(3),a(4),it

c    stop
ccc    write(12,51) xinternalforce,yinternalforce
ccc 51    format('f12.2,1x,f12.2)
c    write(12,51) appliedforce
c 51    format('f12.2)

c    write(13,52) a(3)
cc    write(13,52) a(5)
c 18    write(13,52) a(20)
carch    write(13,52) a(44)
cc 52    format('f10.6)

c 51    continue
c
cc 10    format('5,'Load',t13,'Load',
cc    $    c28,'External',t62,'No. of')
cc 20    format('5,'Step',t13,'Multiplier',

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cc $ t28,'Load',i45,'Displacement',
cc $ 162,'Iter.')
cc 30 format(i5,i3,i13,i10,6,i28,i10,6,i45,i12,6,i62,i3)
c
c print *,'end of result'
c pause
c stop

c Endif

return
end

C*****
C*** SUBROUTINE: ITNRML ***
C*****
c subroutine itnrm1(itemax,toldis,tolfor,dli,dlim1,
c $ exlk,iconv,iflag,it,ne,iplvl)
c subroutine itnrm1(itemax,dli,dlim1,b,exfor,ad,nctype,qk,
c $ iflag,it,ne,iplvl,ndof,ia,ncl,ncoef1,jeall,
c $ ijeall,ie,je,iet,iet, maxdofpe,dqtot,dqi,dqim1,
c $ ja,an,propmat,propsect,x,y,z,ndofpn,numnodes,
c $ ip,iu,disp,ianal,ndofpe,iskip,itimepo2,iarc,lm,
c $ itnrm1on,iboundc,esm,clk)
c $ itnrm1on,iboundc,ae,di,istep,iarea,
c $ strainel,strainE,strainD,weight,iopt,Anew,Apart,Fin1,
c $ Fin2,VED,VEDold,xlie,exlkdl0,exlkdl1,exlkdlk,exlk)
c use

implicit real*8(a-h,o-z)
c common/RIK/ stiff(20,20),dqk(500),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stiff(20,20),dqim1(50),dqk(50),dqk1(50),
c $ dqk2(50),dqtot(50),exfor(50),qk(50),fintk(50),
c $ resk(50),scali(50),work1(50),indx(50),neq
c common/RIK/ stiff(60,60),dqk1(5000),
c $ dqk2(5000),fintk(5000),
c $ resk(5000),scali(5000),work1(5000),indx(5000),neq

c common/deltaqi/dqi(500)

common/av/a(1500),jg,fjgsm,np,nbw,np2,nbw2
common/disp/ux(2),uy(2),uz(2)
common/mfor/getforce,fmx(2),fmy(2),finz(2),getstiff,getsolve
common/zvector/za1(1500),za2(1500),za3(1500),ipick
common/testing/toldis,tolfor,exlk,iconv

dimension iet(*),iet(*),iet(*),h(*),exfor(*),nel(*)
c dimension dqtot(*),dqi(*),dqim1(*),ad(*),qk(*)
c dimension dqtot(*),dqim1(*),qk(*),ad(*)
c dimension dqtot(*),dqim1(*),ad(*),qk(*)
c dimension ja(*),an(*),disp(*)
c dimension an(*),disp(*)
c dimension propmat(1),propsect(1),x(*),y(*),ip(*),iu(*)
dimension itempo2(*),lm(1),ae(1)
c dimension iboundc(*),iarea(1)

c dimension dqk(5000),dqk(5000)
c dimension strainel(*),strainE(*),strainD(*),weight(*),Anew(*),
c $ Apart(*),Fin1(*),Fin2(*),VED(*),VEDold(*),xlie(*)

c dimension itempo2(*),lm(1), clk(maxdofpe,maxdofpe)

c dimension stiff(neq,neq),dqk(neq),dqim1(neq),dqk(neq),
c $ dqk1(neq),dqk2(neq),exfor(neq),fintk(neq),qk(neq),
c $ resk(neq),scali(neq),work1(neq)

c deallocate (ja)

itnrm1on=1 !Let everyone know we are going thru "itnrm1"
c "sysqcn" "&" "assembly" need to do something more

c print *, '!!!!!!!!!!!!!! starting itnrm1 !!!!!!!!!!!!!!!'
c pause
c print *, 'itimepo2(1) inside itnrm1=',itimepo2(1)
c pause

c print *, 'ad stiff=',(ad(i),i=1,maxdofpe**2)
c pause

c print *, 'ipick =',ipick
c print *, 'istep=',istep
c print *, 'it=',it
c print *, 'getforce =',getforce
c print *, 'getstiff =',getstiff
c print *, 'qk(-) start of itnrm1=',(qk(i),i=1,ndof)
c print *, 'b start of itnrm1=',(b(i),i=1,ndof)
c print *, 'ad( ) start itnrm1=',(ad(ic),ic=1,ndof)
c print *, 'an( ) start itnrm1=',(an(ic),ic=1,50)
c pause

c stop
c print *, 'a at start of itnrm1 =',a
c print *, 'exlk at start of itnrm1 =',exlk
c print *, 'dqi at start of itnrm1 =',(dqi(i),i=1,ndof)
c print *, 'exfor at start of itnrm1 =',(exfor(i),i=1,ndof)
c pause

c stop
c dlk = 0.00
c dli = 0.00
c iconv = 1
c iflag = 0
c it = 0

c do 20 i=1,neq
c do 10 j=1,neq
c stiff(j,i) = 0.00
c 10 continue

c print *, 'exfor(i) start =',exfor(i)
c dqk(i) = 0.00
c dqk1(i) = 0.00
c dqk2(i) = 0.00
c fintk(i) = 0.00
c work1(i) = 0.00
c print *, 'exfor(i) end =',exfor(i)
c 20 continue
c** set counter equal to zero for next "it"
iam = 0
c print *, 'exfor =',exfor
c stop
c print *, 'iconv =',iconv
c print *, 'itemax =',itemax
c print *, 'it =',it
c pause
c+++++
c+++++
1002 if (iconv .ne. 0 .and. it .le. itemax) then
c print *, 'iconv =',iconv
c Print *, 'it =',it
c print *, 'itemax =',itemax
c stop
c it = it + 1
c write(*,*) 'Beginning Iteration Number:',it
c stop
c... compute Kik for eqn. 4.97
cc print *, 'ne & iplvl inside itnrm1 =',ne,iplvl
cc print *, 'qk inside itnrm1=',qk
c pause
c stop
c Getforce=1
c**Only get stiffness
c Getsolve=0
c Getforce=0
c Getstiff=1
c print *, 'exfor =',exfor
c print *, 'chk before sysqcn inside itnrm1'
c write(6,*) 'chk before sysqcn inside itnrm1'
c stop

c deallocate (ja)
c deallocate (itimepo1)
c deallocate (an)
c print *, '***** [skip in itnrm1] *****'
c print *, '***** [skip in itnrm1] *****'
c pause
c print *, 'iskip in itnrm1 before 1st sysqcn=',iskip
c pause
c print *, 'iskip in itnrm1 before 1st sysqcn=',iskip
c pause
c print *, 'iskip in itnrm1 before 1st sysqcn=',iskip
c pause
c print *, 'iskip in itnrm1 before 1st sysqcn=',iskip
c pause
c print *, 'getforce in itnrm1 before 1st sysqcn=',getforce
c print *, 'getstiff in itnrm1 before 1st sysqcn=',getstiff
c pause
c print *, '*****'
c print *, '*****'
c print *, 'disp before 1st sysqcn in itnrm1=',(disp(i),i=1,ndof)
c print *, '*****'
c print *, '*****'
c print *, '*****'
c pause
c print *, 'ad stiff before=',(ad(i),i=1,ndof)
c pause
c print *, 'an stiff=',(an(i),i=1,maxdofpe**2)
c print *, 'ae( ) before 1st sysqcn in itnrm1=',(ae(ic),ic=1,18)
c print *, 'b( ) before=',(b(ic),ic=1,ndof)
c pause
c print *, 'exfor( ) =',(exfor(ic),ic=1,ndof)
c pause
c pause
c call sysqcn(ne,iplvl,b,ndof,disp,iarc,qk,
c $ ical,ie,je,iet,jeall,ia,ae,maxdofpe,
c $ nctype,ncl,ndofpe,x,y,z,propmat,propsect,lm,
c $ iboundc,ad,an,iperm,iu,ip,iu,dqtot,dqi,dqim1,
c $ ux,uy,uz,di,ie,arcs,youngm,iarea,
c $ ianal,lumpmass,iskip,itimepo2,itnrm1on,exfor,istep,
c $ jallo,
c $ strainel,strainE,strainD,weight,iopt,Anew,Apart,Fin1,
c $ Fin2,VED,VEDold,xlie,SED)

c $ja,iboundc,ndofpcd,be,lm,ndofpcd,ad,ip,tempo1,dm,am,ianal,lumpmass)
c print *, 'dqk1 after sysqcn in itnrm1=',dqk1
c print *, '*****'
c print *, '*****'
c print *, 'disp after 1st sysqcn in itnrm1=',(disp(i),i=1,ndof)
c pause
c print *, 'b after 1st sysqcn in itnrm1=',(b(i),i=1,ndof)
c pause
c print *, 'ad stiff after 1st sysqcn=',(ad(i),i=1,ndof)
c pause
c print *, 'an( ) after 1st sysqcn in itnrm1=',(an(ic),ic=1,50)
c print *, 'ac stiff after 1st sysqcn=',(ae(ic),i=1,maxdofpe**2)
c print *, '*****'
c print *, '*****'
c pause
c print *, 'exfor( ) =',(exfor(ic),ic=1,ndof)
c pause

c If it .eq. 2) then
c print *, 'it =',it
c print *, 'disp after 1st sysqcn in itnrm1=',(disp(ic),ic=1,ndof)
c print *, 'b( ) after 1st sysqcn in itnrm1=',(b(ic),ic=1,ndof)
c print *, 'ad stiff after 1st sysqcn=',(ad(ic),ic=1,maxdofpe**2)
c print *, 'an( ) after 1st sysqcn in itnrm1=',(an(ic),ic=1,50)
c stop
c endif

```



```

c      stop
c      call ludcmp(stifi,n,np,indx,X)
cc c      print *, 'n after ludcmp = ',n
c      stop
c      call lubksb(stifi,n,np,indx,dqk1)
c      print *, 'np=',np
c      print *, 'n eq=',n eq
c      pause
c      do 12 i=1,np
c      do 12 i=1,n eq
12      indx(i)=0

c** Now do the same for dqk2

c      call solve(dqk2)

c put dqk2(i) into big "a(i) as a force, get out as displacement"
c      j=0
cc      print *, 'n eq, n eq2, np2 = ',n eq,n eq2,np2
c      stop
c*****
c      If (ityp .eq. 6) then
c      do 32 i=1,n eq
c      j=j+1
c      a(i)=dqk2(j)      b(i)=dqk2(i)
cc      print *, 'a(i) = ',a(i)
c      print *, 'dqk2(i) = ',dqk2(i)
32      continue
c      print *, '##### After 3rd Sysseqn inside itmml #####'
c      pause
c      If (istep .gt. 900) Then
c      print *, 'dqk2( ) inside itmml=',(dqk2(ic),ic=1,n dof)
c      print *, 'b( ) inside itmml=',(b(ic),ic=1,n dof)
c      pause
c      Endif
c      write(6,*) 'dqk2( ) inside itmml=',(dqk2(ic),ic=1,n dof)
c      Endif
c      If (ityp .eq. 12) then
c      do 33 i=n eq+1,n eq*3
c      j=j+1
c      a(i)=dqk2(j)
cc      print *, 'a(i) = ',a(i)
c      print *, 'dqk2(j) = ',dqk2(j)
c 33      continue
c      Endif
c*****
c      stop
cc      write(*,*) 'Before dcmprbd inside itmml 2nd time'
c      stop
c      ipick = 2
c*****

* Not sure if "a" is getting rewritten and used properly????

c*****
cc      print *, 'a before dcmprbd = ',a
c      print *, 'dq before dcmprbd = ',dq
c      print *, 'dqk1( ) inside itmml =',(dqk1(ic),ic=1,n dof)
c      pause
c      call dcmprbd
c      stop
c      write(*,*) 'After dcmprbd inside itmml 2nd time'
cc      call slvbd
c      write(*,*) 'After slvbd & ipick=2 inside itmml 2nd time'
c      print *, '##### END SYSEQN 3 #####'
c... I only want to solve, I don't want update forces or stiff
c      getforce=0
c      getstiff=0
c      getsolve=1
c      print *, 'getsolve=1 inside itmml before 3rd sysseqn'
c      pause
c      print *, 'b(i) before new 3rd sysseqn=',(b(ic),ic=1,n dof)
c      pause
c      print *, 'ad before 3rd sysseqn solve=',(ad(i),i=1,maxdofpe**2)
c      pause
c      print *, 'disp( ) before 3rd sysseqn solve only=',(disp(ic),ic=1,n dof)
c      pause
c... Need to solve eqns only, no new loads or stiff!
c      call sysseqn(ne,iplvl,b,ndof,disp,lar,c,qk,
$      icall,ic,jc,ic,jc,icall,ia,ae,maxdofpe,
$      nctype,nel,ndofpe,x,y,z,propmat,propsect,lm,
$      iboundc,ad,an,iperm,an,ip,int,dqtot,dqi,dqim1,
$      ux,uy,uz,di,area,young,m,lar,c,
$      ialal,lumpmass,iskop,itemp02,itmmlon,exfor,istep,
$      jallo,
$      straincl,strainE,strainD,weight,iop1,Anew,Aparr,Fin1,
$      Fin2,VED,VEDold,xlie,SED)
c      print *, '##### END SYSEQN 3 #####'
c      pause
c      print *, 'n eq=',n eq
c      print *, 'b(i) after new 3rd sysseqn=',(b(ic),ic=1,n dof)
c      pause
c      print *, 'ad after 3rd sysseqn solve=',(ad(i),i=1,maxdofpe**2)
c      pause
c      print *, 'an after 2nd sysseqn solve=',(an(i),i=1,50)
c      stop
c      If (i .eq. 2) then
c      print *, 'it = ',it
c      print *, 'disp after 3rd sysseqn in itmml=',(disp(ic),ic=1,n dof)
c      print *, 'b( ) after 3rd sysseqn in itmml=',(b(ic),ic=1,n dof)
c      print *, 'ad stiff after 3rd sysseqn=',(ad(ic),ic=1,maxdofpe**2)
c      print *, 'an( ) after 3rd sysseqn in itmml=',(an(ic),ic=1,50)
c      stop
c      endif
c      print *, 'disp( ) after 3rd sysseqn solve only=',(disp(ic),ic=1,n dof)
c      pause
c** set "dqk1" equal to the solution displ stored in "a"
c      DO 179 LL=1,n eq
cc      dqk2(LL) = a(LL)
c      dqk2(LL) = disp(LL)
c      print *, 'dqk2 = ',dqk2(LL)
179      continue
cc      print *, 'a after slvbd = ',a
c      print *, 'dqk1 = ',dqk1
c      print *, 'dqk2 = ',dqk2
c      pause
c      stop
c      call stiff
cccc      call sysseqn(ne,iplvl)
c      stop
c      do 13 i=1,np
13      indx(i)=0
c... compute dlk using eqn. 4.101
c      dprdl = 0.d0
c      dprdl2 = 0.d0
c      do 40 i=1,n eq
c      print *, 'dq( ) dqk1( ) dqk2( ) = ',dq(i),dqk1(i),dqk2(i)
c      dprdl = dprdl + dq(i)*dqk2(i)
c      dprdl2 = dprdl + dq(i)*dqk1(i)
c      If (istep .eq. 1) Then
c      dprdl = 0.d0
c      endif
40      continue
c      print *, 'dprdl inside itmml=',dprdl
c      print *, 'dprdl2 inside itmml=',dprdl2
c      If (istep .eq. 1) Then
c      print *, 'dq(i) = ',dq(i)
c      print *, 'istep = ',istep
c      print *, 'dq(i) =',(dq(i),ic=1,n dof)
c      print *, 'dqk1(i) =',(dqk1(ic),ic=1,n dof)
c      print *, 'dqk2(i) =',(dqk2(ic),ic=1,n dof)
c      print *, 'dprdl = ',dprdl
c      print *, 'dprdl2 = ',dprdl2
c      print *, 'ad( ) =',(ad(ic),ic=1,n dof)
c      pause
c      Endif
c      Testv2=dlk*(dprdl2+dlm1)
c      print *, 'istep = ',istep
c      print *, 'Testv2 = ',testv2
c      pause
c      If (Testv2.lt.-1.6e-5) Then
c      dli=-1.*dli
c      Else
c      dli=1.*dli
c      Endif
c      If (dprdl .lt. 0.0 .and. dprdl2 .lt. 0.0) Then
c      If (dprdl .gt. -.00001 .and. dprdl2 .gt. -.1) Then
c      dli=-1.*dli
c      Endif
c      Else
c      dli=1.*dli
c      Endif
c      print *, 'dprdl = ',dprdl
c      print *, 'dprdl2 inside itmml = ',dprdl2
c      pause
cc      print *, 'dli inside itmml = ',dli
c      stop
c      stop
c      dlk = (dprdl)/(dprdl2 + dli)
c      print *, 'dlk inside itmml = ',dlk
c      stop
c... update the external load multiplier exlk
c      print *, 'exlk before = ',exlk
c      If (istep .gt. 561) then
c      dlk = -1.d0*dlk
c      Endif
c      If (exlk .GT. .98) then
c      print *, 'after exlk 3 chk'
c      print *, 'resk( ) =',(resk(ic),ic=1,n eq)
c      pause
c      endif
c      If (exlk .LT. exlk-dlk) then
c      exlkdlk=exlk-dlk
c      exlk=3
c      print *, 'After 3rd exlk check'
c      print *, 'exlk = ',exlk
c      print *, 'exlk-dlk = ',exlkdlk
c      print *, 'ad(i) after exlk =',(ad(i),i=1,n dof)
c      print *, 'resk( ) =',(resk(ic),ic=1,n eq)
c      pause
c      deallocate (dqtot)
c      deallocate (dq)
c      deallocate (dqim1)

```

```

c      pause
c      GOTO 7000

c      STOP
c      ENDIF

c      If(istep.eq.1)then
c      print *, 'istep = 1'
c      print *, 'exlk=', exlk
c      print *, 'dlk=', dlk
c      pause
c      Endif

c      exlk = exlk - dlk

c      print *, 'exlk=', exlk
c      pause

c      If(istep.eq.561)then
c      exlk = -1.d0*exlk
c      Endif

c      print *, '1st exlk in itmml = ', exlk
c      pause
c      print *, 'dlk in itmml=', dlk
c      pause
c      write(6,*) '1st exlk in itmml = ', exlk
c      write(6,*) 'dlk in itmml=', dlk
c      stop

ccc      pause

c      stop
c      ... update dlim1 for next load step
c      dlim1 = dlim1 - dlk
c      stop
c      ... compute dqk using eqn. 4.94
c      ... update dqim1 for next load step
c      ... update the total displacements using eqn. 4.103
c      print *, 'neq = ', neq
c      stop
c      do 50 i=1, neq
c      If(istep.eq.914)Then
c      dqk(i) = dqk2(i) + dlk*dqk1(i)
c      Else
c      dqk(i) = dqk2(i) - dlk*dqk1(i)
c      Endif
c      If(dqk(11).lt.0)Then
c      print *, 'istep=', istep
c      print *, 'dqk(11)=', dqk(11)
c      pause
c      Endif
c      stop
c      dlim1(i) = dlim1(i) + dqk(i)
c      dqim1(i) = dqim1(i) + dqk(i)
c      print *, 'dqim1(i) & i = ', dqim1(i), i
c      print *, 'qk(11) before=', qk(11)
c      qk(i) = qk(i) + dqk(i) !Update Total Displacements
c      print *, 'qk(11) after=', qk(11)
50      continue

c      print *, 'istep=', istep
c      print *, 'dqk(11)=', dqk(11)
c      print *, 'qk(11)=', qk(11)
c      pause

c      If(istep.gt.900)Then
c      print *, 'istep=', istep
c      print *, 'dq( )=', (dq(i), ic=1, neq)
c      print *, 'dqk( )=', (dqk(i), ic=1, neq)
c      print *, 'qk( )=', (qk(i), ic=1, neq)
c      print *, 'dli( )=', (dli(i), ic=1, neq)
c      print *, 'dlk( )=', (dlk(i), ic=1, neq)
c      print *, 'ad( )=', (ad(i), ic=1, neq)
c      pause
c      endif
c      Do 5050 ii=1, neq
c      dqim1(ii) = dqim1(ii) + dqk(ii)
5050      continue
cc      If(istep.gt.911)Then
c      If(istep.gt.136)Then
cc      print *, 'istep=', istep
cc      print *, 'dqk1(i)=', (dqk1(i), ic=1, neq)
cc      print *, 'dlk=', dlk
cc      print *, 'dqk2(i)=', (dqk2(i), ic=1, neq)
cc      print *, 'dqk(i)=', (dqk(i), ic=1, neq)
cc      print *, 'qk(i)=', (qk(i), ic=1, neq)
cc      print *, 'ad(i)=', (ad(i), ic=1, neq)
cc      pause
cc      Endif
cc      write(6,*) 'qk(i)=', (qk(i), i=1, neq)
c      print *, 'qk(i)=', (qk(i), ic=1, neq)
c      pause
c      stop

c      print *, 'exlk =', exlk
cc      print *, 'dlim1 =', dlim1
cc      print *, 'dqk =', dqk
cc      print *, 'qk =', qk
cc      print *, 'dqim1(i)=', dqim1
c      ... compute the internal forces, fintk, at qk
c      call forces

c      print *, 'Check inside itmml before sysqn'
c      stop
c      put qk(i) into big "a(i) as a disp, get out fintk"
c      j=0
cc      print *, 'neq, neq2, np2 = ', neq, neq2, np2
c      stop
c      do 51 j=1, neq
cc      a(j)=qk(j)

c      disp(j)=qk(j)
c      print *, 'a(j) = ', a(j)
c      print *, 'qk(j) = ', qk(j)
51      continue
c      stop

c      getsolve = 0

c      getforce = 1
c      getstiff = 0
c      print *, 'fintk = ', fintk
c      stop
c      write(6,*) 'Check inside itmml before 4th sysqn'

c      print *, 'b(i) before 4th sysqn=', (b(i), ic=1, ndof)
c      print *, 'ad before 4th sysqn solve=', (ad(i), i=1, maxdofpe**2)
c      print *, 'an before 4th sysqn solve=', (an(i), i=1, 50)
c      print *, 'disp before 4th sysqn in itmml=', (disp(i), ic=1, neq)
c      stop

c      print *, 'Check inside itmml before 4th sysqn'
c      print *, '!!!!!! 4th sysqn inside itmml !!!!!!!'
c      pause
c      stop
c      call sysqn(ne, ipvl, h, ndof, disp, iarc, qk,
$      ical, ic, iet, jcal, ia, ae, maxdofpe,
$      netype, nel, ndofpe, x, y, z, propmat, propsect, lin,
$      iboundc, ad, an, iperm, iu, ip, iut, dqtot, dq1, dqim1,
$      ux, uy, uz, di, il, area, youngm, iarea,
$      ianal, lumpmass, iskip, itempo2, iurmlon, exfor, istep,
$      jallo,
$      strainel, strainE, strainD, weight, iopt, Anew, Apart, Fin1,
$      Fin2, VED, VEDold, xlie, SED)

c      $ja, iboundc, ndofped, bc, lm, ndofped, ac, ip, tempo1, dm, am, ianal, lumpmass)
c      print *, 'getforce = ', getforce
c      write(6,*) 'Check inside itmml after 4th sysqn'
c      print *, 'Check inside itmml after 4th sysqn'
c      pause
c      print *, 'ad( ) in itmml after 4th sysqn=', (ad(i), ic=1, neq)
c      pause

c      ~~~~~ SETTING ZERO DIAGONAL VALUES TO ONE ~~~~~
c      Do 1015 i=neq*2+1, neq*3
c      Do 1015 i=1, neq
c      If(ad(i).GT..000001) GoTo 1015
c      If(ad(i).GT.1.e-8) GoTo 1015
c      a(i)=1.0
c      ad(i)=1.e-8
c      ad(i)=0.d0
1015      Continue

c      print *, 'b(i) after new 2nd sysqn=', (b(i), ic=1, ndof)
c      print *, 'ad after 2nd sysqn solve=', (ad(i), i=1, maxdofpe**2)
c      print *, 'an after 2nd sysqn solve=', (an(i), i=1, 50)
c      print *, 'disp after 4th sysqn in itmml=', (disp(i), ic=1, neq)
c      stop

c      print *, 'qk after 4th sysqn in itmml=', (qk(i), ic=1, 20)
c      print *, 'dq1 after 4th sysqn in itmml=', (dq1(i), ic=1, neq)
c      pause

c      do 703 i=1, neq
c      scali(i) = 1.d0/stiff(i,i)
c      c      print *, 'a(neq*2+i) = ', a(neq*2+i)
cc      scali(i) = 1.d0/a(neq*2+i) !!!Get diagonal
c      scali(i) = 1.d0/ad(i) !!!Get diagonal

c      print *, 'scali =', scali(i)
703      continue
c      pause

c      write(6,*) 'scali after 4th sysqn itmml=', (scali(i), i=1, neq)
c      print *, 'scali after 4th sysqn itmml=', (scali(i), i=1, neq)

c      print *, 'a=', a
c      stop
cc      call modify
c      print *, 'Check after sixth modify'
c      print *, 'a' after 6th modify = ', a
c      pause
c      getforce=0 !set back to zero
c      print *, 'a' after 3rd sysqn to getforce = ', a
c      stop
c** The DO below looks at dqk and assigns 0 to correspond
c** to the boundary conditions which were zeroed out in "a"
c** so if the displacements "qk" stored in the beginning of
c** big "a" equal zero, then "dqk(i)" must be zero.
c      Do 49 i=1, neq
c      If(a(i).eq.0.0)then
cc      If(disp(i).eq.0.0)then
c      dqk(i)=0.d0
cc      If(iboundc(i).eq.1)then
c      dqk(i)=0.d0
cc      Endif
c      print *, 'dqk(i)=', dqk(i)
49      continue

cc      print *, 'fintk 1a = ', fintk
c      stop

c      If(it.eq.2)then
cc      print *, 'it = ', it
cc      print *, 'dqk(i) = ', dqk
c      stop
cc      Endif
c      print *, 'a before resid = ', a
c      stop
c      print *, '***chk before resid end itmml***'
c      pause
c      print *, 'exlk before resid=', exlk
c      print *, 'exfor before resid=', (exfor(i), i=1, neq)
c      print *, 'b before resid=', (b(i), i=1, neq)
c      pause
c      ... compute the residual forces, resk, at qk and exlk
c      call resid(dqtot, dq1, dqim1, qk, b, exfor)
c      print *, 'resk( ) after 3rd resid in itmml= ', (resk(i), ic=1, neq)

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```

c      pause
c      print *, 'a after 3rd resid in itnrm1 = ', a
c      stop
c      print *, 'exlk after resid = ', exlk

c      print *, 'disp after resid in itnrm1 = ', (disp(ic), ic=1, ndof)
c      print *, 'dqtot after 4th sysoqn in itnrm1 = ', (dqtot(ic), ic=1, noq)

c      If(it .eq. 2) then
c      print *, 'it = ', it
c      print *, 'disp end itnrm1 = ', (disp(ic), ic=1, ndof)
c      print *, 'b( ) end itnrm1 = ', (b(ic), ic=1, ndof)
c      print *, 'ad end itnrm1 = ', (ad(ic), ic=1, maxdofpe**2)
c      print *, 'an( ) end itnrm1 = ', (an(ic), ic=1, 50)
c      stop
c      endif

c      pause
c      If(it .eq. 2) then
c      print *, 'resk( ) = ', (resk(ic), ic=1, noq)
c      print *, 'exlk = ', exlk
c      pause
c      stop
c      endif
c      print *, 'stop after resid'
c      stop

c ... test for convergence
cc      print *, 'toldis tolfor exlk iconv = ', toldis, tolfor, exlk, iconv
c      call test(toldis, tolfor, exlk, iconv)
c      print *, 'chk before test at end itnrm1'
c      print *, 'istep = ', istep
c      pause
c      print *, 'Before test 3'

c      call test(dqtot, dqim1, qk, exfor, h)
c      call test(disp, dqim1, qk, exfor)
c      print *, 'iflag after test = ', iflag
c      print *, 'iconv after test = ', iconv

c      If(it .eq. 2) then
c      print *, 'it = ', it
c      print *, 'iconv when it=2 = ', iconv
c      print *, 'iflag when it=2 = ', iflag
c      stop
c      endif

c      pause
c      print *, 'stop after test'
c      print *, 'a at end of itnrm1 = ', a

c      print *, 'b(i) end itnrm1 = ', (b(ic), ic=1, ndof)
c      pause
c      print *, 'ad end itnrm1 = ', (ad(i), i=1, maxdofpe**2)
c      print *, 'an end itnrm1 = ', (an(i), i=1, 50)
c      pause
c      print *, 'disp end itnrm1 = ', (disp(ic), ic=1, noq)
c      pause
c      stop

c** Initiate a counter for going back to 1002
iam=iam+1
cc      print *, 'iam at end = ', iam
c      print *, 'exlk at end = ', exlk
c      stop
c      print *, 'iconv = ', iconv
c      print *, 'it = ', it
c      print *, 'itemax = ', itemax
c      pause
c      go to 1002
c+++++
c+++++
c      elseif (iconv .ne. 0 .and. it .gt. itemax) then
c      print *, 'it = ', it

```

```

c      print *, 'Check at iflag = 2'
c      print *, 'iconv = ', iconv
c      print *, 'it at end of itnrm1 = ', it
c      print *, 'itemax = ', itemax
c      iflag = 2
c      end if
c      print *, 'exlk at end of itnrm1 = ', exlk
c      print *, 'Ready to leave itnrm1'
c      stop
7000      return
c      end

C *****
C ***      SUBROUTINE: STRAIN      ***
C *****
c      subroutine strain(istep, it, dqtot, dqim1, qk, exfor, ad)
c      implicit real*8(a-h,o-z)

c      common/RK/ stiff(60,60), dqk1(5000),
c      $      dqk2(5000), fntkc(5000),
c      $      resk(5000), scal(5000), work1(5000), indx(5000), neq

c      common/av/a(1500), jgt,jgsm,np,nbw,np2,nbw2
c      common/testing/toldis,tolfor,exlk,iconv

c      dimension dqtot(*), dqim1(*), exfor(*), qk(*), ad(*)

c      open(15, file='fca3d2_out.txt', status='unknown')

c*****
c** "cris_sdof_in.dat"*****
c      appliedforce = exlk * exfor(5)
c      if(istep .eq. 1) then
c      write(15,53)
c      format(' istep exlk appliedforce a(1)
c      $      a(2) n(5) it ad(3) ad(4)')
c      write(15,53)
c      format(' istep exlk appliedforce a(1)
c      $      a(2) a(3) a(4) a(5) a(6)
c      $      it ad(4) ad(5)')
c      endif
c      write(15,50) '**, istep, exlk, appliedforce,
c      $      dqtot(1), dqtot(2), dqtot(3), it,
c      $      ad(1), ad(2)
c50      format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3X,e10.4,
c      $      4x,i5,4x,e10.4,3x,e10.4)
c      write(15,50) '**, istep, exlk, appliedforce,
c      $      dqtot(1), dqtot(2), dqtot(3), dqtot(4), dqtot(5), dqtot(6), it,
c      $      ad(4), ad(5)
50      format(a1,2x,i4,5x,e14.6,3x,e10.2,6x,e10.4,6x,e10.4,3X,e10.4,
c      $      3x,e10.4,3x,e10.4,3X,e10.4,4x,i5,4x,e10.4,3x,e10.4)
c      return
c      end

```

VITA

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Doctor of Philosophy in Civil Engineering	2009
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Master of Science in Civil Engineering	1992

Old Dominion University	Norfolk, VA
Bachelor of Science in Civil Engineering	1988

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Research Engineer	July 2000 to present

Federal Data Corp. /NASA	1/1998 - 6/2000
Structural Engineer	

Newport News Shipbuilding	10/1996 - 12/1997
Structural Engineer	

U.S. Government/Army/Air Force	10/1994 - 10/1996
Project Engineer	

Sverdrup/Planning Research Corp.	5/1990 - 10/1994
Structural Test Engineer	

Hampton University	2003-2004
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